



Electromagnetics I

NoteBook

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بِالْفَكَارَةِ - نُجُعٌ

1st Exam Material

Ex. Use Dimensional Analysis (DA) to show that

$$d = ut + \frac{1}{2}at^2 \text{ is wrong.}$$

Note: all the quantities should be of the same dimension.

e.g. distance = distance + distance

Sol.

$$[d] = L$$

$$[ut] = \frac{L}{T} T = L$$

$$[\cancel{\frac{1}{2}}at] = \frac{L}{T^2} T = \frac{L}{T} \rightarrow \text{Wrong (should be } L\text{)}$$

dimension less

∴ the given equation is wrong. !!

The first wrong equation: $[\frac{1}{2}at^2] = \frac{L}{T^2} T^2 = L$

+ but if it was $[\cancel{2}at^2] = \frac{L}{T^2} T^2 = L$ (Wrong but we can't know that)

Ex (next page)

Examples from observation

$$T_p \propto l g$$

$$[T_p] = [K l g]$$

K is dimensionless

$$T = L^n \left(\frac{L}{T^2} \right)^d = L^{n+d} T^{-2d}$$

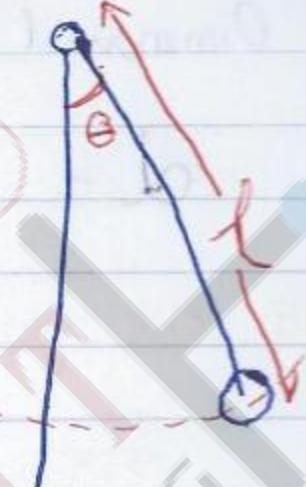
Thus:

$$n+d=0 \Rightarrow n=-d$$

$$-2d=1 \Rightarrow d=-\frac{1}{2} \Rightarrow n=\frac{1}{2}$$

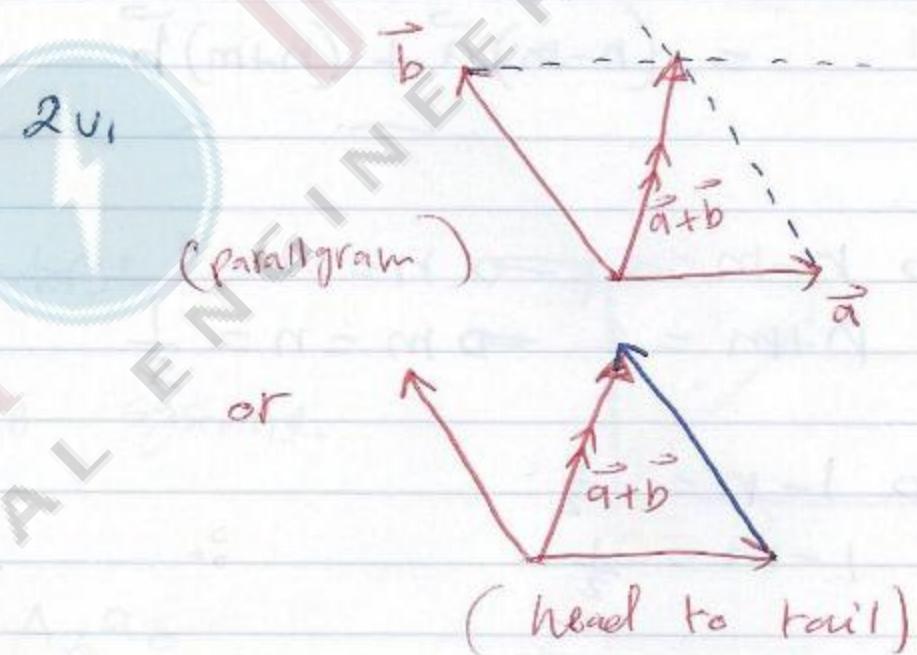
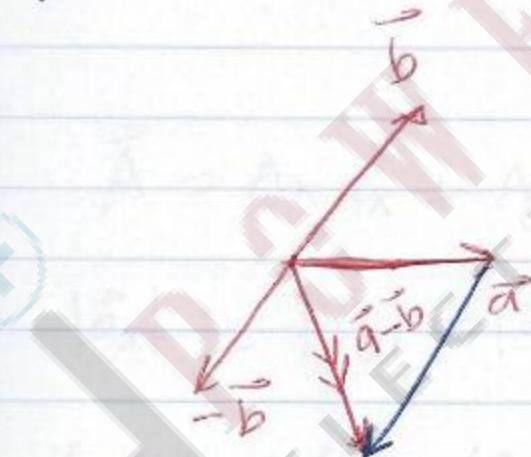
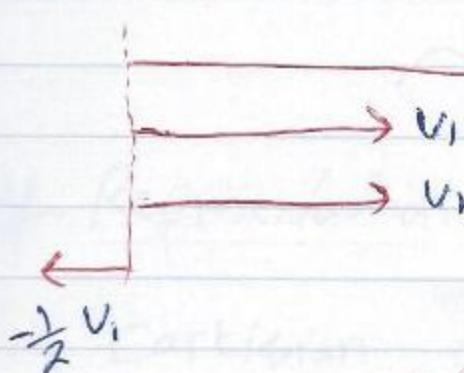
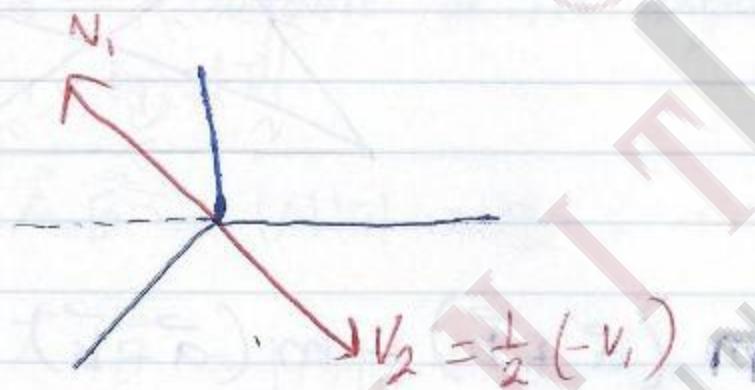
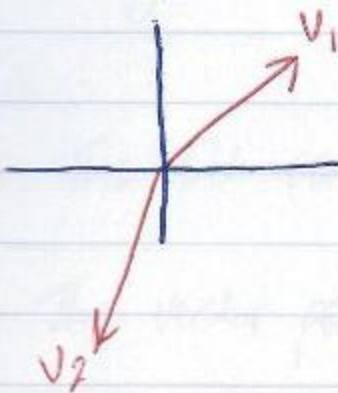
$$T_p = K l^{\frac{1}{2}} g^{\frac{-1}{2}} = K \sqrt{\frac{l}{g}}$$

* DA doesn't help in determining K .



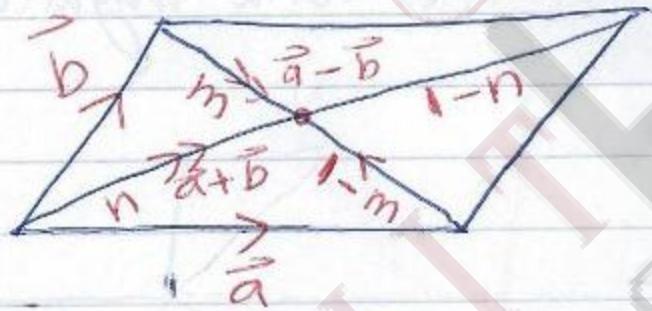
Vectors:

Quantities with magnitude and direction.



$$\vec{a} - \vec{b} = \vec{a} + (-\vec{b})$$

Examples



Sol. $\vec{b} = m(\vec{a} + \vec{b}) - m(\vec{a} - \vec{b})$
 $= (m-m)\vec{a} + (m+m)\vec{b}$

$\Rightarrow m-m=0 \Rightarrow m=m$

$m+m=1 \Rightarrow m=n=\frac{1}{2}$

$\Rightarrow 1-n=\frac{1}{2}$

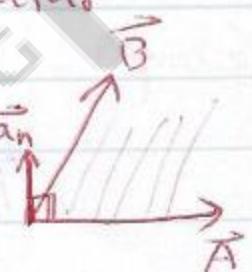
$1-m=\frac{1}{2}$

* Operations on Vectors:

① Magnitude of a vector: A measure of its length, denoted by $|\vec{v}|$

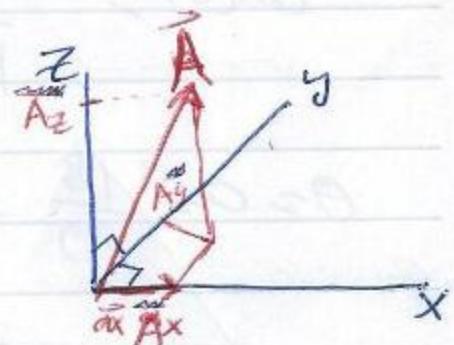
② The Dot product: $\vec{A} \cdot \vec{B} = |A||B| \cos \theta_{AB}$; a scalar

③ The vector product: $\vec{A} \times \vec{B} = |A||B| \sin \theta_{AB} \hat{a}_n$



* Representation of Vectors:

① Cartesian Coordinate Systems.



