

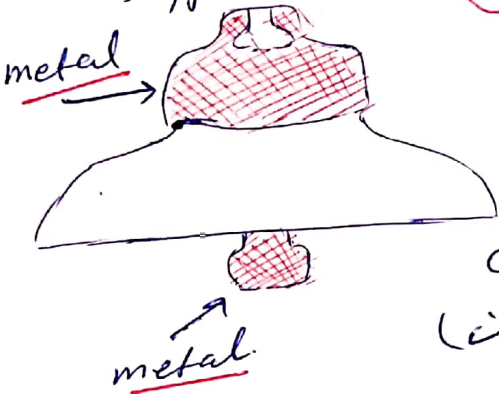
PART ONE

Exp. 1

المسألة 2)

- Voltage distribution → Insulator. (on suspension type insulator)
- Over head lines & Under ground cables → suspended
- Insulator type: PIN type, post type, and suspension type.

Suspension type الـ تعليق



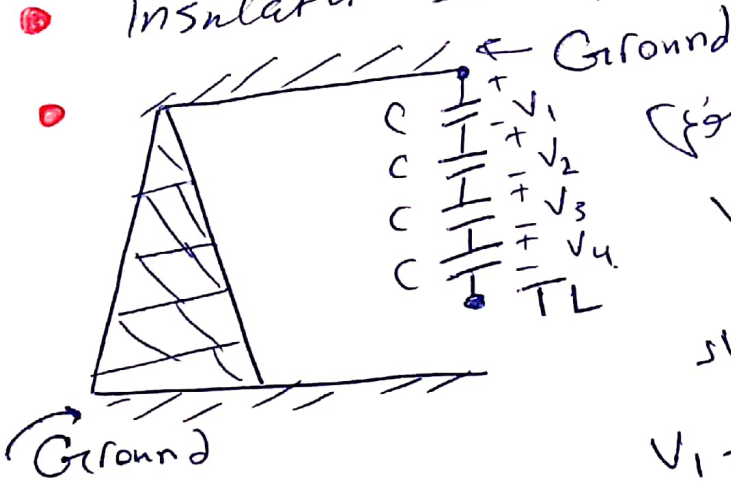
1) cheap

2) up to 44 kV

3) سلسلة من الوحدات ⇒ String of insulator.

cap (بجسرلات)

Insulator ≡ Capacitor.



سلسلة من الوحدات C المس

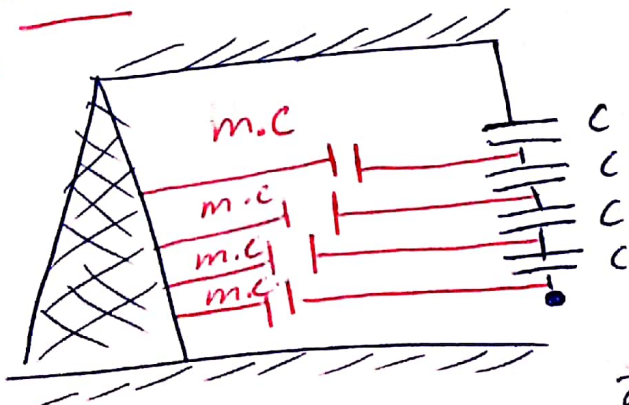
$$V_1 + V_2 + V_3 + V_4 = \frac{V_L}{\sqrt{3}} = V_T \cdot L$$

التي لا تحمل charging current

$V_1 \neq V_2 \neq V_3 \neq V_4$ (non-uniform voltage distribution)

• Capacitor to ground between:

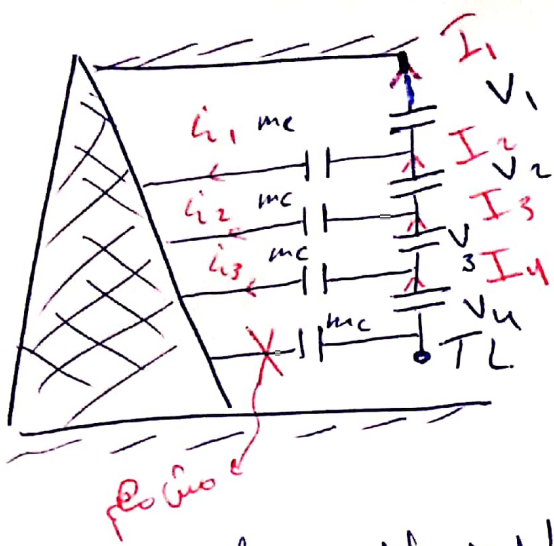
Cap & Tower of insulator 2



$$m = \frac{\text{Insulator capacitance}}{\text{Ground capacitance}}$$

$$= \frac{C}{m \cdot C}$$

$$m \rightarrow (0-1)$$



$$I_2 = I_1 + i_1$$

$$V_2 \omega C = V_1 \omega C + V_1 \omega mc$$

$$V_2 = V_1 (1 + m)$$

Therefore $V_4 > V_3 > V_2 > V_1$

ولذلك كلما قربنا كابل الى T.L كانت الفولتية اعلى كما
بسبب مشاكل وال Insulator ح يوصل على فولتية اعلى من الفولتية

الخط، الفولتية → flash over

Solutions: 1) Grading for units.

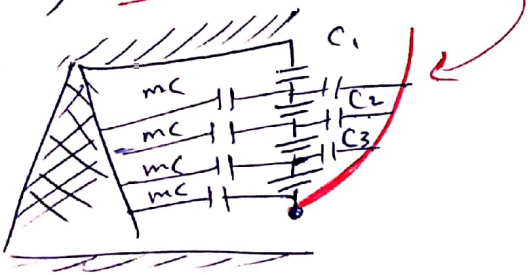
$$C_1 \neq C_2 \neq C_3 \neq C_4$$

بحيث ان C_4 تكون قبة اعلى، ويقل فولتية اعلى.

→ Dis advantage: not practical

لانه اذا
خرب واحد من الجوارد بي الخطر كله، وان كل قبة لكل
واحد. Hard in maintenance.

2) Guard link



$$I_2 + i_1' = I_1 + i_1$$

$$i_1' = i_1$$

$$C_1 (4V_1 - V_1) = V_1 mc$$

$$V = V_1 + V_2 + V_3 + V_4$$

$$= 4V$$

$$\rightarrow C_1 3V_1 = V_1 mc$$

$$C_1 = \frac{mc}{3}$$

Exp 2

$E = \frac{1}{I_2}$
 withstanding negative sequence.

