



EM

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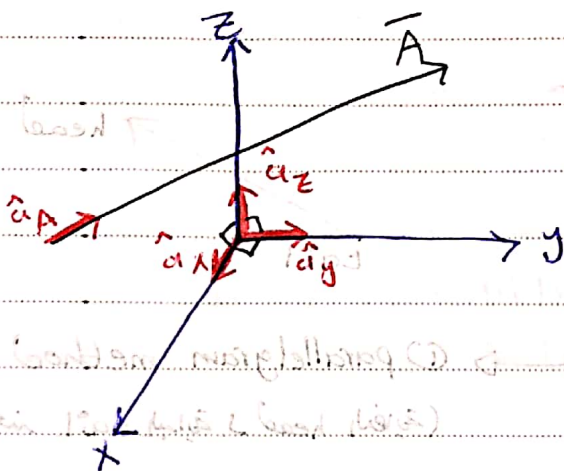
 **POWER@UNIT**

Chapter 1 \Rightarrow Vectors Review

• How to write a vector?

$\vec{A} \Rightarrow$ vector A (magnitude & direction)

\rightarrow In cartesian coordinates :-



long format \Rightarrow
 $\vec{A} = A_x \hat{a}_x + A_y \hat{a}_y + A_z \hat{a}_z$

short format \Rightarrow

$$\vec{A} = (A_x, A_y, A_z)$$

where $A_x, A_y, A_z \equiv$ vector components

\hookrightarrow (scalar) (magnitude only)

$\hat{a}_x, \hat{a}_y, \hat{a}_z \equiv$ unit vectors

\hookrightarrow magnitude = 1 (Direction only)

$|\vec{A}| \Rightarrow$ magnitude, $|\vec{A}| = A = \sqrt{A_x^2 + A_y^2 + A_z^2}$

$\hat{a}_A \Rightarrow$ direction, $\hat{a}_A = \frac{\vec{A}}{A} = \frac{A_x \hat{a}_x + A_y \hat{a}_y + A_z \hat{a}_z}{\sqrt{A_x^2 + A_y^2 + A_z^2}}$

$$\hookrightarrow \vec{A} = A \hat{a}_A$$

* If vector B

$$\vec{B} = B_x \hat{a}_x + B_y \hat{a}_y + B_z \hat{a}_z$$

$$\vec{B} = (B_x, B_y, B_z)$$

- ex: $\vec{B} = (4, 0, 5)$

- ex: $\vec{C} = 3\hat{a}_x + 5\hat{a}_z$

$$\hookrightarrow \hat{a}_C = \frac{\vec{C}}{C}, C = \sqrt{34}$$

$$= \frac{3\hat{a}_x}{\sqrt{34}} + \frac{5\hat{a}_z}{\sqrt{34}}$$

Operations on vectors :-

III Addition & subtraction \Rightarrow vector \vec{C} will

$$\vec{B} = B_x \hat{a}_x + B_y \hat{a}_y + B_z \hat{a}_z$$

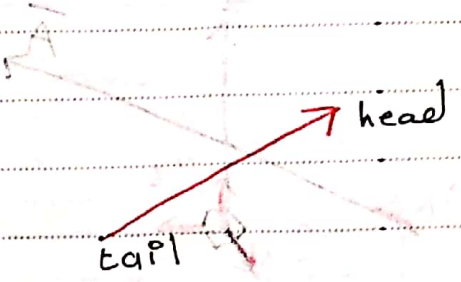
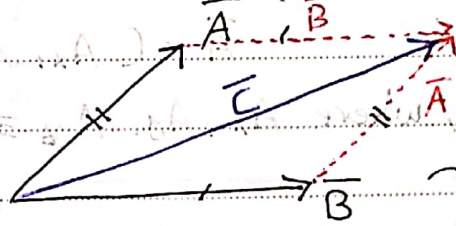
$$\vec{C} = \vec{A} + \vec{B} = (A_x + B_x) \hat{a}_x + (A_y + B_y) \hat{a}_y + (A_z + B_z) \hat{a}_z$$

$$\vec{C} = \vec{A} - \vec{B} = (A_x - B_x) \hat{a}_x + (A_y - B_y) \hat{a}_y + (A_z - B_z) \hat{a}_z$$

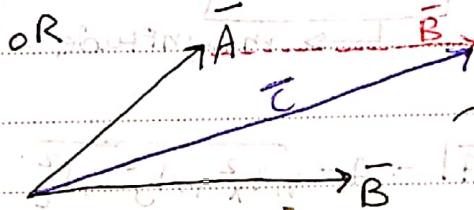
$$= C_x \hat{a}_x + C_y \hat{a}_y + C_z \hat{a}_z$$

Graphical addition :-

$$\vec{C} = \vec{A} + \vec{B}$$

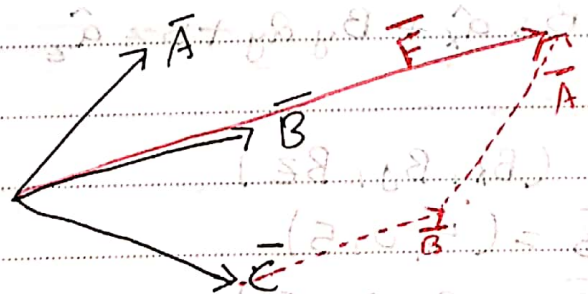


① parallelgram method
(منه tail الى head)

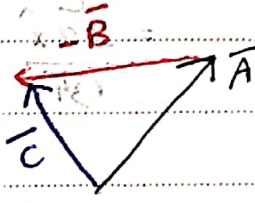
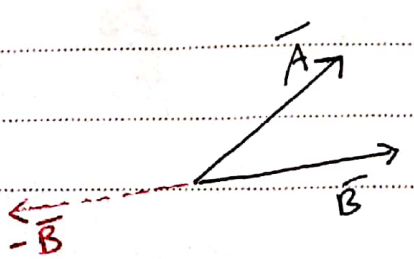


② Arrow method
(منه tail الى head)
vector وبعدها vector
الذي وبعدها vector

ex:- $\vec{F} = \vec{A} + \vec{B} + \vec{C}$



Graphical subtraction :-



$$\vec{C} = \vec{A} - \vec{B}$$

$$= \vec{A} + (-\vec{B})$$

• Properties of Addition & subtraction :

① $\vec{A} + \vec{B} = \vec{B} + \vec{A}$, $\vec{A} - \vec{B} \neq \vec{B} - \vec{A}$

② $k(\vec{A} \pm \vec{B}) = k\vec{A} \pm k\vec{B}$

③ $\vec{A} + (\vec{B} + \vec{C}) = (\vec{A} + \vec{B}) + \vec{C}$, $\vec{A} - (\vec{B} - \vec{C}) \neq (\vec{A} - \vec{B}) - \vec{C}$

2] Multiplication :

1- Dot product \rightarrow scalar

$\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \theta_{AB}$

$\vec{A} \cdot \vec{B} \rightarrow$ $(A_x \hat{a}_x + A_y \hat{a}_y + A_z \hat{a}_z) \cdot (B_x \hat{a}_x + B_y \hat{a}_y + B_z \hat{a}_z)$

$\Rightarrow \hat{a}_x \cdot \hat{a}_x = 1 \cdot 1 \cdot \cos(0) = 1$

$\hat{a}_x \cdot \hat{a}_y = 1 \cdot 1 \cdot \cos(90^\circ) = 0$

$\Rightarrow \vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$

so $\left[\begin{aligned} \cos \theta_{AB} &= \frac{\vec{A} \cdot \vec{B}}{AB} \quad \frac{\text{scalar}}{\text{scalar}} \\ \theta_{AB} &= \cos^{-1} \left(\frac{\vec{A} \cdot \vec{B}}{AB} \right) \end{aligned} \right]$

• properties :

① $\vec{A} \cdot \vec{B} = \vec{B} \cdot \vec{A}$

② $\vec{A} \cdot (\vec{B} + \vec{C}) = \vec{A} \cdot \vec{B} + \vec{A} \cdot \vec{C}$

③ $\vec{A} \cdot \vec{A} = A^2 = A_x^2 + A_y^2 + A_z^2$

2- cross product \rightarrow vector

$|\vec{A} \times \vec{B}| = |\vec{A}| |\vec{B}| \sin \theta_{AB}$, $\vec{A} \times \vec{B} \perp \vec{A}$ & $\perp \vec{B}$

$\sin \theta_{AB} = \frac{|\vec{A} \times \vec{B}|}{AB}$ $\underbrace{\vec{A} \times \vec{B}}_{\text{new vector}}$



$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

row ← → column

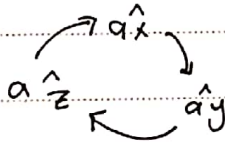
$$\begin{aligned} \vec{A} \times \vec{B} &= (-1)^{1+1} (A_y B_z - A_z B_y) \hat{a}_x \\ &+ (-1)^{1+2} (A_x B_z - A_z B_x) \hat{a}_y \\ &+ (-1)^{1+3} (A_x B_y - A_y B_x) \hat{a}_z \end{aligned}$$

$$* |\hat{a}_x \times \hat{a}_y| = ||| \sin 90^\circ = 1$$

$$|\hat{a}_x \times \hat{a}_x| = 0$$

$$|\hat{a}_x \times \hat{a}_z| = 1$$

$$\hookrightarrow \hat{a}_x \times \hat{a}_y = \hat{a}_z \quad (\text{Right hand Rule - RHR})$$



جانب اليمين
مساوية
لها

$$\hookrightarrow \hat{a}_z \times \hat{a}_y = -\hat{a}_x$$

o Properties

$$\textcircled{1} \vec{A} \times \vec{B} \neq \vec{B} \times \vec{A}$$

$$\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$$

$$\textcircled{2} \vec{A} \times (\vec{B} + \vec{C}) = (\vec{A} \times \vec{B}) + (\vec{A} \times \vec{C})$$

$$\textcircled{3} \vec{A} \times (\vec{B} \times \vec{C}) \neq (\vec{A} \times \vec{B}) \times \vec{C}$$

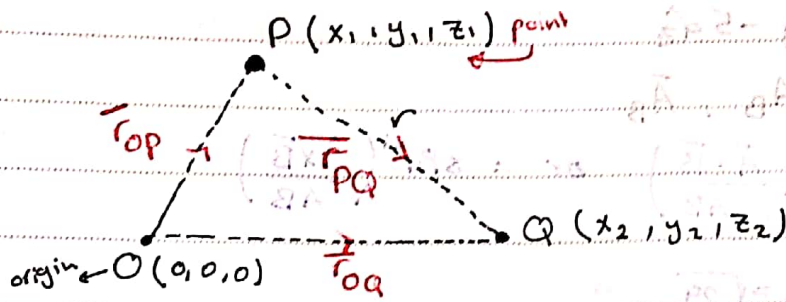
$\vec{A} \times \vec{B} \times \vec{C} \Rightarrow$ Triple cross product

و لست بـ $||\vec{a}|| ||\vec{b}|| ||\vec{c}||$ باستخدام

2 cross product $\vec{A} \times \vec{B}$

* division \Rightarrow $\frac{\text{vec}}{\text{scaler}}$ or $\frac{\text{scaler}}{\text{scaler}}$ \Rightarrow vector

→ Distance: \vec{r}_{PQ} [vector]



$$\vec{r}_P \equiv \vec{r}_{OP}$$

$$\vec{r}_Q \equiv \vec{r}_{OQ}$$

\vec{r}_{PQ} → vector

$$\vec{r}_{PQ} = \vec{r}_Q - \vec{r}_P$$

$$= (x_2, y_2, z_2) - (x_1, y_1, z_1)$$

$$= (x_2 - x_1)\hat{a}_x + (y_2 - y_1)\hat{a}_y + (z_2 - z_1)\hat{a}_z$$

↳ magnitude

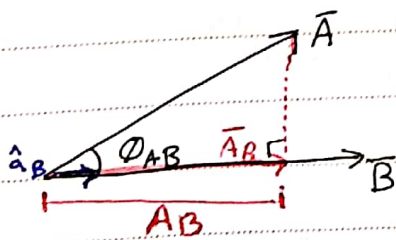
$$|\vec{r}_{PQ}| = r_{PQ} = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

↳ direction

$$\hat{a}_{r_{PQ}} = \frac{\vec{r}_{PQ}}{r_{PQ}} = \hat{a}_{r_{PQ}}$$

* $|\vec{r}_{QP}| = |\vec{r}_{PQ}|$ but $\vec{r}_{QP} = -\vec{r}_{PQ}$

→ Vector projection along another vector :-



$$\cos \phi_{AB} = \frac{A_B}{A}$$

A_B → scalar projection of \vec{A} along \vec{B} [\vec{B} & \vec{A} are in same direction]

\vec{A}_B → vector " " " "

* $\cos \phi_{AB} = \frac{A_B}{A} \Rightarrow A_B = A \cos \phi_{AB}$ where $\cos \phi_{AB} = \frac{\vec{A} \cdot \vec{B}}{AB}$

$$\vec{A}_B = \vec{A} \cdot \hat{a}_B = \frac{\vec{A} \cdot \vec{B}}{A}$$

$$\vec{A}_B = A_B \hat{a}_B = (\vec{A} \cdot \hat{a}_B) \hat{a}_B$$

ex: Pf $\vec{A} = 3\hat{a}_x + 4\hat{a}_y + \hat{a}_z \rightarrow \vec{A} = (3, 4, 1)$

$\vec{B} = 2\hat{a}_y - 5\hat{a}_z$

Find θ_{AB} , A_B , \vec{A}_B

sol: $\theta_{AB} = \cos^{-1}\left(\frac{\vec{A} \cdot \vec{B}}{AB}\right)$ or $= \sin^{-1}\left(\frac{|\vec{A} \times \vec{B}|}{AB}\right)$

$A = \sqrt{26}$, $B = \sqrt{29}$

$\vec{A} \cdot \vec{B} = 0 + 8 - 5 = 3$

$\theta_{AB} = \cos^{-1}\left(\frac{3}{\sqrt{26}\sqrt{29}}\right) = \boxed{83.73^\circ}$
20 degree

$A_B = \vec{A} \cdot \hat{a}_B$, $\hat{a}_B = \frac{\vec{B}}{|\vec{B}|} = \frac{2\hat{a}_y - 5\hat{a}_z}{\sqrt{29}}$
 $= (3, 4, 1) \cdot \frac{(0, 2, -5)}{\sqrt{29}}$

$A_B = 0 + \frac{8}{\sqrt{29}} - \frac{5}{\sqrt{29}} = \boxed{\frac{3}{\sqrt{29}}}$

$\vec{A}_B = A_B \hat{a}_B$

$= \frac{3}{\sqrt{29}} \left(0, \frac{2}{\sqrt{29}}, \frac{-5}{\sqrt{29}}\right)$

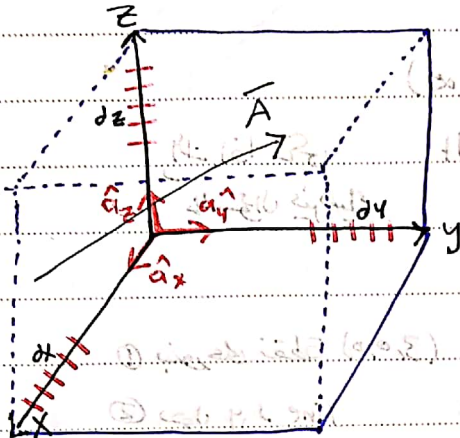
$= \frac{6}{(\sqrt{29})^2} \hat{a}_y - \frac{15}{(\sqrt{29})^2} \hat{a}_z = \frac{6}{29} \hat{a}_y - \frac{15}{29} \hat{a}_z$

CH2: Coordinate systems

□ Cartesian coordinates

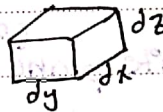
$$\left. \begin{aligned} -\infty < x < \infty \\ -\infty < y < \infty \\ -\infty < z < \infty \end{aligned} \right\} \rightarrow \text{3D object} \text{ Infinite Box}$$

unit vectors: $\hat{a}_x, \hat{a}_y, \hat{a}_z$



• Differential elements:

$$dx, dy, dz$$



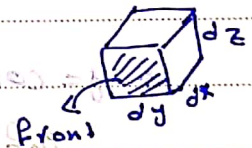
• Differential length (\overline{dl}) [vector]

$$\overline{dl} = dx \hat{a}_x + dy \hat{a}_y + dz \hat{a}_z$$

• Differential Normal surface Area (\overline{ds}) [vector]

$$\overline{ds}_{\text{front}} = dy \cdot dz \cdot \hat{a}_x$$

[Normal]



$$\overline{ds}_{\text{back}} = dy \cdot dz \cdot (-\hat{a}_x)$$

$$\overline{ds}_{\text{right}} = dx \cdot dz \cdot \hat{a}_y$$

$$\overline{ds}_{\text{left}} = -dx \cdot dz \cdot \hat{a}_y$$

$$\overline{ds}_{\text{top}} = dx \cdot dy \cdot \hat{a}_z$$

$$\overline{ds}_{\text{bot}} = -dx \cdot dy \cdot \hat{a}_z$$

• Differential volume (dv) := [scalar]

$$dv = dx dy dz$$

→ 2D surfaces $z=0$

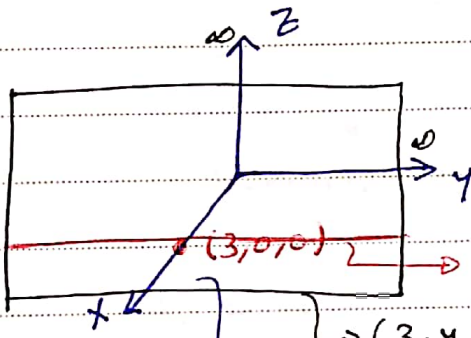
2D by fixing one variable

* $x = \text{constant}$

$$x = 3 \quad (-\infty < y < \infty)$$

2D default

الا اذا دعي بالسؤال غير هذا

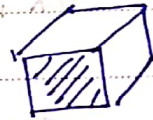


① بنوعه على نقطة $(3, 0, 0)$

② حول y line

③ جعل y/z variable بس x عند 3

(parallel)
infinite plane // yz plane



→ what is the normal on that surface :-

$$\hat{a}_x \quad | \quad -\hat{a}_x$$

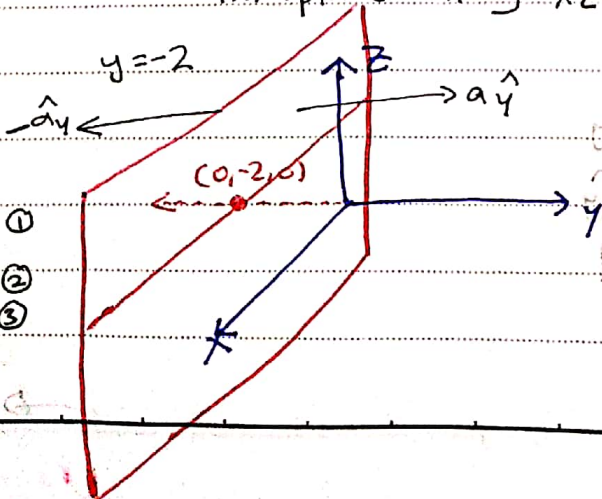
$$\text{if } (6, 0, 0) \rightarrow \hat{a}_x = \hat{i}$$

if $x=0 \rightarrow$ inf. plane along yz plane

* $y = \text{constant}$

inf. plane // xz plane if $(y \neq 0)$

inf. plane along xz plane if $(y=0)$



① نقطة $(0, -2, 0)$

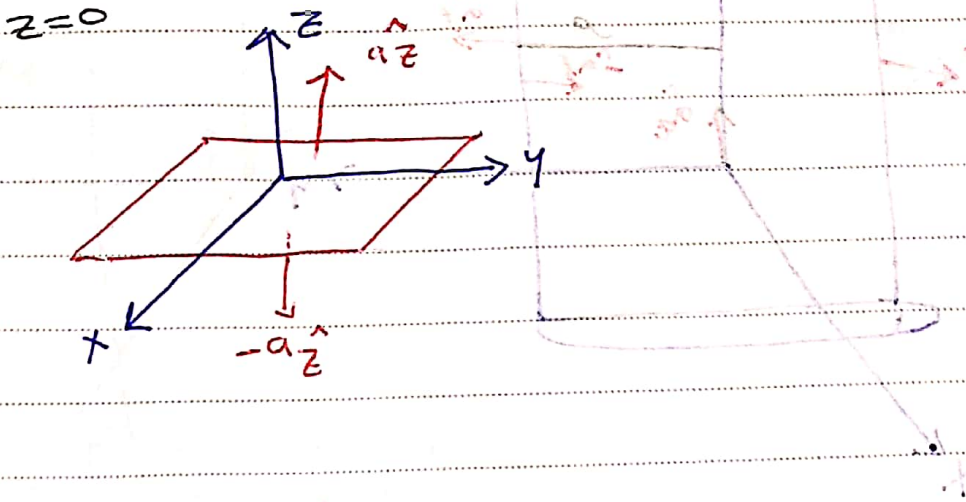
② line $\leftarrow x$

③ x/z نغير

* $z = \text{constant}$

pt. plane // xy plane if ($z \neq 0$)

pt. plane along xy plane if ($z = 0$)



→ 1D segment:

↳ by fixing two variables.

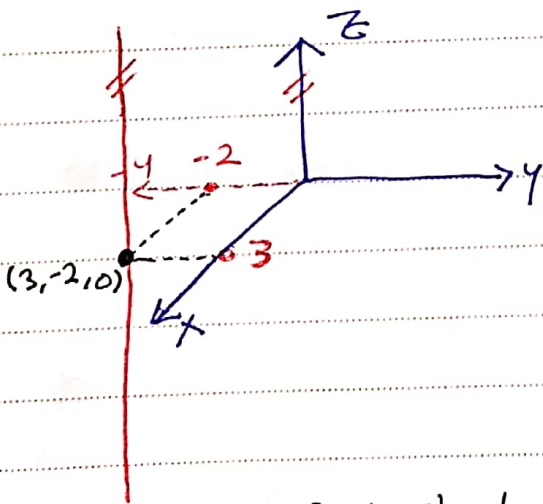
* x, y are constants ($-\infty < z < \infty$)

↳ pt. line // z axis, otherwise (ex: $x=0, y \neq 0$)

pt. line along z axis if ($x=0$ or $y=0$)

لا لازم اثنين

$x = 3, y = -2$



* x, z are constant → pt. line // y -axis

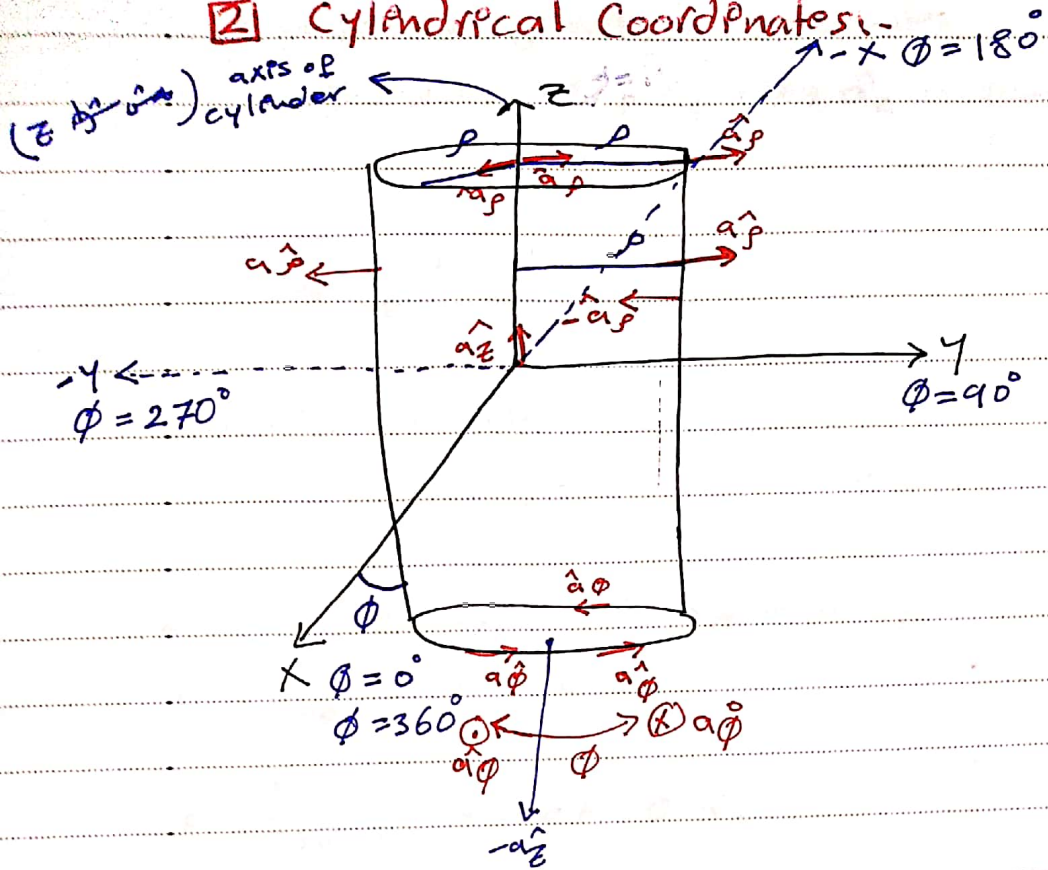
↳ pt. line along y -axis (if $x=0$ or $z=0$)

* y, z are constant → pt. line // x -axis

↳ pt. line along x -axis (if $y=0$ or $z=0$)

→ point by fixing the three variables.