$$\vec{A} = A_x \vec{a}_x + A_y \vec{a}_y + A_z \vec{a}_z$$

$$|\vec{a}_x| = |\vec{a}_y| = |\vec{a}_z| = 1$$

* if two vectors are orthogonal (perpendicular to each other), then:

$$\vec{A} \cdot \vec{B} = |A||B| \cos 90^\circ = 0$$

* Using the fact that $\vec{a}_x, \vec{a}_y, \vec{a}_z$ are mutually orthogonal, then:

$$a_x \cdot a_y = a_y \cdot a_z = a_z \cdot a_x = 0$$

Based on this; $\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$

$$*\vec{A} \times \vec{B} = \begin{vmatrix} a_x & a_y & a_z \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix} = (A_y B_z - A_z B_y) \vec{a}_x + (A_z B_x - A_x B_z) \vec{a}_y + (A_x B_y - A_y B_x) \vec{a}_z$$

Example $\vec{A} = 2a_x - 3a_y + 4a_z$

$$\vec{B} = 5a_x + 2a_z$$

so,

$$\cos(\theta) = \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|} = \frac{10 + 0 + 8}{\sqrt{29} \sqrt{29}} = \frac{18}{29}$$

$$\theta = \cos^{-1} \frac{18}{29} =$$

$$\vec{a}_A = \frac{\vec{A}}{|\vec{A}|} = \frac{2}{\sqrt{29}} a_x - \frac{3}{\sqrt{29}} a_y + \frac{4}{\sqrt{29}} a_z$$

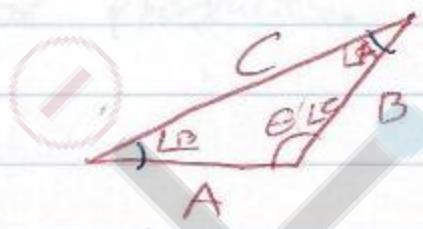
$$\frac{\vec{A}}{|\vec{A}|}$$

Ex. Determine the unit vector normal (orthogonal) to \vec{A} & \vec{B}

ex. For the following triangle with lengths A, B and C . prove:

i) $C^2 = a^2 + b^2 - 2AB \cos\theta$

ii) $\frac{A}{\sin A} = \frac{B}{\sin B} = \frac{C}{\sin C}$



* Properties of the scalar and vector products:

* $\vec{A} \cdot \vec{B} = \vec{B} \cdot \vec{A}$ Commutative.

* $\vec{A} \cdot (\vec{B} + \vec{C}) = \vec{A} \cdot \vec{B} + \vec{A} \cdot \vec{C}$ distributive

* $\vec{A} \cdot \vec{A} = |\vec{A}|^2$

* $\vec{A} \cdot \vec{B} = 0$ if $\theta = 90^\circ$

* $\vec{A} \times \vec{B} \neq \vec{B} \times \vec{A}$

* $\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$

* $\vec{A} \times (\vec{B} + \vec{C}) = \vec{A} \times \vec{B} + \vec{A} \times \vec{C}$

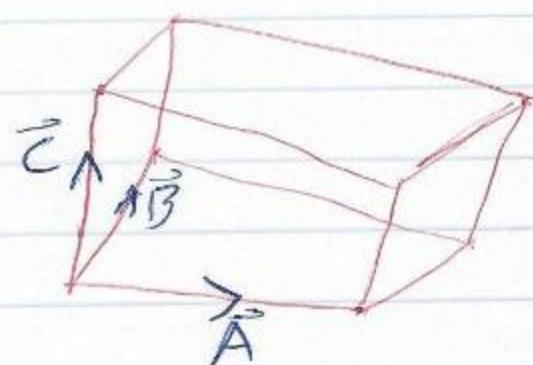
* $\vec{A} \times \vec{A} = 0$ if $\theta = 0^\circ$

* $\vec{A} \cdot (\vec{B} \times \vec{C}) = \vec{C} \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot (\vec{C} \times \vec{A})$ Scalar triple product

→ it gives the volume of the parallelopiped generated by $\vec{A}, \vec{B}, \vec{C}$.

* Calculated as:

$$\begin{vmatrix} A_x & A_y & A_z \\ B_x & B_y & B_z \\ C_x & C_y & C_z \end{vmatrix}$$



bac - cab

$$\# \vec{A} \times (\vec{B} \times \vec{C}) = \vec{B}(\vec{A} \cdot \vec{C}) - \vec{C}(\vec{A} \cdot \vec{B})$$

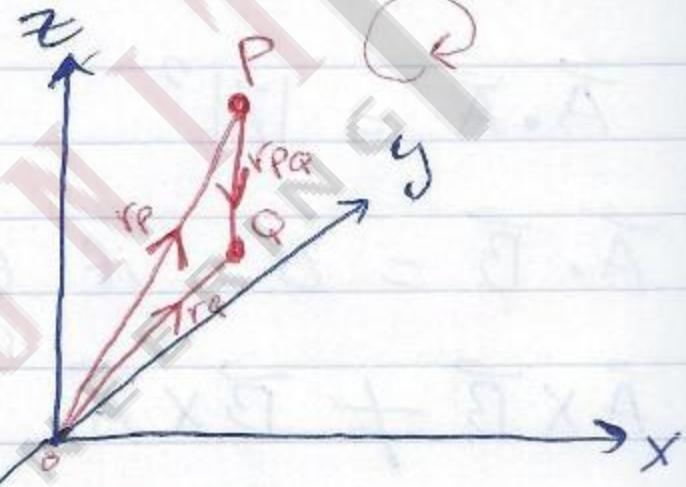
"Vector Triple Product"

The Position Vector:

$$\vec{r}_P = x_p \vec{a}_x + y_p \vec{a}_y + z_p \vec{a}_z$$

$$\vec{r}_Q = x_Q \vec{a}_x + y_Q \vec{a}_y + z_Q \vec{a}_z$$

$$\vec{r}_{PQ} = \vec{r}_Q - \vec{r}_P \quad \begin{matrix} \text{(distance vector)} \\ \text{or} \\ \text{(displacement vector)} \end{matrix}$$



from loop P:

$$\vec{r}_P + \vec{r}_{PQ} - \vec{r}_Q = 0$$

$$\vec{r}_{PQ} = \vec{r}_Q - \vec{r}_P$$

ex.



$$a + b + c + d - e + f + g = 0$$

#Ch.2

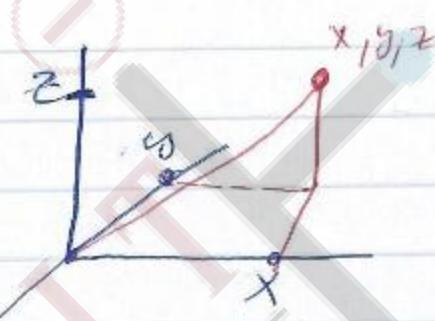
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* Coordinate Systems:

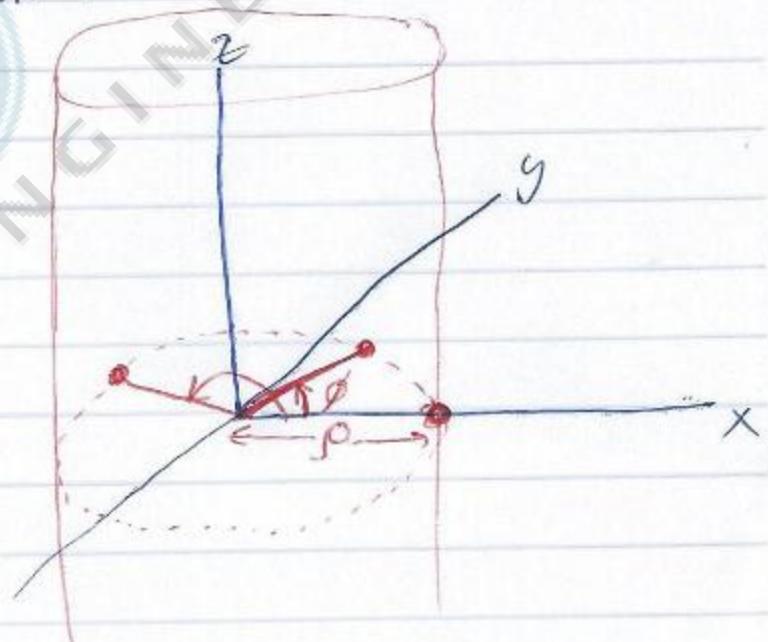
* cartesian Coordinate system.