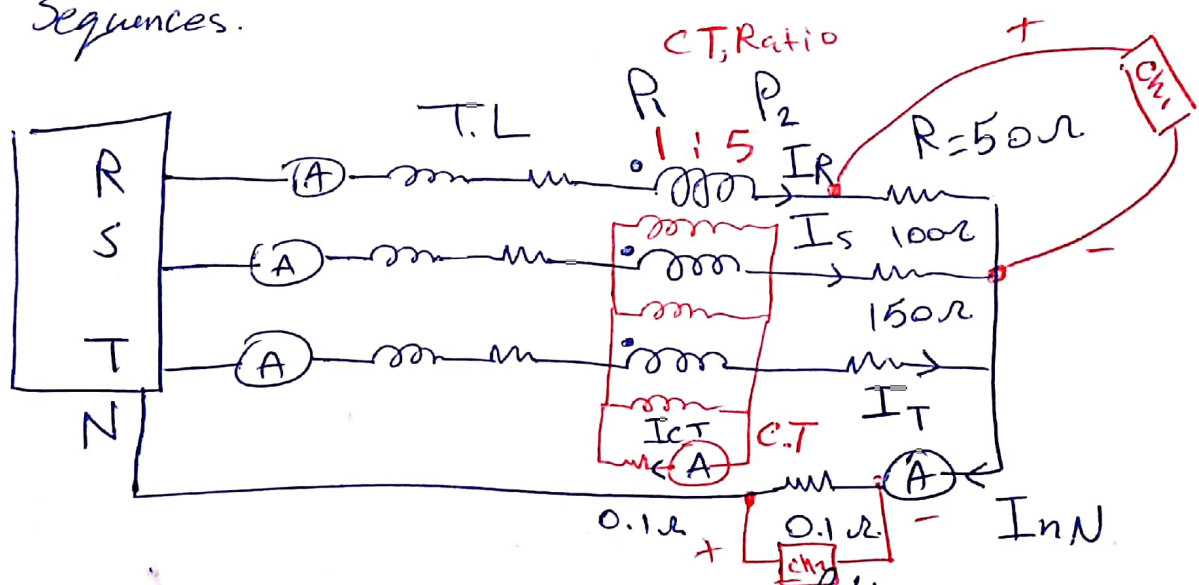
• Our system is balanced \rightarrow unbalancing the load

• I_{CT} ratio, I_{CT} ratio is 2000:500:1000

\rightarrow the sequence \rightarrow in all balanced systems.

\rightarrow Zero sequence \rightarrow when a fault is there.

• We will make filters to obtain the, -ve & Zero Sequences.



This is a Zero sequence filter.

• 0.1Ω : to see phase shifts for wave currents.

$$I_{nN} = I_R + I_S + I_T$$

$$I^{(0)} = \frac{I_{nN}}{3}$$

$$I_{CT} = \frac{I_{nN}}{5} = \frac{3I^{(0)}}{5} = I_{CT}$$

$$I^{(0)} = \frac{I_{CT} \times 5}{3}$$

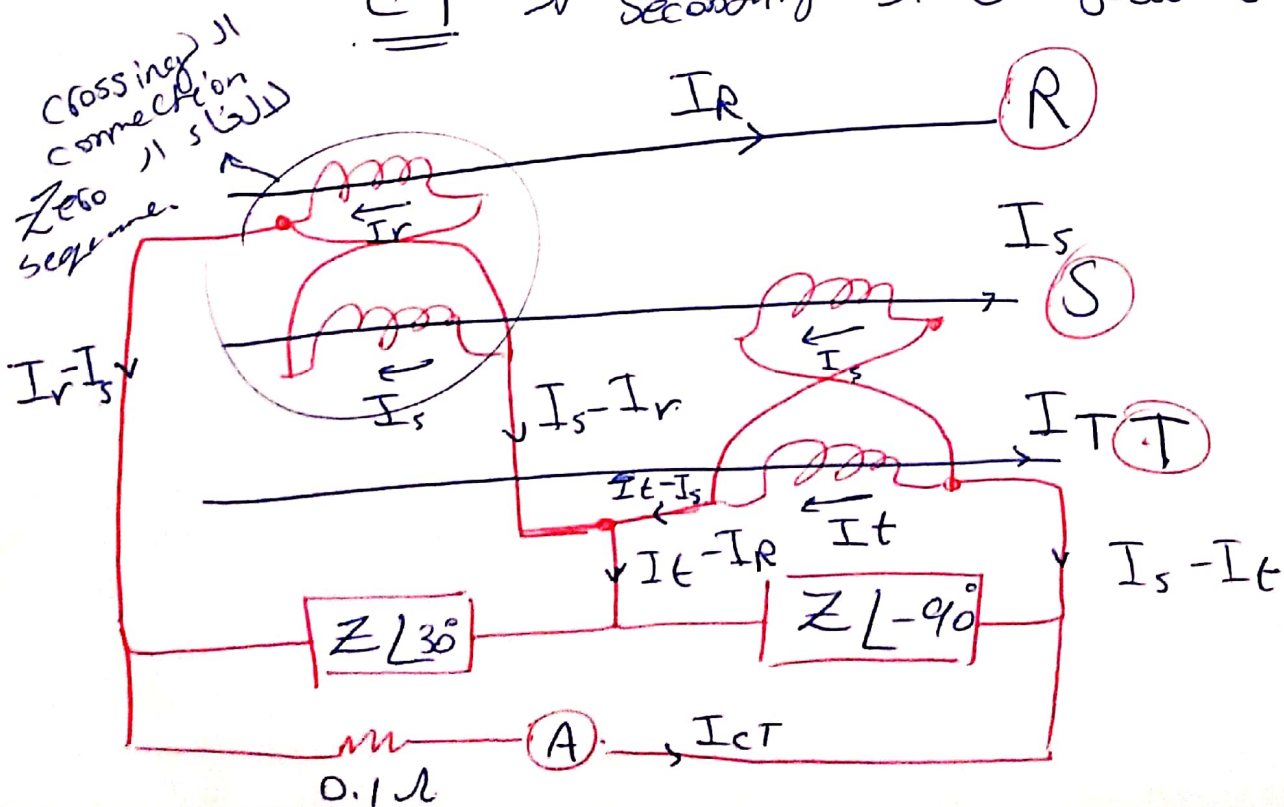
- (Vs) I_R, I_S ١) حسب ١) ←
- I_R, I_T ٢)
- I_R, I_{nN} ٣)
- I_R, I_{CT} ٤)