2] Cylindrical Coordinates:-

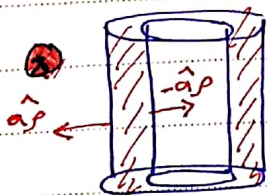


$a_\rho \rightarrow$ الخارج عن المحاور
 $-a_\rho \rightarrow$ داخل المحاور

$0 \leq \rho < \infty$ [$\rho \rightarrow$ radius] [من محور المحاور]
 $0 \leq \phi \leq 2\pi$ [$\phi \rightarrow$ rotation] [زاوية المحاور]
 $-\infty \leq z < \infty$
 3D object
 Inf. solid
 cylinder
 ارتفاع المحاور

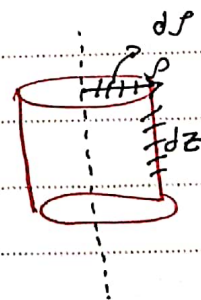
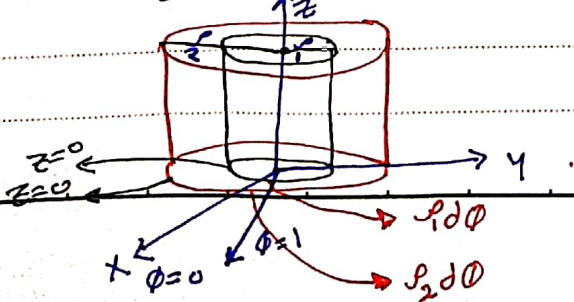
unit vectors:-

$$a_\rho, a_\phi, a_z$$



Differential elements 3D

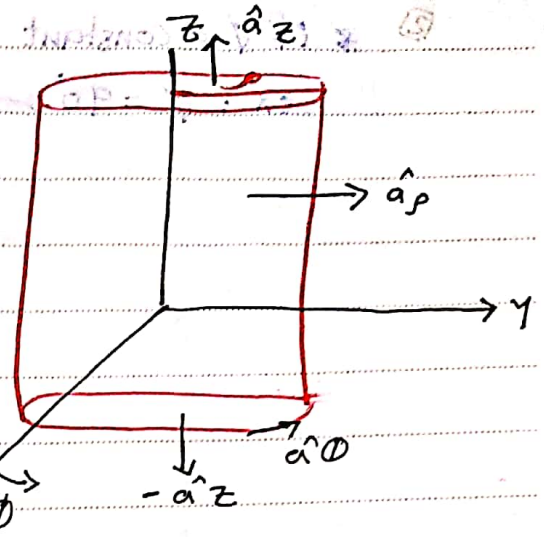
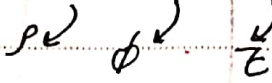
$$d\rho, \rho d\phi, dz$$



→ vector in cylindrical coordinates

$$\vec{A} = A_\rho \hat{a}_\rho + A_\phi \hat{a}_\phi + A_z \hat{a}_z$$

* (3, 60°, 4)



* differential elements

$$d\rho, \rho d\phi, dz$$

* $d\vec{L} = d\rho \hat{a}_\rho + \rho d\phi \hat{a}_\phi + dz \hat{a}_z$

* $d\vec{S}_{top} = \rho d\rho d\phi \hat{a}_z$

* $d\vec{S}_{bottom} = -\rho d\rho d\phi \hat{a}_z$

* $d\vec{S}_{side} = \rho d\phi dz \hat{a}_\rho$

* $d\vec{S}_{cut} = d\rho dz \hat{a}_\phi$ ($\phi = \text{constant}$)

* $dV = \rho d\rho d\phi dz$ } scalar

vectors

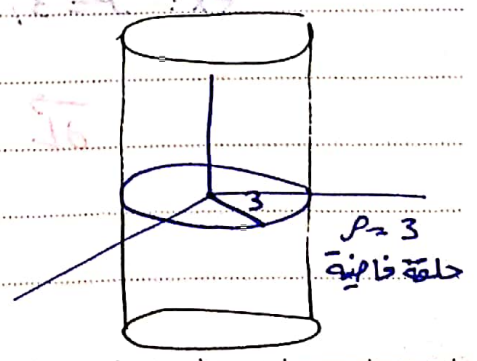
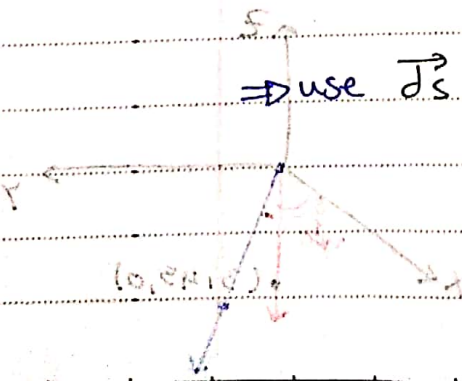
→ 2D surface :-

① * if $\rho = \text{constant}$ → infinite hollow cylinder

(ex: $\rho = 3$, $[\phi, z]$ → variables)

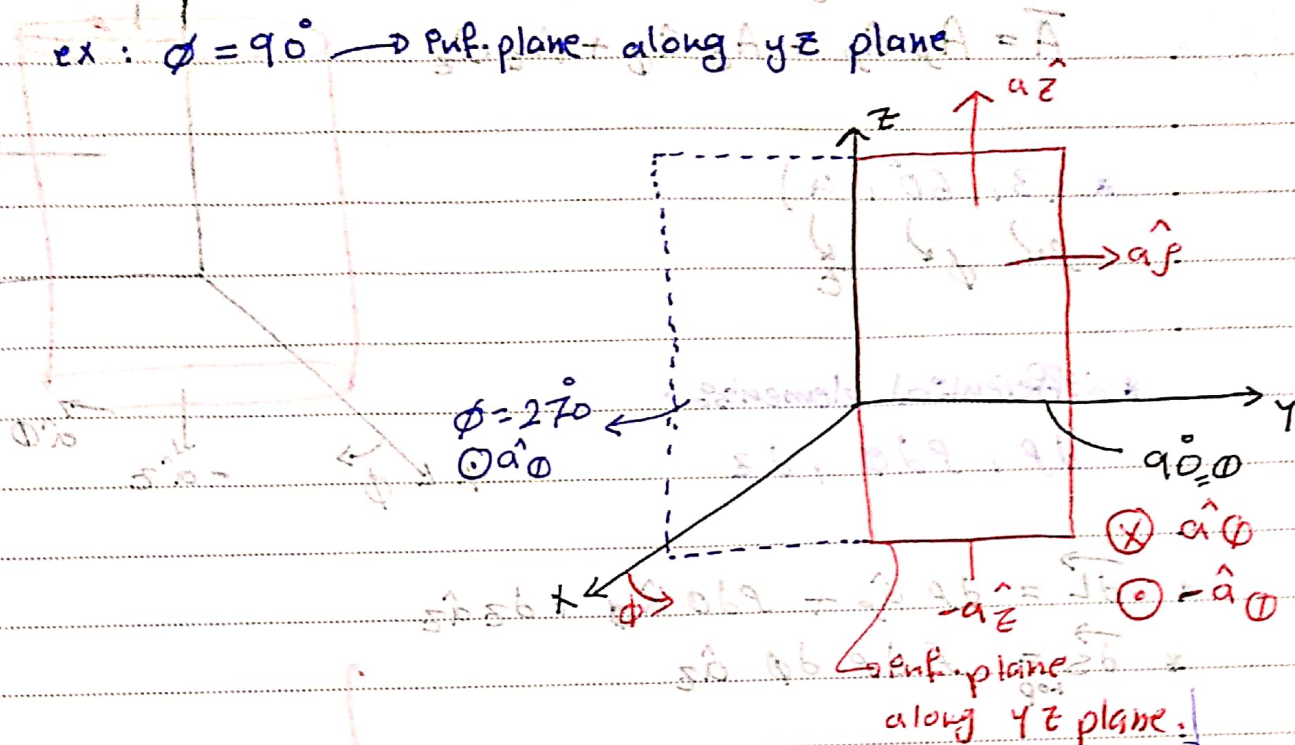
but if $\rho = 0$ → infinite line along z-axis [1D segment]

⇒ use $d\vec{S} = \rho d\phi dz \hat{a}_\rho$



2) * if $\phi = \text{constant} \rightarrow$ PNF. plane

ex: $\phi = 90^\circ \rightarrow$ PNF. plane along yz plane

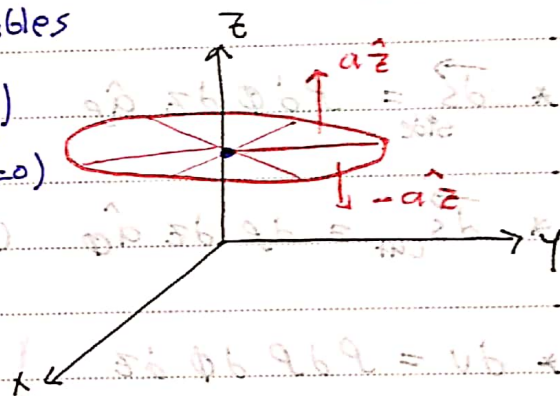


3) * PF $z = \text{constant}$

ex: $z = 2$, $(\phi, \rho) \rightarrow$ variables

\hookrightarrow PNF. DPSK // xy plane ($z \neq 0$)

PNF. DPSK along xy plane ($z=0$)



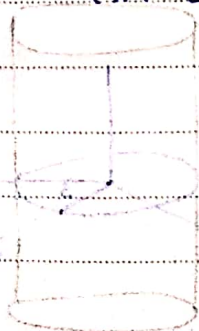
\hookrightarrow 1D segment

\square ρ, ϕ are constants

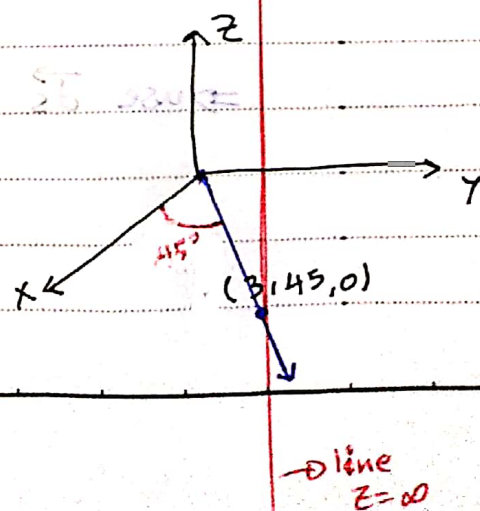
\hookrightarrow PNF. line // z axis ($\rho \neq 0, \phi > 0$)

\hookrightarrow PNF. line along z axis ($\rho = 0$)

ex: $\rho = 3, \phi = 45^\circ$



$$dL = dz a_z$$



2] ρ, z are constants

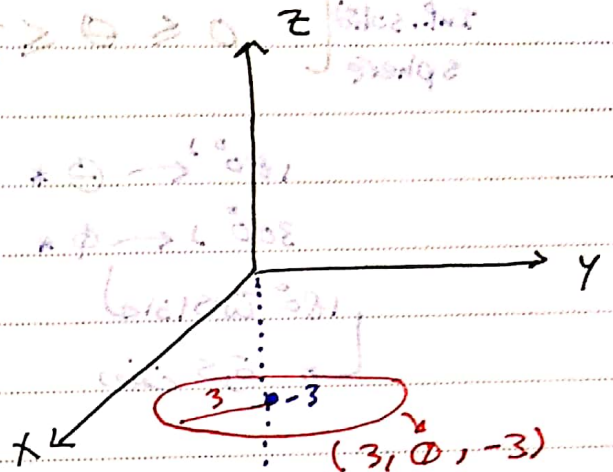
↳ circle (not on $z=0$) // xy plane [$\rho > 0, z \neq 0$]

↳ circle along xy ($z=0$) ($\rho > 0$)

↳ point at z axis [$\rho=0$]

ex: $\rho=3, z=-3$

$$\vec{r} = 3 \cos \phi \hat{a}_\rho$$

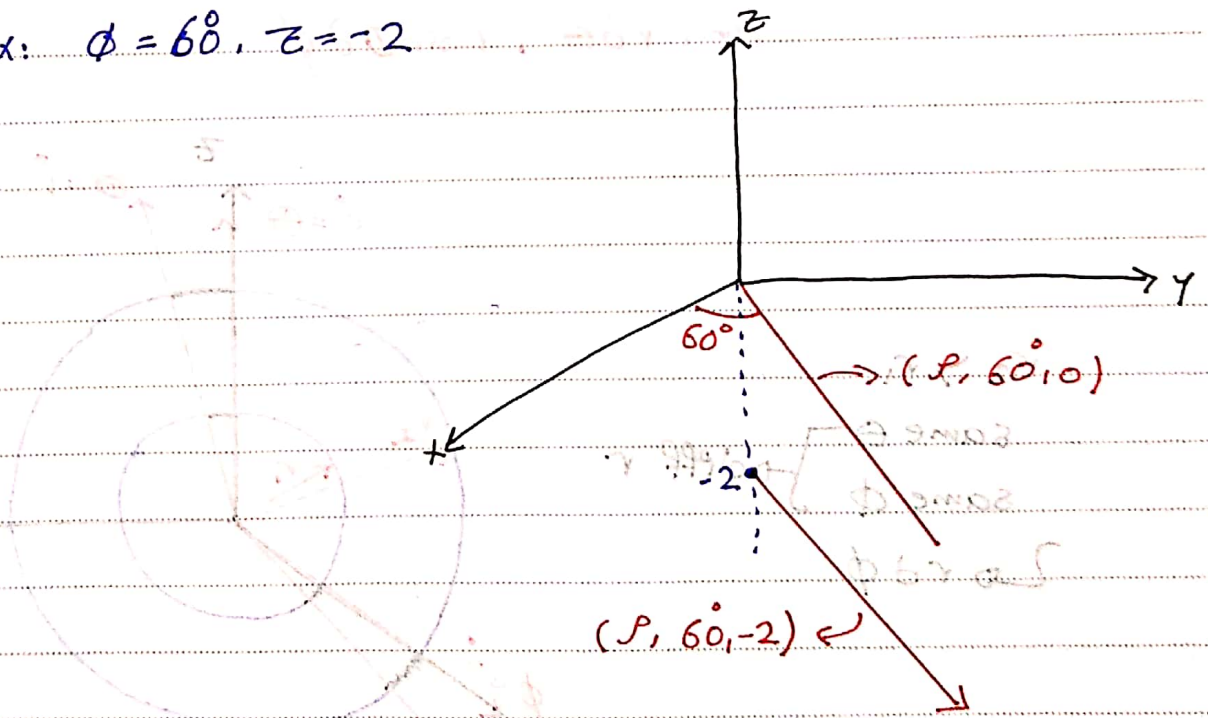


3] ϕ, z are constants

$$0 \leq \rho < \infty$$

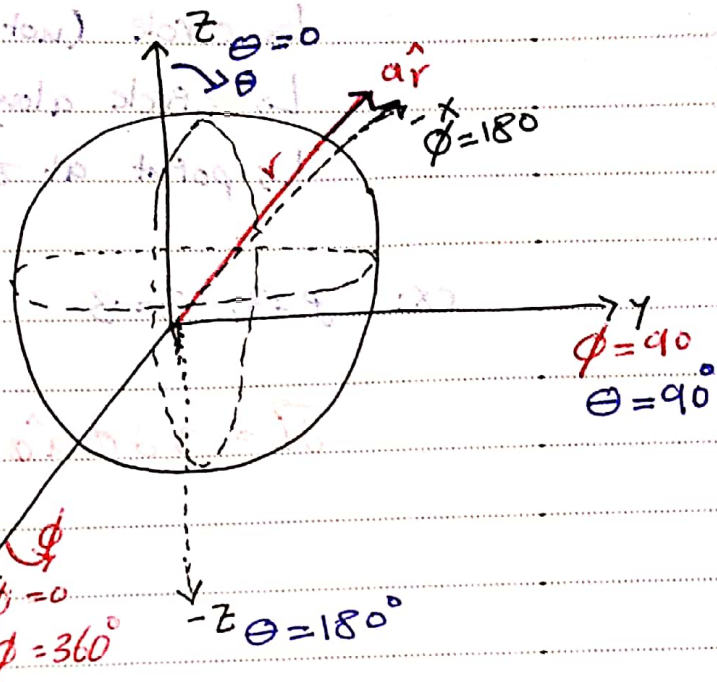
↳ semi-circular line

ex: $\phi = 60^\circ, z = -2$



3] Spherical coordinates

3D object
Inf. solid sphere

$$\begin{cases} 0 \leq r < \infty \\ 0 \leq \phi \leq 2\pi \\ 0 \leq \theta \leq \pi \end{cases}$$


$180^\circ \leftarrow \theta^*$
 $360^\circ \leftarrow \phi^*$

180° (circle)
PS circle

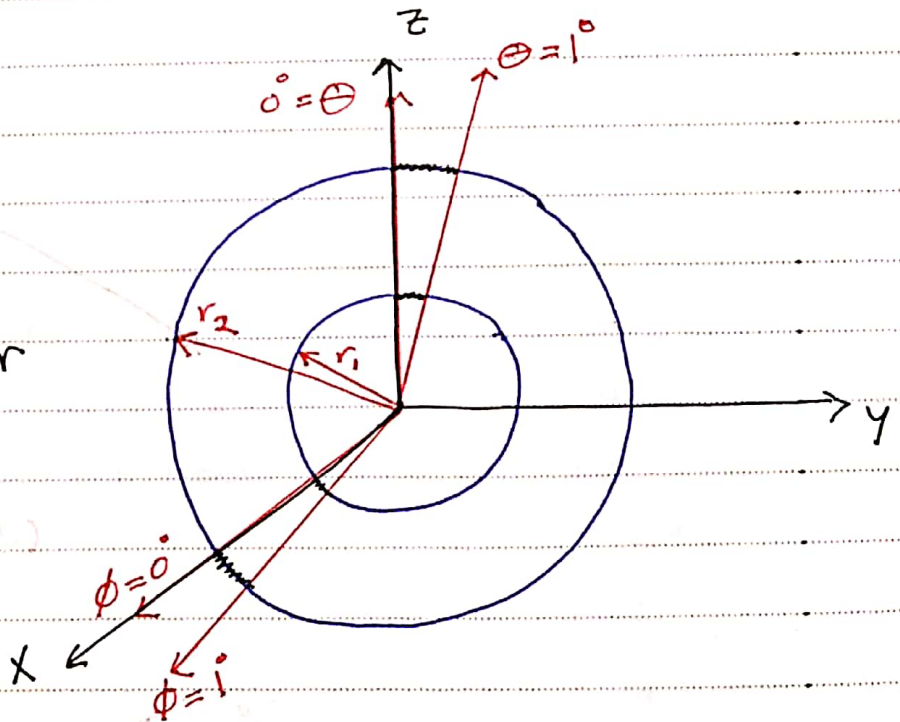
* unit vectors

$$\hat{a}_r, \hat{a}_\phi, \hat{a}_\theta$$

* Differential elements

$$dr, r d\theta, r \sin\theta d\phi$$

$r_2 > r_1$
same θ
same ϕ
 \rightarrow diff r
 $\rightarrow r d\phi$



$$\vec{dL} = dr \hat{r} + r d\theta \hat{\theta} + r \sin \theta d\phi \hat{\phi}$$

$$d\vec{s}_{\text{surface}} = r^2 \sin \theta d\theta d\phi \hat{r}$$

$$d\vec{s}_{\text{H-cut}} = r \sin \theta dr d\phi \hat{\theta}$$

$$d\vec{s}_{\text{V-cut}} = r dr d\theta \hat{\phi}$$

$$dV = r^2 \sin \theta dr d\theta d\phi \quad (\text{scalar})$$

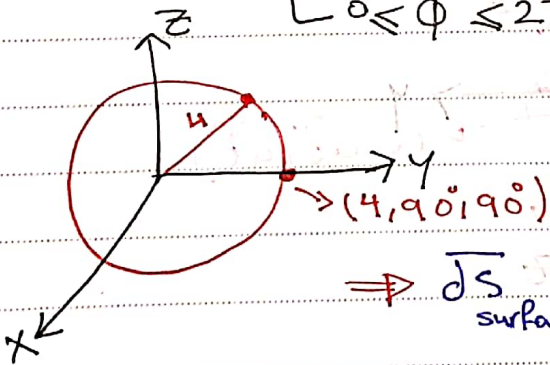
→ 2D surface

$$\square * r = \text{constant}$$

→ hollow sphere ($r > 0$)

→ point at the origin ($r = 0$)

$$\text{ex: } r=4 \quad \begin{cases} 0 \leq \theta \leq \pi \\ 0 \leq \phi \leq 2\pi \end{cases}$$



$$\Rightarrow d\vec{s}_{\text{surface}} = r^2 \sin \theta d\theta d\phi \hat{r}$$

[بالتفصيل في المحاور] θ / ϕ

② * $\Theta = \text{constant}$

لغوة cone ←

لغوة cone ←

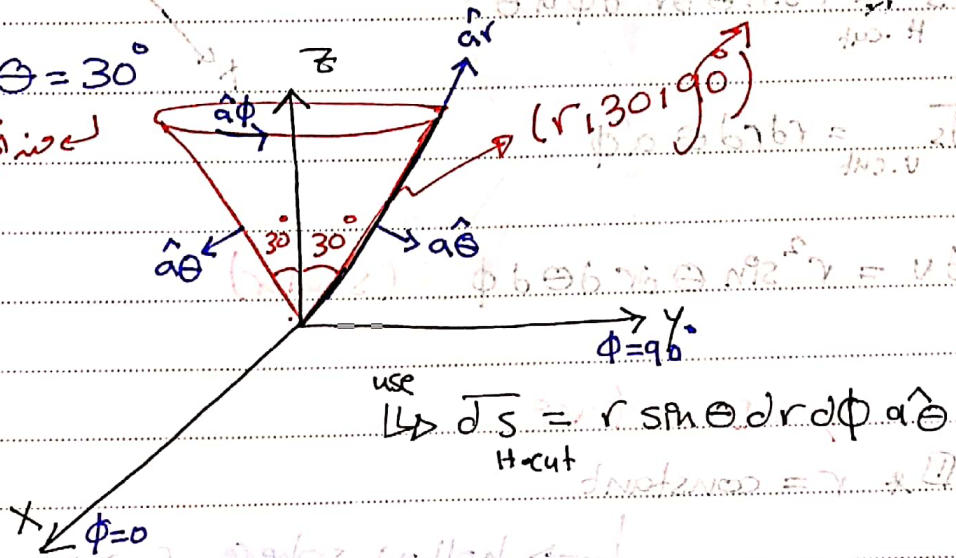
↳ inf. hollow cone $[\Theta \in (0, 90^\circ) / \Theta \in (90^\circ, 180^\circ)]$

↳ inf. disk along x-y plane $[\Theta = 90^\circ]$

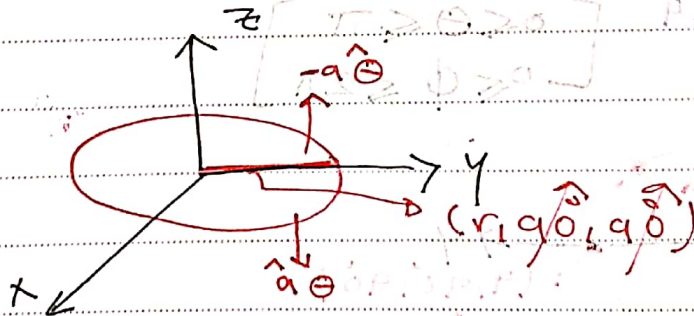
↳ semi-inf. line → +ve z axis $[\Theta = 0^\circ]$
or -ve z axis $[\Theta = 180^\circ]$

ex: $\Theta = 30^\circ$

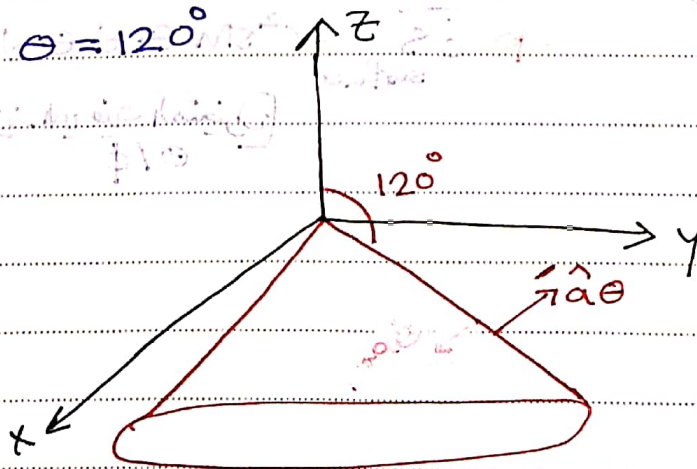
لغوة cone



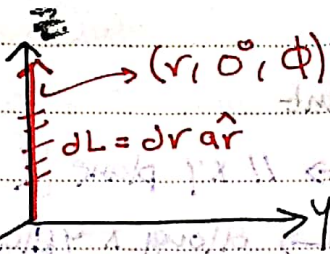
ex: $\Theta = 90^\circ \rightarrow$ inf. disk along x-y plane



ex: $\Theta = 120^\circ$



ex: $\theta = 0^\circ$



إذا كان $\theta = 0^\circ$ \rightarrow $r \sin \theta d\phi = 0$
 مع $dL = dr ar$

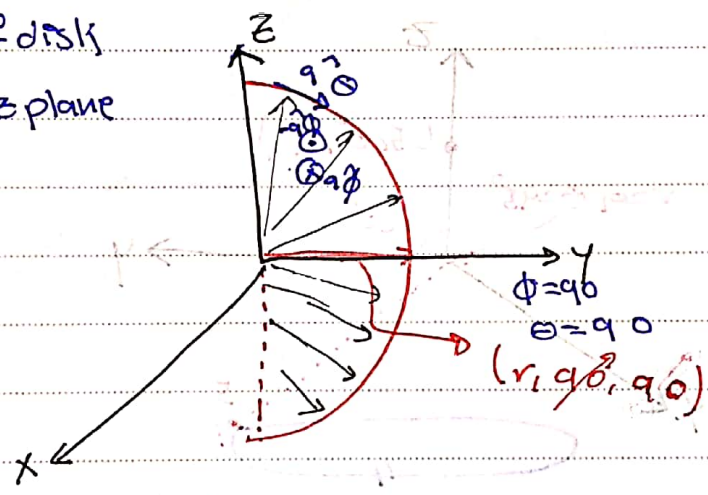
* ال ϕ بطل اذا $\theta = 0^\circ$ بالبرهان
 جالتين: $r \sin \theta d\phi$ \rightarrow $r \sin 0 d\phi = 0$
 $r = 0$ or $\theta = 0, 180^\circ$

3 * $\phi = \text{constant}$

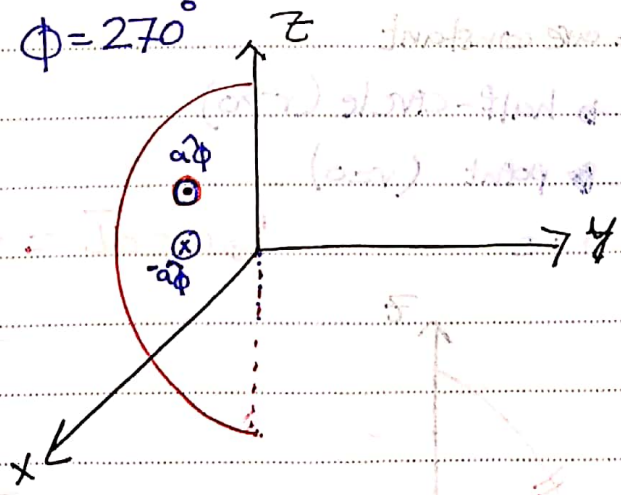
\rightarrow semi-inf Disk

ex: $\phi = 90^\circ$

semi-inf disk
 along yz plane



ex: $\phi = 270^\circ$



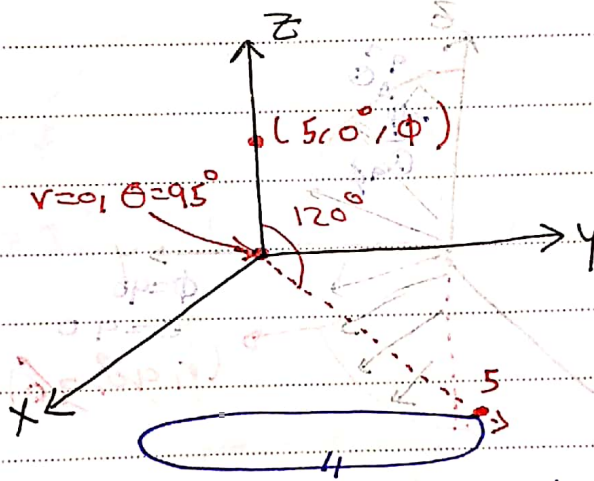
→ 1D segment

① * r, θ = are constant

- circle → // xy plane [$(\theta \neq 0, 180^\circ)$]
- along xy plane [$(\theta = 90, r > 0)$]
- point along +ve z axis [$(\theta = 0^\circ, r > 0)$]
- point along -ve z axis [$(\theta = 180^\circ, r > 0)$]
- point at the origin [$(r = 0)$]

↳ use $d\vec{L} = r \sin \theta d\phi \hat{a}_\phi$

ex: $r=5, \theta=120^\circ$



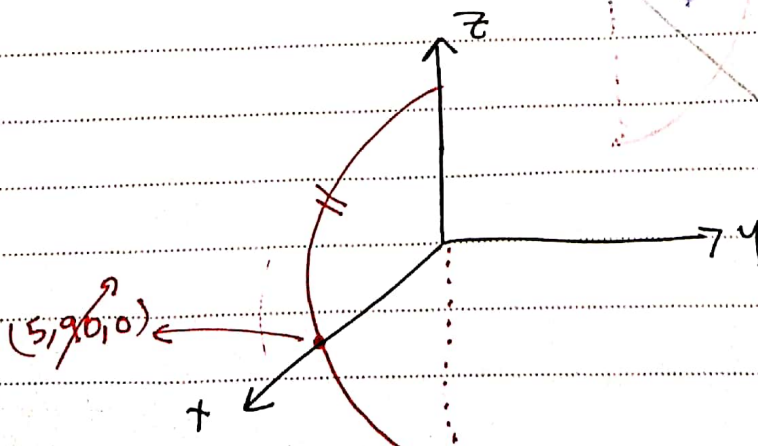
↳ circle not comp.