$$\vec{r}_p = x \hat{a}_x + y \hat{a}_y + z \hat{a}_z$$

$$|r_p| = \sqrt{x^2 + y^2 + z^2}$$



* Circular Cylindrical system:



$$x = \rho \cos \phi$$

$$y = \rho \sin \phi$$

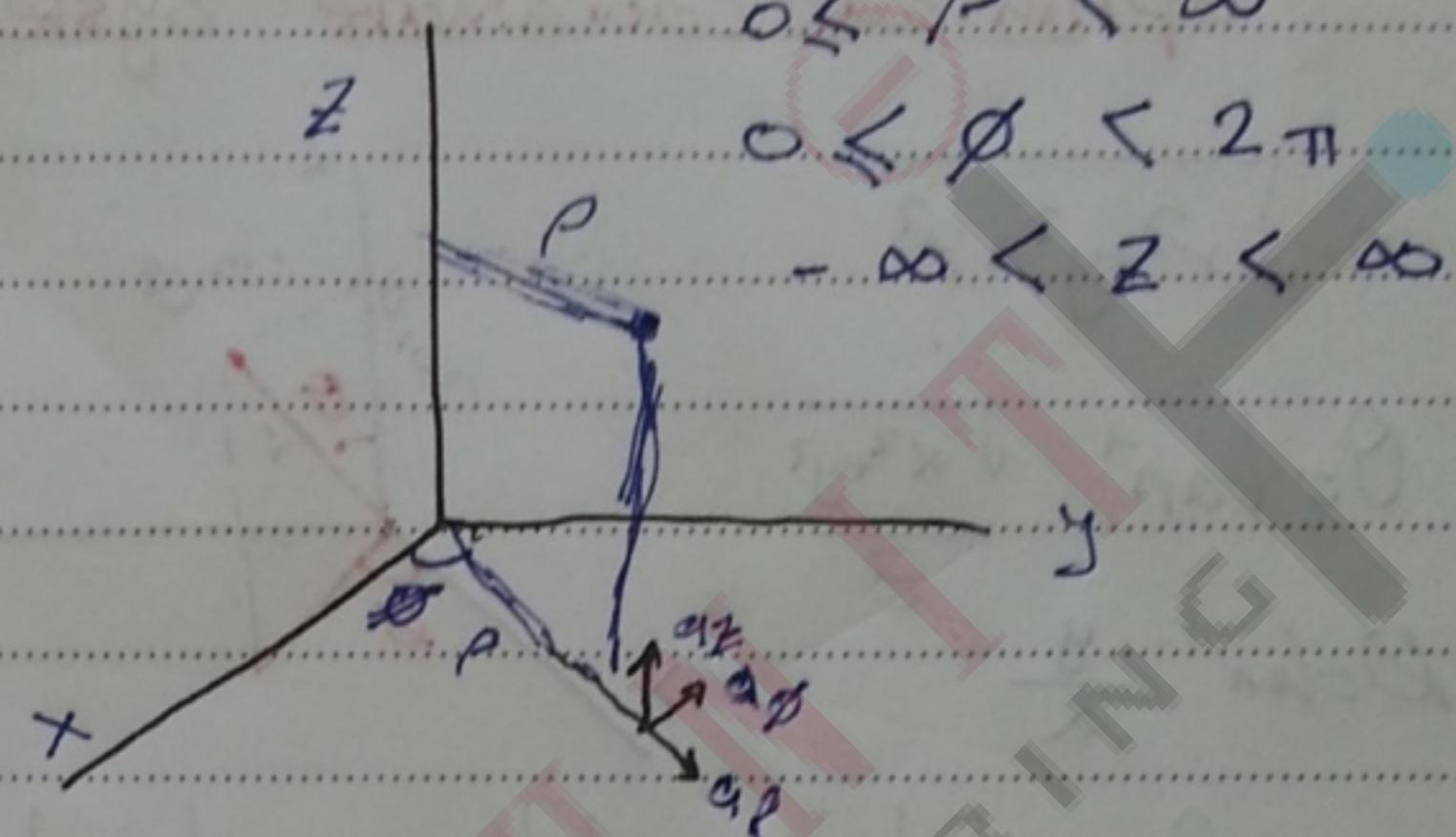
$$z = z$$

OR

$$\rho = \sqrt{x^2 + y^2}$$

$$\phi = \tan^{-1} \frac{y}{x}$$

$$z = z$$



$$\vec{A} = A_\rho \hat{a}_\rho + A_\phi \hat{a}_\phi + A_z \hat{a}_z$$

$$|\vec{A}| = [A_\rho^2 + A_\phi^2 + A_z^2]^{1/2}$$

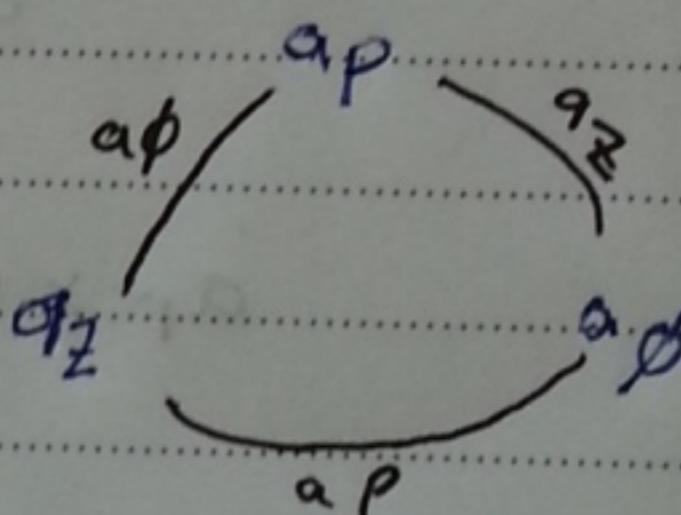
$$\hat{a}_\rho \cdot \hat{a}_\rho = \hat{a}_\phi \cdot \hat{a}_\phi = \hat{a}_z \cdot \hat{a}_z = 1$$

$$\hat{a}_\rho \cdot \hat{a}_\phi = \hat{a}_\rho \cdot \hat{a}_z = 0$$

$$\hat{a}_\rho \times \hat{a}_\phi = \hat{a}_z$$

$$\hat{a}_\phi \times \hat{a}_z = \hat{a}_\rho$$

$$\hat{a}_z \times \hat{a}_\rho = \hat{a}_\phi$$



act 9

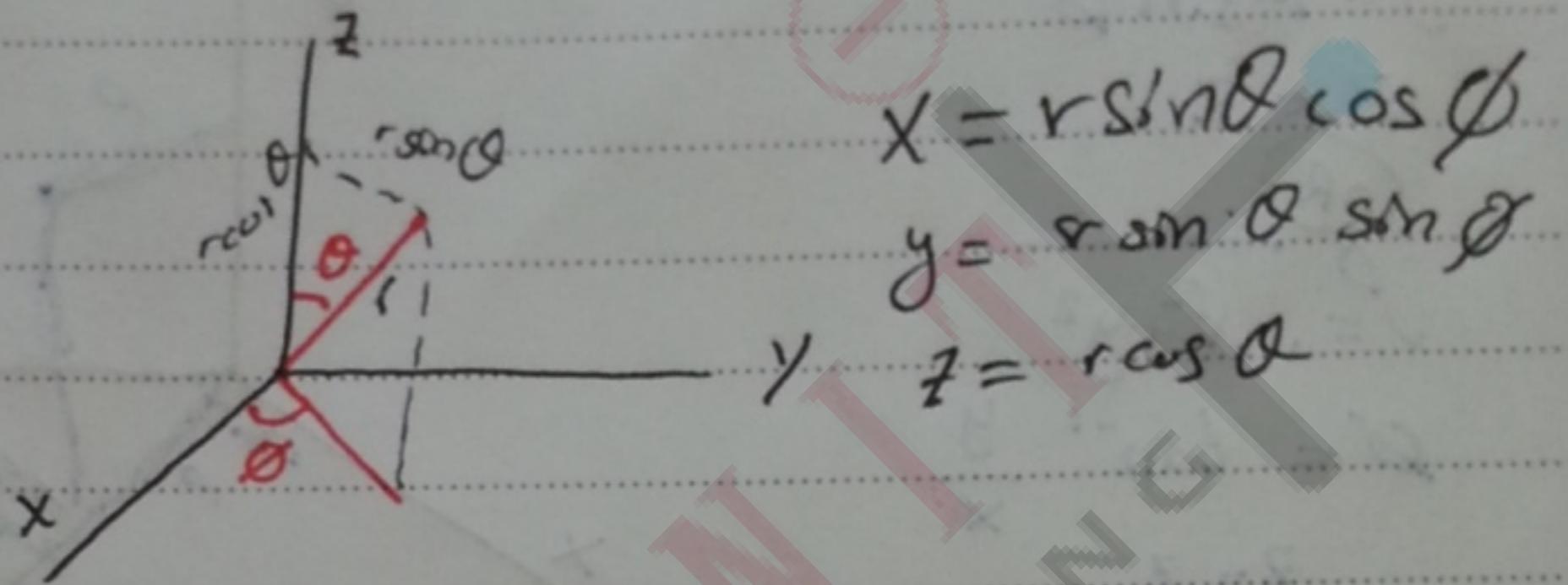
No. continued

Spherical coordinate system:

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\theta = \tan^{-1} \frac{\sqrt{x^2 + y^2}}{z}$$

$$\phi = \tan^{-1} \frac{y}{x}$$



A point is determined by a distance r .
and two angles θ, ϕ .