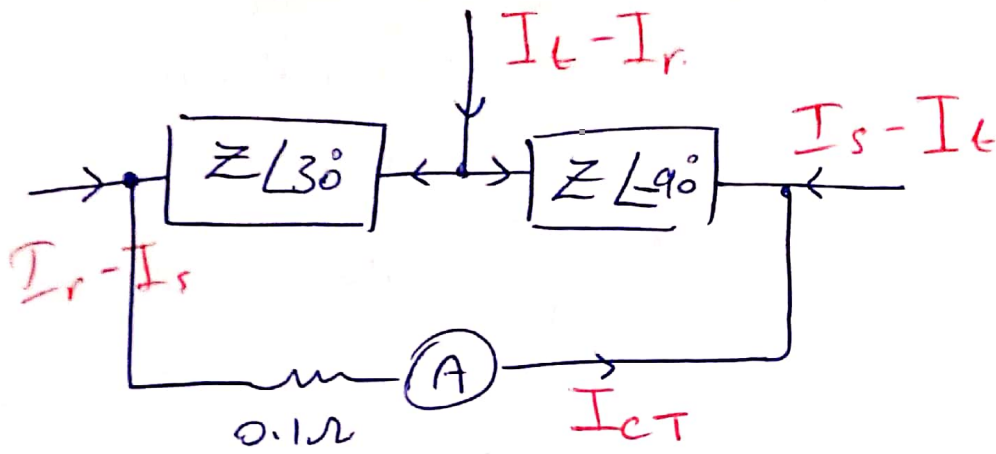
• if $I_R \neq I_S \neq I_T \Rightarrow$ neutral jump V_{nN}
 ↳ phase shift between them = 120° .

$V_{nN}: V_{RN} = I \cdot R \dots$ بقيهم
 $3 \times V^{(0)}$ بلا وي

positive & negative sequence current.

CT secondary ١) كل اللى فى الـ CT





$$I_{CT} = \frac{Z_{L90}}{Z_{L30} + Z_{L90}} * (I_{ct} - I_r) + I_r - I_s$$

$$I_{CT} = - \frac{Z_{L30}}{Z_{L30} + Z_{L90}} * (I_{ct} - I_r) - (I_s - I_{ct})$$

① Zero Sequence.

$$1 \angle -60^\circ (I_{ct}^{(0)} - I_r^{(0)}) + I_r^{(0)} - I_s^{(0)}$$

$$I_{CT}^{(0)} = \text{Zero}$$

② Positive Sequence.

$$1 \angle -60^\circ (I_{ct}^{(1)} - I_r^{(1)}) + I_r^{(1)} - I_s^{(1)}$$

$$1 \angle -60^\circ (I \angle 120^\circ - I \angle 0^\circ) + I \angle 0^\circ - I \angle 120^\circ$$

Negative = Zero

$$I_{CT} = 3 I^{(1)} \angle +60^\circ$$

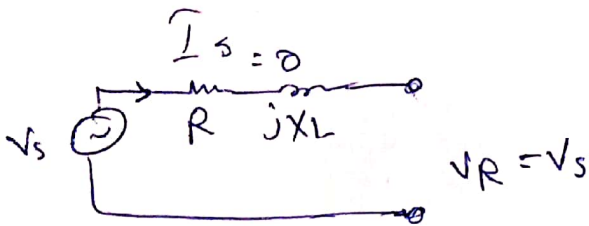
positive sequence

$$\underline{Z_B} \neq \underline{Z_A} \text{ سبب } \otimes$$

negative sequence current.

Power Lab Experiment

Short transmission line.



open circuit

$$I_s = 0, V_s = V_R$$

$$V_s = A V_R + B I_R$$

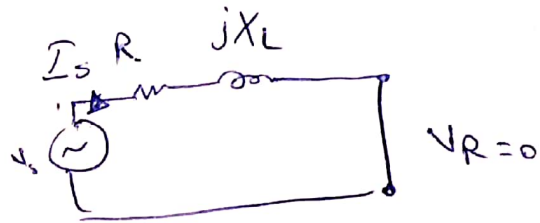
$$I_s = C V_R + D I_R$$

$$A = \left. \frac{V_s}{V_R} \right|_{I_R=0} \approx 1$$

$$C = \left. \frac{I_s}{V_R} \right|_{I_R=0}$$

short circuit

$$B = \left. \frac{V_s}{V_R} \right|_{V_R=0} = \text{in ohms}$$



$$A = D$$

$$\begin{bmatrix} V_s \\ I_s \end{bmatrix} = \begin{bmatrix} 1 & Z \\ 0 & 1 \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}, Z = R + jX_L$$

Voltage Regulation: when there's a load

$V_R \downarrow \rightarrow$ Better (no much losses on the receiving side)

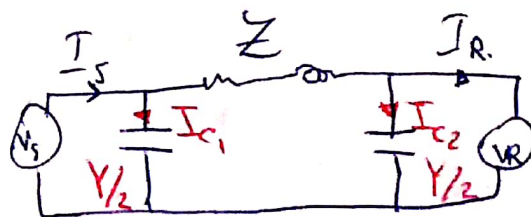
$$VR \% = \frac{V_{RNL} - V_{RFL}}{V_{RFL}} \times 100\%$$

Medium Transmission line

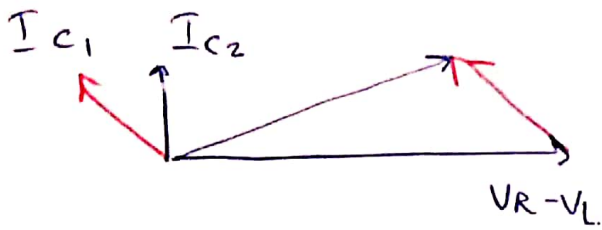
open circuit test

$$A = D = \frac{ZY}{2} + 1$$

$$B = Z \cosh(\gamma l), \quad C = Y \left(1 + \frac{ZY}{4} \right)$$



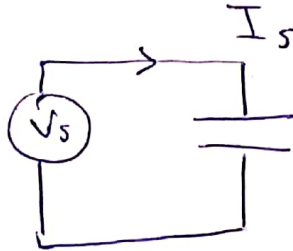
[2]



$V_R > V_S$

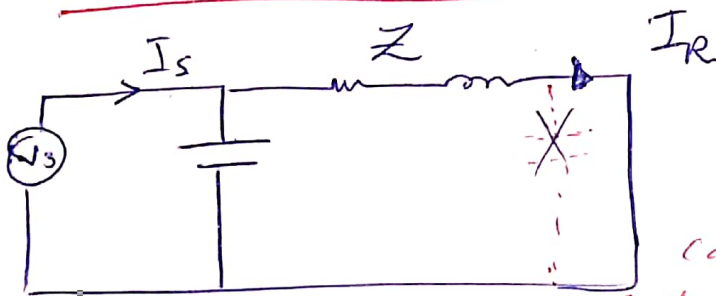
Solution: inductive compensation.

open circuit test



$I_S = Y V_S$

Short circuit test



2) capacitor short. \rightarrow I_{c2}

$P_{dc} = I^2 R$, $C \rightarrow$ open circuit test ✓

$R \rightarrow$ short circuit test ✓

$V_S I_S = S$
 $(S = P + jQ)$

$Q = I V \sin \theta$
 $P = I V \cos \theta$

$\Rightarrow Z \checkmark$

- Voltage on V_R very high $\begin{cases} \textcircled{1} \text{ light load} \\ \textcircled{2} \text{ no load.} \end{cases}$

\rightarrow Use inductive compensation.