② * r, ϕ = are constant

- ↳ half-circle ($r > 0$)
- ↳ point ($r = 0$)

ex: $r=5, \phi=0$

↳ use $d\vec{L} = r d\theta \hat{a}_\theta$

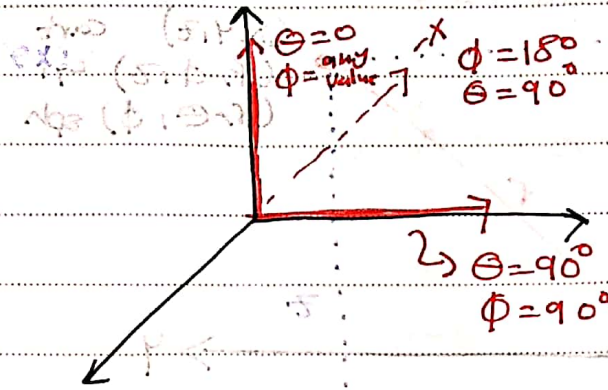


$d\vec{L} = 5 d\theta \hat{a}_\theta$

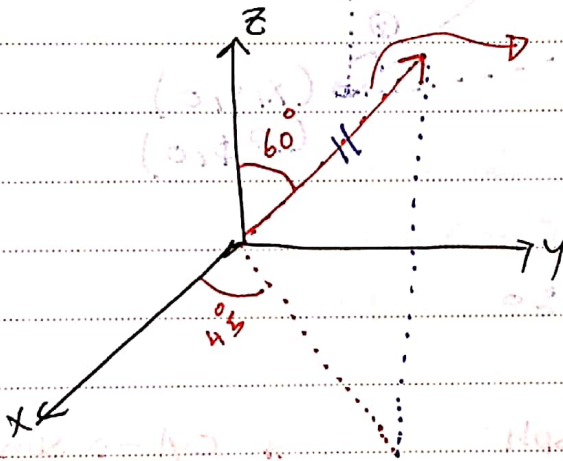
3 * θ, ϕ are constants! -

→ same - in plane (Ray)

→ use $dL = dr \hat{r}$



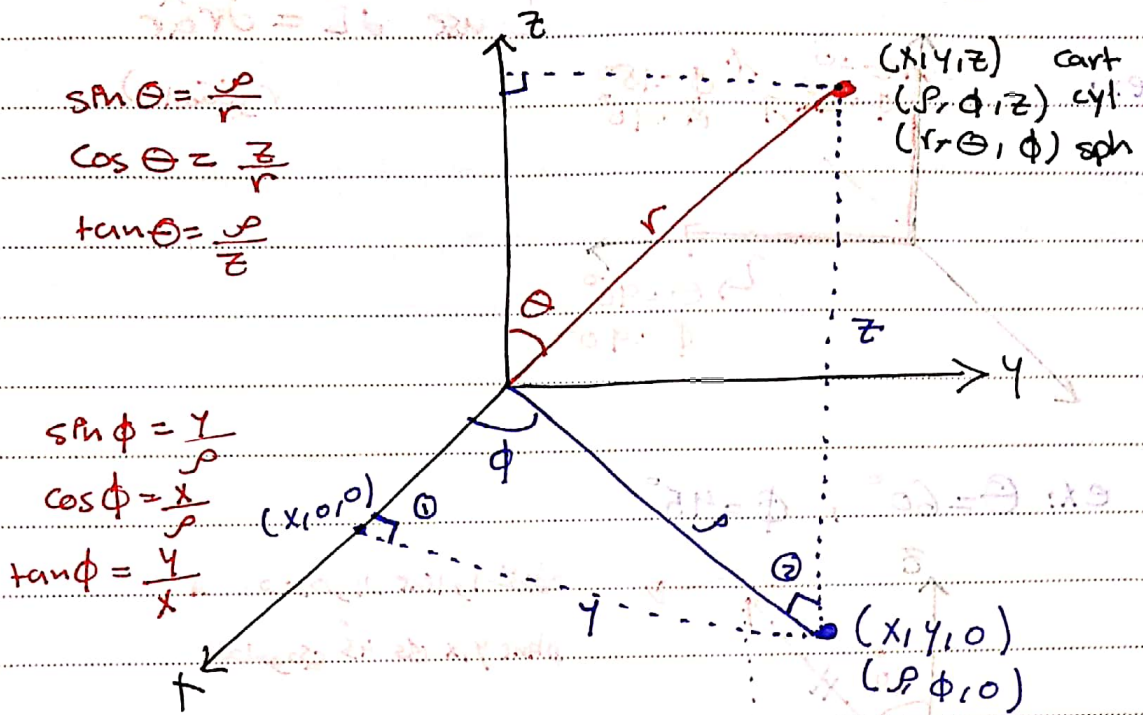
ex: $\theta = 60^\circ, \phi = 45^\circ$



→ same - in plane (Ray) *
plane y, x is 45

$(\frac{x}{r})^2 + (\frac{y}{r})^2 + (\frac{z}{r})^2 = 1$
 $(\frac{x}{r})^2 + (\frac{y}{r})^2 = 1 - (\frac{z}{r})^2$
 $(\frac{x}{r})^2 + (\frac{y}{r})^2 = \cos^2 \theta$
 $\sqrt{(\frac{x}{r})^2 + (\frac{y}{r})^2} = \cos \theta$
 $\frac{\sqrt{x^2 + y^2}}{r} = \cos \theta$
 $\sqrt{x^2 + y^2} = r \cos \theta$
 $r \sin \theta = \sqrt{x^2 + y^2}$
 $r \sin \theta \cos \phi = x$
 $r \sin \theta \sin \phi = y$
 $r \cos \theta = z$

→ Conversion between coordinates based on the given geometry



$$\sin \theta = \frac{\rho}{r}$$

$$\cos \theta = \frac{z}{r}$$

$$\tan \theta = \frac{\rho}{z}$$

$$\sin \phi = \frac{y}{\rho}$$

$$\cos \phi = \frac{x}{\rho}$$

$$\tan \phi = \frac{y}{x}$$

1 point conversion

* cart \rightarrow cyl
 $(x, y, z) \rightarrow (\rho, \phi, z)$

$$\rho = \sqrt{x^2 + y^2}$$

$$\phi = \tan^{-1}\left(\frac{y}{x}\right)$$

$$z = z$$

* cart \rightarrow sph
 $(x, y, z) \rightarrow (r, \theta, \phi)$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\theta = \tan^{-1}\left(\frac{\sqrt{x^2 + y^2}}{z}\right)$$

$$\phi = \tan^{-1}\left(\frac{y}{x}\right)$$

* cyl \rightarrow sph
 $(\rho, \phi, z) \rightarrow (r, \theta, \phi)$

$$r = \sqrt{\rho^2 + z^2}$$

$$\theta = \tan^{-1}\left(\frac{\rho}{z}\right)$$

$$\phi = \phi$$

* cyl \rightarrow cart
 $(\rho, \phi, z) \rightarrow (x, y, z)$

$$x = \rho \cos \phi$$

$$y = \rho \sin \phi$$

$$z = z$$

* sph \rightarrow cart
 $(r, \theta, \phi) \rightarrow (x, y, z)$

$$x = r \sin \theta \cos \phi$$

$$y = r \sin \theta \sin \phi$$

$$z = r \cos \theta$$

* sph \rightarrow cyl
 $(r, \theta, \phi) \rightarrow (\rho, \phi, z)$

$$\rho = r \sin \theta$$

$$\phi = \phi$$

$$z = r \cos \theta$$

1

2

3

3) ترتیب میں قوانین

2] vectors conversion

* [cart → cyl]

$$\vec{A} = A_x \hat{a}_x + A_y \hat{a}_y + A_z \hat{a}_z$$

$$\vec{A} = A_\rho \hat{a}_\rho + A_\phi \hat{a}_\phi + A_z \hat{a}_z$$

$$\begin{bmatrix} A_\rho \\ A_\phi \\ A_z \end{bmatrix} = \begin{bmatrix} \cos \phi & \sin \phi & 0 \\ -\sin \phi & \cos \phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix}$$

3x1 3x3 3x1

How?? 2 steps

1] matrix

$$A_\rho = \cos \phi A_x + \sin \phi A_y$$

$$A_\phi = -\sin \phi A_x + \cos \phi A_y$$

$$A_z = A_z$$

متریب، نصف القطر بالعمود

$$A_x = x, A_y = y$$

2]

$$x = \rho \cos \phi, y = \rho \sin \phi, z = z$$

$$A_\rho = \cos \phi x + \sin \phi y$$

$$= \cos \phi (\rho \cos \phi) + \sin \phi (\rho \sin \phi)$$

* [cyl \rightarrow cart]

$$\begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} = \begin{bmatrix} \cos \phi & -\sin \phi & 0 \\ \sin \phi & \cos \phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} A_\rho \\ A_\phi \\ A_z \end{bmatrix}$$

transpose T^{-1}
 ← jeldi matrix u

Same steps.

unit vector conversion view u matrix

$$\begin{bmatrix} a_x \\ a_y \\ a_z \end{bmatrix} = \begin{bmatrix} \cos \phi & -\sin \phi & 0 \\ \sin \phi & \cos \phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a_\rho \\ a_\phi \\ a_z \end{bmatrix}$$

$$a_y = \sin \phi a_\rho + \cos \phi a_\phi$$

* [cart \rightarrow sph]

$$\text{cart } \bar{A} = A_x a_x + A_y a_y + A_z a_z$$

$$\text{sph } \bar{A} = A_r a_r + A_\theta a_\theta + A_\phi a_\phi$$

given

$$\begin{bmatrix} A_r \\ A_\theta \\ A_\phi \end{bmatrix} = \begin{bmatrix} \sin \theta \cos \phi & \sin \theta \sin \phi & \cos \theta \\ \cos \theta \cos \phi & \cos \theta \sin \phi & -\sin \theta \\ -\sin \phi & \cos \phi & 0 \end{bmatrix} \begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix}$$

or unit vector

$$\begin{bmatrix} a_r \\ a_\theta \\ a_\phi \end{bmatrix} = \begin{bmatrix} \sin \theta \cos \phi & \sin \theta \sin \phi & \cos \theta \\ \cos \theta \cos \phi & \cos \theta \sin \phi & -\sin \theta \\ -\sin \phi & \cos \phi & 0 \end{bmatrix} \begin{bmatrix} a_x \\ a_y \\ a_z \end{bmatrix}$$

$$\text{ex: } a_\phi = -\sin \phi a_x + \cos \phi a_y$$

* [sph \rightarrow cart]

جهت T^{-1} و matrix جهت

$$\begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} = \begin{bmatrix} \sin \theta \cos \phi & \cos \theta \cos \phi & -\sin \phi \\ \sin \theta \sin \phi & \cos \theta \sin \phi & \cos \phi \\ \cos \theta & -\sin \theta & 0 \end{bmatrix} \begin{bmatrix} A_r \\ A_\theta \\ A_\phi \end{bmatrix}$$

or unit vector \checkmark

* [cyl \rightarrow sph]

cyl. $\vec{A} = A_\rho \hat{a}_\rho + A_\phi \hat{a}_\phi + A_z \hat{a}_z$

sph $\vec{A} = A_r \hat{a}_r + A_\theta \hat{a}_\theta + A_\phi \hat{a}_\phi$

$$\begin{bmatrix} A_r \\ A_\theta \\ A_\phi \end{bmatrix} = \begin{bmatrix} \sin \theta & 0 & \cos \theta \\ \cos \theta & 0 & -\sin \theta \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} A_\rho \\ A_\phi \\ A_z \end{bmatrix}$$

$$A_r = \sin \theta A_\rho + \cos \theta A_z$$

$$A_\theta = \cos \theta A_\rho - \sin \theta A_z$$

$$A_\phi = A_\phi$$

or unit vector \checkmark

* درست جهت cyl \rightarrow cart & cart \rightarrow sph

\uparrow جهت

* [sph \rightarrow cyl]

T^{-1} و matrix جهت

$$\begin{bmatrix} A_\rho \\ A_\phi \\ A_z \end{bmatrix} = \begin{bmatrix} \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \\ \cos \theta & -\sin \theta & 0 \end{bmatrix} \begin{bmatrix} A_r \\ A_\theta \\ A_\phi \end{bmatrix}$$

or unit vector

CH3: Vector Calculus

Integration:-

(cart) $\vec{dL} = dx\hat{x} + dy\hat{y} + dz\hat{z}$

(cyl) $\vec{dL} = \rho d\phi\hat{\phi} + dz\hat{z}$

(sph) $\vec{dL} = r d\theta\hat{\theta} + r \sin\theta d\phi\hat{\phi}$

Line Integral:-

$$\int \vec{A} \cdot \vec{dL}$$

i.e: $\vec{A} = (A_x, 0, A_z) \rightarrow$ cart

$\vec{dL} = dx\hat{x} + dz\hat{z} \rightarrow$ step 1

$\vec{A} \cdot \vec{dL} = A_x dx + A_z dz \rightarrow$ step 2 (dot product)

$\int (A_x dx + A_z dz) \rightarrow$ step 3 (integral)

$= \int_x A_x dx + \int_z A_z dz$

2 or single.

$L(x,y,z)$
general

i.e: $\vec{A} = (A_\rho, A_\phi, A_z) \rightarrow$ cyl

$\vec{dL} = \rho d\phi\hat{\phi} + dz\hat{z} \rightarrow$ ①

$\vec{A} \cdot \vec{dL} = A_\rho d\rho + \rho A_\phi d\phi + A_z dz \rightarrow$ ②

$\int A_\rho d\rho + \rho A_\phi d\phi + A_z dz \rightarrow$ ③

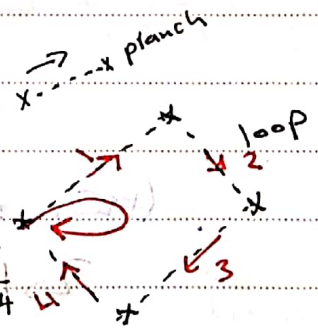
$= \int_\rho A_\rho d\rho + \int_\phi \rho A_\phi d\phi + \int_z A_z dz$

\rightarrow closed Line Integral

$$\oint \vec{A} \cdot \vec{dL}$$

$$= \int_{l_1} \vec{A} \cdot \vec{dL}_1 + \int_{l_2} \vec{A} \cdot \vec{dL}_2 + \int_{l_3} \vec{A} \cdot \vec{dL}_3 + \int_{l_4} \vec{A} \cdot \vec{dL}_4$$

$\rightarrow dy\hat{y} + dz\hat{z} \quad \rightarrow dy\hat{y} + dz\hat{z}$



Step 1
in (circulation)

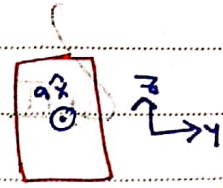
Step 2
بخطوط
مغلقة

[*]

2. [2] surface Integral :

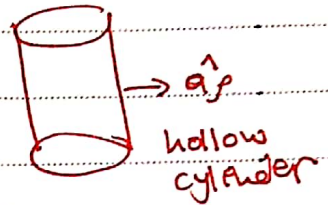
$$\oint_S \vec{A} \cdot d\vec{S}$$

i.e. $d\vec{S} = \rho dz \hat{a}_z$
 $\vec{A} = (A_x, A_y, A_z)$



i.e. $\vec{A} = (A_\rho, A_\phi, A_z)$

$$d\vec{S} = \rho d\phi dz \hat{a}_\rho$$

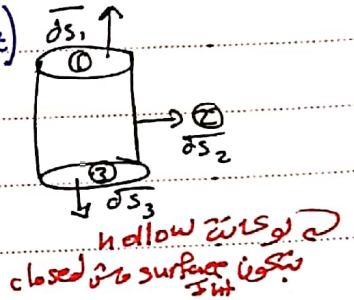


$$\oint_S \vec{A} \cdot d\vec{S} = \int_z \int_\phi A_\rho \rho d\phi dz$$

→ closed surface Integral :

Volume $\oint_S \vec{A} \cdot d\vec{S}$, $\vec{A} = (A_\rho, A_\phi, A_z)$

cyl. $\left\{ \begin{aligned} d\vec{S}_1 &= \rho d\rho d\phi \hat{a}_z \\ d\vec{S}_2 &= \rho d\phi dz \hat{a}_\rho \\ d\vec{S}_3 &= \rho d\rho d\phi \hat{a}_z \end{aligned} \right.$



$$\oint_S \vec{A} \cdot d\vec{S} = \int_{S_1} \vec{A} \cdot d\vec{S}_1 + \int_{S_2} \vec{A} \cdot d\vec{S}_2 + \int_{S_3} \vec{A} \cdot d\vec{S}_3$$

(...)

3. Volume Integral :

$$\int_V |\vec{A}| dV$$

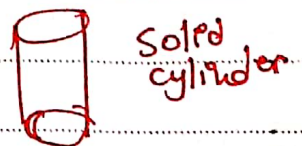
i.e. $dV = dx dy dz$



$$\int_V |\vec{A}| dV = \int_z \int_y \int_x A dx dy dz$$

i.e. $dV = \rho d\rho d\phi dz$

$$\int_V |\vec{A}| dV = \int_z \int_\phi \int_\rho A \rho d\rho d\phi dz$$



→ Del operator :: (vector tool)

$\nabla \rightarrow$ vector ^{أو} ^{بناظر} -

$$\nabla = \frac{\partial}{\partial x} \hat{a}_x + \frac{\partial}{\partial y} \hat{a}_y + \frac{\partial}{\partial z} \hat{a}_z$$

استخدامات 4 هي

1 Gradient $\rightarrow \nabla V$ \rightarrow vector

2 Divergence $\rightarrow \nabla \cdot \vec{A}$ \rightarrow scalar

3 curl $\rightarrow \nabla \times \vec{A}$ \rightarrow vector

4 Laplacian $\rightarrow \nabla \cdot (\nabla V) = \nabla^2 V$

→ Gradient :-

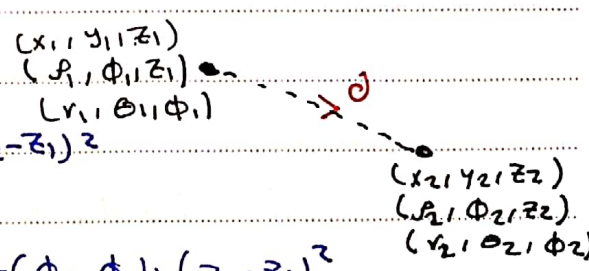
in cart :- $\nabla V = \frac{\partial V}{\partial x} \hat{a}_x + \frac{\partial V}{\partial y} \hat{a}_y + \frac{\partial V}{\partial z} \hat{a}_z$

in cyl :- $\nabla V = \frac{\partial V}{\partial \rho} \hat{a}_\rho + \frac{1}{\rho} \frac{\partial V}{\partial \phi} \hat{a}_\phi + \frac{\partial V}{\partial z} \hat{a}_z$

in sph :- $\nabla V = \frac{\partial V}{\partial r} \hat{a}_r + \frac{1}{r} \frac{\partial V}{\partial \theta} \hat{a}_\theta + \frac{1}{r \sin \theta} \frac{\partial V}{\partial \phi} \hat{a}_\phi$

→ Distance :-

* cart: $d^2 = (x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2$



* cyl: $d^2 = r_1^2 + r_2^2 - 2r_1r_2 \cos(\phi_2 - \phi_1) + (z_2 - z_1)^2$

OR $\text{if } (\phi_1 = \phi_2) \rightarrow d^2 = (r_2 - r_1)^2 + (z_2 - z_1)^2$

لا تستخدم/بنجور
cart

* sph :- $d^2 = \dots$ ^{مطلوبه}

OR $\text{if } (\theta_1 = \theta_2 \text{ و } \phi_1 = \phi_2) \rightarrow d^2 = (r_2 - r_1)^2$

لا تستخدم/بنجور
cart

على أغلب بيجو

EM → part 1 :- mathematics Review

CH 1 → CH 3

→ part 2 :- electrostatics

CH 4 → CH 6

→ part 3 :- magnetostatics

CH 7 - CH 8

→ part 4 :- AC fields of application

CH 9 → CH 11

CH4 : Electrostatic Fields : (DC Field)

* Electrostatic sources :

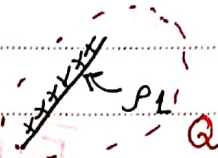
[1] point charge (Q) [C] p.c.s

[2] continuous charge distribution

↳ a) line charge (1D segment)

(ρ_L) \rightarrow (C/m)

$$Q = \int_L \rho_L dL$$



↳ b) surface charge (ρ_s) (2D surface)

(ρ_s) \rightarrow (C/m²)

$$Q = \int_S \rho_s ds$$

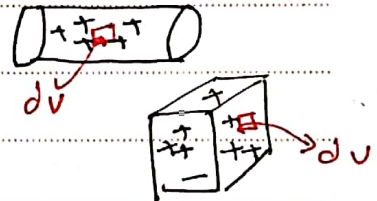


↳ c) Volume charge (3D object) (ρ_v)

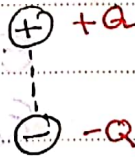
(ρ_v) \rightarrow (C/m³)

$$Q = \int_V \rho_v dv$$

$\rho_v \equiv$ density
(Volume charge)



[3] electric Dipole



[4] polarized Dielectric : [CH5]

* Static \rightarrow not moving
* No current \rightarrow No magnetic field

Major laws :-

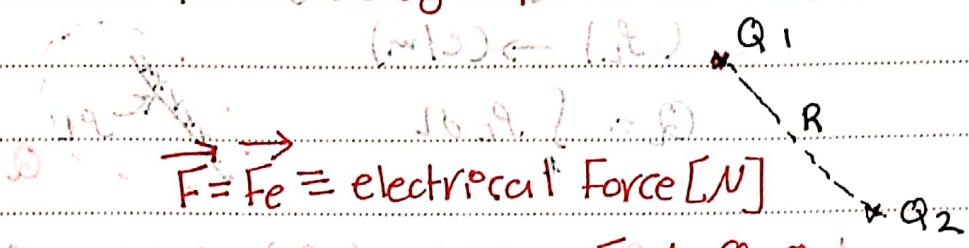
1] Colomb's law [general]

2] Gauss's law [special case of 1]

2 applied in 4 cases.

* Colomb's Law :-

↳ by experiments



Relation $F \propto \frac{Q_1 Q_2}{R^2}$

$$F = k \frac{Q_1 Q_2}{R^2} \text{ [N]}, \quad k = \frac{1}{4\pi \epsilon_0}$$

↳ this gives magnitude only.

k: proportionality constant.

↳ depends in 2 factors :-

$k = \frac{1}{4\pi \epsilon_0}$ } unit used ($\frac{1}{4\pi}$)
 } Media surrounded the two charge (ϵ_0)

ϵ : permittivity

ϵ_0 : Free space permittivity (F/M)

$$\epsilon_0 = \frac{10^{-9}}{36\pi} \text{ F/M} = 8.85 \times 10^{-12} \text{ F/M}$$

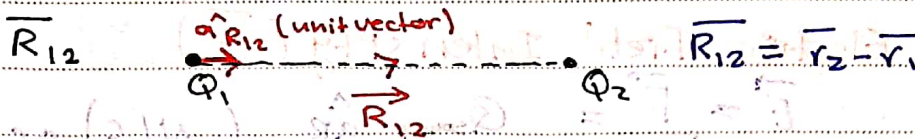
$$k = \frac{1}{4\pi \times 10^{-9} \times 36\pi} = 9 \times 10^9 \text{ in free space}$$

\vec{F} - vector quantity

$$\left[F = \frac{Q_1 Q_2}{4\pi \epsilon_0 R^2} \right] \rightarrow \text{magnitude only}$$

→ the Force on (Q_2) due to (Q_1)

$$\vec{F}_{12} = \frac{Q_1 Q_2}{4\pi \epsilon_0 R_{12}^2} \hat{a}_{R_{12}} \text{ [N]}$$



* $|\vec{F}_{21}| = |\vec{F}_{12}|$

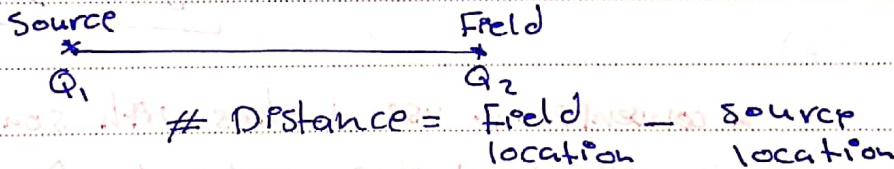
* $\vec{F}_{21} = -\vec{F}_{12}$, $\hat{a}_{R_{12}} = -\hat{a}_{R_{21}}$ (نفس المقدار بس عكس الاتجاه)

* $\hat{a}_{R_{12}} = \frac{\vec{R}_{12}}{R_{12}}$

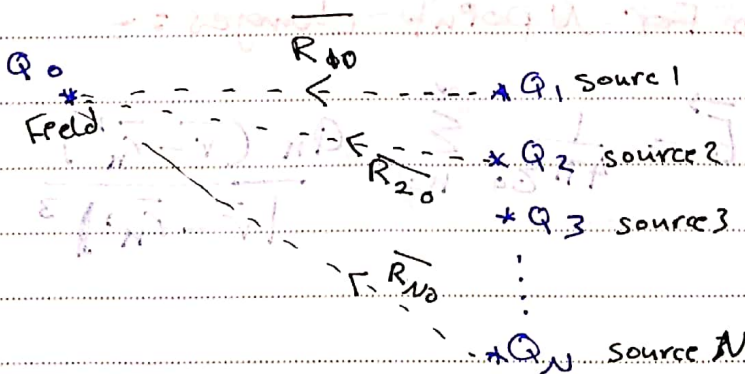
So → $\vec{F}_{12} = \frac{Q_1 Q_2}{4\pi \epsilon_0 R_{12}^2} \hat{a}_{R_{12}} \text{ (N)} = \frac{\vec{R}_{12}}{R_{12}^3}$

or $\vec{F}_{12} = \frac{Q_1 Q_2 \vec{R}_{12}}{4\pi \epsilon_0 R_{12}^3} \text{ (N)} = \frac{\vec{r}_2 - \vec{r}_1}{|\vec{r}_2 - \vec{r}_1|^3}$

or $\vec{F}_{12} = \frac{Q_1 Q_2 (\vec{r}_2 - \vec{r}_1)}{4\pi \epsilon_0 |\vec{r}_2 - \vec{r}_1|^3} \text{ (N)}$ الذاتر استخدام



→ the Force on a point charge due to N-point charges.



* $\vec{F}_0 = \vec{F}_{10} + \vec{F}_{20} + \dots + \vec{F}_{N0}$
 $\equiv \frac{Q_1 Q_0 (\vec{r}_0 - \vec{r}_1)}{4\pi \epsilon_0 |\vec{r}_0 - \vec{r}_1|^3} + \dots + \frac{Q_N Q_0 (\vec{r}_0 - \vec{r}_N)}{4\pi \epsilon_0 |\vec{r}_0 - \vec{r}_N|^3}$

→

$$\rightarrow \vec{F}_0 = \frac{Q_0}{4\pi\epsilon_0} \sum_{k=1}^N \frac{Q_k (\vec{r}_0 - \vec{r}_k)}{|\vec{r}_0 - \vec{r}_k|^3} \quad (N)$$

→ Electric Field Intensity (\vec{E})

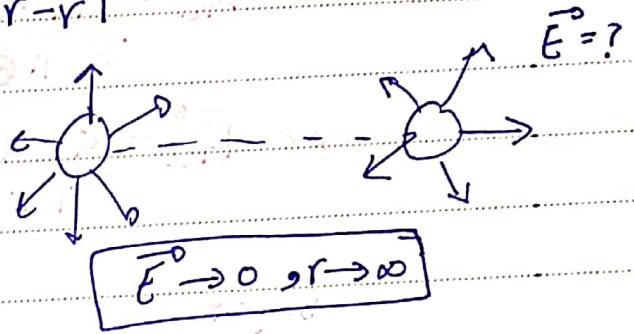
$$\vec{E} = \frac{\vec{F}}{Q} = \frac{Q_{\text{source}} \hat{a}_R}{4\pi\epsilon_0 R^2} \quad (N/C) \text{ or } (V/m)$$

Field point

→ For a point charge

$$\text{OR } \vec{E} = \frac{Q \vec{R}}{4\pi\epsilon_0 R^3}$$

$$\vec{E} = \frac{Q (\vec{r} - \vec{r}')}{4\pi\epsilon_0 |\vec{r} - \vec{r}'|^3}$$



* convention - use dashes with source and without dashes with the field.

