

LINEAR ALGEBRA

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POWER@UNIT

[Inner Product Spaces]

[Definition]

let V be a vector space, let $\langle \cdot, \cdot \rangle$ be a map $V \times V \rightarrow \mathbb{R}$, then V is called an Inner product space under the map $\langle \cdot, \cdot \rangle$ if the following is satisfied:-

$$\rightarrow \langle u, v \rangle = \langle v, u \rangle \quad \text{for all } u, v \in V$$

$$\rightarrow \langle ku, v \rangle = k \langle u, v \rangle \quad \text{for all } u, v \in V$$

$$\langle u, kv \rangle = k \langle u, v \rangle$$

$$\rightarrow \langle u + w, v \rangle = \langle u, v \rangle + \langle w, v \rangle$$

$$\langle v, u + w \rangle = \langle v, u \rangle + \langle v, w \rangle$$

$$\rightarrow \langle v, v \rangle \geq 0 \quad \text{and} \quad \langle v, v \rangle = 0 \quad \text{if } v = 0$$

عنازل (تفاهة)

example: $P^2 = \{ (x, y) \mid x, y \in \mathbb{R} \}$ [unit: (b, a)]

البيانات التي تأتي من الفضاءات العامة (general vector spaces) (البيانات التي)

سؤال
البيانات التي تأتي من

مبني عليها mapping (البيانات التي تأتي من)

mapping
البيانات التي تأتي من
مطلوب منها
تتبعها

given that $\langle (a_1, a_2), (b_1, b_2) \rangle = a_1 b_1 + a_2 b_2$
the way of mapping \checkmark

$\langle u, v \rangle = \langle v, u \rangle$
 $\langle (a_1, a_2), (b_1, b_2) \rangle \stackrel{P}{=} \langle (b_1, b_2), (a_1, a_2) \rangle$

$\rightarrow \langle ku, v \rangle = k \langle u, v \rangle$
so $\langle (ka_1, ka_2), (b_1, b_2) \rangle \stackrel{P}{=} k \langle (a_1, a_2), (b_1, b_2) \rangle$

$ka_1 b_1 + ka_2 b_2 \stackrel{P}{=} k(a_1 b_1 + a_2 b_2) \rightarrow$ توزيع الـ k
دفعوا متساويين \checkmark اذاً الشرط متحقق \checkmark

$\rightarrow \langle u + w, v \rangle = \langle u, v \rangle + \langle w, v \rangle$

$\langle (a_1, a_2) + (b_1, b_2), (c_1, c_2) \rangle \stackrel{P}{=} \langle (a_1 + b_1, a_2 + b_2), (c_1, c_2) \rangle +$
 $\langle (b_1, b_2), (c_1, c_2) \rangle$
 $(a_1 + b_1)c_1 + (a_2 + b_2)c_2 = (a_1 c_1 + a_2 c_2) + (b_1 c_1 + b_2 c_2)$

مع اقتران بالبيانات التي تأتي من الفضاءات العامة (البيانات التي)
Inner product spaces

examples:-

① let $x = (-1, 2, 3)$, $y = (-2, 0, 1) \in \mathbb{R}^3$

find:

① $\langle x, y \rangle \rightarrow$ mapping $a_1 \hat{b}_1 + a_2 \hat{b}_2 + a_3 \hat{b}_3$

$$= -2 + 0 + 3 = 1$$

② $\langle x + 2y, z \rangle$, where $z = (0, 1, -2)$

$$\langle x, z \rangle + \langle 2y, z \rangle$$

$$\langle x, z \rangle + 2\langle y, z \rangle$$

$$-4 + 2(-2)$$

$$-4 + -4 = -8$$

③ if $\langle x + ky, y \rangle = 4 \rightarrow$ find k

$$\langle x, y \rangle + \langle ky, y \rangle$$

$$\langle x, y \rangle + k\langle y, y \rangle = 4$$

$$1 + k(5) = 4$$

$$5k = 3$$

$$k = \frac{3}{5} \checkmark$$

حتى نستطيع معرفة الكمية التي map و norm خصائصها \mathbb{R}^n
 ← أصلاً دقة را دقتی برده، مثلاً دقت را حسب طول ال vector الی
 ← دقت را طرز او را حسب مسافت بین 2 vectors
 خلینا دقتی را لیب و -