- Voltage drop \rightarrow Use capacitive compensation.

change in Q

Exp 4

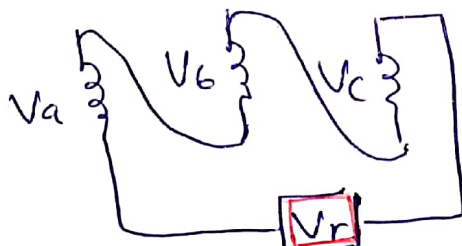
* at balanced conditions $V_n = \text{earth voltage} = \text{Zero}$

* If one phase was earth faulted, the other phases V_{L-G} will be 60° out of phase.

→ The current in case of one phase - earth faulted is small and won't be detected except by an alarm circuit from open delta secondary winding of a voltage transformer @ sending

End.

→ To avoid prolonged outages, the line is switched off.



open Δ earth fault detection.

$V_r = 3V_a$ → fault between a & earth.

* Arcing ground: The process by which the clearing and restriking of the arc caused recurring high surge voltages.

* Solidly earthed neutrals: earthing conductor between earth rod and ground.
 → also called effectively earthed. → when phase fault voltage do not exceed 80% of V_{phase} .

$$\frac{X_0}{X_1} < 3$$

* Treating neutral points:

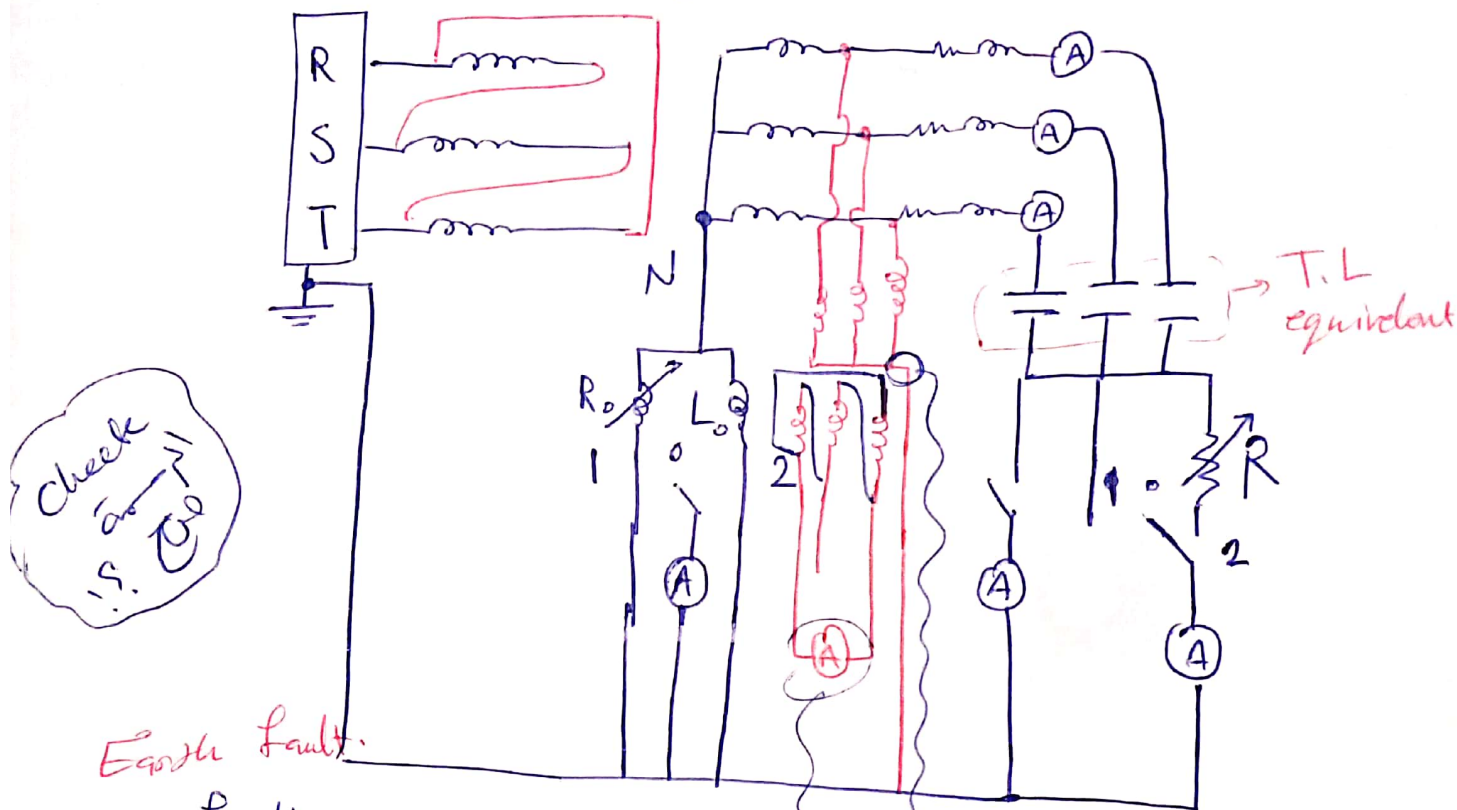
- | | | | | |
|---|------------|------------------------------|---------------------|-----------------------|
| 1 | ΔY | 6.6k or 11k / 380 or 415 | solidly grounded | $\frac{R_0}{R_1} < 1$ |
| 2 | ΔY | 33/11k or 132/11k or 132/33k | or | $\frac{R_0}{R_1} < 1$ |
| 3 | | 132k & above | are solidly earthed | through resistance |

Experiment 4

II

● Grounding to protect human & Equipments

220/230 → Isolator



Earth Fault.