→ For N point charges :-

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \sum_{k=1}^N \frac{Q_k (\vec{r} - \vec{r}_k')}{|\vec{r} - \vec{r}_k'|^3} \quad (V/m)$$

→ Electric Flux Density (\vec{D})

$$D = \epsilon_0 \vec{E} = \frac{\epsilon_0 F}{Q_{\text{Field}}} \quad \frac{F \cdot V}{m^2} \equiv C/m^2$$

\downarrow F/m \downarrow V/m \downarrow Q_{Field} \downarrow C/m^2

$$\vec{D} = \frac{Q}{4\pi R^2} \hat{a}_r \equiv \frac{Q \vec{R}}{4\pi R^3} = \frac{Q (\vec{r} - \vec{r}')}{4\pi |\vec{r} - \vec{r}'|^3}$$

Ex: Point charges ($1 \mu\text{C}$) and ($-2 \mu\text{C}$) are located at $(3, 2, -1)$ and $(-1, -1, 4)$, Find \vec{F} and \vec{E} and \vec{D} at $(10 \mu\text{C})$ charge located at $(0, 3, 1)$

\downarrow Source 1 \downarrow Source 2 \downarrow Field

Sol: $\vec{F} = \frac{(1 \times 10^{-3}) \cdot (10 \times 10^{-9}) \cdot (-3, 1, 2)}{4\pi \cdot 10^{-9} \cdot (14)^{3/2}}$ → vector

+ $\frac{(-2 \times 10^{-3}) \cdot (10 \times 10^{-9}) \cdot (1, 4, -3)}{4\pi \cdot 10^{-9} \cdot (26)^{3/2}}$ → vector

$$= -6.567 \hat{a}_x - 3.817 \hat{a}_y + 7.506 \hat{a}_z \text{ (mN)}$$

$$\vec{E} = \frac{\vec{F}}{Q} = \frac{\vec{F}}{10 \times 10^{-9}} = 10^8 \cdot \vec{F}$$

$$= -656.7 \hat{a}_x - 381.7 \hat{a}_y + 750.6 \hat{a}_z \text{ (kV/m) or (kN/C)}$$

$$\vec{D} = \epsilon_0 \vec{E} = \frac{10^{-9}}{36\pi} \cdot \vec{E} = \dots$$

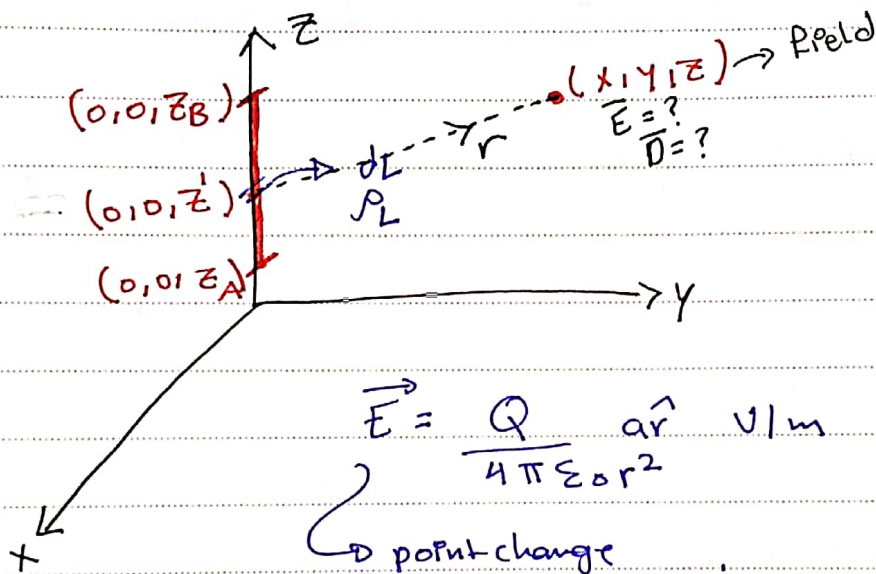
* Continuous Charge distribution 3 -

↳ \vec{E} Field for a line charge

$(\rho_L) \text{ in } (C/m)$

ex:- ρ derivative + ρ on finite line.

consider a finite line along z-axis carry charge of ρ_L (C/m). Find \vec{E} and \vec{D} at point (x, y, z)



$$\vec{E} = \frac{Q}{4\pi\epsilon_0 r^2} \hat{a}_r \text{ V/m}$$

↳ point charge

but in this example \rightarrow line charge

$$Q = \int \rho_L dL$$

↳
$$\vec{E} = \int \frac{\rho_L dL}{4\pi\epsilon_0 r^2} \hat{a}_r$$

$$\vec{E} = \int \frac{\rho_L \vec{r} dL}{4\pi\epsilon_0 r^3}$$

$$dL = dz' \rightarrow \text{along z-axis} + \hat{a}_z$$

$$\vec{r} = x\hat{a}_x + y\hat{a}_y + (z - z')\hat{a}_z$$

$$r = \sqrt{x^2 + y^2 + (z - z')^2}$$

↳
$$\vec{E} = \frac{\rho_L}{4\pi\epsilon_0} \int_{z_A}^{z_B} \frac{(x\hat{a}_x + y\hat{a}_y + (z - z')\hat{a}_z)}{[x^2 + y^2 + (z - z')^2]^{3/2}} dz'$$

* z_A, z_B المسك

Cart
↳ cart كس جيب و
table كس جيب و
table كس جيب و
table كس جيب و
table كس جيب و
table كس جيب و



→ Line is a cylinder of $\rho=0$ so convert to cyl.

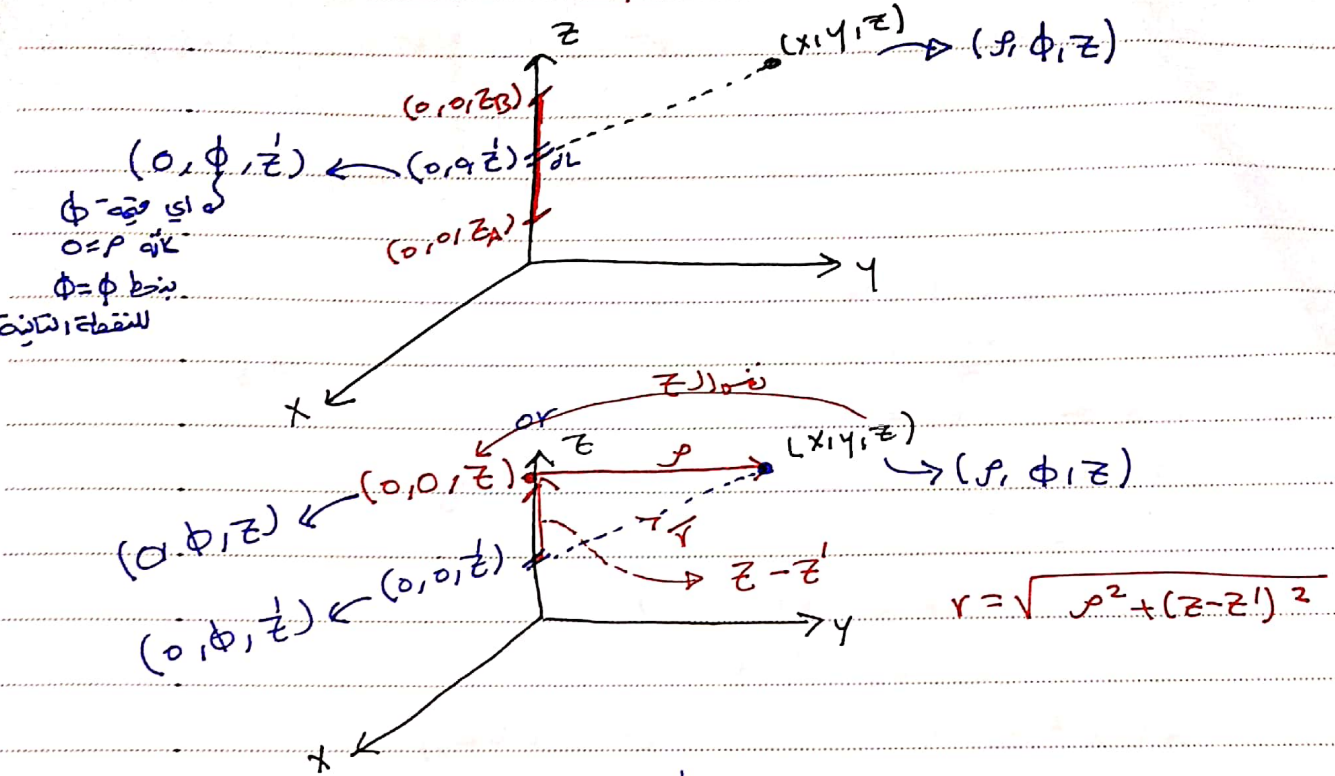
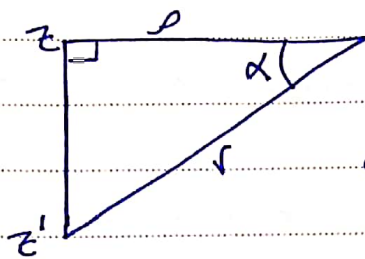
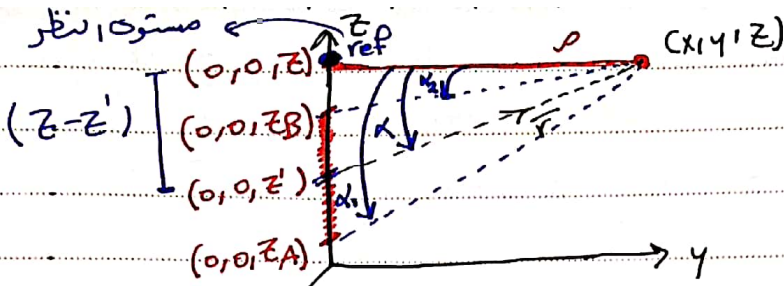


table of integrals and table of integrals

introduce angle

Instead of integration from $z_A \rightarrow z_B$ we will introduce angles α_1, α_2



في الـ z من z الى z'

$$\sin \alpha = \frac{z-z'}{r} \rightarrow z-z' = r \sin \alpha$$

$$\cos \alpha = \frac{\rho}{r} \rightarrow \rho = r \cos \alpha$$

$$\tan \alpha = \frac{z-z'}{\rho} \rightarrow z-z' = \rho \tan \alpha$$

$$dZ' \rightarrow d\alpha$$

$$z-z' = \rho \tan \alpha$$

(اشتقاق صغرى) $-1(dz') = \rho \sec^2 \alpha d\alpha$

بسط بقانون الـ \bar{E} و dZ' $dz' = -\rho \sec^2 \alpha d\alpha$ $\rightarrow *$

$$r^2 = \rho^2 + (z-z')^2$$

$$= \rho^2 + \rho^2 \tan^2 \alpha$$

$$= \rho^2 (1 + \tan^2 \alpha) \rightarrow \text{قانون فيثاغورس}$$

$$= \rho^2 \left(\frac{\cos^2 \alpha}{\cos^2 \alpha} + \frac{\sin^2 \alpha}{\cos^2 \alpha} \right)$$

$$= \frac{\rho^2}{\cos^2 \alpha} = \rho^2 \sec^2 \alpha$$

$$r = \rho \sec \alpha$$

$r^3 = \rho^3 \sec^3 \alpha$ $\rightarrow *$

$z-z' = r \sin \alpha$ $\rightarrow *$

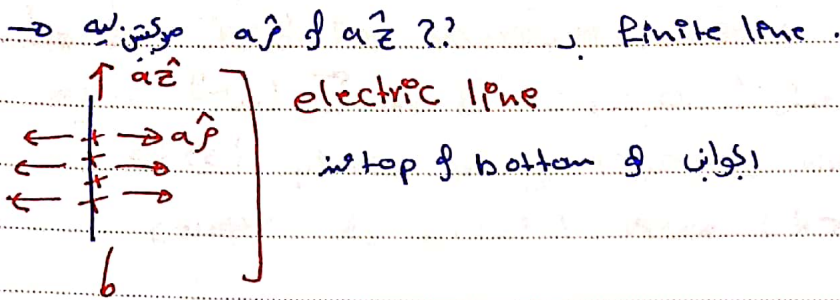
$$z-z' = \rho \tan \alpha$$

$\rho = r \cos \alpha$ $\rightarrow *$

$$\vec{E} = \frac{\rho}{4\pi \epsilon_0} \int_{\alpha_1}^{\alpha_2} \frac{\rho^3 \sec^3 \alpha}{r^3} \sec \alpha (\cos \alpha \hat{a}_\rho + \sin \alpha \hat{a}_z) \cdot -\rho \sec^2 \alpha d\alpha$$

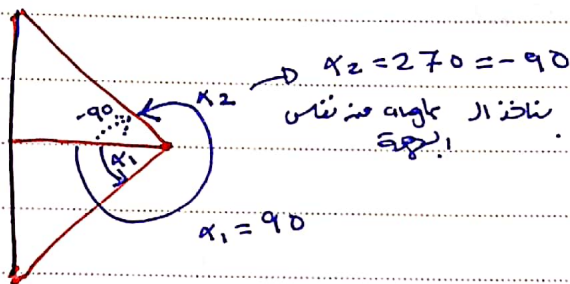
$\leftarrow \frac{\rho^3 \sec^3 \alpha}{r^3} \rightarrow \frac{\rho^3 \sec^3 \alpha}{\rho^3 \sec^3 \alpha} = 1$

$$\vec{E} = \frac{-\rho}{4\pi \epsilon_0 \rho} \left[(\sin \alpha_2 - \sin \alpha_1) \hat{a}_\rho - (\cos \alpha_2 - \cos \alpha_1) \hat{a}_z \right] \text{ V/m}$$



→ line infinite \hat{a}_z is

⇒ For an infinite line.



د الـ \hat{a}_z direction
($\cos -90 - \cos -90$) \hat{a}_z

$\sin \alpha = 1$

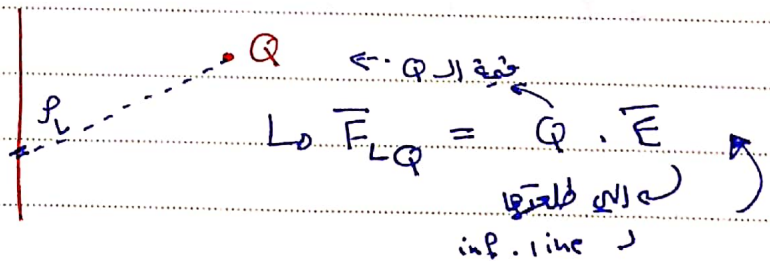
⇒
$$\vec{E} = \frac{\rho_L}{2\pi \epsilon_0 \rho} \hat{a}_r \quad \text{V/M}$$

always for any inf. line

$$\vec{D} = \epsilon_0 \vec{E}$$

ρ :- the shortest distance between the source of the field.

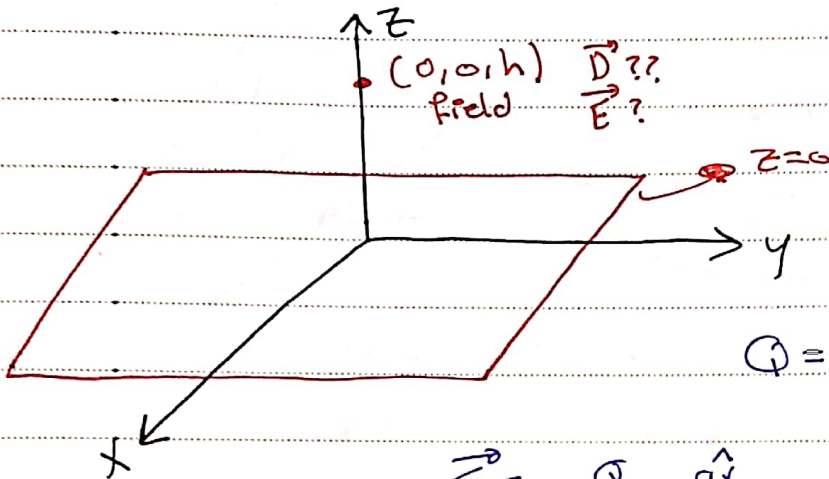
$$\vec{F} = Q \vec{E}$$



لـ $\vec{F}_{Q,L} = Q \vec{E}_Q$
 $\int \rho_L dL$ (line)
 \hat{a}_r point charge
 $= \frac{Q}{4\pi \epsilon_0 r^2} \hat{a}_r$

↳ \vec{E} field for a surface charge :-

ex.. find \vec{E} and \vec{D} at $(0,0,h)$ due to an infinite sheet placed along xy plane and carry a charge ρ_s (C/m^2), where $(h > 0)$.



cdom law

$$Q = \int_S \rho_s ds$$

$$\vec{E} = \frac{Q}{4\pi\epsilon_0 r^2} \hat{a}_r \rightarrow \text{point charge}$$

$$\vec{E} = \int_S \frac{\rho_s ds \hat{a}_r}{4\pi\epsilon_0 r^2}$$

↳ for surface charge.

$$\vec{E} = \int_S \frac{\rho_s \vec{r} ds}{4\pi\epsilon_0 r^3}$$

table for 2 integral for \vec{E} in cart

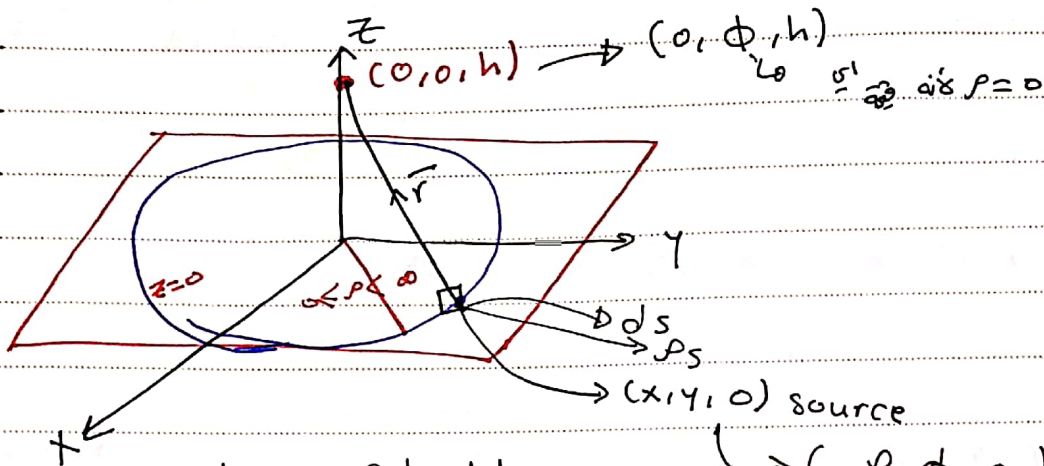
$$\vec{E} = \frac{\rho_s}{4\pi\epsilon_0} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (\dots) dx' dy'$$

infinite sheet \rightarrow disk
 (cart)



→ convert to cyl.

infinite sheet → inf. disk



$$ds = \rho d\rho d\phi$$

$$\vec{r} = -\rho \hat{a}_\rho + h \hat{a}_z$$

$$r = \sqrt{\rho^2 + h^2}$$

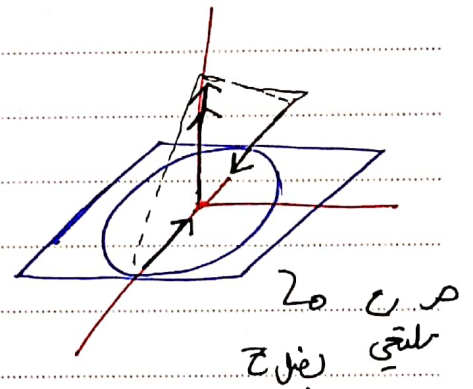
$$\vec{E} = \frac{\rho_s}{4\pi\epsilon_0} \int_0^{2\pi} \int_0^\infty \frac{-\rho \hat{a}_\rho + h \hat{a}_z}{[\rho^2 + h^2]^{3/2}} \rho d\rho d\phi$$

∫₀^{2π} dφ

due to symmetry

(0 → 2π) ∫₀[∞] ρ dρ

the ρ-component will be cancelled



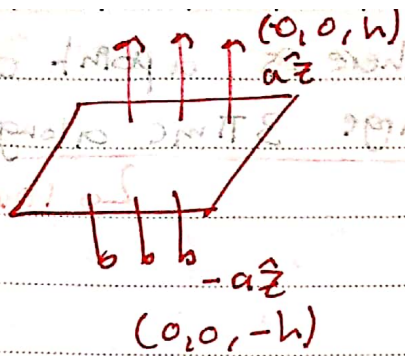
$$\Rightarrow \vec{E} = \frac{\rho_s h}{2\epsilon_0} \int_0^\infty \frac{\rho d\rho}{[\rho^2 + h^2]^{3/2}} \hat{a}_z$$

let $\rho^2 + h^2 = u \Rightarrow du = 2\rho d\rho \rightarrow \rho d\rho = \frac{du}{2}$

$$\vec{E} = \frac{\rho_s h}{2(2\epsilon_0)} \int \frac{du}{u^{3/2}} \hat{a}_z$$

$$= \frac{\rho_s h}{(2)2\epsilon_0} \cdot \frac{1}{\frac{1}{2}} \Big|_{\hat{a}_z} \Rightarrow \vec{E} = \frac{\rho_s h}{2\epsilon_0} \frac{1}{\sqrt{\rho^2 + h^2}} \Big|_0^\infty \hat{a}_z$$

$$\Rightarrow \vec{E} = \frac{-\rho_s h}{2\epsilon_0} \left(0 - \frac{1}{h}\right) \hat{a}_z \Rightarrow \vec{E} = \frac{\rho_s}{2\epsilon_0} \hat{a}_z \quad \text{V/m}$$



$$\vec{E} = \frac{\rho_s}{2\epsilon_0} a\hat{z}$$

for infinite sheet along
x y plane

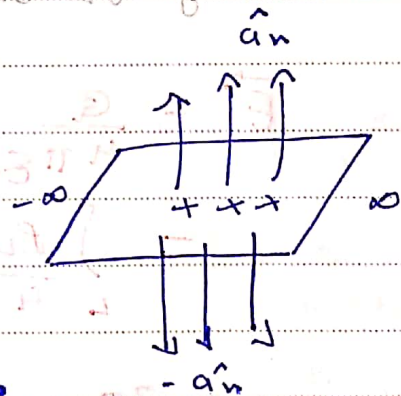
in general \Rightarrow

$$\vec{E} = \frac{\rho_s}{2\epsilon_0} a\hat{n}$$

always for any infinite sheet.

along x $a\hat{x}$
along y $a\hat{y}$
along z $a\hat{z}$

$$\vec{D} = \frac{\rho_s}{2} a\hat{n}$$



Example --- parallel plate capacitor

Find \vec{D} @ point (a) & (b)

$$\Rightarrow \vec{D}|_a = \vec{D}_+ + \vec{D}_-$$

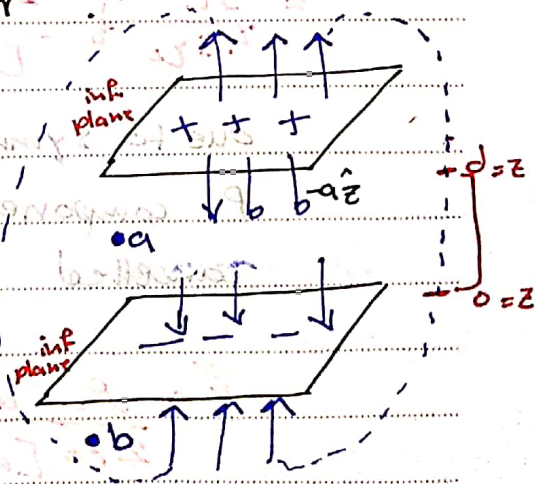
$$= \frac{\rho_s}{2} (-a\hat{z}) + \frac{-\rho_s}{2} (a\hat{z})$$

$$\vec{D} = -\rho_s a\hat{z} \rightarrow \text{C/m}^2$$

$$\Rightarrow \vec{D}|_b = \vec{D}_+ + \vec{D}_-$$

$$= \frac{\rho_s}{2} a\hat{z} + \frac{-\rho_s}{2} a\hat{z} = 0$$

at z = d



Ex: Find \vec{D} at $(4, 0, 3)$ if there is a point charge $-5\pi \text{ mc}$ at $(4, 0, 0)$ and a line charge $3\pi \text{ mc}$ along y-axis

point charge src (\vec{D}_Q) line charge (\vec{D}_L)

Sol: $\vec{D} = \vec{D}_Q + \vec{D}_L$

$$= \frac{Q}{4\pi r^2} \hat{r} + \frac{\rho_L}{2\pi \rho} \hat{\rho}$$

$$= \frac{Q \vec{r}}{4\pi r^3} + \frac{\rho_L \vec{\rho}}{2\pi \rho^2}$$

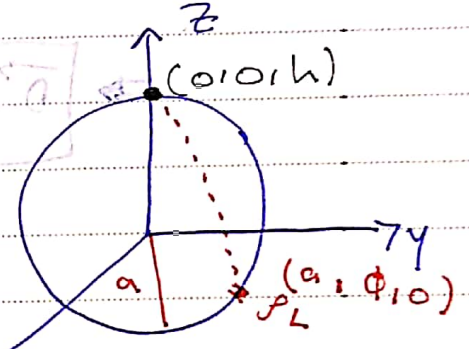
$\vec{r} = 3\hat{a}_z$
 $r = 3$
 $\vec{\rho} = 4\hat{a}_x + 3\hat{a}_z$
 $\rho = 5 \text{ m}$

$\vec{D} = 240 \hat{a}_x + 42 \hat{a}_z \text{ Mc/m}^2$ shortest distance

Ex: For a ring of radius a placed along xy plane carry $\rho_L \text{ c/m}$. Find \vec{E} at $(0, 0, h)$

$$\vec{E} = \frac{Q}{4\pi \epsilon_0 r^2} \hat{r}$$

$$= \int \frac{\rho_L dL}{4\pi \epsilon_0 r^3} \vec{r}$$



$$= \frac{\rho_L}{4\pi \epsilon_0} \int_0^{2\pi} \frac{-a \hat{a}_\rho + h \hat{a}_z}{[a^2 + h^2]^{3/2}} a d\phi$$

due to symmetry other P. component will be cancelled

$$dL = a d\phi$$

$$\vec{r} = -a \hat{a}_\rho + h \hat{a}_z$$

$$r = \sqrt{a^2 + h^2}$$

$$\vec{E} = \frac{\rho_L a h}{2 \epsilon_0 [a^2 + h^2]^{3/2}} \hat{a}_z \text{ V/m}$$

if $a=0 \Rightarrow$ show \vec{E} will look like \vec{E} of a point charge $= \frac{Q}{4\pi \epsilon_0 r^2} \hat{r}$

$$Q = \int \rho_L dL = \int_0^{2\pi} \rho_L a d\phi \Rightarrow Q = \rho_L 2\pi a \Rightarrow \rho_L = \frac{Q}{2\pi a}$$

$$\vec{E} = \frac{Q}{2\pi a} \cdot \frac{ah}{2 \epsilon_0 [a^2 + h^2]^{3/2}} \hat{a}_z \quad | \quad a=0 \Rightarrow \vec{E} = \frac{Q}{4\pi \epsilon_0 h^2} \hat{a}_z$$

$r = h$
 $\hat{a}_r = \hat{a}_z$

* \vec{E} field due to volume charge ρ :-

Gaussian $\frac{ds}{s}$ volume $\frac{1}{\epsilon_0}$

$$\vec{E}^o = \frac{Q}{4\pi\epsilon_0 r^2} \hat{a}_r, \quad Q = \int_V \rho dv$$

↳ point charge

$$\Rightarrow \vec{E} = \int_V \frac{\rho dv}{4\pi\epsilon_0 r^2} \hat{a}_r \quad v/m$$

* Gauss's law

↳ special case from Coulomb's Law.

$$\oint_S \vec{D} \cdot d\vec{s} = Q_{\text{enclosed}}$$

$$= Q \quad \rightarrow \text{point charge, } \vec{E} = \frac{Q}{4\pi\epsilon_0 r^2} \hat{a}_r$$

$$= \int_L \rho_L dL \rightarrow \text{infinitesimal line, } \vec{E} = \frac{\rho_L}{2\pi\epsilon_0 r} \hat{a}_r$$

$$= \int_S \rho_s ds \rightarrow \text{infinitesimal sheet, } \vec{E} = \frac{\rho_s}{2\epsilon_0} \hat{a}_n$$

$$= \int_V \rho dv \rightarrow \text{uniform volume charge, } \vec{E} = ??$$

$$\left[\oint_S \vec{D} \cdot d\vec{s} = \int_V \rho dv \right] \Rightarrow \text{First Maxwell's eq. in integral form (Gauss's Law)}$$

1) \vec{E} or \vec{D} for a point charge

3 steps :-

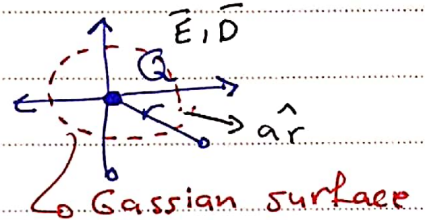
1) $\oint_S \vec{D} \cdot d\vec{s} = Q$

1) Q enclosed

2) \vec{D} of $d\vec{s}$

3) integral

2) $\vec{D} = D_r \hat{a}_r + D_\theta \hat{a}_\theta + D_\phi \hat{a}_\phi$
 $d\vec{s} = r^2 \sin \theta d\theta d\phi \hat{a}_r$