① Definition:-

let $a = (a_1, a_2, \dots, a_n) \in \mathbb{R}^n$, then

norm = the length of vector $a = \|a\| = \sqrt{\langle a, a \rangle}$

ال vector الی map الی و دقتی

② Definition:-

let $u, v \in \mathbb{R}^n$, the distance between u, v

$$d(u, v) = \|u - v\| = \sqrt{\langle u - v, u - v \rangle}$$

But you should note that:-

If norm of $v = 1$, then v is said to be a unit vector ✓

example:-

let $u = (\frac{1}{\sqrt{2}}, 0, x)$, find all values of x

such that u is a unit vector.

$$\|u\| = 1$$

$$\sqrt{\langle u, u \rangle} = \sqrt{\frac{1}{2} + 0 + x^2} = 1 \rightarrow \text{جواب صحیح}$$

$$\frac{1}{2} + x^2 = 1$$

$$x^2 = \frac{1}{2} \rightarrow x = \sqrt{\frac{1}{2}}$$

Example :-

$$u = (3, -1, 2), v = (1, 1, 0) \in \mathbb{R}^3$$

Find $d(u, v)$

$$\|u - v\| = \sqrt{\langle u - v, u - v \rangle} \rightarrow u - v = (2, -2, 2)$$

$$= \sqrt{4 + 4 + 4} = \sqrt{12}$$

✓ $\|u - v\| = \|v - u\|$ دیرھنوں نکوڑا ماریں ایتہ

$$\hookrightarrow d(v - u) = \|v - u\|$$

$$v - u = -2, 2, -2 \rightarrow$$

$$\|v - u\| = \sqrt{4 + 4 + 4} = \sqrt{12}$$

example 1 -

If $u, v \in \mathbb{R}^n$ with $\rightarrow \|u\| = 2, \|v\| = 1, \langle u, v \rangle = -3$

Find $\|2u - 3v\|$

$= \sqrt{\langle 2u - 3v, 2u - 3v \rangle}$

$\rightarrow \langle 2u - 3v, 2u - 3v \rangle =$

$\langle 2u, 2u - 3v \rangle - \langle 3v, 2u - 3v \rangle =$

$\langle 2u, 2u \rangle - \langle 2u, 3v \rangle - (\langle 3v, 2u \rangle - \langle 3v, 3v \rangle)$

$4\langle u, u \rangle - 6\langle u, v \rangle - (6\langle v, u \rangle - 9\langle v, v \rangle)$

$4 * 4 - 6(-3) - (6(-3) - 9(1))$

$16 + 18 - (-18 - 9)$

$16 + 18 + 18 + 9$

then find the final result and the square root of it

note: If $u \in \mathbb{R}^n$ with $\|u\| \neq 0$, then $\frac{u}{\|u\|}$ is

a unit vector: the norm of $\left(\frac{u}{\|u\|}\right) = \frac{1}{1} = 1$

example:-

$u = (-1, 2, 3) \in \mathbb{R}^3$ show that $\frac{u}{\|u\|}$ is

a unit vector

$$\|u\| = \sqrt{1 + 4 + 9} = \sqrt{14}$$

$$\frac{u}{\|u\|} = \left(\frac{-1}{\sqrt{14}}, \frac{2}{\sqrt{14}}, \frac{3}{\sqrt{14}} \right)$$

now to get sure :-

$$\left\| \frac{u}{\|u\|} \right\| = \sqrt{\frac{1}{14} + \frac{4}{14} + \frac{9}{14}} = \sqrt{\frac{14}{14}} = 1 \quad \checkmark$$