- When fault occurs, change in one phases $\uparrow\uparrow = \text{Zero}$ & healthy = V_{L-L}

for fault detection
 voltage transformer
 connections of 10
 phase, 120V
 100V, 100V
 100V, 100V
 current 1

● Solid Earth fault

↳ without a resistor

$$I_t = 0.$$

$$I_c = I_R + I_S$$

$$I_c = \frac{V_{LL}}{X_c} + \frac{V_{LL}}{X_c}$$

$$= \frac{\sqrt{3} V_p}{X_c} + \frac{\sqrt{3} V_p}{X_c} \quad L-120$$

$$I_c = \frac{3V_p}{X_c}$$

When there's an R (Grounding)
 ↳ current (Fault) will decrease

Note - Best grounding
 ↳ minimum $I_{F \text{ fault}}$ is when $\frac{X_c}{X_L}$ is Resonated with inductor in transmission line.
 capacitors

Resonance $I_c = I_L \Rightarrow$ equal.

$$\frac{V_p}{X_L} = \frac{3V_p}{X_c}$$

$$X_c = 3X_L$$

$$\frac{1}{\omega c} = 3\omega L$$

$$1 = 3\omega^2 cL$$

$$L = \frac{1}{3\omega^2 c}$$

for minimum fault current

Question in Final Exam:- Given:

→ $I_f = 0$, X_c & V_n -? L, P, I_c → you can calculate them & find $I_L = I_c$. X_L can also be found!
 & find other thing →
 This is the way to begin.

Exp 5

RXIG

I: over current relay.

→ In Lab, the current base value is 2.5A

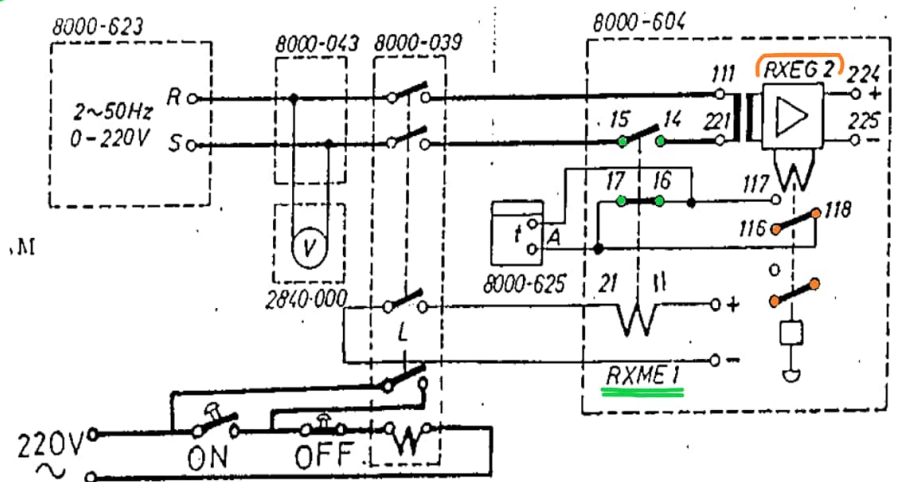
* If the scale factor is 1 the relay will trip at 2 ⇒ $2 * 2.5 = 5A$

$1 * 2.5 = 2.5A$

* It's an instantaneous over current relay (High Sensitivity)

* the signal to trip will change the state of switches: N.O → closes.
N.C → opens.

دائماً بالرسومات
اتبع الخط الممنهج
حتى تعرف كل Relay
Switch
للاي تابع



Exp 5 cont.

RXEG

→ E: over voltage relay.

→ Base Value for the relay in Lab = 80V.

* If the scale factor = 1, the relay will give signal to trip @ $1 * 80 = 80V$.

* **Resetting Value**: the amount of time that the relay take to be able to clear another fault after the clearing the first one.

* RXEG has a flag for when a fault occurs. (Disadvantage) لا يمكن إعادة هذا ال flag إلا manually والسبب هو عند حدوث fault يمكن ان يزول به فنتيجة لكن على العكس ان يعلم بصوتة ولذا يبقى ال flag.

* **RXF₁**: Indication relay.

يطع flag لما ال overvoltage relay يستعمل

*
$$\text{Resetting Ratio} = \frac{\text{Resetting Value}}{\text{Operating Value}}$$

$$RR < 1$$

< 0.95 - 0.98 > كما ان اى يتكون ال Sensitivity أكبر

Exp 5 Cont.

* $R_x F_1$ \rightarrow Flag is up @ resetting value.
 \rightarrow Flag is down @ operating value.

* $R_x I_G$ & $R_x E_G$ are designed for AC. But need DC auxiliary supply.

\rightarrow Has two change over contacts and one flag.

\rightarrow $R_x I_G$ \rightarrow Has air gap in input transformer:
Insensitive to DC component.

\rightarrow Doesn't have air gap:

1] Sensitive to DC.

2] Low power consumption

3] High sensitive earth-fault protection.

4] High operating values @ higher frequencies.

5] High over load capacity.

\rightarrow $R_x E_G$

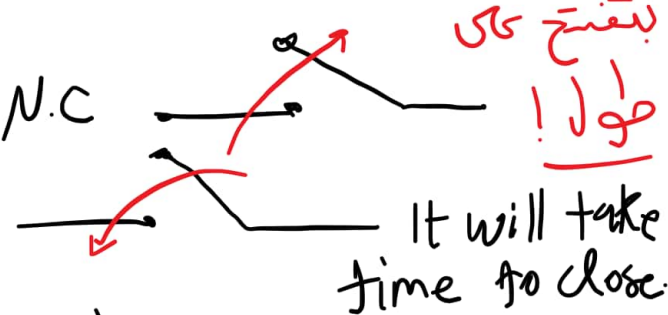
Up to 400 Hz \rightarrow operating values has no variations.

* power consumption: $V_{operating} * I_{operating}$
 ≈ 0.3 VA due to High input Impedance.

Exp 5 cont.

* **RXME** : this relay to trigger the timer.
 ↳ measure pickup time.

* When the switch is N.C
 But when it's N.O



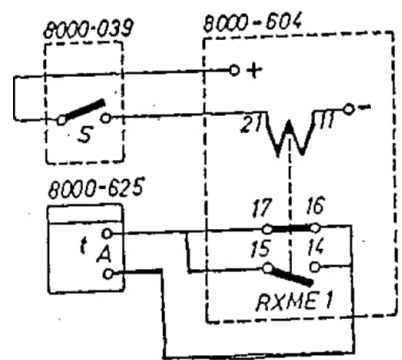
* That's why we have two times

11 Real time
 ↳ باضد من ال timer

2 Correct time
 ↳ بحسب اسطريخ

$$\text{Correct time} = \text{Real time} - \text{Switch time}$$

* Changing voltage doesn't affect time
 Relay ال ال instantaneous.