3) $\oint_S \vec{D} \cdot d\vec{s}$ واحد

$$\oint_S \vec{D} \cdot d\vec{s} = \int_S \vec{D} \cdot d\vec{s} = \int_0^{2\pi} \int_0^\pi D_r r^2 \sin \theta d\theta d\phi = Q$$

التي تطلع من Q
 كنه أخرج نقطة
 كرة وفضة
 (hollow) sph
 فقط

$$D_r r^2 (2) (2\pi) = Q$$

$$4\pi r^2 D_r = Q$$

مساحة كرة نصف قطرها r

$$\int_0^\pi \sin \theta d\theta = -\cos \theta \Big|_0^\pi = 2$$

$$D_r = \frac{Q}{4\pi r^2}$$

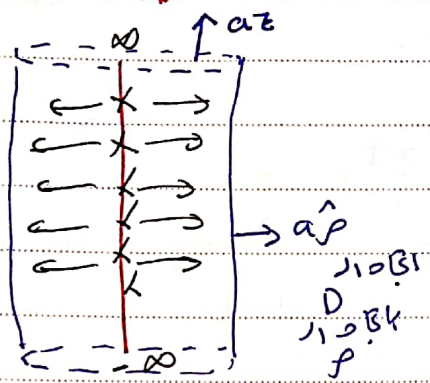
$$\vec{D} = \frac{Q}{4\pi r^2} \hat{a}_r = D_r \hat{a}_r$$

$$\vec{E} = \frac{\vec{D}}{\epsilon_0} = \frac{Q}{4\pi \epsilon_0 r^2} \hat{a}_r$$

\Rightarrow point charge

\rightarrow

21 \vec{E}, \vec{D} For an infinite line of charge



Cylinder axis line of charge
 hollow
 Gaussian surface (cylinder)

$$\textcircled{1} \int_S \vec{D} \cdot d\vec{s} = Q_{enc} = \int_L \rho_L dL$$

$$\textcircled{2} \vec{D} = D_\rho a_\rho$$

$$d\vec{s} = \rho d\phi dz a_\rho$$

$$\textcircled{3} \int_S \vec{D} \cdot d\vec{s} \Rightarrow \int_L \rho_L dL$$

$$\int_{-L}^L \int_0^{2\pi} D_\rho \rho d\phi dz = \int_{-L}^L \rho_L dz$$

$$D_\rho \rho 2\pi(2/L) = \rho_L (2/L)$$

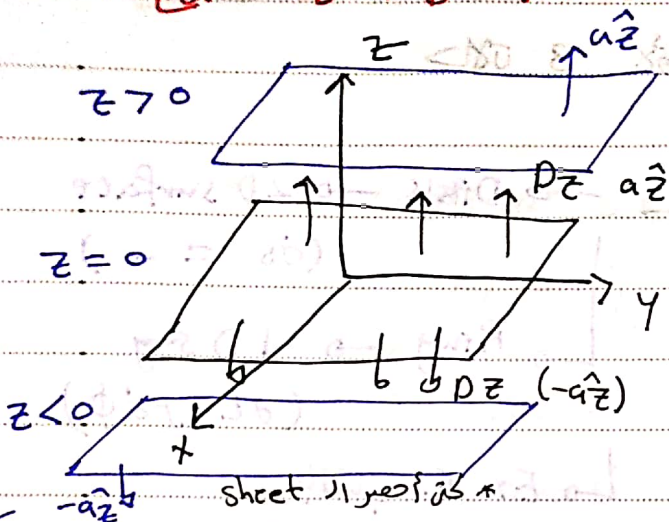
Left side: $\int_{-L}^L \int_0^{2\pi} D_\rho \rho d\phi dz$ (Note: $L \rightarrow \infty$ in original image)
 Right side: $\int_{-L}^L \rho_L dz$ (Note: $L \rightarrow \infty$ in original image)

$$D_\rho = \frac{\rho_L}{2\pi\rho}$$

$$\vec{D} = \frac{\rho_L}{2\pi\rho} a_\rho$$

$$\vec{E} = \frac{\rho_L}{2\pi\epsilon_0\rho} a_\rho$$

[3] \vec{E} or \vec{D} for an inf. sheet of charge



یہ box فارغ ہے اس لیے اس میں کوئی چارج نہیں ہے

اس لیے اس کے لیے \vec{D} کا حساب لگانا ہے

Gaussian surfaces

$$\textcircled{1} \rightarrow \oint_S \vec{D} \cdot d\vec{s} = Q_{enc} = \int_S \rho_s ds$$

$$\textcircled{2} \rightarrow \vec{D} = \begin{cases} Dz a_z & , z > 0 \\ Dz (-a_z) & , z < 0 \end{cases}$$

$$d\vec{s}_{top} = dx dy a_z \quad , z > 0$$

$$d\vec{s}_{bot} = -dx dy a_z \quad , z < 0$$

$\textcircled{3} \rightarrow$ اس لیے اس کے لیے 2 surface [top and bot] $\oint_S \vec{D} \cdot d\vec{s}$

$$\oint_S \vec{D} \cdot d\vec{s} = \int_{S_{top}} \vec{D} \cdot d\vec{s}_{top} + \int_{S_{bot}} \vec{D} \cdot d\vec{s}_{bot} = \int_S \rho_s ds$$

$$\hookrightarrow = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} Dz dx dy + \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} Dz dx dy = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \rho_s dx dy$$

$$\text{put } \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} dx dy = A$$

$$= Dz A + Dz A = \rho_s A$$

$$2 Dz = \rho_s$$

$$\boxed{Dz = \frac{\rho_s}{2}}$$

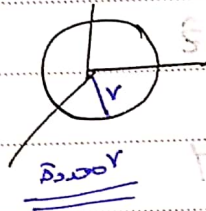
$$\vec{D} = \begin{cases} \frac{\rho_s}{2} a_z & , z > 0 \\ \frac{\rho_s}{2} (-a_z) & , z < 0 \end{cases}$$

$$\boxed{\vec{E} = \frac{\rho_s}{2 \epsilon_0} a_n}$$

$$\boxed{\vec{D} = \frac{\rho_s}{2} a_n}$$

↳ in general 3 cases

Note :-



↳ Disk \rightarrow 2D surface
($ds = \dots$)

↳ Ring \rightarrow 1D seg
($dL = r d\phi$)

↳ Ex. Ex. \dots

← دائرة الكتل

Gauss's law

• Coulomb's law

$$\left. \begin{aligned} & \dots \\ & \dots \end{aligned} \right\} = \dots$$

4] \vec{E} or \vec{D} for a uniform volume charge

استعمل قانون كولومب أو Gauss's law

ex:- Consider a sphere of radius (a) has

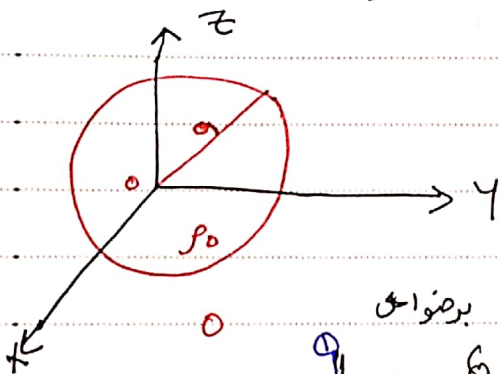
$$\rho_v = \begin{cases} \rho_0, & r \leq a \\ 0, & r > a \end{cases} \text{ in C/m}^3$$

volume charge density.

Find \vec{E} and \vec{D} every where

every where uniform

Indicate Gauss's law



3 steps:

$$\oint_S \vec{D} \cdot d\vec{s} = Q_{enc} = \int_V \rho_v dV$$

but for $0 < r < a$

$$\vec{D} = D r \hat{a}_r$$

$$d\vec{s} = r^2 \sin\theta d\theta d\phi \hat{a}_r$$

$$\oint_S \vec{D} \cdot d\vec{s} =$$

$$\int_0^{2\pi} \int_0^\pi \int_0^r \rho_0 r^2 \sin\theta dr d\theta d\phi = \int_0^{2\pi} \int_0^\pi \rho_0 r^2 \sin\theta d\theta d\phi$$

$$4\pi r^2 D = \rho_0 \frac{r^3}{3} (2)(2\pi)$$

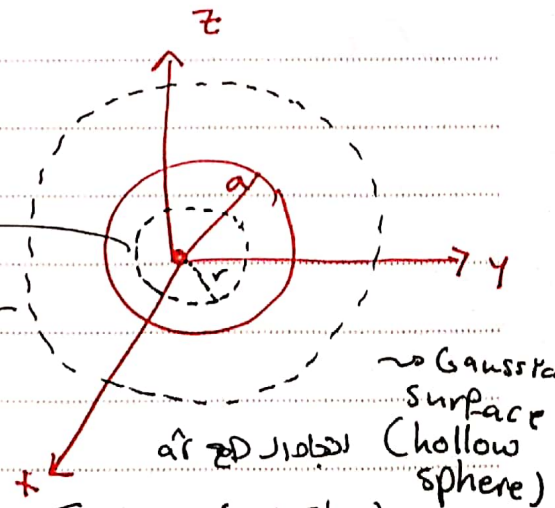
$$D = \frac{\rho_0 r}{3}$$

$$\vec{D} = \frac{\rho_0 r}{3} \hat{a}_r$$

$$\vec{E} = \frac{\rho_0 r}{3 \epsilon_0} \hat{a}_r \Rightarrow 0 \leq r < a$$

منه الى اليمين

منه الى اليمين



Gaussian surface (hollow sphere)

حلقه كروية رقيقة نصفها \vec{E}

كل وحدة كاره ودائماً ينشأ من

origin يجرى يجرى بعيداً

For $a < r < \infty$

$$\rightarrow 4\pi r^2 D r = \int_0^{2\pi} \int_0^{\pi} \int_0^a \rho_0 r^2 \sin \theta dr d\theta d\phi + \int_0^{2\pi} \int_0^{\pi} \int_a^r \rho_0 r^2 \sin \theta dr d\theta d\phi$$

السلطة ρ_0
الكاربية ρ_0

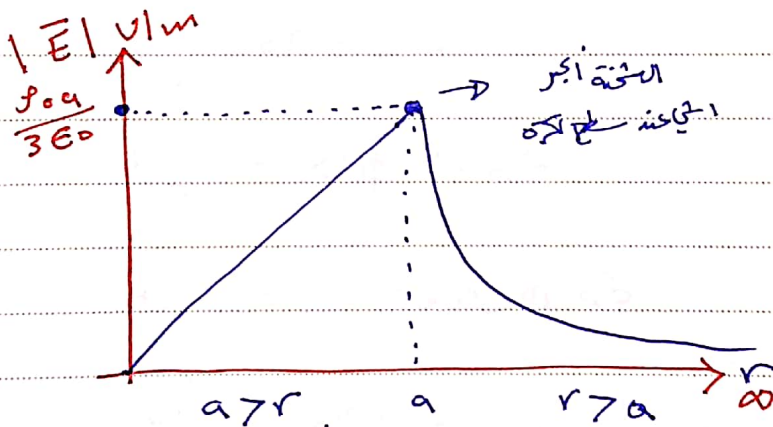
$$4\pi r^2 D r = \frac{\rho_0 4\pi a^3}{3}$$

$$D r = \frac{\rho_0 a^3}{3 r^2} \hat{a}_r$$

$$\boxed{\vec{D} = \frac{\rho_0 a^3}{3 r^2} \hat{a}_r}$$

$$\boxed{\vec{E} = \frac{\rho_0 a^3}{3 \epsilon_0 r^2} \hat{a}_r} \rightarrow a < r < \infty$$

فقط عند a



هذا كاسا السلطنة خارج الكرة
التي
التي

\Rightarrow * Electric Flux (Ψ_e)

$$\Psi_e = \int_s \vec{D} \cdot d\vec{s} = (c)$$

$c/m^2 \leftarrow \quad \quad \quad L/m^2$

- Electric Flux (Ψ_e) in (c)

* Gauss's law

$$\Psi_e = \oint_s \vec{D} \cdot d\vec{s} = Q_{enc}$$

$$\left[\oint_s \vec{D} \cdot d\vec{s} = \int \rho_v dv \right] \rightarrow \text{1st max well's eq. in integral form.}$$

Ex: Given $\vec{D} = z \rho \cos^2 \phi \hat{z}$ C/m².

calculate: a) the charge density at $(1, \pi/4, 3)$

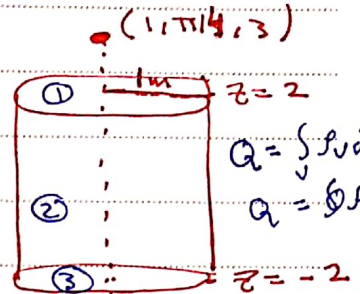
b) The total charge enclosed by the cylinder of radius 1m with $-2 \leq z \leq 2$

$$\rho_s = \vec{D} \cdot \hat{n}$$

$$\begin{aligned} \textcircled{b} Q &= \oint_S \rho_s ds \\ &= \oint_S \vec{D} \cdot \hat{n} ds \end{aligned}$$

$$= \oint_S \vec{D} \cdot \vec{ds}$$

$$= \int_{S_{top}} \vec{D} \cdot \vec{ds}_{top} + \int_{S_{side}} \vec{D} \cdot \vec{ds}_{side} + \int_{S_{bot}} \vec{D} \cdot \vec{ds}_{bot}$$



$$\vec{ds}_{top} = \rho d\rho d\phi \hat{z}$$

$$\vec{ds}_{side} = \rho d\phi dz \hat{\rho}$$

$$\vec{ds}_{bot} = -\rho d\rho d\phi \hat{z}$$

$$Q = \int_0^{2\pi} \int_0^1 z \rho \cos^2 \phi \rho d\rho d\phi \Big|_{z=2} + \int_0^{2\pi} \int_0^1 z \rho \cos^2 \phi \rho d\rho d\phi \Big|_{z=-2}$$

$$= 2 \left(\frac{1}{3} \right) \pi + 2 \left(\frac{1}{3} \right) \pi$$

$$Q = \left(\frac{4\pi}{3} \right) C$$

\textcircled{a} $\rho_s = \vec{D} \cdot \hat{n}$

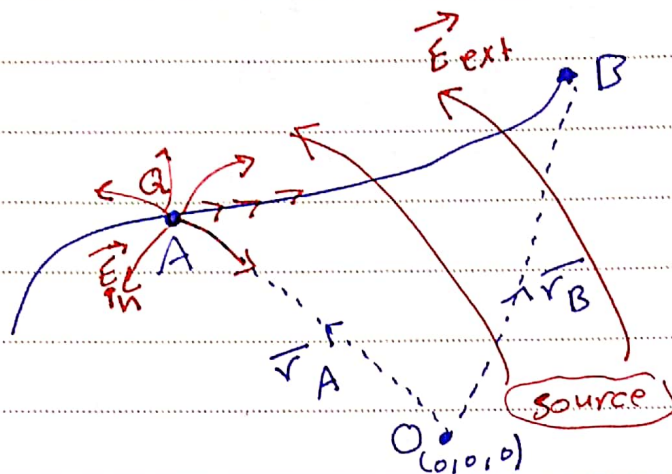
$$\rho_{s_{top}} = z \rho \cos^2 \phi$$

$$\rho_{s_{top}} \Big|_{(1, \pi/4, 3)} = (3)(1) \left(\frac{1}{2} \right) = 1.5 \text{ C/m}^2$$

$(1, \pi/4, 3)$

$$\rho_{bot} = -z \rho \cos^2 \phi = -1.5 \text{ C/m}^2$$

* Electric Potential $\equiv \phi(r)$ [scalar quantity]



Work $\equiv (W)$

To move Q from A to B

$$V_{AB} = V_B - V_A$$

$$\text{voltage} = \frac{\text{work}}{\text{charge}}$$

$$V = \frac{1}{C} \int \frac{dq}{r}$$

work = voltage * charge

$$W = Q V_{AB}$$

$$W = \vec{F} \cdot \vec{L} \quad (\text{N.m})$$

$$W = -Q \vec{E}_{\text{ext}} \cdot \vec{L} \quad \rightarrow \text{The work is done by the } \vec{E}_{\text{ext}}$$

$$\Rightarrow \int_{\text{scalar}} dW = \int -Q \vec{E}_{\text{ext}} \cdot d\vec{L}$$

$$W = -Q \int \vec{E} \cdot d\vec{L}$$

potential diff between 2 points.

$$V_{AB} = \frac{W}{Q} = - \int \vec{E} \cdot d\vec{L} = V_B - V_A = - \int_{r_A}^{r_B} \vec{E} \cdot d\vec{L}$$

$$V = - \int \vec{E} \cdot d\vec{L} \Rightarrow \text{potential diff. (V)}$$

→ For moving a point charge $q = 0$

$$\vec{E} = \frac{Q}{4\pi\epsilon_0 r^2} \hat{r}$$

$$U_{AB} = - \int_{r_A}^{r_B} \frac{Q}{4\pi\epsilon_0 r^2} \cdot dr \hat{r} \cdot \hat{r}$$

$dL = dr \hat{r}$

$$= \frac{Q}{4\pi\epsilon_0} \int_{r_A}^{r_B} \frac{1}{r^2} dr$$

$$U_{AB} = \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{r_B} - \frac{1}{r_A} \right) V$$

$$U_{AB} = \frac{Q}{4\pi\epsilon_0 r_B} - \frac{Q}{4\pi\epsilon_0 r_A}$$

$$U_{AB} = V_B - V_A$$

if point A is at ∞

$$r_A \rightarrow \infty$$

$$U_{\infty B} = \frac{Q}{4\pi\epsilon_0 r_B} - 0$$

$$= V_B - V_{\infty} \quad , V_{\infty} = 0 \text{ since } r_{\infty} \rightarrow \infty$$

* ∞ default ref if it is not mentioned

→ ref = dest and voltage

المرجع هو الهدف والجهد

$$V = \frac{Q}{4\pi\epsilon_0 r} \rightarrow \text{if ref is at } \infty$$

* Electric Potential \Rightarrow

$$V_{AB} = \frac{W}{Q} = - \int_L \vec{E} \cdot d\vec{L}$$

\rightarrow From \vec{E} (field)

\rightarrow From the source

\rightarrow For a point charge From A \rightarrow B

$$* V_{AB} = \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{r_B} - \frac{1}{r_A} \right) \quad (V)$$

* if ref is at $\infty \Rightarrow V = \frac{Q}{4\pi\epsilon_0 r}$, $V_{\infty} = 0$
point \leftarrow

\rightarrow For Line charge ρ_L .

$$* \text{if ref is at } \infty \Rightarrow V = \int \frac{\rho_L dL}{4\pi\epsilon_0 r}$$

\rightarrow For surface charge ρ_S .

$$* \text{if ref is at } \infty, V_{\infty} = 0 \Rightarrow V = \int \frac{\rho_S dS}{4\pi\epsilon_0 r}$$

\rightarrow For volume charge ρ_V .

$$* \text{ref is at } \infty, V_{\infty} = 0 \Rightarrow V = \int \frac{\rho_V dV'}{4\pi\epsilon_0 r}$$

Potential \leftarrow V' \rightarrow volume
Volume

\leftarrow تستخدم في القوانين كما أُعَدَّر أُطْعَمُ حَيْثُ أُفَلَّحُ نُونًا [أولاً \vec{E} بالفضة]

Ex 00 Two point charges $-4 \mu\text{C}$ & $5 \mu\text{C}$ are located at $(2, -1, 3)$ and point $(0, 4, -2)$, Find the potential at $p(1, 0, 1)$

↳ Field

Sol:- ref is at $\infty (V_\infty = 0) \rightarrow$ potential plus ref اذا ما ذكرنا (الاول ابي) potential plus ref
 صلا لكونان $c [10V] \leftarrow$ چون هو ار ref
 اذا ما ذكرنا ∞ ref $\rightarrow \infty$

\Rightarrow V at $p \Rightarrow V$ point charge of ref $\rightarrow \infty$

$$V = \frac{Q}{4\pi\epsilon_0 r}$$

\rightarrow we can write it as for N -charges

$$V = \frac{1}{4\pi\epsilon_0} \sum_{k=1}^N \frac{Q_k}{r_k}$$

OR
$$V = \frac{-4 \times 10^{-6}}{4\pi \times 10^{-9} \times \sqrt{6}} + \frac{5 \times 10^{-6}}{4\pi \times 10^{-9} \times \sqrt{26}}$$

$\vec{r}_1 = \text{field} - S_1 = (1, 0, 1) - (2, -1, 3) \quad |\vec{r}_2| = |(1, -4, 3)|$
 $|\vec{r}_1| = |(-1, 1, -2)| \quad |\vec{r}_2| = \sqrt{26}$

$\Rightarrow V|_{(1,0,1)} = V_p = -5.872 \text{ kV}$

$[V_{\text{ref}} = V_p - V_\infty = V_p - 0 = V_p]$ لازم يكتب انو $[\infty = \text{ref}]$ او $[\infty = \text{ref}]$

* $V_p = -5.872 \text{ kV}$, what is the meaning of the minus sign?

\rightarrow drop in potential (the work is done by the field it self) $\left[\int_L E \cdot dL \text{ is +ve} \right]$

if V is (+ve)

\rightarrow gain in potential (the work is done by the external field) $\left[\int_L E \cdot dL \text{ is -ve} \right]$

Ex :- A point charge of 5 nC located at $(-3, 4, 0)$ and a line $y=1, z=1$ carries uniform charge (ρ_L) of 2 nC/m. (infinite line).

a) ref = ∞ ...

b) If $V = 100V$ at B (1, 2, 1), Find V at C (-2, 5, 3)

sol :- المطلوب $V_C \rightarrow$ في V_C or V_{BC} ref $\neq \infty$'s ref at B

$\Rightarrow V_{BC} = V_C - V_B = V_C - 100$

$V_C = V_{BC} + 100$

$V_{BC} ??$

$\Rightarrow V_{BC} = V_{BCQ} + V_{BCL}$
 point charge line

بعل صحت اذا كان في حافة القانون

$V_{BCQ} = - \int_L \vec{E} \cdot d\vec{L}$, $\vec{E} = \frac{Q}{4\pi\epsilon_0 r^2} \hat{a}_r$
 $= - \int_{r_B}^{r_C} \frac{Q}{4\pi\epsilon_0 r^2} dr$ (to give E sphere)
 $= \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{r_C} - \frac{1}{r_B} \right)$

[C] $r_C =$ Field - source = $|(1, 1, 3)| = \sqrt{11}$

[B] $r_B =$ Field - source = $|(4, -2, 1)| = \sqrt{21}$

so $V_{BCQ} = \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{\sqrt{11}} - \frac{1}{\sqrt{21}} \right)$



$$* V_{BCL} = - \int_L \vec{E} \cdot d\vec{L}, \quad \vec{E} = \frac{\rho_L}{2\pi\epsilon_0 r} \hat{r}$$

$$= - \int_{\rho_B}^{\rho_C} \frac{\rho_L}{2\pi\epsilon_0 r} \hat{r} \cdot d\vec{r}$$

بتغير بار \vec{E} ال \hat{r} وال

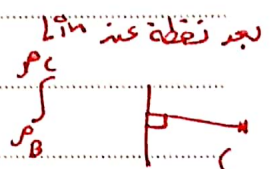
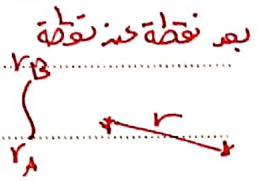
$$= \frac{-\rho_L}{2\pi\epsilon_0} (\ln \rho_C - \ln \rho_B)$$

$$= \frac{-\rho_L}{2\pi\epsilon_0} \ln \left(\frac{\rho_C}{\rho_B} \right)$$

$$\rho_C = \left| (-2, 5, 3) - (-2, 1, 1) \right|$$

$$= \sqrt{20}$$

field-source
 أنظر مسافة
 = 1, 2, 1 وال x مثل



بناخذ اقصى مسافة
 كأنه صيغ

$$\rho_B = \left| (1, 2, 1) - (1, 1, 1) \right|$$

$$= 1$$

field-source
 كما انحر، ا= 1 وال y مثل

$$\ln \left(\frac{\rho_C}{\rho_B} \right) > 1 \Rightarrow +ve \Rightarrow U_{BCL} (-ve)$$

لازمنة: يمكن ان يتم
 بسهولة

$$U_{BCL} = \int_L \frac{\rho_L dL}{4\pi\epsilon_0 r}$$

وال انحر مثل على اول قانون الين فيه \vec{E}

$$\Rightarrow U_{BC} = U_{BCQ} + U_{BCL} = -50.175 (V)$$

↳ drop in potential.

$$\hookrightarrow U_B > U_C$$

$$U_C = U_{BC} + U_B = -50.175 + 100 = \boxed{49.825 (V)}$$

⇒ For the (4th) case in Gauss's [volume]

↳ pn sphere example

$$\Rightarrow \rho_v = \begin{cases} \rho_0 & ; r < a \\ 0 & ; r > a \end{cases}$$

$$\Rightarrow \vec{E} = \begin{cases} \frac{\rho_0 r}{3\epsilon_0} & ; 0 \leq r < a \\ \frac{\rho_0 a^3}{3\epsilon_0 r^2} & ; a \leq r < \infty \end{cases}$$

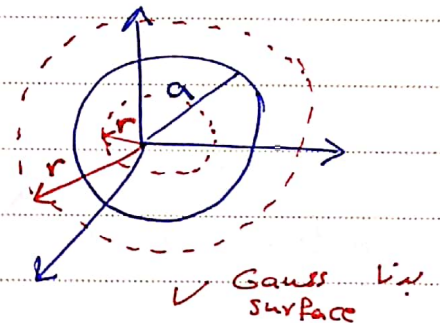
Find (V) everywhere ρ_0

* بار \vec{E} اجباري تبدأ من $r=0$ لبرا $r=\infty$

* بار \vec{V} دائماً تبدأ من ref (ممكن ان ref

يكون عند 0 يعني تبدأ من ∞ لبرا $r=0$

ان ref $\leftarrow \infty$ (من لبرا ∞)



⇒ ref ps at ∞

ref $\leftarrow \infty$ + ∞

→ ① for $a < r < \infty$

$$V = - \int_L \vec{E} \cdot d\vec{L} = - \int_{\infty}^r \frac{\rho_0 a^3}{3\epsilon_0 r^2} dr$$

$$= + \frac{\rho_0 a^3}{3\epsilon_0} \left(\frac{1}{r} - \frac{1}{\infty} \right) = \frac{\rho_0 a^3}{3\epsilon_0 r} (V)$$

→ ② for $0 < r < a$

$$V = - \int_L \vec{E} \cdot d\vec{L} = - \int_{\infty}^a \vec{E} \cdot d\vec{L} - \int_a^r \vec{E} \cdot d\vec{L}$$

← يقسم \vec{E} في راجحة ∞ لبرا r (من ∞ لبرا r)

$$= \frac{\rho_0 a^3}{3\epsilon_0 a} - \int_a^r \frac{\rho_0 r}{3\epsilon_0} dr$$

[conting \vec{E}]
أما V

$$V = \frac{\rho_0 a^2}{3\epsilon_0} - \frac{\rho_0}{3\epsilon_0} \left(\frac{r^2 - a^2}{2} \right)$$

عند $r=0$ لطلب V منقصة الكرة $\Rightarrow V$

Note :-

$$V = - \int_L \vec{E} \cdot d\vec{L} \quad , \quad V = \int_L \frac{\rho_L dL}{4\pi\epsilon_0 r}$$

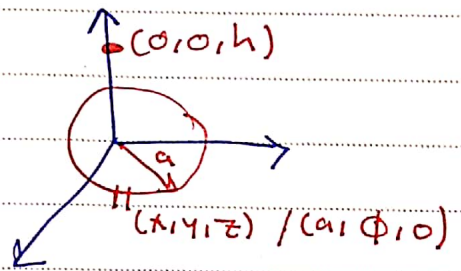
→ Finding (V) From the field .

→ Finding (V) From the source .

Ex :- Ring

↑ V عكس القافوس تكون موجا بين التاني اقول

a) E? b) V?