Definition:-

$u, v \in \mathbb{R}^n$ are called orthogonal vectors

if $\langle u, v \rangle = 0$ ($u \perp v$)

example:-

$u = (3, x-1, 4)$, $v = (2, 2, -1)$, find x if

$u \perp v$

if $u \perp v$ then $\langle u, v \rangle = 0$

$$6 + 2(x-1) - 4 = 0$$

$$x = 0$$

Definition:-

let $u \neq 0 \in \mathbb{R}^n$ and $v \in \mathbb{R}^n$

then, the orthogonal projection of v on u

$$= \text{proj}_u v = \frac{\langle v, u \rangle}{\langle u, u \rangle} u$$

Theorem:-

$$\langle v - \text{proj}_u v, u \rangle = 0$$

$$\therefore v - \text{proj}_u v \perp u$$

example:-

$$\text{let } u = (2, 1, -1), v = (3, 0, 2) \in \mathbb{R}^3$$

$$\text{find } \textcircled{1} \text{proj}_u v = \frac{\langle v, u \rangle}{\langle u, u \rangle} u$$

$$= \frac{-6 + 0 + 2}{4 + 1 + 1} u = \frac{-4}{6} (2, 1, -1)$$

$$\textcircled{2} \text{proj}_v u = \frac{\langle u, v \rangle}{\langle v, v \rangle} v =$$

$$= \frac{9}{13} (3, 0, 2)$$

Definition let w be a subspace of \mathbb{R}^n , then

$B = \{y_1, y_2, \dots, y_n\}$ is called the orthogonal

basis for w if \rightarrow

- ① B is Basis for w
- ② $\langle y_i, y_j \rangle = 0 \rightarrow y_i \perp y_j$

and if you add ③ $\|y_i\| = 1$ for all $i = 1, 2, 3, \dots$ it will become orthonormal basis for w .

\rightarrow We use G.S.P to find an orthogonal basis

method let $\{x_1, x_2, \dots, x_m\}$

$$y_1 = x_1$$

$$y_2 = x_2 - \text{proj}_{y_1} x_2$$

$$y_3 = x_3 - \text{proj}_{y_1} x_3 - \text{proj}_{y_2} x_3$$

example 9

$$\text{let } R = \{(1, 0, -1, 2), (1, 1, 0, 1), (2, 1, 1, 1)\}$$

use G.S.P to find an orthogonal basis.

use the rule, and you'll have these answers:

$$y_1 = x_1 = (1, 0, -1, 2)$$

$$y_2 = x_2 - \text{proj}_{y_1} x_2$$

$$= \left(\frac{1}{2}, 1, \frac{1}{2}, 0\right)$$

$$y_3 = x_3 - \text{proj}_{y_1} x_3 - \text{proj}_{y_2} x_3$$

$$= \left(\frac{4}{6}, \frac{-2}{5}, \frac{4}{6}, 0\right)$$

and put them in the space $B = \{y_1, y_2, y_3\}$

note:- $A_{n \times m}$ is called orthogonal matrix

$$\text{if } AA^T = A^T A = I_n$$

اذا كانت A من الرتبة $n \times n$ وكانت $A^{-1} = A^T$ فإن A تسمى مصفوفة متعامدة.

$A \rightarrow$ orthogonal matrix $A^{-1} = A^T$ فإن A^{-1} تكون A^T تكون

► Subject :

Definition

$$\text{let } B_1 = \{u_1, u_2, \dots, u_n\},$$

$$B_2 = \{v_1, v_2, \dots, v_n\}$$

then, the transition matrices from B_1 to B_2

$$P_{B_1}^{B_2} = \begin{bmatrix} (u_1)_{B_2} & (u_2)_{B_2} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix}$$

Theorem:

$$\rightarrow \left(P_{B_1}^{B_2} \right)^{-1} = P_{B_2}^{B_1} \text{ and } \left(P_{B_2}^{B_1} \right)^{-1} = P_{B_1}^{B_2}$$

$$\rightarrow v \in W, \text{ then } P_{B_1}^{B_2} * (v)_{B_1} = (v)_{B_2}$$

* past papers questions:-

① let $B_1 = \{(1, 1), (2, 1)\}$, $B_2 = \{(1, 3), (2, 5)\}$

find ① $P_{B_2}^{B_1}$

implement the rules in the theorem

then $P_{B_1}^{B_2} = \begin{bmatrix} -3 & -8 \\ 2 & 5 \end{bmatrix} \rightarrow$ linear combinations