$$0 \leq r < \infty$$

$$0 \leq \theta \leq \pi$$

$$0 \leq \phi < 2\pi$$

$$\vec{A} = A_r \vec{a}_r + A_\theta \vec{a}_\theta + A_\phi \vec{a}_\phi$$

$$= (A_r, A_\theta, A_\phi)$$

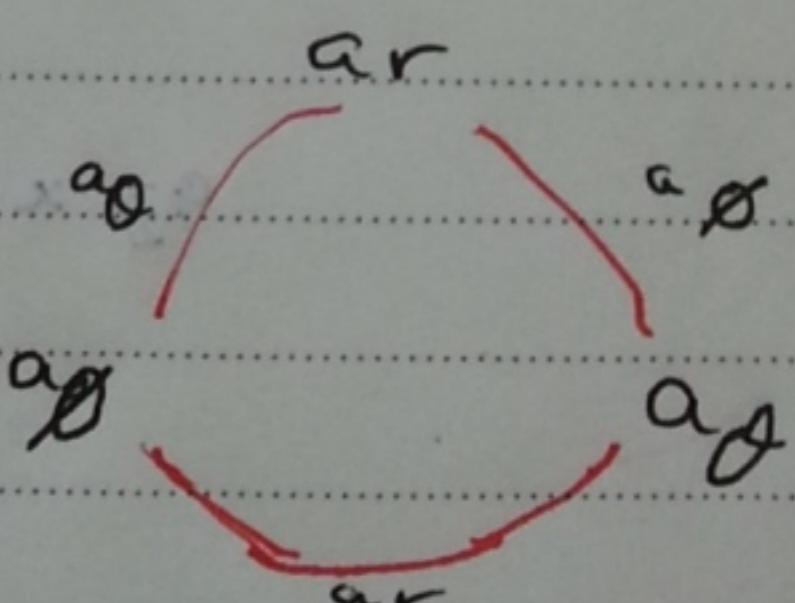
$$\vec{a}_r \cdot \vec{a}_r = \vec{a}_\theta \cdot \vec{a}_\theta = \vec{a}_\phi \cdot \vec{a}_\phi = 1$$

$$\vec{a}_r \cdot \vec{a}_\theta = \vec{a}_r \cdot \vec{a}_\phi = 0$$

$$\vec{a}_r \times \vec{a}_\theta = \vec{a}_\phi$$

$$\vec{a}_\theta \times \vec{a}_\phi = \vec{a}_r$$

$$\vec{a}_\phi \times \vec{a}_r = \vec{a}_\theta$$



Coordinate Transformation:

$$a_x = \cos\phi a_p + \sin\phi (-a_\phi)$$

$$a_x = a_p \cos\phi - a_\phi \sin\phi$$

Similarly:

$$a_y = \sin\phi a_p + \cos\phi a_\phi$$

In matrix form:

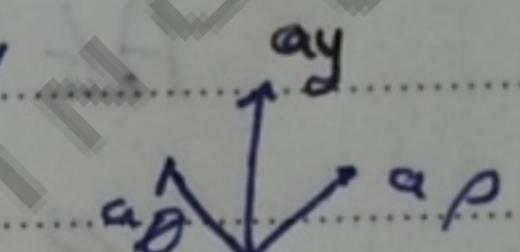
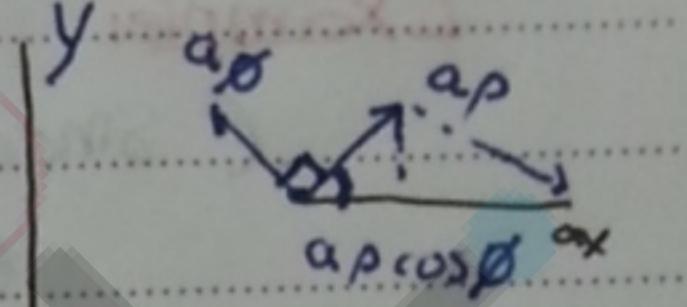
$$\begin{bmatrix} a_x \\ a_y \end{bmatrix} = \underbrace{\begin{bmatrix} \cos\phi & -\sin\phi \\ \sin\phi & \cos\phi \end{bmatrix}}_Q \begin{bmatrix} a_p \\ a_\phi \end{bmatrix} \xrightarrow{-j\phi}$$

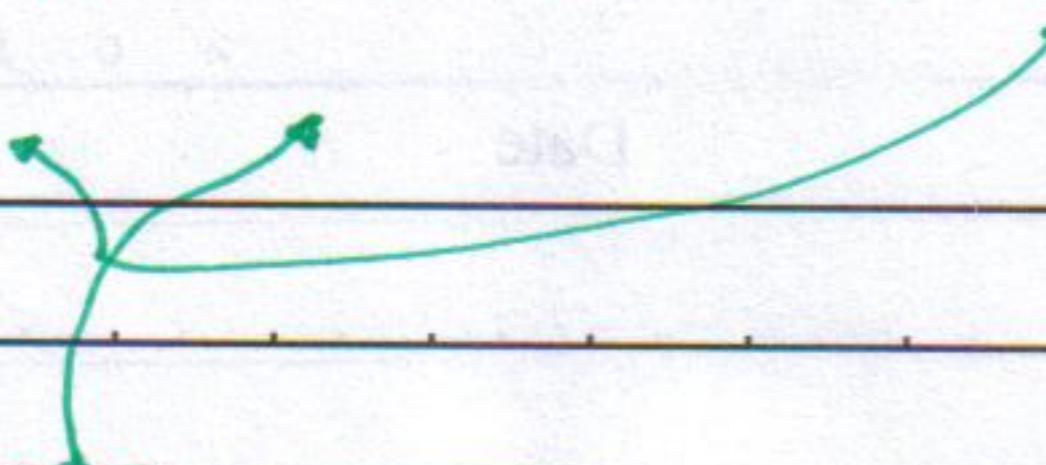
Where $Q Q^T = I_n$ i.e. Q is orthogonal matrix.

$$\Rightarrow Q^{-1} = Q^T$$

$$\begin{bmatrix} a_p \\ a_\phi \end{bmatrix} = Q^{-1} \begin{bmatrix} a_x \\ a_y \end{bmatrix} = \begin{bmatrix} \cos\phi & \sin\phi \\ -\sin\phi & \cos\phi \end{bmatrix} \begin{bmatrix} a_x \\ a_y \end{bmatrix}$$

$$\therefore Q Q^T = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$





Ex) $P(-2, 6, 3)$ and Vector $\vec{A} = yax + (x+z)ay$

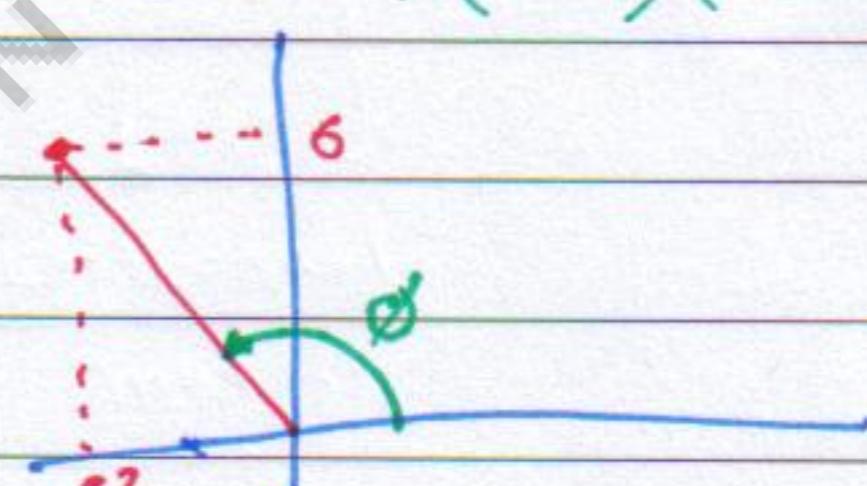
So:-

$$\vec{A} \text{ at } P \Rightarrow x = -2, y = 6, z = 3$$

*1 Convert to cylindrical:

$$\rho = \sqrt{x^2 + y^2} = \sqrt{(-2)^2 + 6^2} = 6.32$$

$$\phi = \tan^{-1}\left(\frac{y}{x}\right) = \tan^{-1}\left(\frac{6}{-2}\right) = 108.34^\circ$$



*2 Convert to spherical:

$$r = \sqrt{x^2 + y^2 + z^2} = \sqrt{\rho^2 + z^2} = 7$$

$$\theta = \tan^{-1}\left(\frac{\sqrt{x^2 + y^2}}{z}\right) = 64.62^\circ$$

$$\phi_s = \phi_c = 108.43^\circ$$

No. continued

P is $(-2, 6, 3)$

or $(6.32, 108.43^\circ, 3)$

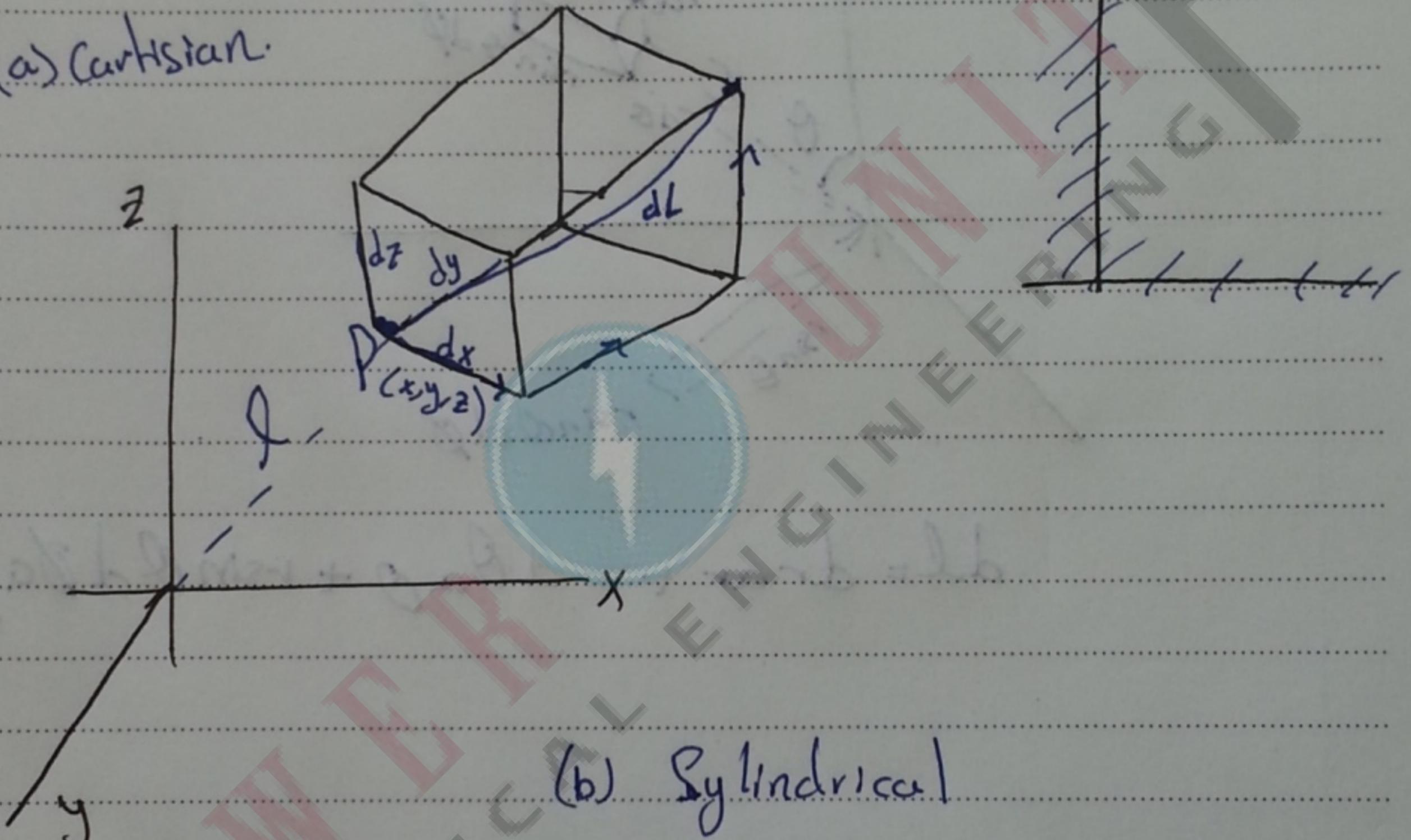
or $(7,$

Vector calculus:

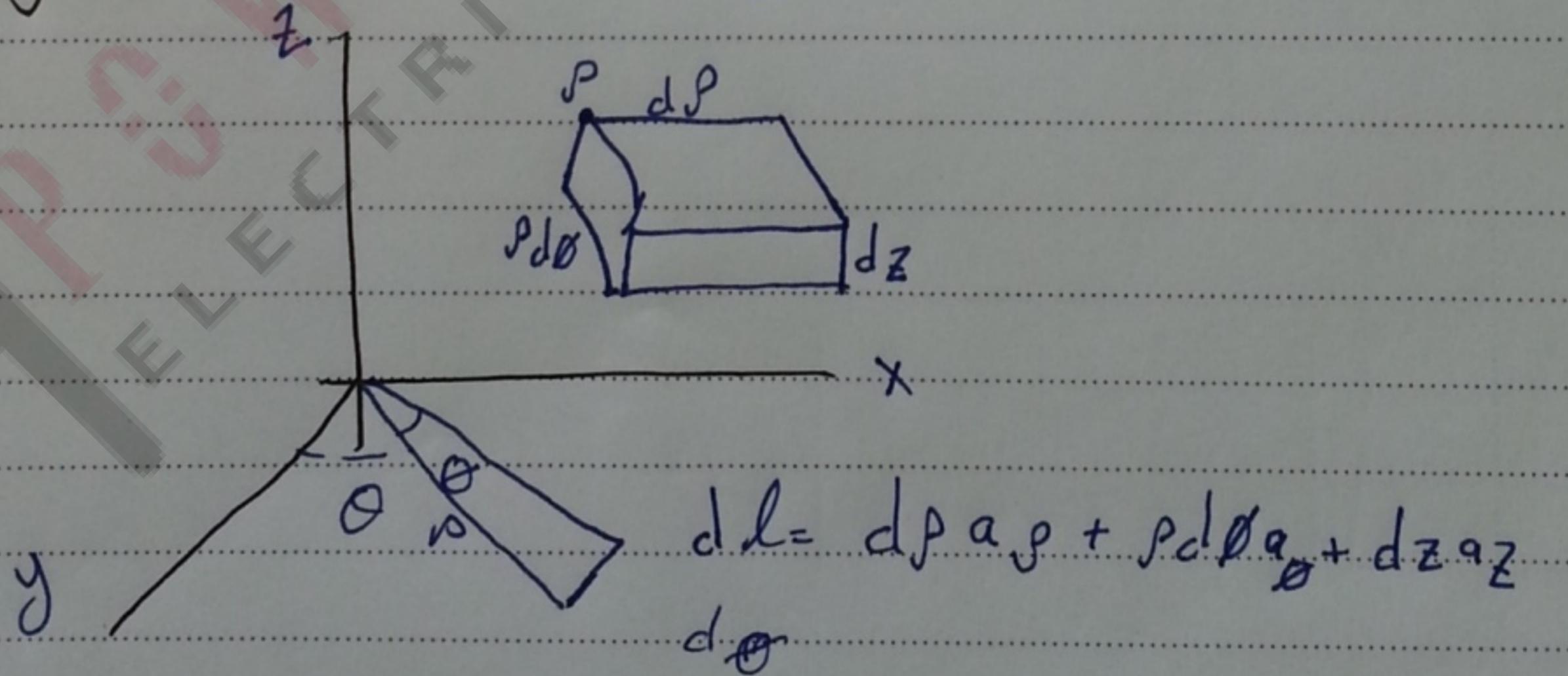
(a) Differential line (length):

$$dL = dx \alpha_x + dy \alpha_y + dz \alpha_z$$

(a) Cartesian:

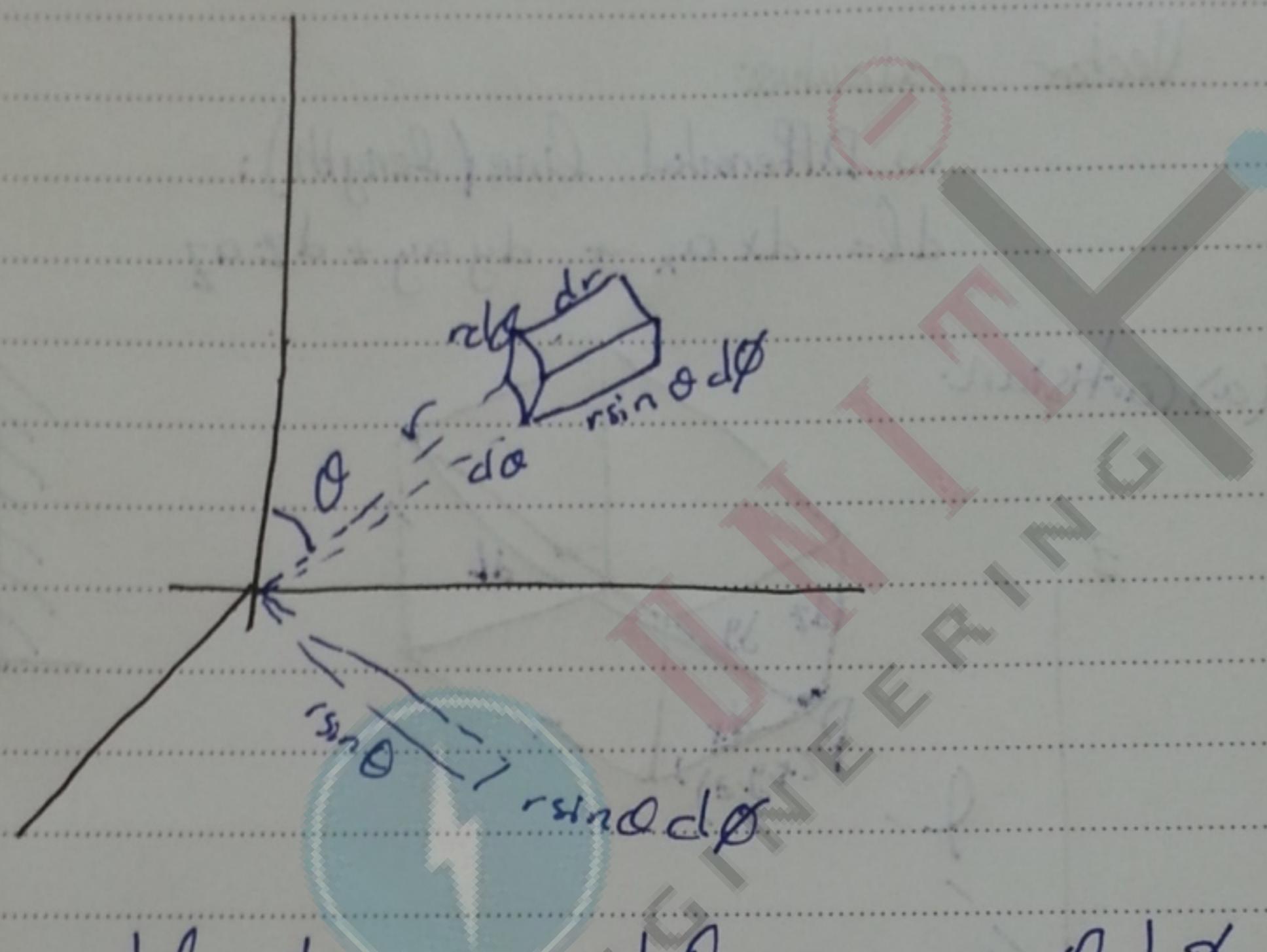


(b) Spherical



$$dL = d\rho \alpha_\rho + \rho d\theta \alpha_\theta + d\phi \alpha_\phi$$

No. continued



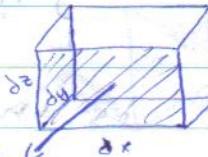
$$dL = dr \sin \theta + r d\theta \sin \theta + r \sin \theta d\theta \cos \theta$$

[2] differential area isogenfri svit

* defined as a vector quantity $\vec{d}s = \vec{s} \cdot \vec{a}_n$
where \vec{a}_n is the normal to the area.