[نوطاب بين V بقدر نستقيم]

$$V = - \int_L \vec{E} \cdot d\vec{L} \quad \text{أو} \quad V = \int_L \frac{\rho_L dL}{4\pi\epsilon_0 r}$$

لصورتنا لاصب (z)
 $dL = dz a \hat{z}$
 $\int_{-\infty}^{\infty} = \int_L$ يعني

حسب ϕ
 $dL = a d\phi$
 $\int_0^{2\pi} = \int_L$ يعني

لو استخفنا $V = - \int_L \vec{E} \cdot d\vec{L} \rightarrow d\vec{L} = dz a \hat{z}$

$$\vec{E} = \int_L \frac{\rho_L \cdot d\vec{L}}{4\pi\epsilon_0 r^2} \hat{r} = \int_L \frac{\rho_L \cdot \vec{r} dL}{4\pi\epsilon_0 r^3} \quad \left. \begin{array}{l} \vec{E} \text{ in cyl.} \\ \text{so } dL = a d\phi \\ \text{bin } \vec{E} \end{array} \right\}$$

$$\Rightarrow \vec{r} = (0, \phi, h) - (a, \phi, 0)$$

$$\vec{r} = -a a \hat{r} + h a \hat{z} \quad , \quad r = \sqrt{a^2 + h^2} \quad , \quad dL \rho_L \vec{E} = a d\phi$$

$$\vec{E} = \frac{\rho_L a}{4\pi\epsilon_0} \int_0^{2\pi} \frac{-a a \hat{r} + h a \hat{z}}{[a^2 + h^2]^{3/2}} d\phi \quad \Rightarrow = \frac{\rho_L a h}{2\epsilon_0 [a^2 + h^2]^{3/2}} \hat{z}$$

$$\Rightarrow V = - \int_L \vec{E} \cdot d\vec{L} \rightarrow d\vec{L} = dz a \hat{z}$$

$$= - \int_{-h}^h \frac{\rho_L a h a \hat{z} \cdot dz a \hat{z}}{2\epsilon_0 [a^2 + h^2]^{3/2}} \quad , \quad \text{replace (h) by (z)}$$

$$= - \int_{-h}^h \frac{\rho_L a z}{2\epsilon_0 [a^2 + z^2]^{3/2}} dz \quad \rightarrow$$

→ $V = \int \frac{\rho_L dL}{4\pi\epsilon_0 r}$ → $dL = a d\phi$, $\int_0^{2\pi} = \int_0^{2\pi}$

$$V = \int_0^{2\pi} \frac{\rho_L a d\phi}{4\pi\epsilon_0 \sqrt{a^2 + h^2}}$$

$$V = \frac{\rho_L a}{2\epsilon_0 \sqrt{a^2 + h^2}} \quad (V)$$

⇒ How to Find \vec{E} From potential :-

$$V = - \int \vec{E} \cdot d\vec{L}$$

In cart^s -

$$\vec{E} = E_x \hat{a}_x + E_y \hat{a}_y + E_z \hat{a}_z$$

$$d\vec{L} = dx \hat{a}_x + dy \hat{a}_y + dz \hat{a}_z$$

$$\vec{E} \cdot d\vec{L} = E_x dx + E_y dy + E_z dz$$

$$\Rightarrow dV = - \vec{E} \cdot d\vec{L}$$

$$dV = \frac{dV}{dx} dx + \frac{dV}{dy} dy + \frac{dV}{dz} dz$$

by equating similar components

$$\frac{dV}{dx} dx = -E_x dx \Rightarrow E_x = - \frac{dV}{dx}$$

$$E_y = - \frac{dV}{dy}$$

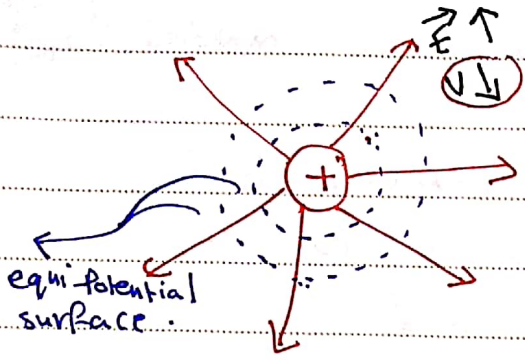
$$E_z = - \frac{dV}{dz}$$

$$\vec{E} = - \left[\frac{dV}{dx} \hat{a}_x + \frac{dV}{dy} \hat{a}_y + \frac{dV}{dz} \hat{a}_z \right]$$

$$\vec{E} = - \nabla V$$

cart
cyl
sph

⇒ to find \vec{E} if potential is given.



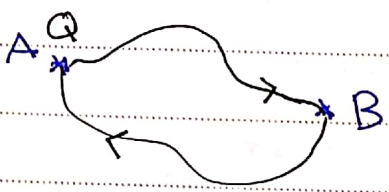
$$V = \frac{Q}{4\pi\epsilon_0 r}$$

$$\vec{D} = \epsilon_0 \vec{E} \quad \vec{E} \text{ of } \vec{D} \text{ الهم نفس الاتجاه}$$

⇒ Potential over a closed loop 0

Q From A to A

$$V_{AA} = - \int_A^B \vec{E} \cdot d\vec{L} - \int_B^A \vec{E} \cdot d\vec{L} = 0$$



$$= V_A - V_A$$

$$V_A \neq 0$$

$$W = Q \cdot V_{AA} = 0$$

W = الشغل

$$V = \oint_L \vec{E} \cdot d\vec{L} = 0$$

closed / non path

⇒ second Maxwell's eq. in integral form.

L_0 (equipotential surface)

$$V = - \int_L \vec{E} \cdot d\vec{L}$$

no closed path.

Ex :- Given $U = \frac{10}{r^2} \sin \Theta \cos \Phi$ (v)

Find a) \vec{D} at $(2, \frac{\pi}{2}, 0) \rightarrow$ cyl & sph

b) The work done in moving a 10 μ C charge from $A(1, 30^\circ, 120^\circ)$ to $B(4, 90^\circ, 60^\circ)$.

Sol :-

(a) $\vec{D} = \epsilon_0 \vec{E}$, $\vec{D} = -\epsilon_0 \nabla V$ ($\vec{E} = -\nabla V$)

$$\vec{E} = - \left(\frac{dV}{dr} \hat{r} + \frac{\partial V}{r \partial \Theta} \hat{\Theta} + \frac{\partial V}{r \sin \Theta \partial \Phi} \hat{\Phi} \right)$$

$$\vec{E} = - \left(\underbrace{-\frac{20}{r^3} \sin \Theta \cos \Phi}_{E_r} \hat{r} + \underbrace{\frac{10}{r^3} \cos \Theta \cos \Phi}_{E_\Theta} \hat{\Theta} + \underbrace{-\frac{10}{r^3 \sin \Theta} \sin \Phi}_{E_\Phi} \hat{\Phi} \right)$$

$$\Rightarrow \vec{D} \Big|_{(2, \frac{\pi}{2}, 0)} = \epsilon_0 \vec{E} \Big|_{(2, \frac{\pi}{2}, 0)} = \frac{10^{-9}}{36\pi} \left(\frac{20}{8} \hat{r} \right) \text{ C/m}^2$$

(b) work.

Method (1) :-

$$\begin{aligned} W &= Q V_{AB} = Q (V_B - V_A) \\ &= 10 \times 10^{-6} \left(\frac{10}{16} \cdot \left(\frac{1}{2}\right) (1) - 10 \left(\frac{1}{2}\right) \left(-\frac{1}{2}\right) \right) \\ &= 10 \times 10^{-6} \left(\frac{5}{16} - \frac{40}{16} \right) \\ &= 10 \times 10^{-6} \left(\frac{45}{16} \right) \text{ J} = \boxed{28.125 \mu\text{J}} \end{aligned}$$

Method (2) :-

$$\begin{aligned} W &= Q V_{AB} = -Q \int_{r_A}^{r_B} \vec{E} \cdot d\vec{L} \\ &= -10 \times 10^{-6} \left[\int_{r_A}^{r_B} [E_r dr + E_\Theta r d\Theta + E_\Phi r \sin \Theta d\Phi] \right] \end{aligned}$$

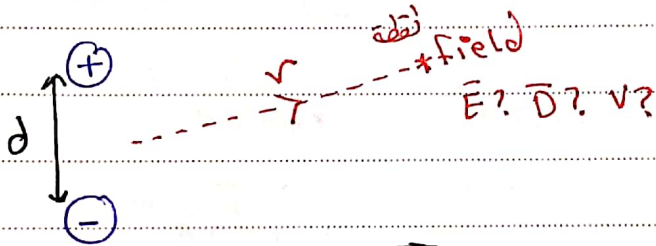
$$= -10 \times 10^{-6} \left[\int_1^4 E_r dr \right] + \int_{30}^{90} E_\theta r d\theta \left[\right] + \int_{120}^{60} E_\phi r \sin\theta d\phi \left[\right]$$

$\int_1^4 E_r dr$: r بقدر ϕ/θ سے ما بقیہ
 $\int_{30}^{90} E_\theta r d\theta$: $\theta=30^\circ$ $\phi=120$ $r=4$ θ بقدر r نقلیہ ϕ سے ما بقیہ
 $\int_{120}^{60} E_\phi r \sin\theta d\phi$: $r=4$ $\theta=90$ ϕ بقدر r نقلیہ θ سے ما بقیہ

معین نہیں ترتیب
 النقل
 لہذا نقلت θ اولیٰ
 $\int_{30}^{90} E_\theta d\theta$
 $r=1$ $\phi=120$ θ سے ما بقیہ
 آگلی

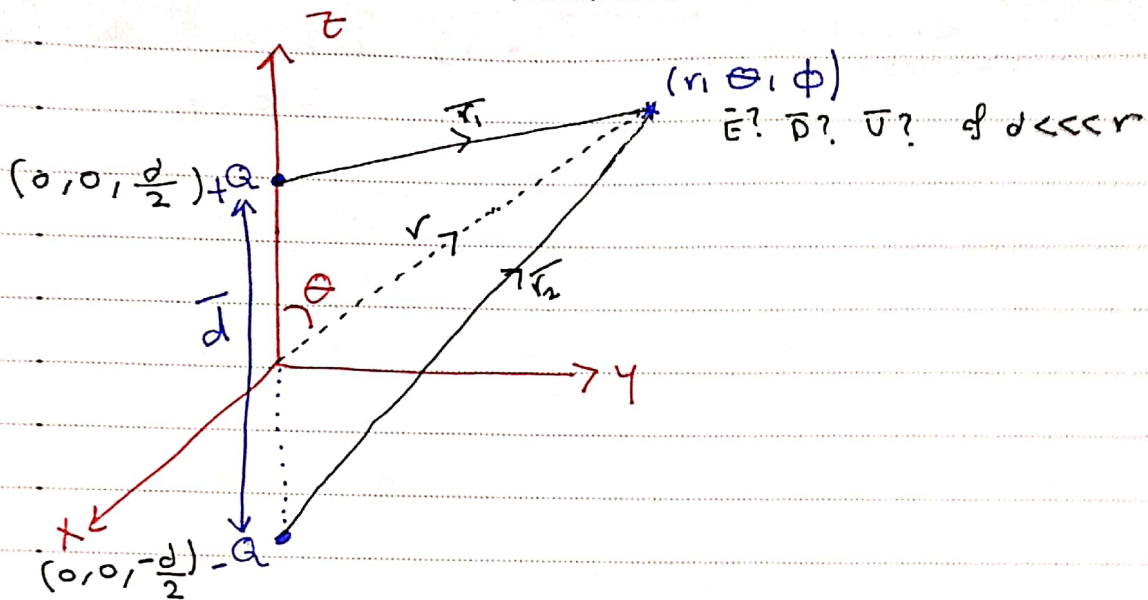
$$= 28.125 \text{ MJ}$$

Electric Dipole :-



$$d \ll r \rightarrow \text{dipole condition.}$$

کہ کا نو انساظر عندیہ
 بشوہم کاہم حثتہ و مدہ



sd: ∞ ref is at ∞ , $V_{\infty} = 0$

$$V = V_+ + V_-$$

$$= \frac{Q}{4\pi\epsilon_0 r_1} - \frac{Q}{4\pi\epsilon_0 r_2}$$

$$= \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{r_1} - \frac{1}{r_2} \right)$$

$$V = \frac{Q (r_2 - r_1)}{4\pi\epsilon_0 r_1 r_2} \quad (1)$$

بالواقع حسب موقعه صوح

يعني Q/d / r_2/r_1 صبح نجيبها الا اذا اخطم

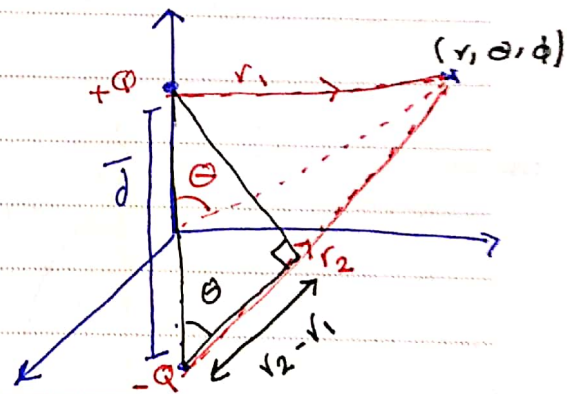
$$(*) \cos \theta = \frac{r_2 - r_1}{d}$$

$$r_1 r_2 \approx r^2$$

$$\Rightarrow V = \frac{Q d \cos \theta}{4\pi\epsilon_0 r^2} \quad (2)$$

لـ كان الـ Q/d صبح نجيبها

defining dipole moment (\vec{p})



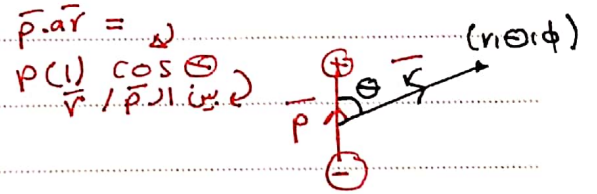
$\Rightarrow \vec{p} = q \vec{d}$ (C.m) → قيمة السالب للوجوب
(الاتجاه الرابطة عندها انبطار \vec{E})
 $p = qd$

$$V = \frac{p \cos \theta}{4 \pi \epsilon_0 r^2}$$
(3)

r = field - center of the dipole (source)

\vec{p} و \vec{r} هما vector

$$V = \frac{\vec{p} \cdot \hat{a}_r}{4 \pi \epsilon_0 r^2}$$
(3)
 $\Rightarrow V = \frac{\vec{p} \cdot \vec{r}}{4 \pi \epsilon_0 r^3}$



$\vec{E} = \vec{E}_+ + \vec{E}_-$

OR $\vec{E} = -\nabla V \Rightarrow \text{في } \theta, r \rightarrow \text{ sph}$

$$\Rightarrow \vec{E} = \frac{-p}{4 \pi \epsilon_0} \left(-\frac{2 \cos \theta}{r^3} \hat{a}_r - \frac{\sin \theta}{r^3} \hat{a}_\theta \right)$$

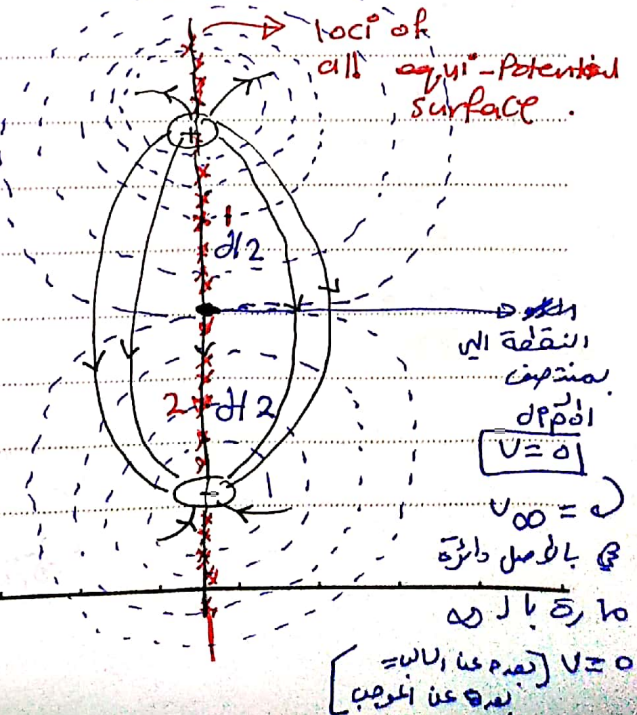
$$\vec{E} = \frac{p}{4 \pi \epsilon_0 r^3} (2 \cos \theta \hat{a}_r + \sin \theta \hat{a}_\theta)$$
V/m

$\vec{D} = \epsilon_0 \vec{E}$ (C/m²)

[في الأصل دائرة من قطع]

Flux line

$\psi = \frac{Q}{4 \pi \epsilon_0 r^2}$



⇒ For N Dipoles $q \cdot a$

Field \vec{E} \rightarrow النقطة على
center of dipole (source)

$$V = \frac{\vec{p} \cdot \vec{a}\vec{r}}{4\pi\epsilon_0 r^2} = \frac{\vec{p} \cdot (\vec{r} - \vec{r}')}{4\pi\epsilon_0 |\vec{r} - \vec{r}'|^3}$$

$$V = \frac{1}{4\pi\epsilon_0} \sum_{k=1}^N \frac{\vec{p}_k \cdot (\vec{r} - \vec{r}'_k)}{|\vec{r} - \vec{r}'_k|^3} \quad (V)$$

Ex 80 Two dipoles with dipole moments $-5a\hat{z}$ n.c.m and $9a\hat{z}$ n.c.m are located at $(0,0,-2)$ and $(0,0,3)$. Find the potential and \vec{E} at the origin.

sol: ref \vec{E} at ∞

بقدر نقطة

$$\Rightarrow V = \frac{\vec{p}_1 \cdot \vec{a}\vec{r}_1}{4\pi\epsilon_0 r_1^2} + \frac{\vec{p}_2 \cdot \vec{a}\vec{r}_2}{4\pi\epsilon_0 r_2^2}$$

$$= \frac{-5a\hat{z} \times 10^{-9} \cdot 2a\hat{z}}{4\pi \times 10^{-9} \times 8} + \frac{9a\hat{z} \times 10^{-9} \cdot -3a\hat{z}}{4\pi \times 10^{-9} \times 27}$$

$$V = 0.25 \text{ V}$$

drop, work done by field itself.

$$\Rightarrow \vec{E} = \vec{E}_1 + \vec{E}_2 \quad \vec{E} \text{ بقدر نقطة}$$

$-5a\hat{z}$ direction.

(-5 \rightarrow 5 scale) $p_1 = 5 \text{ n.c.m}$
(-2 \rightarrow 2 scale) $r_1 = 2 \text{ m}$

$$\theta_1 = 180^\circ$$

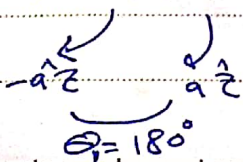
$p_2 = 9 \text{ n.c.m}$

$r_2 = 3 \text{ m}$

$$\theta_2 = 180^\circ$$

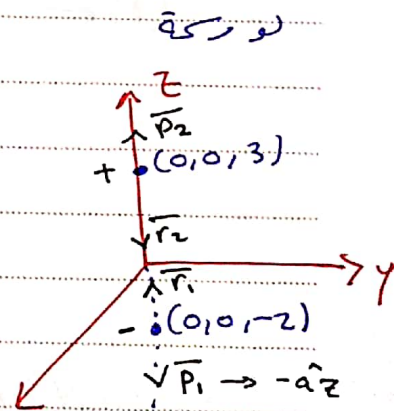
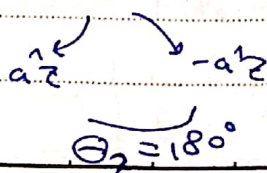
angle between \vec{p}_1 & \vec{r}_1

$$\theta_1 \angle \vec{p}_1 \text{ & } \vec{r}_1$$



angle between \vec{p}_2 & \vec{r}_2

$$\theta_2 \angle \vec{p}_2 \text{ & } \vec{r}_2$$



$$* V = \frac{\bar{P} \cdot \hat{a}_r}{4\pi \epsilon_0 r^2} (V)$$

Point charge

$$V \propto \frac{1}{r}$$

$$E \propto \frac{1}{r^2}$$

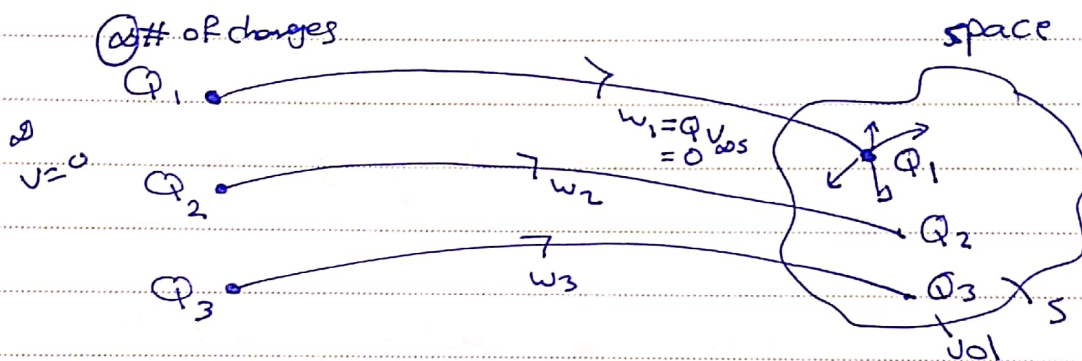
Dipole

$$V \propto \frac{1}{r^2}$$

$$E \propto \frac{1}{r^3}$$

Energy Density in Electrostatic Fields

$W_E = \text{Electrical Energy in (J)}$



* $Q_1 \rightarrow Q_2 \rightarrow Q_3$ بنا نقطه لـ space بعد ترتيب

$$[0 = W] \leftarrow \text{البراقه صافيه} \leftarrow V=0 \text{ ref } \leftarrow V=0 \text{ لـ } Q_1$$

بعد ما نقلنا Q_2 كانت Q_1 موجوده فـ ترتيب واحدنا وعند نقل Q_3 اترت عليها Q_1, Q_2

$$W_E = w_1 + w_2 + w_3$$

$$= 0 + Q_2 V_{12} + Q_3 (V_{13} + V_{23}) \rightarrow \textcircled{1}$$

الشف المبدول
لنقل الشحنة الاخرى.

* $Q_3 \rightarrow Q_2 \rightarrow Q_1$

$$W_E = w_1 + w_2 + w_3$$

$$= Q_1 (V_{21} + V_{31}) + Q_2 w_{32} + 0 \rightarrow \textcircled{2}$$

\Rightarrow Add $\textcircled{1}$ & $\textcircled{2}$

$$2W_E = Q_1 (V_{21} + V_{31}) + Q_2 (V_{12} + V_{32}) + Q_3 (V_{13} + V_{23})$$

$V_1 \rightarrow$ total potential on Q_1

$$W_E = \frac{1}{2} (Q_1 \cdot V_1 + Q_2 \cdot V_2 + Q_3 \cdot V_3)$$

$$* W_E = \frac{1}{2} \sum_{k=1}^N Q_k V_k \text{ p.u. (J) for } N\text{-point charges.}$$

ملاحظة: نستخدم قانون (قانون) الطاقة E. Energy ، من لوكي
 Verify your answer by calculate work *
 نستخدم $W_E = W_1 + W_2 + W_3 + W_4 \dots$

⇒ For line charge ∴

$$W_E = \frac{1}{2} \int_L \rho_L V dL \quad \text{potential} \cdot \quad (\text{J})$$

⇒ For surface charge ∴

$$W_E = \frac{1}{2} \int_S \rho_S V ds \quad (\text{J})$$

source plus

⇒ For volume charge ∴

$$W_E = \frac{1}{2} \int_{V'} \rho_V V' dv' \quad (\text{J})$$

⇒ How to relate W_E with \bar{E} ??

$$* W_E = \frac{1}{2} \int_V \rho_V V dv$$

$$\rho_V = \nabla \cdot \bar{D}$$

$$\bar{E} = -\nabla V$$

$$* W_E = \frac{1}{2} \int_V \bar{E} \cdot \bar{D} dv$$

$$= \frac{1}{2} \int_V \epsilon_0 E^2 dv$$

$$= \frac{1}{2} \int_V \frac{D^2}{\epsilon_0} dv$$

التي $\bar{D} = \epsilon_0 \bar{E}$
 هي $\bar{E} = \frac{\bar{D}}{\epsilon_0}$
 Volume. $\bar{E} \cdot \bar{E} = |\bar{E}|^2$

⇒ Energy Density = $\frac{\text{Energy } (W_E)}{\text{Volume}} \quad (\text{J/m}^3)$

$$W_E = \frac{W_E}{\text{volume}}$$

OR

$$W_E = \frac{W_E}{\text{Vol}} \quad (\text{J/m}^3)$$

$$\text{OR } W_E = \frac{1}{2} \bar{E} \cdot \bar{D}$$

$$= \frac{1}{2} \epsilon_0 E^2$$

$$= \frac{1}{2} \frac{D^2}{\epsilon_0}$$

* $W_E = \int_V w_E \cdot dV \rightarrow$ لوکلب W_E وکان
 حلی w_E

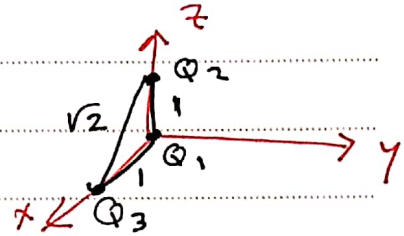
Ex :- The point charges -1 nC , 4 nC and 3 nC are located at $(0, 0, 0)$, $(0, 0, 1)$, $(1, 0, 0)$
 Find the energy in the system??

$$W_E = \frac{1}{2} \sum_{k=1}^N Q_k V_k$$

$$= \frac{1}{2} (Q_1 V_1 + Q_2 V_2 + Q_3 V_3)$$

$$= \frac{1}{2} \left[Q_1 (V_{21} + V_{31}) + Q_2 (V_{12} + V_{32}) + Q_3 (V_{13} + V_{23}) \right]$$

$\frac{Q_2}{4\pi\epsilon_0(1)}$ $\frac{Q_3}{4\pi\epsilon_0(1)}$ $\frac{Q_1}{4\pi\epsilon_0(1)}$ $\frac{Q_3}{4\pi\epsilon_0(\sqrt{2})}$
 $\frac{Q_1}{4\pi\epsilon_0(1)}$ $\frac{Q_2}{4\pi\epsilon_0(\sqrt{2})}$



$W_E = 13.137 \text{ nJ}$

↑
 energy density energy of system work done by system
 $\rightarrow W = W_1 + W_2 + W_3$

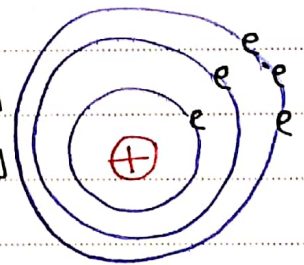
CH5: Electric Field in Materials

* Classification of materials based on its electrical properties:

- Conductors (Metals), $(\sigma \gg \gg 1)$
Cu, Al, Ag, lead
- semi-conductors, $(\sigma > 1)$
Si, GaAs, Ge
- Dielectrics (Insulators), $(0 < \sigma \ll \ll 1)$
Li, Mica, Teflon, glass, polystyrene, polythene

$\sigma \equiv$ Conductivity (S/m), $S = \Omega^{-1}$, $\sigma (\Omega \cdot m)^{-1}$
 $\rho \equiv$ Resistivity ($\Omega \cdot m$) = $\frac{1}{\sigma}$

$T \uparrow \rightarrow \sigma \downarrow$ [إذا زادت الحرارة تزيد حركة الإلكترونات وتقل σ]
 $T \downarrow \rightarrow \sigma \uparrow$ [إذا قلت الحرارة كل إلكترون في مكانه فالحرارة تنزى]



* $\sigma = 0 \Rightarrow$ Free space

* So σ depends on:

- Temperature ($^{\circ}K$)
- Frequency (Hz)

* أي مادة ال $T > 0^{\circ}K$ تكون لها طاقة حركية \leftarrow طاقة
 ل $T = 0^{\circ}K$ \leftarrow ماتكون الطاقة الحركية

* lead at $T = 20^{\circ}C$ ($293^{\circ}K$)

$\rightarrow \sigma \approx 10^6$ (S/m)

if T is reduced to ($4^{\circ}K$)

$\rightarrow \sigma \approx 10^{20}$ (S/m)

- (super conductor)
- (perfect conductor)
- (good conductor)

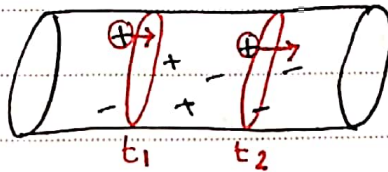
* Types of current :

1] conduction current , (conductors, DC or AC)

2] convection current , (dielectrics, DC)

3] Displacement current , (dielectrics, AC)

C, CH: 9



← يستعمله لما التغير $I = \frac{\Delta Q}{\Delta t} = \frac{Q_2 - Q_1}{t_2 - t_1} \equiv (C/s) \text{ or } (A)$
 يكون منتظم وبالواقع نا
 يكون منتظم في استخدامه .