بحسب ال Switch
 باجراء تجربة يه
 $\approx (12-14) \text{ msec.}$

→ It takes one cycle to calculate the RMS
 therefore (20-30) msec

كمان يستعمل

1. RXIC Relay (Electromechanical)

. Description of RXIC Relay

over current relay

$$RMS = \sqrt{(D_c)^2 + (A_c)^2}$$

The operation principle of this relay depends on the electromagnetic force created by energizing the electromagnet (1), as shown in **Figure 1**.

Then after energizing, the force produced will attract the armature (2).

When the current is no longer running in the coil attached to (1), the spring will help bringing back (2) to its original position.

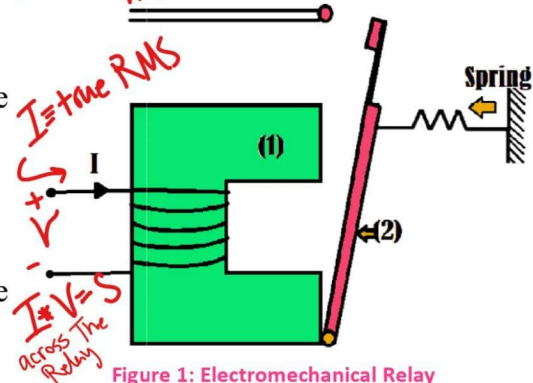


Figure 1: Electromechanical Relay

. Advantage and Disadvantage of the Electromechanical Relay:

- The Apparent Power is greater after energizing the relay compared to the Apparent Power before energizing it.
- It uses Permanent Magnet Moving coil meter (PMM) thus, it works on a linear scale.
- The PMM reads Dc values so it can give us the average value only.
- In order to read the Root Mean Square value (RMS), we must rectify the input, and then use a Form Factor (FF).
- This type of relays can be connected in series with the source and will take the energy directly from it. No need for external sources (Auxiliary).
- The sitting ratio depends on the spring.
- It has low accuracy and sensitivity.
- It may use Moving Iron meter (IM) and when it does, the scale becomes nonlinear.
- In case of IM, the meter reads the True RMS value. This value can be obtained due to the effect of the torque applied on it.

RXIG Relay (Electrostatic)

. Description of RXIG Relay

The **input circuit** to this relay is a **transformer** (1) as shown in **Figure 2**.

The transformer with its air gap works as a **filter for the Dc component**. The relay thus will be affected by the AC part of the input. The relay needs an external Dc source (Auxiliary voltage source) to operate (2).

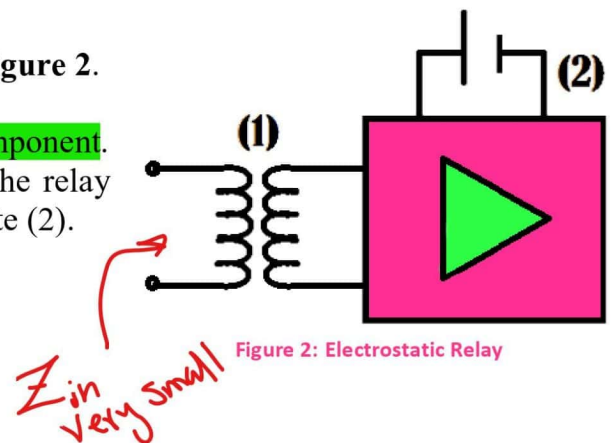
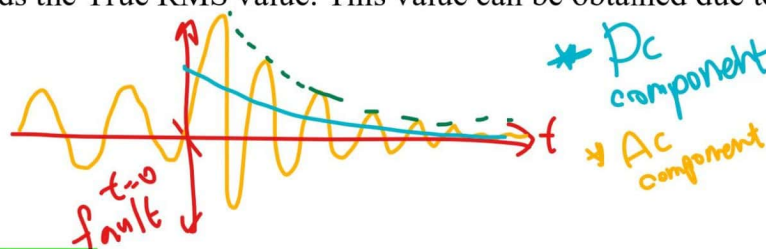


Figure 2: Electrostatic Relay

. Advantage and Disadvantage of the Electrostatic Relay:

- The Apparent Power is fixed and does not change during energizing.
- The value of the apparent power is lower compared to the electromechanical relay.
- The relay works only on the AC and the readings are proportional the instantaneous rate of change.
- It has very low input impedance.
- Very sensitive compared to the electromechanical relay.
- Setting ratio is very high compared to the electromechanical relay.
- Very high accuracy.
- Needs an external DC voltage source.

Comparison between the two relay types

. Operating and resetting values:

The RXIG relay works on AC and the RXIC relay works on DC. The RXIC relay has lower accuracy and sensitivity compared to the RXIG relay. The resetting ratio of the relay RXIG relay is higher than the RXIC relay.

. Power Consumption:

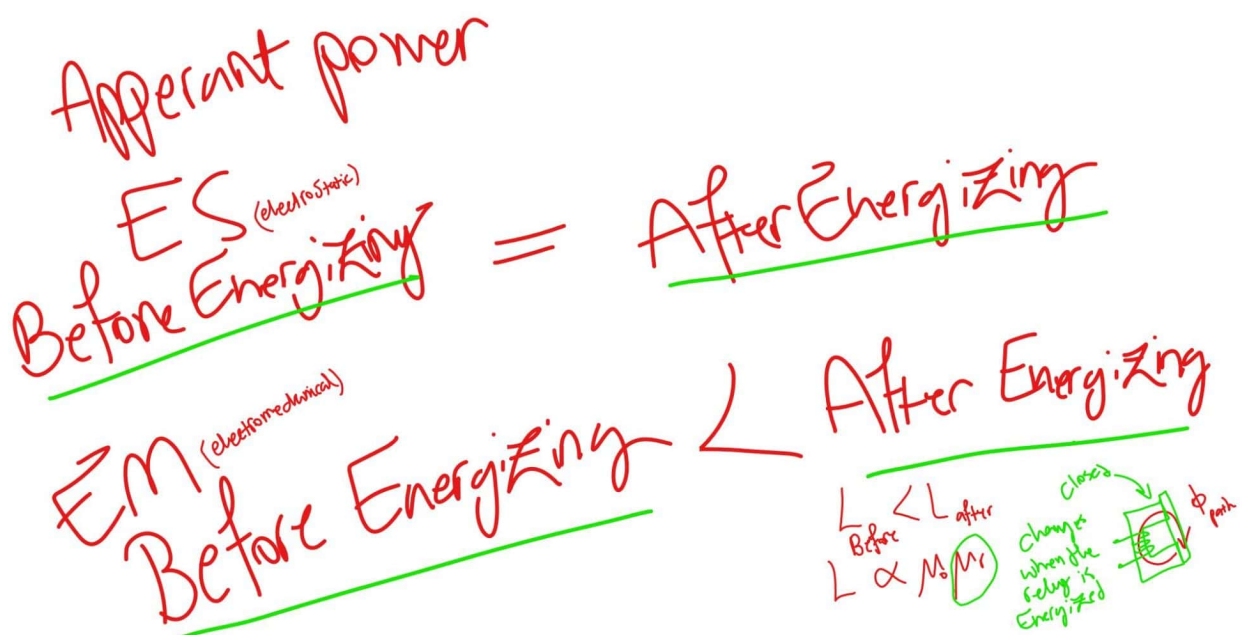
The RXIG relay has lower apparent power consumption compared with the RXIC relay, but the RXIC relay changes apparent power when energizing.