② $P_{B_2}^{B_1} = (P_{B_1}^{B_2})^{-1} = \frac{1}{1} \begin{bmatrix} 5 & 8 \\ -2 & -3 \end{bmatrix}$

[Eigenvectors] and [Eigenvalues]

Definition :-

let A be $n \times n$ matrix and let $\lambda \in \mathbb{R}$, then λ is called an Eigenvalue of A if there exists

$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \neq 0 \text{ such that :-}$$

$$\det(A - \lambda I_n) = 0$$

هنا وجود جبرين
في كل متجهين \checkmark

example :-

let $A = \begin{bmatrix} 2 & -1 \\ 2 & 5 \end{bmatrix}$, find all eigenvalues of A :-

$$\det(A - \lambda I_n) = 0$$

$$\det \begin{bmatrix} 2-\lambda & -1 \\ 2 & 5-\lambda \end{bmatrix} = 0$$

$$(2-\lambda)(5-\lambda) + 2 = 0 \rightarrow \text{هنا متجهين جبرين}$$

$$\lambda = 3, \lambda = 4$$

← جميع الجواب

properties of eigenvalues

Suppose $Ax = \lambda x$

→ λ^k is an eigenvalue of A^k

→ for any $k \in \mathbb{R}$, then $\lambda + k$ is an eigenvalue of $A + kI_n$

→ for $k \in \mathbb{R}$, $k\lambda$ is an eigenvalue of kA .

examples:-

-2, 1, 3 are eigenvalues of 3×3 matrix
find the eigenvalues of

① $A - 7I = -9, -6, -4$

② $A^2 + 2I = 6, 3, 1$

③ $(A - I)^2 = 9, 0, 4$

also :- this is the most important r

for any $k \in \mathbb{R}$, then

$\lambda + k$ is as mentioned above

$A + kI$

Note that:-

① If A is invertible \rightarrow all eigenvalues of A are non-zero, and eigenvalues of $A^{-1} = \frac{1}{\lambda}$ of A

② - summation of all eigenvalues of A = $\text{tr}(A)$
- product of all eigenvalues of A = $\text{det}(A)$

[Reverse Question]

example:-

2, -2 are eigenvalues of $A_{2 \times 2}$

\Rightarrow 4, 4 are the eigenvalues of A^2

\Rightarrow 4, 4 " " " of $2A \rightarrow$ مع أمثلاف الترتيب
التي هو راسي عادي \checkmark

\Rightarrow 1, 5 " " " of $A+3I$

\Rightarrow 9, 10 " " " of $2(A+3I)$

\checkmark قابل للتقطيع \leftarrow

note that:-

① If A is triangular matrix, then the eigenvalues of A are the entries on the main diagonal.

post papers:-

① $[3, -1, -1, 2]$ are eigenvalues of A with $\det(A) = 21$, find $\text{tr}(A)$

$$\det(A) = 21$$

$$\begin{aligned} \hookrightarrow 3 \times -1 \times -1 \times \lambda &= 21 \\ \lambda &= 7 \end{aligned}$$

$$\text{tr}(A) = 8$$

Note that:- the eigenvectors of A relative to λ are the $n \times n$ zero vector ~~space~~ λ in $\text{null}(A - \lambda I)$, this subspace is called eigenspace of λ .

$$\hookrightarrow \text{Eig}(\lambda) = \text{null}(A - \lambda I)$$

[Linear Transformation]

Definition

let V, W be real vector spaces, and
 let $T: V \rightarrow W$ be a map, then T is called
 a linear transformation

if:

$$\rightarrow T(u+v) = T(u) + T(v) \text{ for all } u, v \in V$$

$$\rightarrow T(ku) = kT(u) \text{ for all } u \in V, k \in \mathbb{R}$$

لازم هياي لشروط تحقق عشان اثبت انه transformation

← هاد لمتابرة عن تبار لمتابرة ، بظروف طريقة ال mapping
 الي هو بيها ، وانا بتاكد اذا تحقق لشروط اولاً هوهي هياي الطريقة
 راج استعمل عليها حول لحد ✓

ولكن كيف بي اهل سؤال هو مشي راي فيه صيغة ال mapping ؟