في لا غير منتظم $I = \frac{dq}{dt}$ in general

$\Rightarrow \frac{I}{\Delta S} = J$, $J \equiv \text{current density } (A/m^2)$

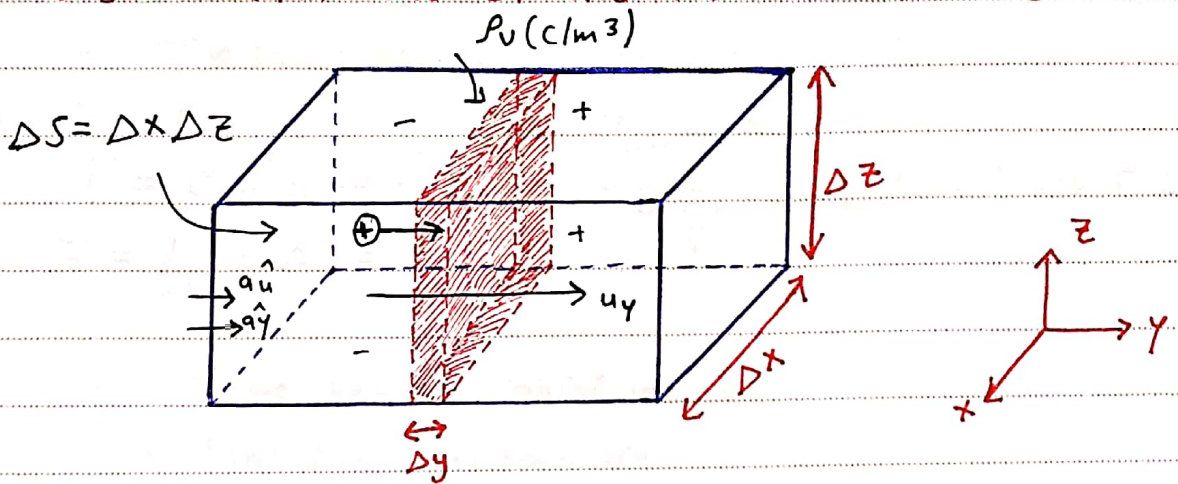
scaler ← $I = \int_S \vec{J} \cdot \vec{ds}$

حده لو واحدية و
 لازم أمخزانة السلك لازم يكون
 مغلقه كذا بصر I فيه .

بمضي
 current
 دايه الاتجاه

$$I = \int_S \vec{J} \cdot \vec{ds}$$

* Consider a filament of a dielectric material of



$$I = \frac{\Delta Q}{\Delta t}$$

$$= \frac{\rho_v \Delta V}{\Delta t}$$

$$= \frac{\rho_v \Delta S \Delta y}{\Delta t}$$

$$I = \rho_v \Delta S u_y$$

$$J = \frac{I}{\Delta S} = \rho_v u_y$$

$$\bar{J} = \rho_v \bar{u} \equiv \frac{\text{C}}{\text{m}^3} \cdot \frac{\text{m}}{\text{s}} = \left(\frac{\text{A}}{\text{m}^2} \right)$$

convection current density

$$Q = \int \rho_v dV$$

$$dQ = \rho_v dV$$

$$\Delta Q = \rho_v \Delta V$$

$$\Delta S = \Delta x \Delta z$$

$$\Delta V = \Delta S \Delta y = \Delta x \Delta y \Delta z$$

$$u_y = \frac{\Delta y}{\Delta t} \quad \bar{u} = u_y \hat{a}_y$$

التيار المتحرك على مساحة Δy وينتقل بكون اتجاه حركة \hat{a}_y

* How to relate \bar{J} with \bar{E} ?

- The force on one electron:

$\Rightarrow Q = -e$

$\bar{F} = Q\bar{E} = -e\bar{E} = m\bar{a} = \frac{m\bar{u}}{\tau}$ [if $\tau \uparrow \rightarrow \bar{F} \downarrow$]

$\bar{a} = \frac{du}{dt} = \Delta u = \frac{\bar{u}}{\tau}$

$\tau \equiv$ Time between collisions (s)

\hookrightarrow affected by temperature

$\tau \downarrow \rightarrow \tau \uparrow$

$\rightarrow -e\bar{E} = \frac{m\bar{u}}{\tau}$

$\bar{u} = \frac{-e\tau}{m}\bar{E}$, τ is fixed if Temp. is fixed

$\bar{u} = \mu \bar{E}$

(drift velocity) $\frac{v_d}{\tau} = \leftarrow$ mobility $\left(\frac{C \cdot s}{kg}\right)$

\Rightarrow For n -electrons per volume

$\rho_v = n(-e) \Rightarrow (C/m^3)$, $n = \#$ of charges per volume ($\#/m^3$)

$\bar{J} = \rho_v \bar{u}$
 $= -ne \left(\frac{-e\tau}{m}\right) \bar{E}$

$\bar{J} = \frac{ne^2\tau}{m} \bar{E}$

$\bar{J} = \sigma \bar{E}$

$\frac{\sigma}{M} = \rho_v$

$\frac{1}{\Omega \cdot m} \cdot \frac{V}{m} = \frac{A}{m^2}$

\rightarrow conduction current density / ohm's law

(بقدر استجابة مع ال electric field من ال س بكون صغيره)

* $R = \frac{L}{\sigma A}$

1. $V = IR$ (ohm's law)

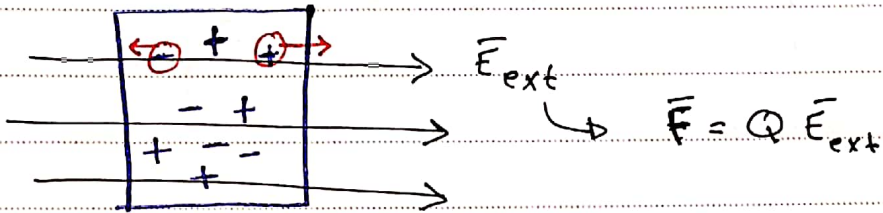
$R = \frac{1}{G}$

$V = \frac{I}{G} \rightarrow I = GV$

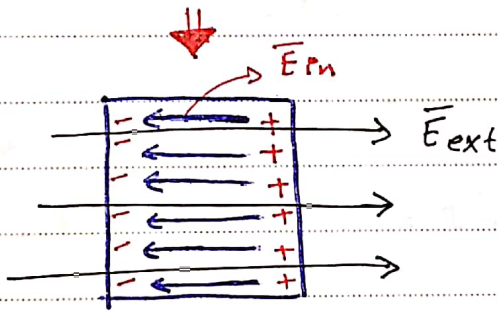
$\vec{J} = \sigma \vec{E}$

$\vec{J} = \sigma \vec{E}$

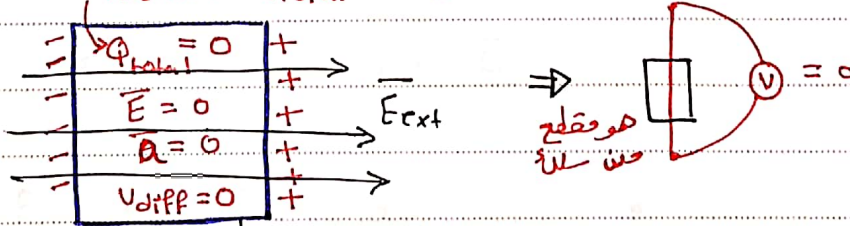
* Conductors



$Q_{total} = 0$



inside :- $Q_{total} = 0, \vec{E} = 0, \vec{a} = 0, V_{diff} = 0, \vec{D} = 0$

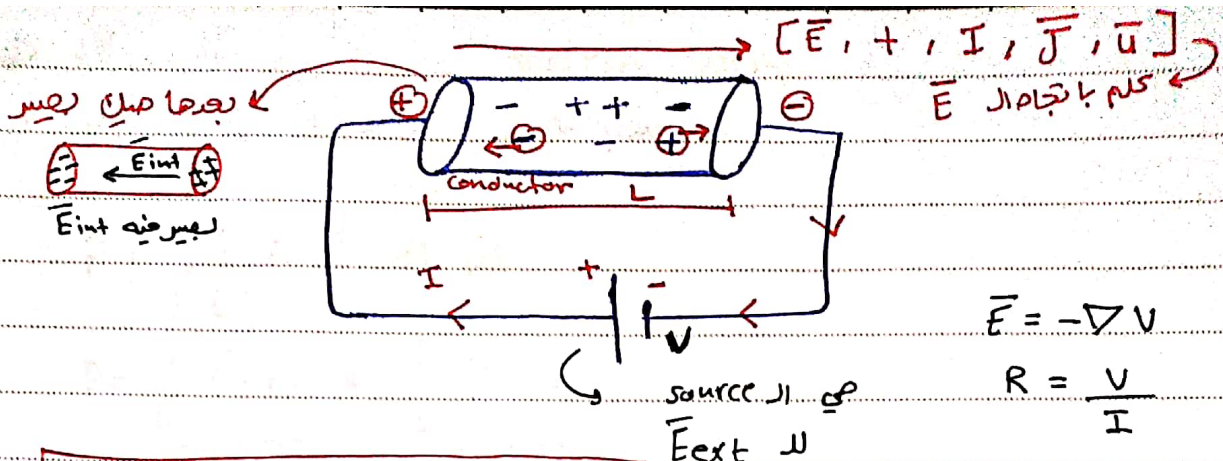


التيارات تتجمع على السطح \rightarrow equi-potential surface

* لم يثبت ان \vec{E}_{ext} يعني قتل

انني اريد البطارية رج يرجع مثل اول مرة





$$R = \frac{V}{I} = - \int_L \vec{E} \cdot d\vec{L}$$

$$\int_S \vec{J} \cdot d\vec{s} \rightarrow \sigma E$$

$$\int_S \sigma \vec{E} \cdot d\vec{s}$$

$$R = \frac{L}{\sigma s} = \frac{\rho L}{s} (\Omega)$$

ohm's law (if uniform)

$$\hookrightarrow R = \frac{E \cdot L}{\sigma E s} = \frac{\rho L}{s}$$

* Power :-

$$\left[P = V \cdot i = \frac{V^2}{R} = I^2 R = G V^2 = \frac{I^2}{G} \right] \text{ Joule's law}$$

$$P = \frac{\text{work}}{\text{Time}} \quad (\text{J/s}) \text{ or } (\text{W}) \rightarrow \text{watt}$$

$$= \frac{\vec{F} \cdot \vec{L}}{t} = \frac{Q \vec{E} \cdot \vec{L}}{t}, \quad Q = \int \rho_v dv$$

$$P = \int_v \frac{\rho_v \vec{E} \cdot \vec{L}}{t} dv, \quad \vec{u} = \frac{\vec{L}}{t}$$

$$P = \int_v \rho_v \vec{E} \cdot \vec{u} dv, \quad \vec{J} = \rho_v \vec{u}$$

Joule's law

$$P = \int_v \vec{E} \cdot \vec{J} dv$$

$$\vec{J} = \sigma \vec{E}, \quad \vec{E} = \frac{\vec{J}}{\sigma}$$

$$P = \int_v \sigma E^2 dv$$

$$P = \int_v \frac{J^2}{\sigma} dv \Rightarrow P = \int_v \rho J^2 dv$$

$\rho = \Omega \cdot m$ (Resistivity)

⇒ if uniform cross section wire

$$P = \int_V \vec{E} \cdot \vec{J} \, dV \rightarrow \text{in general}$$

$$P = \int_S \int_L \vec{E} \cdot \vec{J} \, dL \, ds$$

$$P = \int_L \vec{E} \cdot d\vec{L} * \int_S \vec{J} \cdot d\vec{s}$$

$$P = V \cdot I$$

* Power density :-

$$W_p = \frac{\text{Power}}{\text{Volume}} \quad (\text{W/m}^3)$$

$$W_p = \frac{P}{\text{Vol}} = \vec{E} \cdot \vec{J} = \sigma E^2 = \frac{J^2}{\sigma}$$

$$* P = \int_V W_p \, dV$$

Ex :- if $\vec{J} = \frac{1}{r^3} (2 \cos \theta \hat{a}_r + \sin \theta \hat{a}_\theta)$ (A/m²)

Find the current passing through 20 cm

a) A hemi spherical shell of radius ↑ with

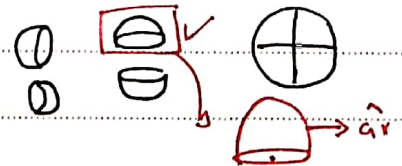
$$0 < \theta < \frac{\pi}{2}, \quad 0 < \phi < 2\pi$$

b) A spherical shell ^{hollow} of radius 10 cm

sol :- a) $I = \int_S \vec{J} \cdot d\vec{s}$, $d\vec{s} = r^2 \sin \theta \, d\theta \, d\phi \hat{a}_r$

$$\Rightarrow I = \int_0^{2\pi} \int_0^{\pi/2} \frac{1}{r} \sin 2\theta \, d\theta \, d\phi \Big|_{r=0.2 \text{ m}}$$

$$= 10\pi \text{ A} = 31.4 \text{ A}$$



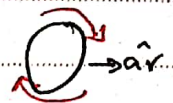
shell (hollow)

التي تسمى I ، كما ان القياس هو موجه

b.)

$$I = \int_0^{2\pi} \int_0^{\pi} \frac{1}{r} \sin 2\theta \, d\theta \, d\phi \Big|_{r=0.1 \text{ m}}$$

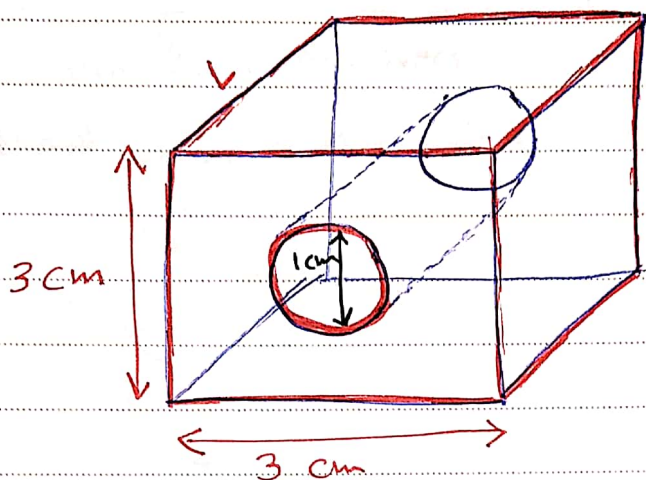
$$= 0 \text{ A}$$



جميع ال current

في الجزء العلوي + الجزء السفلي

Ex 1 - A lead $\sigma = 5 \times 10^6 \text{ S/m}$, $L = 4 \text{ m}$, Find R ?



Sol :- $R = \frac{L}{\sigma A}$, $A = (3 \times 10^{-2})^2 - \pi \left(\frac{1}{2} \times 10^{-2}\right)^2$

$\Rightarrow R = 974 \mu\Omega$

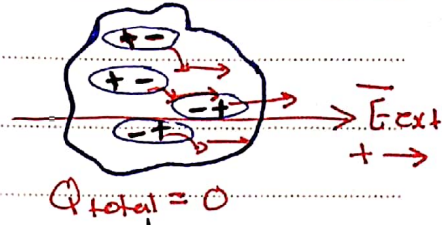
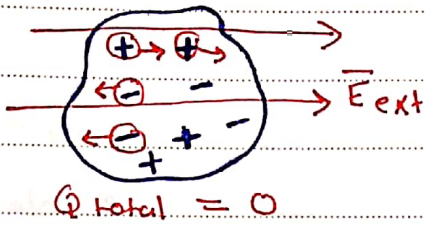
Polarization in Dielectrics

Non-Polar Dielectrics

Polar Dielectric

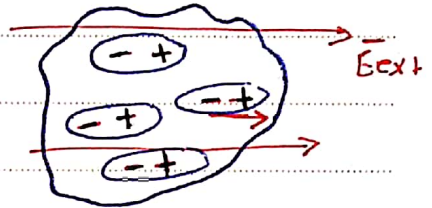
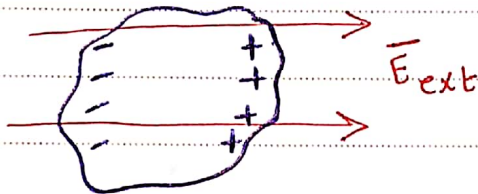
طبيعة $[E_{ext}]$ غير دائمة \Rightarrow dipoles غير دائمة

[permanent dipoles] dipole دائمة



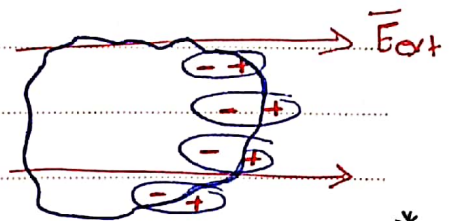
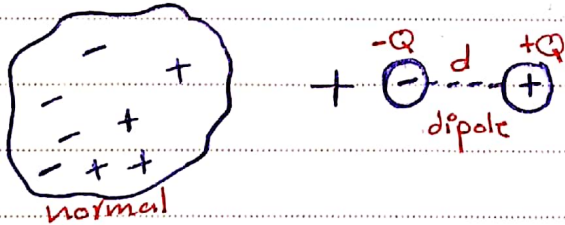
بغيره pressure وتغير مشوهة

بالطريقة السخنة بغير ارجاء إعادة ترتيب
كانت بغير اتجاه E (بدوافقة)



called Distorted charge distribution.

بعدما السخنة الموجبة يتحرك لتغير
ال E وتوصل للسطح الخارجي

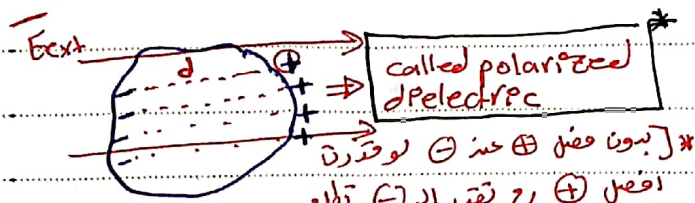


* كما ان E يتبع إعادة طبيعية ويتغير dipole

called polarized dielectric

لطاقه انوا السخنة الموجبة يتحرك تطلع
للسطح من السب يقل حوا المادة لانها خفيفة
وسب يقل في رايه بين \oplus و \ominus [dipole]

لوصار break down
لوصغ, وليس [في عوامل الـ
break down]



$\vec{P} \neq 0$

\vec{P} (polarized Dielectric)

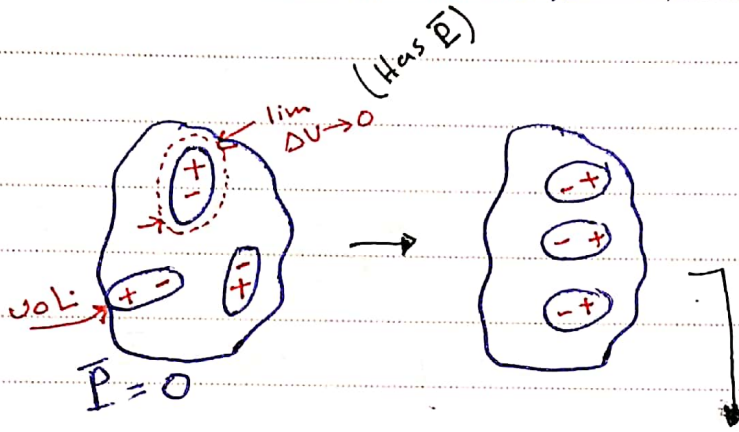
$\vec{P} \neq 0$

الكثافة المادية حارة قطبية [polarized] في سويج وولف الصل

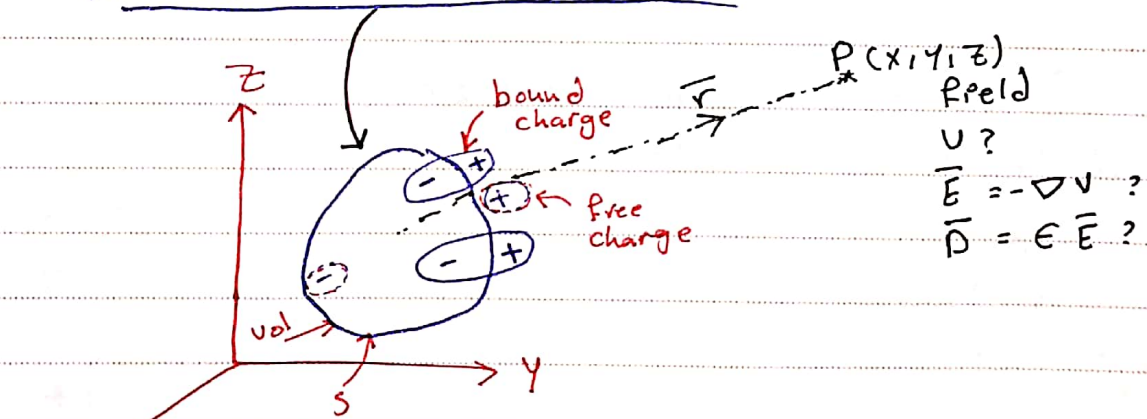
$$\vec{P} = \frac{1}{\Delta V \rightarrow 0} \sum_{k=1}^N \vec{P}_k$$

dipole moment (c.m.)
 m^3
 (C/m^2)

- * Non-polar: H_2, O_2, N_2 , rare gases (Kr, Xe, Ne)
- * Polar: (HCl, H_2O , NH_3)



* For a polarized Dielectric:



* Recall from CH4 (only for Free charges)

$$V = \int_S \frac{\rho_s ds}{4\pi\epsilon_0 r}, \quad V = \int_V \frac{\rho_v dv}{4\pi\epsilon_0 r}$$

\hookrightarrow For surface charge
 \hookrightarrow For volume charge

* For bound or Polarized charges :

$$V = \int_S \frac{\rho_{ps} ds}{4\pi\epsilon_0 r} \quad , \quad V = \int_V \frac{\rho_{pv} dv}{4\pi\epsilon_0 r}$$

↪ Field - location on the surface

ρ_{ps} :: Polarized (bound) surface charge density (C/m^2)
 ρ_{pv} :: " " " " Volume " " (C/m^3)

$$\vec{E} = \int_S \frac{\rho_s ds}{4\pi\epsilon_0 r^2} \hat{a}_r$$

$$\vec{E} = \int_V \frac{\rho_v dv}{4\pi\epsilon_0 r^2} \hat{a}_r$$

$$\vec{E} = \int_S \frac{\rho_{ps} ds}{4\pi\epsilon_0 r^2} \hat{a}_r$$

$$\vec{E} = \int_V \frac{\rho_{pv} dv}{4\pi\epsilon_0 r^2} \hat{a}_r$$

or $\vec{E} = -\nabla V$, $\vec{D} = \epsilon_0 \vec{E}$

For some dielectrics (linear) ::

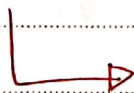
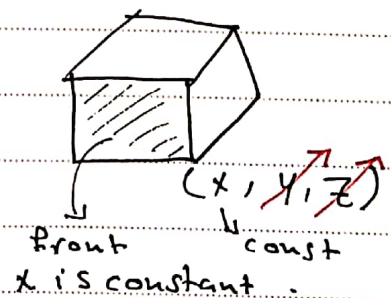
$$\vec{P} = \chi_e \epsilon_0 \vec{E} \quad , \quad \chi_e |_{\text{Apr cond.}} = 0$$

↪ Electrical susceptibility (constant for each material)

* $\rho_s = \vec{D} \cdot \hat{a}_n$

* $\vec{D} = \rho_s \hat{a}_n$

* $\rho_{ps} = \vec{P} \cdot \hat{a}_n$
 $\vec{P} = ?$



Electric Flux Density

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P} \rightarrow \text{only exists on Dielectrics}$$

$$\begin{array}{c} \vec{D} > \vec{D} \\ \text{dielectric} \quad \text{App} \\ \boxed{\epsilon_r > 1} \quad \text{cond.} \\ \quad \quad \quad \boxed{\epsilon_r = 1} \end{array}$$

$$\begin{aligned} \vec{D} &= \epsilon_0 \vec{E} + \chi_e \epsilon_0 \vec{E} \\ &= (1 + \chi_e) \epsilon_0 \vec{E} \\ &= \epsilon_r \epsilon_0 \vec{E} \end{aligned}$$

$$\Downarrow \vec{D} = \epsilon \vec{E}, \quad \epsilon = \epsilon_0 \epsilon_r$$

$\leftarrow \text{F/m} \quad \downarrow \text{F/m} \quad \rightarrow \text{unitless}$

ϵ_r : relative Permittivity

so \Rightarrow $\boxed{\vec{D} = \epsilon \vec{E}}$, $\boxed{\epsilon_r = \frac{\epsilon}{\epsilon_0}}$, $\boxed{\epsilon_r = 1 + \chi_e}$

$$\boxed{P_M = (\epsilon_r - 1) \epsilon_0 \vec{E}} \Rightarrow \text{دیا الکترونیکی } \chi_e$$

* Bound charge $\therefore Q_b$ in (C)

$$Q_{b+} = \int_s \rho_{ps} ds$$

$$Q_{b-} = \int_v \rho_{pv} dv$$

$$Q_b = Q_{b+} + Q_{b-} \left. \begin{array}{l} \text{if} \\ = 0 \\ \hookrightarrow \text{electrically Neutralized} \end{array} \right\}$$

* Dielectric Breakdown :-

→ Factors affects the dielectrics:

- 1] Nature of the material .
- 2] Temperature ($T \downarrow, \sigma \uparrow$)
- 3] Humidity ($H \uparrow, \sigma \uparrow$)
- 4] The applied E -field ($\rightarrow \uparrow, \sigma \uparrow$)
- 5] Time of the field is applied ($\rightarrow \uparrow, \sigma \uparrow$)

* Dielectric strength :- The maximum value of E -field the dielectrics can tolerate without being breaking down .

Ex :- A dielectric cube of length (L) centered at the origin has $\vec{p} = a\vec{r}$ where (a) is constant and $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$. Find all bound charge densities and the total charge if $\rho_{pv} = -3a \text{ C/m}^3$.