. Effect of the DC component:

The RXIG relay is not affected by the DC component because of the input circuit it has. Its input circuit consists of a transformer that filters out the DC component and keeps the AC part only. As for the RXIC relay, it is highly affected by the DC components. It actually operates on it.

Conclusion

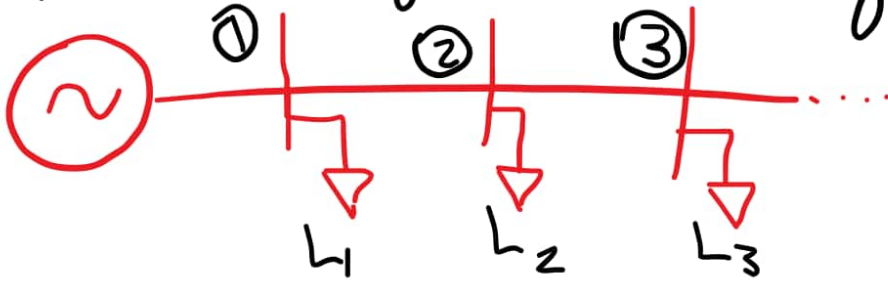
In practice, we use both relays for protection. They are usually connected in **series** so that we are getting advantages from both; the electromechanical relay (RXIC) and the electrostatic relay (RXIG).



Exp 7

RXIDE

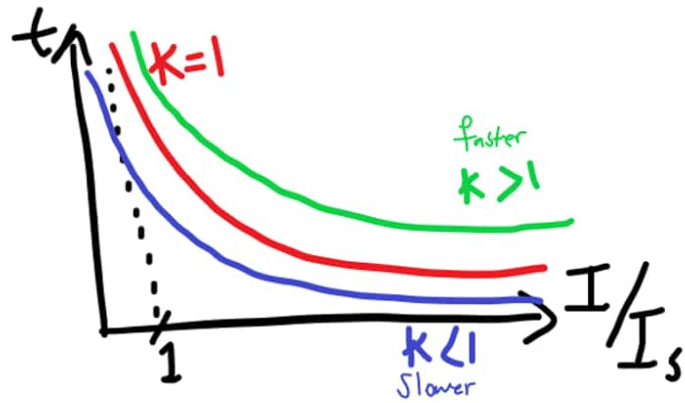
- Inverse time lag over current relay.



$$I_{rated_1} > I_{rated_2} > I_{rated_3} \dots$$

$$I_{setting_1} > I_{setting_2} > I_{setting_3}$$

- * if $I < I_s$ (normal)
- * if $I_s < I < I_{max}$ (inverse)
- * if $I > I_{max}$ (instantaneous over-current relay)



Three control knobs:

① A → current settings

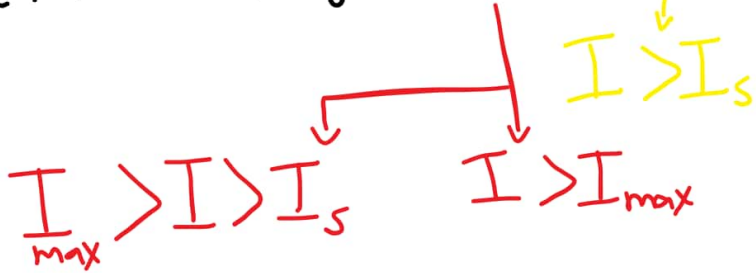
② B → instantaneous settings ($I_B = 4$ in lab)

③ C → time settings (k)

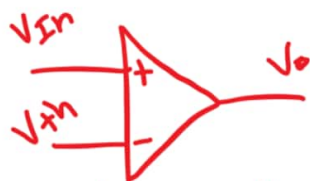
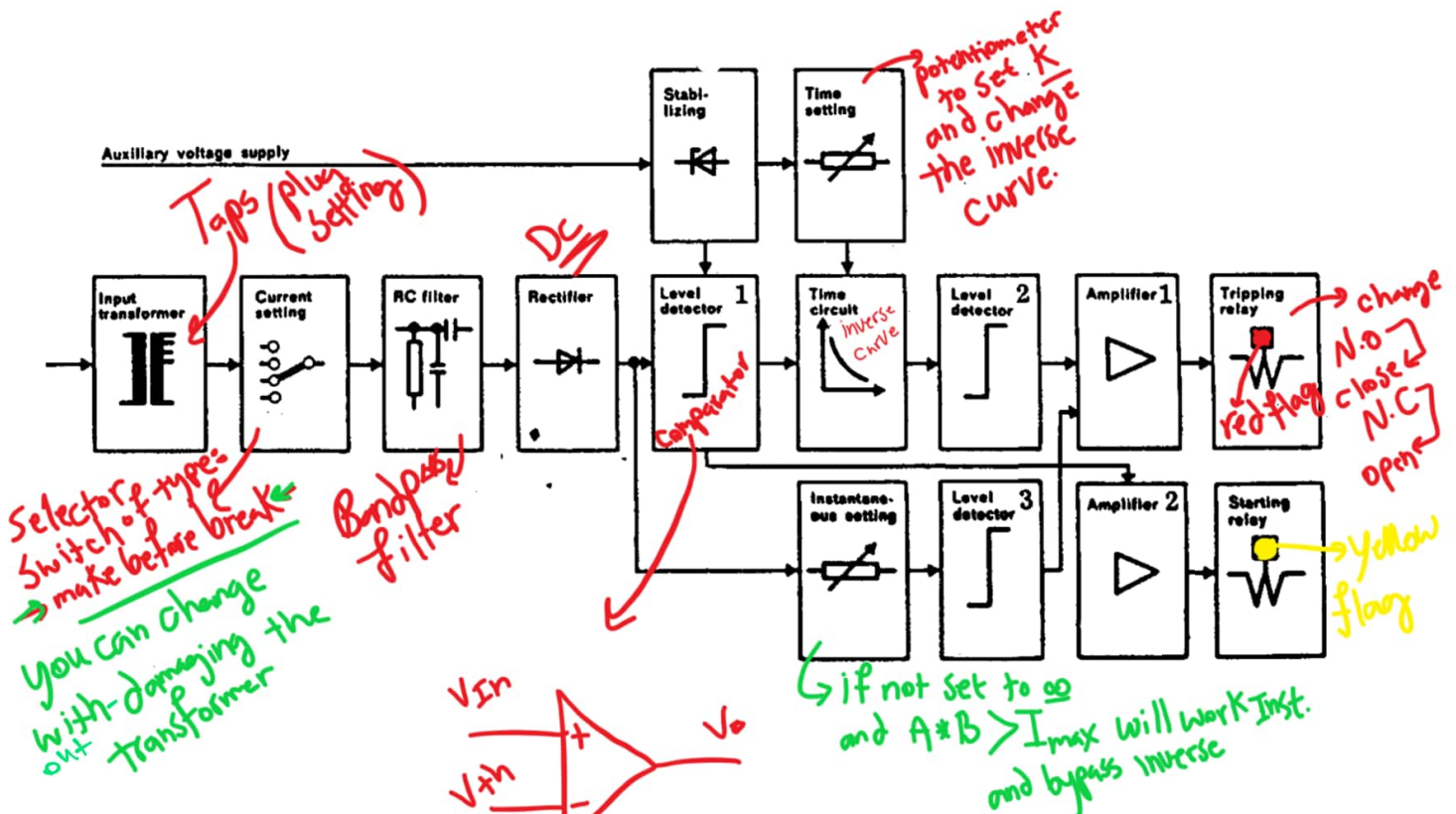
Exp 7 cont.