* consider the differential lines' equations:

$$\text{Cartesian } \left\{ \begin{array}{l} ds_1 = dy \partial z \vec{a}_x \\ ds_2 = dx \partial z \vec{a}_y \\ ds_3 = dx \partial y \vec{a}_z \end{array} \right.$$



$$\text{Cylindrical } \left\{ \begin{array}{l} ds_1 = p \partial \phi \partial z \vec{a}_p \\ ds_2 = \partial p \partial z \vec{a}_\phi \\ ds_3 = p \partial p \partial \phi \vec{a}_z \end{array} \right.$$

$$\text{Spherical } \left\{ \begin{array}{l} ds_1 = r^2 \sin\theta \partial \phi \partial \theta \vec{a}_r \\ ds_2 = r dr \sin\theta \partial \phi \vec{a}_\theta \\ ds_3 = r dr \partial \theta \vec{a}_\phi \end{array} \right.$$

[3] differential volume

* it is a scalar

$$dV_L = dx \partial y \partial z$$

$$dV_C = p \partial p \partial \phi \partial z$$

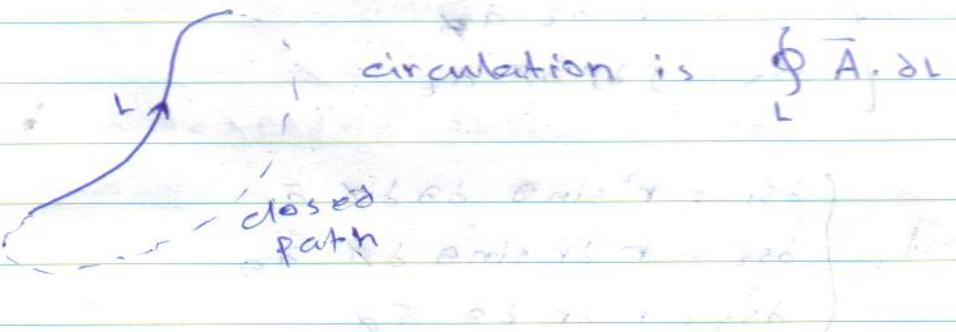
$$dV_S = r^2 dr \partial \theta \partial \phi \sin\theta$$

* line integral

by line we mean the path along a curve in space.

$$\int_L \vec{A} \cdot d\vec{L} \rightarrow |A| \cos \theta * (dL)$$

is the integral of the tangential component of \vec{A} along the curve L



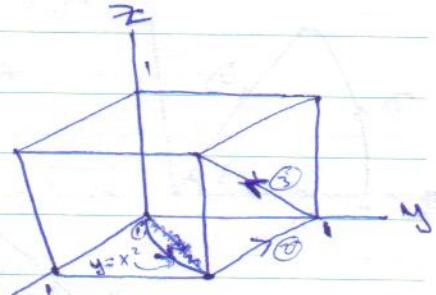
Ex: let $\vec{F} = x^2 \hat{a}_x - xz \hat{a}_y - y^2 \hat{a}_z$

determine $\int_L \vec{F} \cdot d\vec{L}$ where L is as shown

* along L_1 , $y = x^2$, $z = 0$

$$\Rightarrow dL_1 = dx \hat{a}_x + dy \hat{a}_y + dz \hat{a}_z$$

$$\vec{F} \cdot d\vec{L} = x^2 dx - 0 - 0$$



$$\int_{L_1} = \int_0^1 x^2 dx = \frac{1}{3}$$

* along L_2 , $y = 1$, $z = 0$

$$\vec{F} = x^2 \hat{a}_x - 0 - \hat{a}_z$$

$$dL_2 = dx \hat{a}_x + 0 \hat{a}_y + dz \hat{a}_z$$

$$\vec{F} \cdot d\vec{L} = x^2 dx$$

$$\int_{L_2} = \int_1^0 x^2 dx = -\frac{1}{3}$$

* along L_3 , $y = 1$, ~~$x = 2$, $dx = 0$~~

$$\vec{F} = x^2 \hat{a}_x - xz \hat{a}_y - \hat{a}_z$$

$$dL_3 = dx \hat{a}_x + dz \hat{a}_z$$

$$\vec{F} \cdot d\vec{L}_3 = x^2 dx - dz$$

$$\int_{L_3} = \int_0^1 x^2 dx - \int_0^1 dz \rightarrow \left(-\frac{2}{3} \right) \left(\frac{1}{3} - 1 \right)$$

$$= \int_0^1 x^2 dx - dx$$

$$x = z$$

$$dx = dz$$

$$= \int_0^1 (x^2 - 1) dx$$

$$= -\frac{2}{3}, \quad \int F \cdot dL = \frac{1}{3} + \frac{1}{3} - \frac{2}{3} = -\frac{2}{3}$$

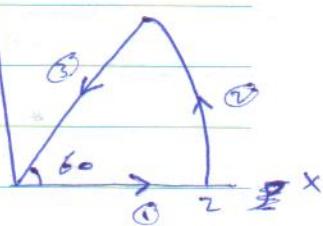
ex: let $\mathbf{F} = p \cos \phi \mathbf{a}_p + z \sin \phi \mathbf{a}_z$

* along 1 $z=0, \phi=0$

$$\mathbf{F} = p \mathbf{a}_p + 0 \mathbf{a}_\phi + 0 \mathbf{a}_z$$

$dL = \mathbf{a}_p d\phi$ since motion only in ϕ

$$\therefore \oint \mathbf{F} \cdot d\mathbf{L} = \oint p d\phi = 2\pi p$$



* along 2 $p=2, z=2$

$$\mathbf{F} = 2 \cos \phi \mathbf{a}_p + 2 \sin \phi \mathbf{a}_z$$

$$dL = p d\phi \mathbf{a}_p$$

$$\mathbf{F} \cdot d\mathbf{L} = 0$$



* along 3 $z=0, \phi=60$

$$\mathbf{F} = p \frac{1}{2} \mathbf{a}_p$$

$$dL = p d\phi \mathbf{a}_p$$

$$\oint \frac{1}{2} p d\phi = -1$$

To write the boundary condition on boundary

using unit

velocity will do integration from min to max

velocity will do integration from min to max

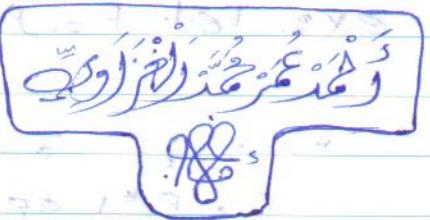
boundary, will be different if we consider

em!

8/7/14 tues

* Surface integral

$$\oint \vec{A} \cdot d\vec{s}$$



* if the surface area enclosed a volume.

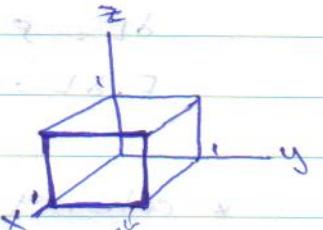
$\oint \vec{A} \cdot d\vec{s}$ it gives the total flux.

ex: let $\vec{A} = x^2 \hat{a}_x - xz \hat{a}_y - y^2 \hat{a}_z$

$$x = 1$$

$$d\vec{s}_1 = dy dz \hat{a}_x$$

$$\vec{A} \cdot d\vec{s}_1 = x^2 dy dz = dy dz$$



$$\oint \vec{A} \cdot d\vec{s} = \iint_{y=0, z=0} dy dz$$

$$= 1$$

ex: * obtain the circumference, or area of the circle

* obtain area, volume of the cylinder

* obtain area, volume of the sphere

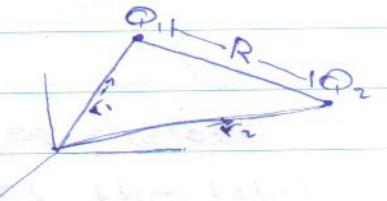
using diff. length, area, volume.