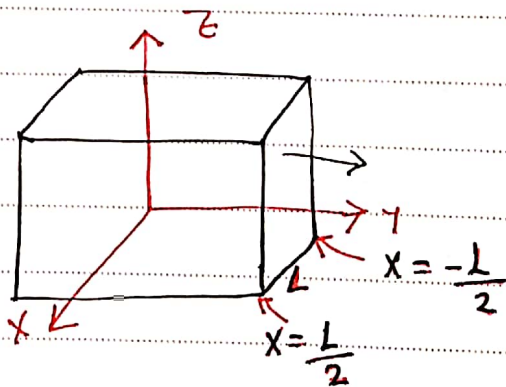
Sol :-

$$\rho_{ps} = \vec{P} \cdot \hat{n}$$

$$\rho_{ps} = \frac{dQ_{ps}}{dA}$$

$x = \frac{L}{2}$ $\rightarrow a \times a\hat{x} \cdot a\hat{x}$

$$= \frac{aL}{2} \text{ C/m}^2$$



$$\rho_{ps} = a \times a\hat{x} \cdot -a\hat{x} = \frac{aL}{2} \text{ C/m}^2$$

→ All surfaces have $\rho_{ps} = \frac{aL}{2} \text{ C/m}^2$

$$Q_{(total)} = Q_{b+} + Q_{b-}$$

$$Q_{b+} = \oint_S \rho_{ps} dS$$

$$\rightarrow = 6 \int_S \rho_{ps} dS, \text{ Area} = L^2 \text{ (integration)}$$

$$= 6a \frac{L}{2} L^2 = \underline{\underline{3aL^3 \text{ C}}}$$

→

$$Q_b = \int_V \rho_v dv$$

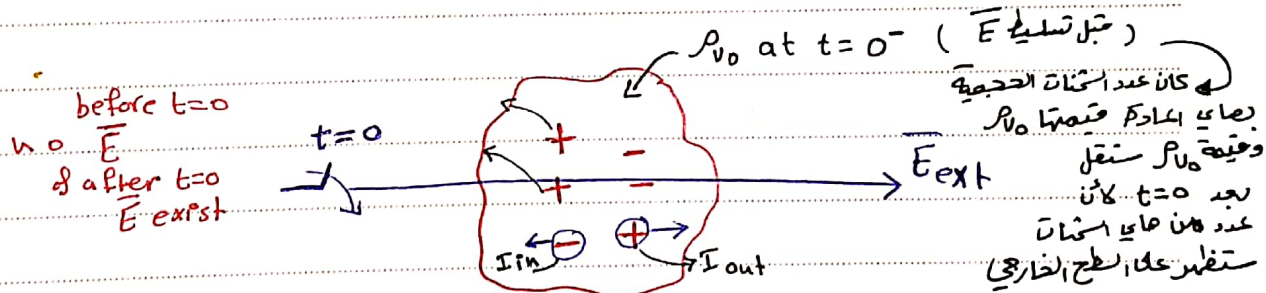
$$= -3a L^3 C$$

$\Rightarrow Q_{b \text{ total}} = 0$ # Neutralized

Continuity Equation

معادلة الاستمرارية

تحدث عند استمرارية حركة الشحنات داخل المادة والتيار المتكون عند حركة هذه الشحنات
 لجميع أنواع المواد [free space, good conductor, dielectric] جميعها
 تحتوي على شحنة موجبة أو سالبة متساوية $total \text{ charge} = 0$ وهذه الشحنات إما تكون
 حركة الحركة أو غير قادرة على الحركة بحرية بسبب تأثر الجوانب الخارجي أو أنها تتصوي على
 dipoles لجزيئية أو احتوت على dipoles بعين [المهم أيضا عادة معادلة كهربائية $Q_{total} = 0$]



الشحنة الموجبة بتطلع للسطح الخارجي وحركتها بتشكل I_{out}
 والشحنة السالبة ربتل داخل المادة وحركتها بتشكل I_{in}

$$\left. \begin{array}{l} t < t_0 \\ (t = 0^-) \end{array} \right\} \rho_v = \rho_{v0}$$

$$\left. \begin{array}{l} t = t_0^+ \\ (t = 0^+) \end{array} \right\} \rho_v < \rho_{v0}$$

KCL:

$I_{out} = I_{in}$ ← حركة التيار على السطح الخارجي ← حركة التيار داخل المادة

$$\oint_S \vec{J} \cdot d\vec{s} = - \frac{dq_{in}}{dt} = - \frac{d}{dt} \int_V \rho_v dv = - \int_V \frac{d\rho_v}{dt} dv$$

the charges inside the [volume are decreasing] تناقص $\Rightarrow \oint_S \vec{J} \cdot d\vec{s} = - \int_V \frac{d\rho_v}{dt} dv$

Continuity Equation in integral form.

الشحنات التي بتثبت جوا المادة هي الشحنة السالبة والموجبة طلعت للسطح

⇒ to calculate the **Relaxation time** from the continuity Equation :-

$$\oint_s \bar{J} \cdot \bar{ds} = - \int_v \frac{d\rho}{dt} dv = - \frac{dQ}{dt} = - \frac{d}{dt} \oint_s \bar{D} \cdot \bar{ds}$$

Q according to Gauss's law

$$\bar{J} = - \frac{d\bar{D}}{dt}$$

▷ in time varying fields (CH 9)

→ For relaxation time:-

$$Tr = \frac{\epsilon}{\sigma} = \frac{\epsilon_0 \epsilon_r}{\sigma}$$

comes from:- $\bar{J} = - \frac{d\bar{D}}{dt}$
 $\rightarrow \sigma \bar{E} = - \frac{d\epsilon \bar{E}}{dt}$

$$\rightarrow \int d \frac{\bar{E}}{E} = - \left(\frac{\sigma}{E} \right) dt$$

$$\rightarrow Tr = \frac{\epsilon}{\sigma}$$

ex! :- For copper $\epsilon_r = 1$, $\sigma = 5.8 \times 10^7 \text{ s/m}$

$$\rightarrow Tr = \frac{\epsilon}{\sigma} = \frac{\epsilon_0 \epsilon_r}{\sigma} = \frac{10^{-9}}{36\pi} \times 1 = 1.53 \times 10^{-19} \text{ S}$$

↳ within this time that means :-

after 1 Tr → 36.8% of charges will remain inside the material of 63.2% will go to the outer surface.

* if we take 5 time constant (5Tr)

↳ the percent inside the material will be less than 1% and more than 99% on the outer surface so the material will be a good conductor. (copper)

1 Tr

36.8%

↳ 63.2%

the lower level of a material to be conducting.

ex 2 ϵ_0 For Fused Quartz $\epsilon_r = 5$, $\sigma = 10^{-17}$ S/m

$$\rightarrow T_r = \frac{10^{-9} \times 5}{36\pi \times 10^{-17}} = \boxed{51.2 \text{ days}}$$

\rightarrow means ϵ_0 to have 63.2% of charges on the outer surface of a material (Fused Quartz) needs 51.2 days.

\rightarrow this material (Fused Quartz) is super dielectric material and most likely this material will be breaking down before this # of charges ~~appear~~ appear on the outer surface

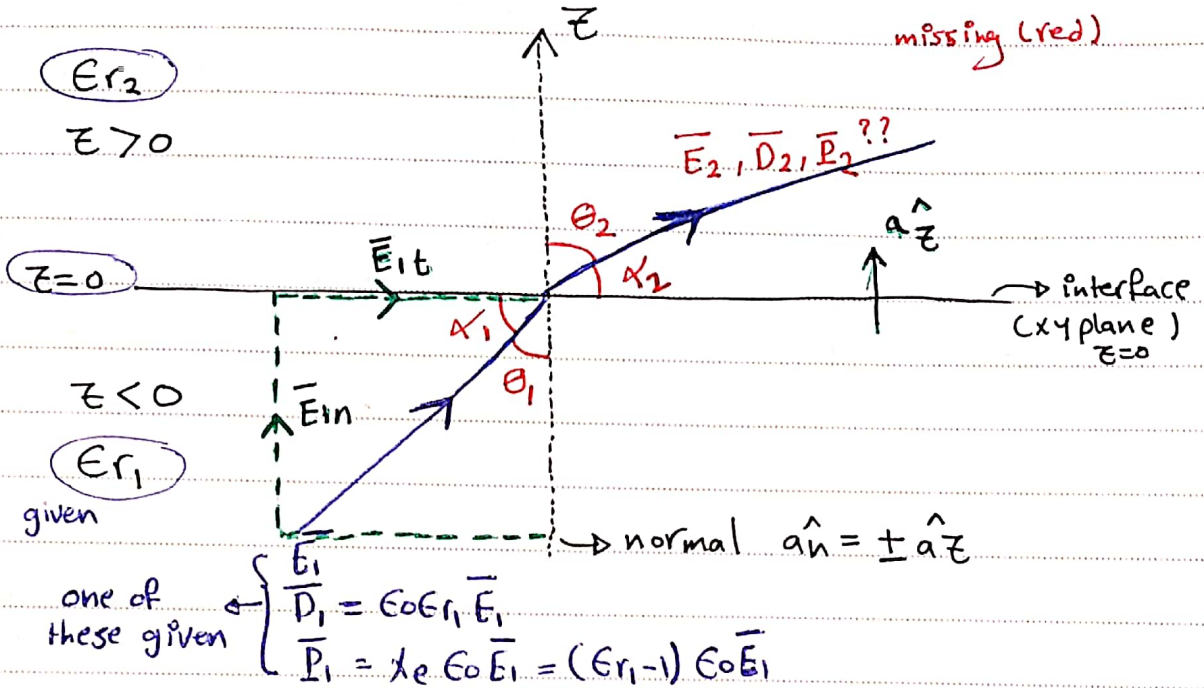
\Rightarrow so T_r (relaxation time) is important to know how the material is good conductor or good dielectric.

Boundary Conditions (B.C)

نظريه الحدود

شئ يسير لاد \vec{E} لما ينتقل من وسط لوسط مختلف بالخصائص

A) Dielectric - to - Dielectric



ϵ_1 & $\epsilon_2 > 1$ [so non of these material is free space]

Region 1 components \vec{E}_1 :-
 given

$\vec{E}_1 = \vec{E}_{in} + \vec{E}_{it}$

\vec{E}_1 normal parallel to normal \leftarrow \vec{E}_1 tangent parallel to surface.

$\hat{a}_n = \hat{a}_z$

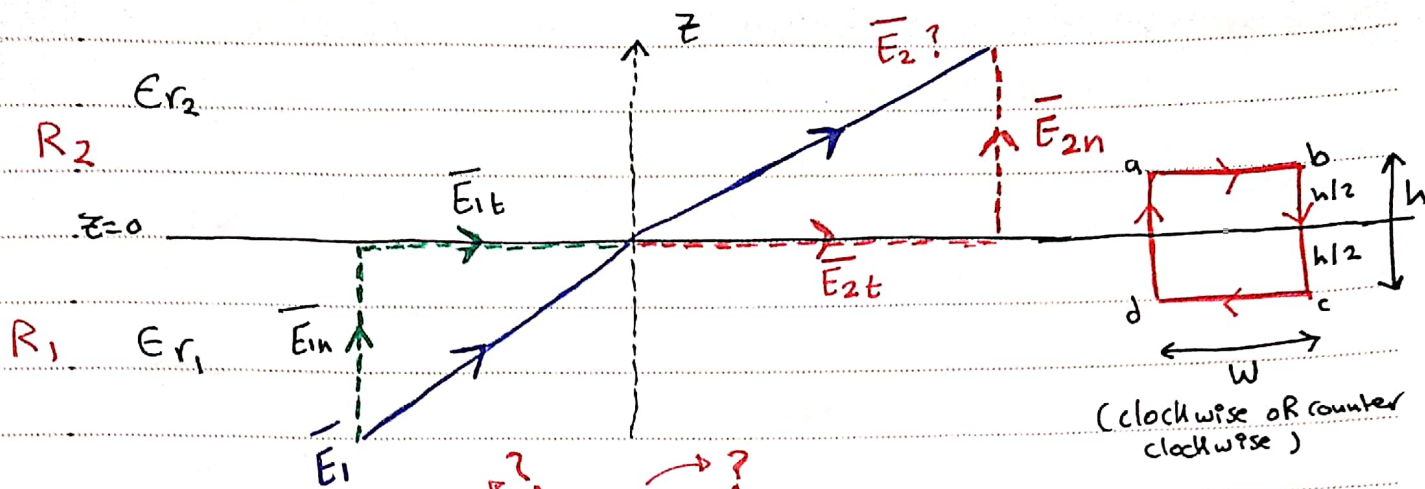
$\vec{E}_{in} = (\underbrace{\vec{E}_1 \cdot \hat{a}_n}_{\text{scalar}}) \hat{a}_n \rightarrow$ vector

$\vec{E}_{it} = \vec{E}_1 - \vec{E}_{in} \rightarrow \vec{E}_{it}$

$\theta_1 = \sin^{-1} \left(\frac{|\vec{E}_{it}|}{E_1} \right) = \cos^{-1} \left(\frac{E_{in}}{E_1} \right) = \tan^{-1} \left(\frac{E_{it}}{E_{in}} \right)$

$\alpha_1 = 90^\circ - \theta_1$

⇒ Region 2 \vec{E}_2 field :-



$$\vec{E}_2 = \vec{E}_{2n} + \vec{E}_{2t}$$

[1st & 2nd] Maxwell's eq. at $z=0$ (~~interface~~), this eq. applied on interface $z=0$.

first max well. eq. $\oint_S \vec{D} \cdot d\vec{s} = Q_{enc.} = \int_S \rho_s dS$

point / line / surface / volume

(since we need apply this eq. in 2D surface)

second max well. eq. $\oint_L \vec{E} \cdot d\vec{L} = 0$

↳ apply 2nd max well. eq. first [make closed path around

$$\oint_L \vec{E} \cdot d\vec{L} = \int_a^b \vec{E} \cdot d\vec{L}_1 + \int_b^c \vec{E} \cdot d\vec{L}_2 + \int_c^d \vec{E} \cdot d\vec{L}_3 + \int_d^a \vec{E} \cdot d\vec{L}_4 = 0$$

$$= E_{2t}W - E_{2n} \frac{h}{2} - E_{1n} \frac{h}{2} - E_{1t}W + E_{1n} \frac{h}{2} + E_{2n} \frac{h}{2} = 0$$

always $\vec{E}_{2t} = \vec{E}_{1t}$ → the tangential component of E-field must be continuous

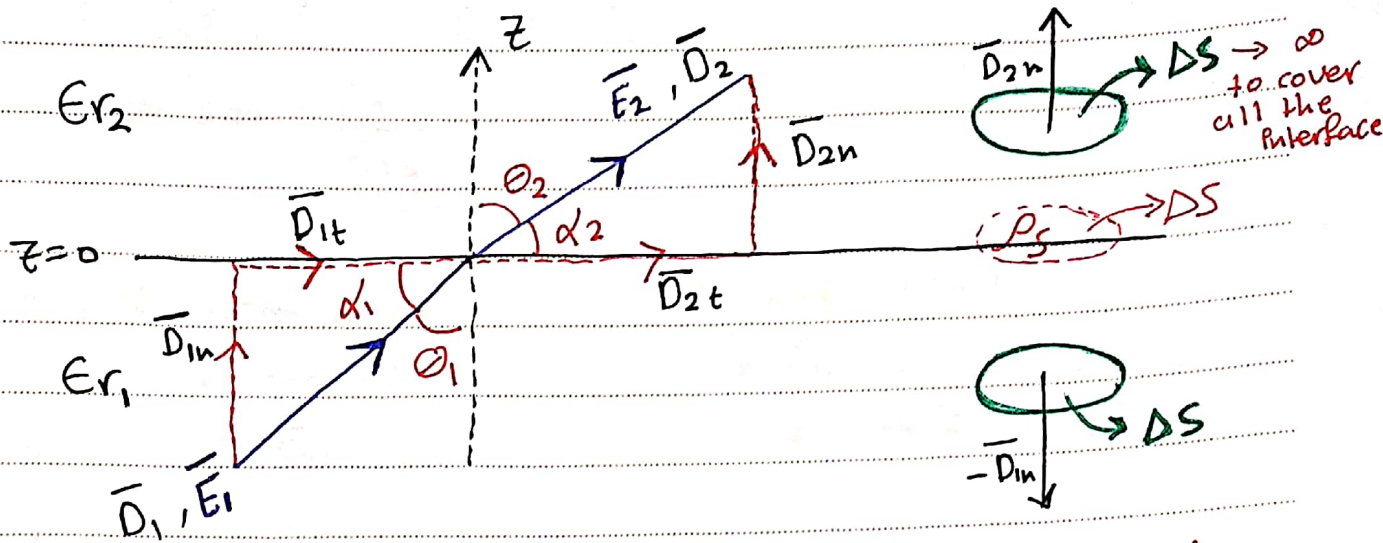
$z=0^+$ (above the interface) $z=0^-$ (below the interface)

[below and above the interface \vec{E} will not change but the change will be appeared in the normal component]

⇒ to find E_{2n} :

$$\oint_S \vec{D} \cdot d\vec{s} = \int_S \rho_s ds \quad] \text{ applied 1st maxwell eq. (Gauss's law)}$$

in interface $z=0$



2 Gaussian ~~is~~ surface should be located above and below the interface, because if there is a charge this charge should be radiated upward or downward the interface, why? this charge (ρ_s) should be located on the whole interface (infinite in x & y direction), we ~~don't~~ don't need the other side faces because all of these faces are located at ∞ .

$$\oint_S \vec{D} \cdot d\vec{s} = \int_S \rho_s ds$$

$$\int_{s_{top}} \vec{D} \cdot d\vec{s}_{top} + \int_{s_{bot}} \vec{D} \cdot d\vec{s}_{bot} = \int_S \rho_s ds$$

$$D_{2n} \Delta s - D_{1n} \Delta s = \rho_s \Delta s$$

$$\boxed{D_{2n} - D_{1n} = \rho_s} \rightarrow \text{if there is a charge at the surface.} \quad (\rho_s)$$

field in new region - field in the original region

$$D_{2n} - D_{1n}$$

(2 vectors - 1 vector is vector)

⇒ if $\rho_s = 0$

$$\boxed{\overline{D}_{2n} = \overline{D}_{1n}} \Rightarrow \text{if there is no charge on surface.}$$

$$\epsilon_0 \epsilon_{r2} \overline{E}_{2n} = \epsilon_0 \epsilon_{r1} \overline{E}_{1n}$$

$$\Rightarrow \boxed{\overline{E}_{2n} = \frac{\epsilon_{r1}}{\epsilon_{r2}} \overline{E}_{1n}}$$

if diff. region, diff. ϵ_r

only normal component of \overline{E}

will be diff. $\overline{E}_{2t} = \overline{E}_{1t}$

if same region $\epsilon_{r1} = \epsilon_{r2}$

$$\hookrightarrow \overline{E}_{2n} = \overline{E}_{1n} \text{ \& \ } \overline{E}_{2t} = \overline{E}_{1t}$$

↳ so the \overline{E} will be same

$$\hookrightarrow \text{so } \boxed{\overline{E}_2 = \overline{E}_{2n} + \overline{E}_{2t}}$$

$$\hookrightarrow \boxed{\overline{D}_2 = \epsilon_0 \epsilon_{r2} \overline{E}_2}$$

$$\boxed{\overline{P}_2 = (\epsilon_{r2} - 1) \epsilon_0 \overline{E}_2}$$

$$\boxed{\theta_2 = \sin^{-1} \left(\frac{E_{2t}}{E_2} \right)}, \quad \boxed{\alpha_2 = 90^\circ - \theta_2}$$

$$\hookrightarrow \text{OR } \overline{E}_{1t} = \overline{E}_{2t} \quad \text{from } \theta_2 = \sin^{-1} \left(\frac{E_{2t}}{E_2} \right)$$

$$E_1 \sin \theta_1 = E_2 \sin \theta_2 \quad \text{--- (1)}$$

if $\rho_s = 0$

$$D_{2n} - D_{1n} = 0 \rightarrow \overline{D}_{1n} = \overline{D}_{2n}$$

$$\epsilon_0 \epsilon_{r1} \overline{E}_{1n} = \epsilon_0 \epsilon_{r2} \overline{E}_{2n}$$

$$\epsilon_{r1} E_1 \cos \theta_1 = \epsilon_{r2} E_2 \cos \theta_2 \quad \text{--- (2)}$$

divide eq.(1) by eq.(2)

$$\frac{\tan \theta_1}{\epsilon_{r1}} = \frac{\tan \theta_2}{\epsilon_{r2}}$$

$$\boxed{\frac{\tan \theta_1}{\tan \theta_2} = \frac{\epsilon_{r1}}{\epsilon_{r2}}}$$

→ only if $\rho_s = 0$

→ we can find θ_2 directly without finding E_2 component (E_{2n} or E_{2t})

B) conductor - to - Dielectric

very large conductivity σ in this region ϵ_s perfect conductor.

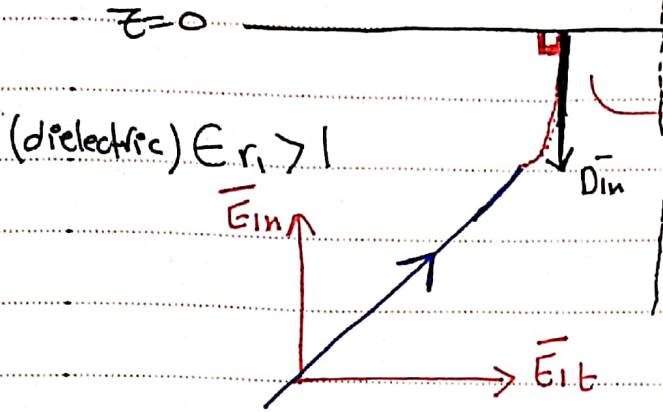
$\sigma_2 \approx \infty$
 (conductor) $\epsilon_{r2} = 1$

$\vec{E}_2 = 0 \rightarrow$ inside the conductor

$\hookrightarrow \vec{E}_{2t} = 0 \ \& \ \vec{E}_{2n} = 0$ [no field in region 2]

$\hookrightarrow \vec{D}_2 = 0$
 $\hookrightarrow \vec{D}_{2t} = 0 \ \& \ \vec{D}_{2n} = 0$

\hookrightarrow so ρ_2 / α_2 doesn't exist.



ما يقرب من interface only normal component appear but tangent component = 0.

$\vec{E}_{1t} = \vec{E}_{2t} \Rightarrow \boxed{\vec{E}_{1t} = 0}$ at interface $z = 0$
 (before reach interface \vec{E}_{1t} exist)

ρ_s has value $\neq 0$

$D_{2n} - D_{1n} = \rho_s$
 $D_{1n} = -\rho_s$

$\vec{D}_{1n} = \rho_s (-\hat{a}_n)$ $\vec{D}_{1n} \rightarrow$ ما يقرب من interface

$\boxed{\vec{E}_{1n} = -\frac{\rho_s \hat{a}_n}{\epsilon_0 \epsilon_{r1}}}$

يسقط بشكل عمودي وينفذ
 بشكل عمودي مؤلفاً
 بعد ما يرجع عادي

$\hookrightarrow \vec{E}_1$ has only normal component without any tangent component

$\boxed{\theta_1 = 0}$
 $\boxed{\alpha_1 = 90^\circ}$

\rightarrow if Region 1

ρ_s free space (conductor to free space)

$\hookrightarrow \epsilon_{r1} = 1$
 $\hookrightarrow \vec{E}_{1t} = 0$
 $\hookrightarrow \vec{E}_{1n} = -\frac{\rho_s \hat{a}_n}{\epsilon_0}$

Ex 5.9 in text book

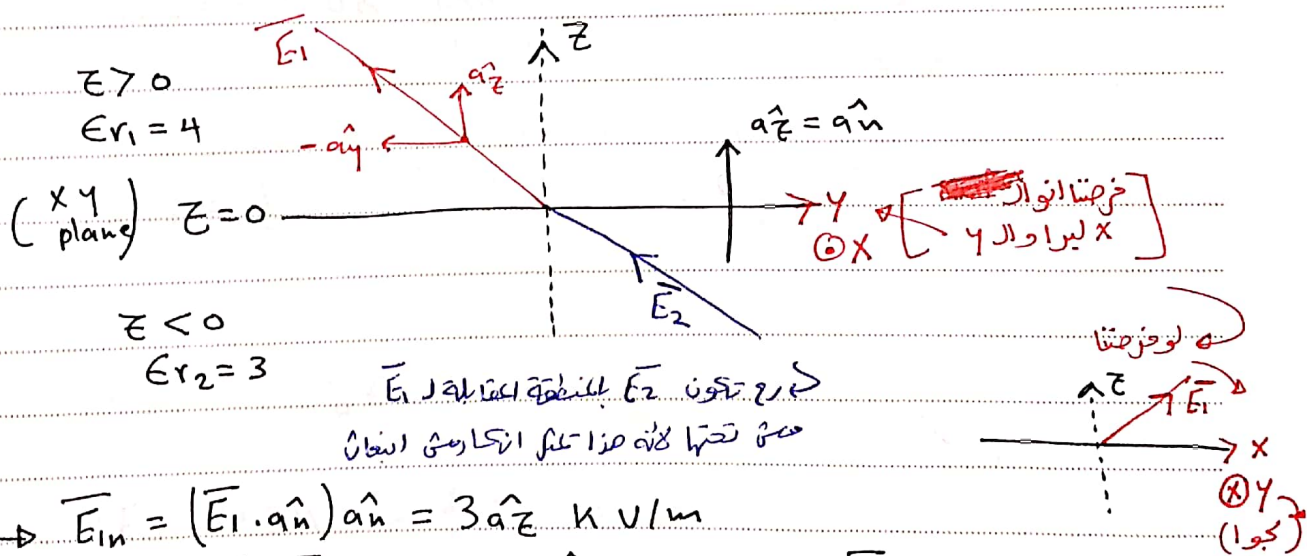
Two homogeneous isotropic dielectrics meet on plane $z=0$. for $z > 0$, $\epsilon_r = 4$ and for $z < 0$, $\epsilon_r = 3$. If $\vec{E}_1 = 5a_x\hat{x} - 2a_y\hat{y} + 3a_z\hat{z}$ K V/m exists for $z > 0$, find \vec{E}_2 for $z \leq 0$?

* homogeneous $\rightarrow \epsilon_r$ is constant for each point (anywhere) in Region.

* isotropic \rightarrow the permittivity is not change with direction
 $\hookrightarrow \epsilon$ is not functional direction.

Sometimes linear $\rightarrow \epsilon$ is not a function of electric field.

ans :- $a_n = a_z$ [\vec{E} field going from R_2 to R_1]



$\rightarrow \vec{E}_{in} = (\vec{E}_1 \cdot a_n) a_n = 3a_z$ K V/m

$\vec{E}_{it} = \vec{E}_1 - \vec{E}_{in} = 5a_x\hat{x} - 2a_y\hat{y}$ K V/m = \vec{E}_{2t}

$f_s = 0$, why? \square not mentioned in question

\square said dielectric (the charge inside dielectrics will need large relaxation time to reach the surface so between 2 dielectrics no charge in the interface).

$$D_{2n} - D_{1n} = \rho_s = 0$$

$$\hookrightarrow \bar{E}_{2n} = \frac{\epsilon_{r1}}{\epsilon_{r2}} \bar{E}_{1n} = \frac{4}{3} 3a\hat{z} = 4a\hat{z} \text{ K V/m}$$

$$\Rightarrow \bar{E}_2 = \bar{E}_{2n} + \bar{E}_{2t} = \boxed{5a\hat{x} - 2a\hat{y} + 4a\hat{z}} \text{ K V/m}$$

\hookrightarrow difference only in the normal component.

(b) The angles E_1 & E_2 makes with the interface?

$\hookrightarrow \alpha_1$ & α_2 ??

$$\hookrightarrow \theta_1 = \sin^{-1} \frac{E_{1t}}{E_1}$$

* (angles makes with the normal $\rightarrow \theta_1$ & θ_2)

$$= \sin^{-1} \left(\frac{\sqrt{29}}{\sqrt{38}} \right) = 60.9^\circ$$

$$\alpha_1 = 90^\circ - \theta_1 = \boxed{29.1^\circ}$$

$$\theta_2 = \dots? \text{ or } \frac{\tan \theta_1}{\tan \theta_2} = \frac{\epsilon_{r1}}{\epsilon_{r2}} = \frac{4}{3} \Rightarrow \theta_2 = 53.4^\circ$$

$$\Rightarrow \alpha_2 = \boxed{36.6^\circ}$$

(c) The energy densities in both dielectrics?

$$W_{E1} = \frac{1}{2} \epsilon_1 E_1^2 = \frac{1}{2} \epsilon_0 \epsilon_{r1} E_1^2 = \frac{1}{2} \frac{10^{-9}}{36\pi} (4) (\sqrt{38} \text{ K})^2 \rightarrow 38 \times 10^6 = 672 \mu\text{J/m}^3$$

$$W_{E2} = \frac{1}{2} \epsilon_0 \epsilon_{r2} E_2^2 = \frac{1}{2} \frac{10^{-9}}{36\pi} (3) (\sqrt{45} \text{ K})^2 \rightarrow 45 \times 10^6 = 597 \mu\text{J/m}^3$$

$$|E_2| = \sqrt{45} \text{ K V/m} \quad |E_1| = \sqrt{38} \text{ K V/m}$$

$$W_{E1} > W_{E2} \text{ since } \epsilon_{r1} > \epsilon_{r2}$$



(d) The energy within a cube of side 2m centered at $(3, 4, -5)$ → total energy (not energy density)

→ we need to know at what region the cube exists.

$$W_E = \int_V W_{E2} dV$$

$$= W_{E2} * V \quad \text{Volum.}$$

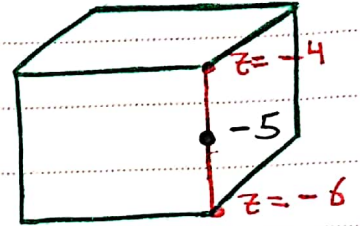
$$= 597 * 10^{-6} * 8$$

$$= 4.776 \text{ mJ}$$

$$R(1) \quad z > 0$$

$$z = 0$$

$$R(2) \quad z < 0$$



so cube in Region 2

pf the cube is centered at the origin

$$\rightarrow W_E = \underbrace{W_{E1} * 4}_{\text{half cube in } R_1} + \underbrace{W_{E2} * 4}_{\text{half cube in } R_2}$$