RXIDE

→ It has Two flags: **RED** **Yellow**



→ Set ∞ to avoid instantaneous operation.



- if $V_{in} < V_{th}$ or $V_{in} = V_{th}$ (low V_o) X
- if $V_{in} > V_{th}$ (V_o High) → signal to trip ✓

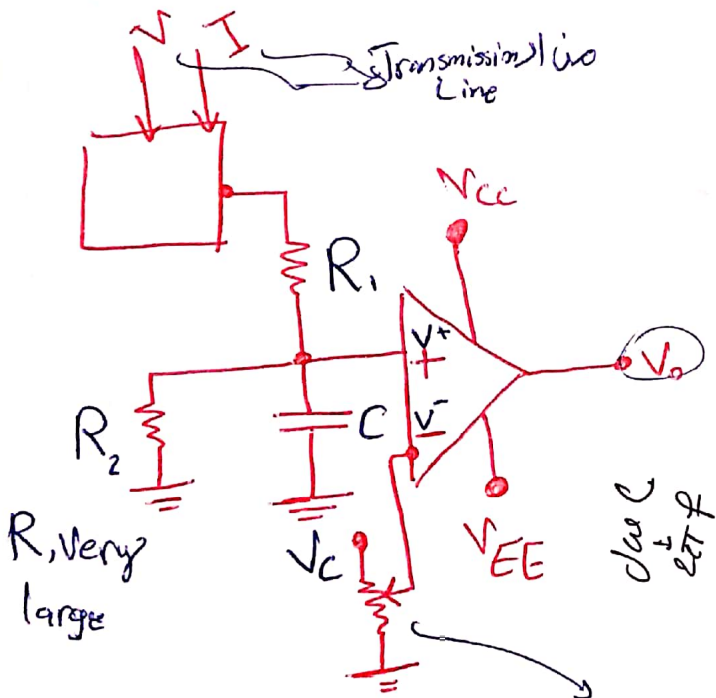
Experiment 8 RXPE-40
40 amp

Type RXPE Directional Relay? also called Power relay?

→ operates on 1-4 times scale constant

* two contacts BUT only one changeover contact

The second contact is a flag that is reset manually.



Constant → Current Multiplier
Higher scale factors → higher operating time.

OP Amp Comparator
 V_0 →

① Zero or negative if $V^- > V^+$

② High or positive Trip signal

if $V^+ > V^-$

! PVEU ...

$$I_s \leq I \cos(\phi - \alpha)$$

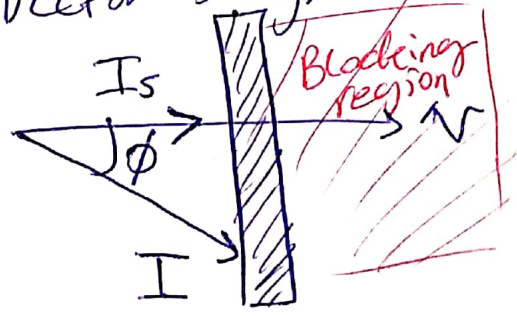
Setting current Transmission Line phase angle Zero Relay

I ...

$$I = \frac{I_s}{\cos(\phi)}$$

... zero

Vector Diagram



There are two coils:
→ Current coil

→ Voltage coil (as reference)

Reference ... Voltage ...

Directional ...

two coils → Power Relay

• ϕ : affects the sensitivity

• α : phase angle

maximum sensitivity

called characteristic angle.

if $\alpha = 0 \rightarrow$ relay will operate for very low values of input voltage.

• Relay is like a DC voltage or current transformer.

• RPE-40 has low power consumption compared to mechanical relays.

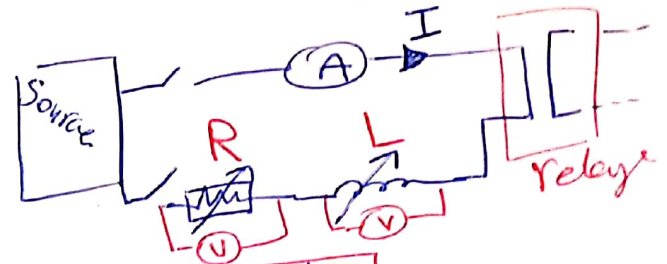
not affected by temperature variations.

• 30-15 sec until the capacitor discharge (الوقت التي لا يفرغ فيها المكثف)

$$I = \frac{I_s}{\cos(\phi - \alpha)}$$

② S_2 : prevent current from entering the circuit & build up voltage across the capacitor and correct the settings.

يمكننا ان نرى في دائرة inductor مع resistor في series مع source.



$$\tan \phi = \frac{V_L}{V_R}$$

$$V_L = I R \tan(\phi)$$

③ Questions

How to measure PF using only multimeter?

→ Inductor voltage across it.

③ The voltage coil is used as reference & to know direction changes in current.