* Chapter 4: electrostatic Fields

* Coulomb's Law

$$|\vec{F}| = K \frac{Q_1 Q_2}{R^2}$$

$$= \frac{Q_1 Q_2}{4\pi\epsilon_0 R^2}$$



$$\vec{F}_{12} = \frac{Q_1 Q_2}{4\pi\epsilon_0 R_{12}^2} \hat{r}_{R_{12}} * \frac{R_{12}}{R_{12}}$$

$$|\vec{R}| = |R| \hat{r}_R$$

$$\vec{F}_{12} = \frac{Q_1 Q_2}{4\pi\epsilon_0 R_{12}^3} \vec{R}_{12}$$

$$\vec{F}_{12} = \frac{Q_1 Q_2 (\vec{r}_2 - \vec{r}_1)}{4\pi\epsilon_0 |\vec{r}_2 - \vec{r}_1|^3}$$

$$\vec{F}_{21} = \frac{Q_1 Q_2 (\vec{r}_1 - \vec{r}_2)}{4\pi\epsilon_0 |\vec{r}_2 - \vec{r}_1|^3}$$

$$\text{So } \vec{F}_{12} = -\vec{F}_{21}$$

* Force due to Assembly of charges

- Let Q_1, Q_2, \dots, Q_N be static charges

- with position vectors $\vec{r}_1, \vec{r}_2, \dots, \vec{r}_N$

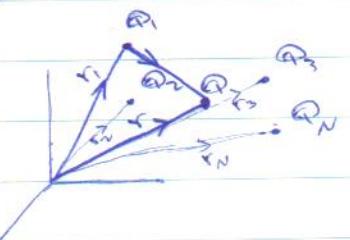
- the force on a test charge Q with

- position vector \vec{r} is

$$\vec{F} = \frac{Q}{4\pi\epsilon_0} \sum_{i=1}^N \frac{Q_i (\vec{r} - \vec{r}_i)}{|\vec{r} - \vec{r}_i|^3}$$

ex. 4.2 (see book)

important



* the electric field intensity (strength)

defined as $\vec{E} = \lim_{Q \rightarrow 0} \frac{\vec{F}}{Q}$

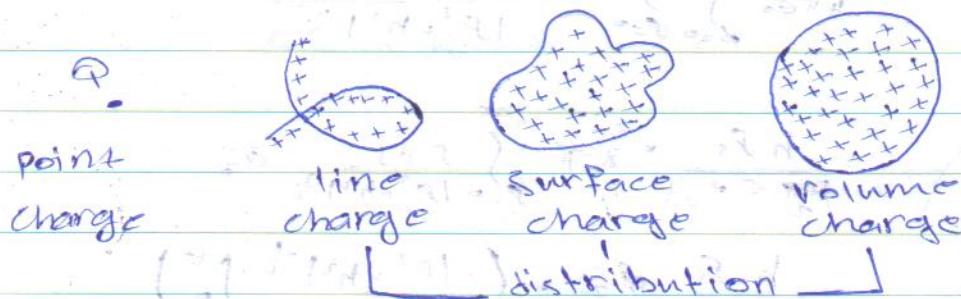
* \vec{E} due to a charge Q_1 is $\vec{E} = \frac{Q_1 \vec{R}_{12}}{4\pi\epsilon_0 |R_{12}|^3}$

$$\text{now } \div \frac{1}{Q} \Rightarrow \vec{E} = \frac{Q_1 \vec{R}_{12}}{4\pi\epsilon_0 |R_{12}|^3}$$

* \vec{E} due to Assembly of charges

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \sum_{i=1}^N \frac{Q_i \vec{r}_{-ri}}{|\vec{r} - \vec{r}_i|^3}$$

* electric Field due to continuous charge distribution



$$dQ = \rho_l dl / dQ = \rho_s ds / dQ = \rho_v dv$$

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$$\vec{E} = \int \frac{\rho_s dL}{4\pi\epsilon_0 R^2} \hat{a}_R = \int \frac{\rho_s ds}{4\pi\epsilon_0 R^2} \hat{a}_R = \int \frac{\rho_s dv}{4\pi\epsilon_0 R^2}$$

line surface volume

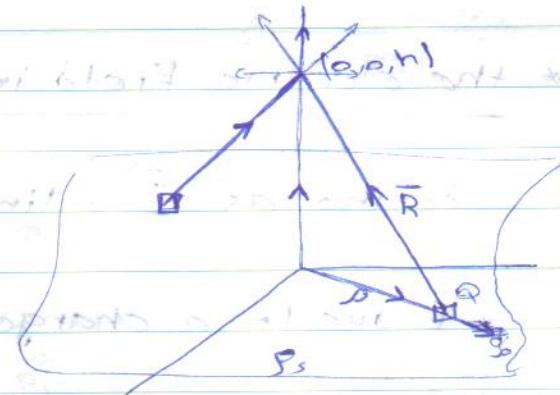
$$(1/\epsilon_0)(R - \rho) + \rho \text{ is constant along } \hat{a}_R$$

$$\vec{R} = h \hat{a}_z - \rho \hat{a}_\phi$$

$$|R| = \sqrt{(-\rho)^2 + h^2}$$

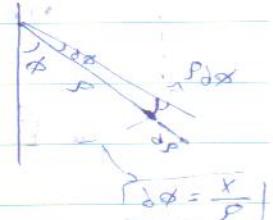
$$= \sqrt{\rho^2 + h^2}$$

$$dP = \rho_s ds$$



$$\int dP = \rho_s ds$$

$$\delta E_\phi = \frac{-\rho_s \rho dP d\phi}{4\pi\epsilon_0 (\rho^2 + h^2)^{3/2}} (-\rho \hat{a}_\phi + h \hat{a}_z)$$



* due to symmetry \vec{E} is in the direction *

$$\text{or } \hat{a}_z$$

$$\vec{E} = \frac{\rho_s}{4\pi\epsilon_0} \int_{\phi=0}^{2\pi} \int_{\rho=0}^{\infty} \frac{\rho d\rho d\phi h \hat{a}_z}{(\rho^2 + h^2)^{3/2}}$$

$$= \frac{h \rho_s}{4\pi\epsilon_0} \int_{\rho=0}^{\infty} \frac{\rho d\rho}{(\rho^2 + h^2)^{3/2}} \hat{a}_z$$

$$= \frac{h \rho_s}{2\epsilon_0} \hat{a}_z \left[-\frac{1}{\sqrt{\rho^2 + h^2}} \right]_0^\infty$$

$$= \frac{\rho_s}{2\epsilon_0} \hat{a}_z h \left(0 + \frac{1}{h} \right) = \frac{\rho_s}{2\epsilon_0} \hat{a}_z$$

$$= \frac{\rho_s}{2\epsilon_0} \hat{a}_z h \left(0 + \frac{1}{h} \right) = \frac{\rho_s}{2\epsilon_0} \hat{a}_z$$

* generally $\vec{E} = \frac{Ps}{2\epsilon_0} \hat{a}_n$

\hat{a}_n is the unit vector normal to the plain that the \vec{E} resides in.

* \vec{E} within a parallel plate capacitor

$$\vec{E} = \frac{Ps}{2\epsilon_0} \hat{a}_n + \frac{-Ps}{2\epsilon_0} (-\hat{a}_n) = \frac{Ps}{\epsilon_0} \hat{a}_n$$

Ex: a sphere of radius R charge of density P_V C/m^3 is uniformly distributed over a sphere of radius R . calculate the total charge.

$$dL = dr \hat{a}_r + r d\theta \hat{a}_\theta + r \sin\theta d\phi \hat{a}_\phi$$

$$dV = r^2 \sin\theta dr d\theta d\phi$$

$$dQ = P_V dV$$

$$Q = \int \int \int dQ$$

$$= \int_{r=0}^R \int_{\theta=0}^{\pi} \int_{\phi=0}^{2\pi} P_V r^2 \sin\theta dr d\theta d\phi$$

$$= P_V \frac{4}{3} \pi R^3$$

ex: line charge along a circle, a is const.

$$\vec{R} = a\hat{i} - a\phi\hat{\theta} + h\hat{z}$$

$$dQ = \rho_L a d\phi$$

$$d\vec{E} = \frac{\rho_L a d\phi}{4\pi\epsilon_0 |R|^3} \vec{R}$$

$$\Rightarrow |R| = (a^2 + h^2)^{\frac{1}{2}}$$

due to symmetry

$$d\vec{E} = \frac{\rho_L a d\phi (-a\hat{\theta} + h\hat{z})}{4\pi\epsilon_0 (a^2 + h^2)^{\frac{3}{2}}}$$

$$\vec{E} = \frac{\rho_L a h \hat{z}}{4\pi\epsilon_0 (a^2 + h^2)^{\frac{3}{2}}} \int_{\phi=0}^{2\pi} d\phi (-a\hat{\theta} + h\hat{z})$$

$$= \frac{\rho_L a h \hat{z}}{2\epsilon_0 (a^2 + h^2)^{\frac{3}{2}}}$$

along z-axis

along z-axis $\vec{E} = E_z \hat{z}$

$$E_z = \frac{\rho_L a h}{2\epsilon_0 (a^2 + h^2)^{\frac{3}{2}}}$$

$$E_z = \frac{\rho_L a h}{2\epsilon_0 (a^2 + h^2)^{\frac{3}{2}}}$$

ex: line charge

circle - σ is const

$$\vec{R} = a(-\hat{a}_p) + h\hat{a}_z$$

$$dQ = \rho_L a d\phi$$

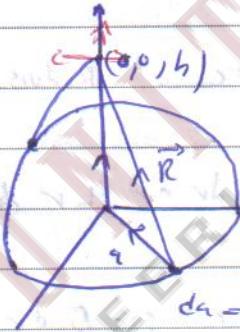
$$d\vec{E} = \frac{\rho_L a d\phi}{4\pi\epsilon_0 |R|^2} \vec{R}$$

$$|R| = \sqrt{a^2 + h^2}^{1/2}$$

$$d\vec{E} = \frac{\rho_L a d\phi (-a\hat{a}_p + h\hat{a}_z)}{4\pi\epsilon_0 (a^2 + h^2)^{3/2}}$$

$$\vec{E} = \frac{\rho_L a h \hat{a}_z}{4\pi\epsilon_0 (a^2 + h^2)^{3/2}} \int_{0}^{2\pi} d\phi$$

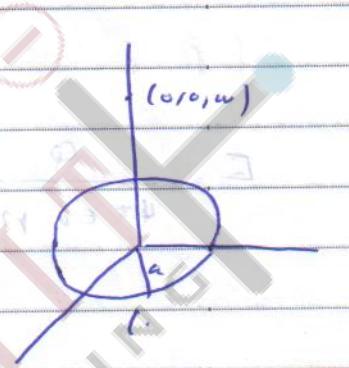
$$= \frac{\rho_L a h \hat{a}_z}{2\epsilon_0 (a^2 + h^2)^{3/2}}$$



$$\frac{d\vec{E}}{dh} = 0 \Rightarrow h = + \frac{a}{\sqrt{2}}$$

when

$$\vec{E} = \frac{P_L a h}{2\epsilon_0 (a^2 + h^2)^{3/2}} \hat{a}_z$$

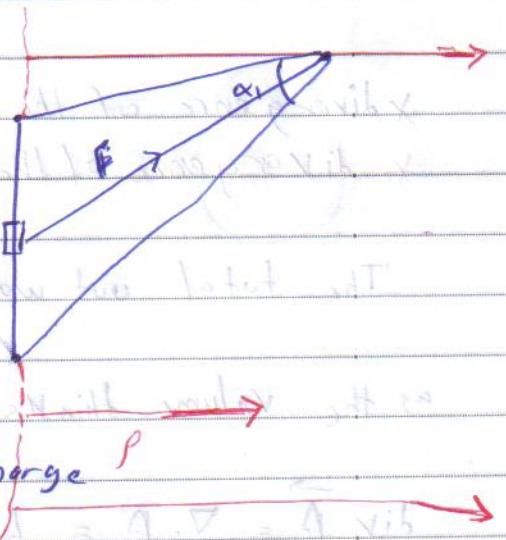


$$\lim_{h \rightarrow 0} \vec{E} = \frac{Q h}{4\pi\epsilon_0 [a^2 + h^2]^{3/2}} \hat{a}_n \quad Q = P_L 2\pi a$$

$$\vec{E} = \frac{Q}{4\pi\epsilon_0 h^2} \hat{a}_n$$

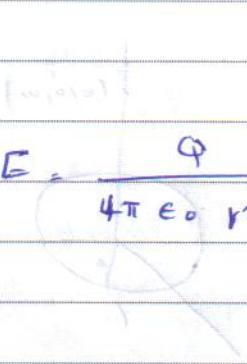
Example

$$\vec{E} = \frac{P_L}{4\pi\epsilon_0 p} \left[-\sin\alpha_2 \sin\alpha_1 \hat{a}_p + (\cos\alpha_2 - \cos\alpha_1) \hat{a}_z \right]$$



For an infinite line of charge P

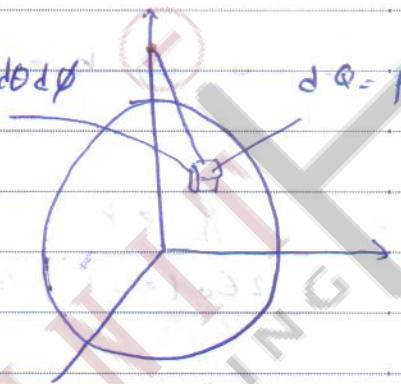
$$\vec{E} = \frac{P_L \sqrt{4}}{2\pi\epsilon_0 p} \hat{a}_p$$



$$E = \frac{Q}{4\pi \epsilon_0 r^2} \quad \text{at } r$$

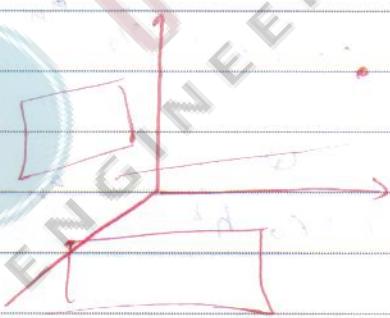
$$dV = r^2 \sin\theta \, dr \, d\theta \, d\phi$$

$$dQ = \rho_V \, dV$$



Ex:

Don't solve it from first principles; Utilize solution already obtained



* divergence of the field.

* divergence of the field:

The total outward flux per unit volume.

as the volume tends to zero (about a point)

$$\operatorname{div} \vec{A} = \nabla \cdot \vec{A} = \lim_{\Delta V \rightarrow 0} \frac{\oint \vec{A} \cdot d\vec{s}}{\Delta V}$$

Based is this definition, if $\vec{A} = A_x \hat{a}_x + A_y \hat{a}_y + A_z \hat{a}_z$

$$\vec{A} = A_x \hat{a}_x + A_y \hat{a}_y + A_z \hat{a}_z$$

It can be show (see book)

$$\nabla \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

* Electric flux density (\vec{D})

$$\vec{D} = \epsilon_0 \vec{E}$$

Ψ is the electric flux,

coulomb coulomb $^{-2}$

$$\Psi = \int_S \vec{D} \cdot d\vec{s}$$

$$\Psi = \oint \vec{D} \cdot d\vec{s}$$

$$\Psi = \oint \vec{D} \cdot d\vec{s} = Q_{enc.}$$

$$\int_V P_v \cdot dv = \int_V \nabla \cdot \vec{D} dv$$

$$\Rightarrow \nabla \cdot \vec{D} = P_v$$

$$\oint \vec{D} \cdot d\vec{s} = \int p_v dv$$

\uparrow
easier to calculate than $\oint \vec{D} \cdot d\vec{s}$

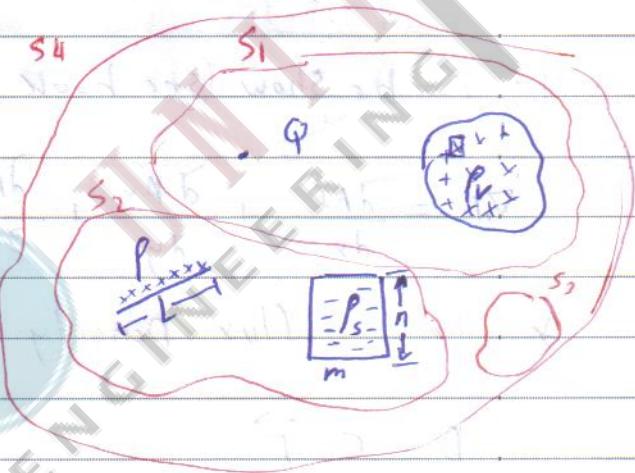
Example :

$$\Psi_{S_1} = Q + \int_V p_v$$

$$\Psi_{S_2} = p_L L + (-p_s) MN$$

$$\Psi_{S_3} = 0$$

$$\Psi_4 = Q + \int_V p_v + p_L L + (-p_s) MN$$



* Gauss Surface :

Used to simplify calculation of \vec{E} & \vec{D} when symmetry exists.

Example:

$$P_L \cdot L = \int \int D_p p d\phi dz \cdot a_p$$

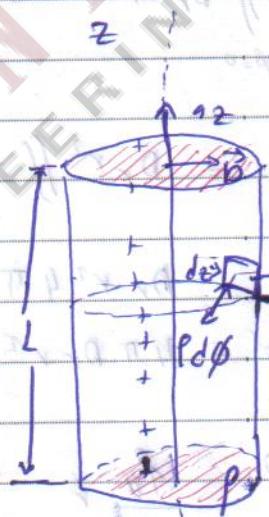
$$= \int \int D_p p d\phi dz$$

$$P_L K = P D_p 2\pi L$$

$$D_p = \frac{P_L}{2\pi R}$$

$$\vec{D} = \frac{P_L}{2\pi R} a_p$$

$$\vec{E} = \frac{P_L}{2\pi \epsilon_0 R} a_p$$



-Cos

Example:

$$P_v \frac{4}{3} \pi r^3 = \iint D_r ar \cdot r d\theta r \sin\theta d\phi$$

$$= \iint_{\theta=0}^{\pi} D_r ar \cdot r d\theta r \sin\theta d\phi$$

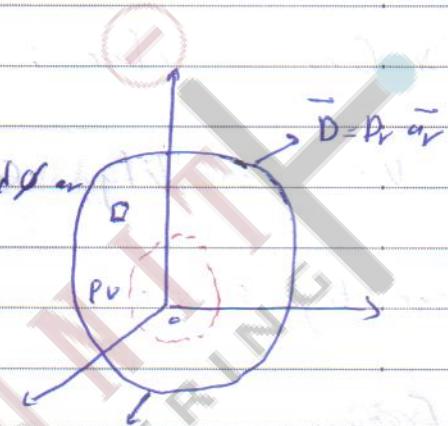
$$= D_r r^2 \iint \sin\theta d\theta d\phi$$

$$= D_r r^2 4\pi$$

$$P_v \frac{4}{3} \pi r^3 = 4\pi D_r r^2$$

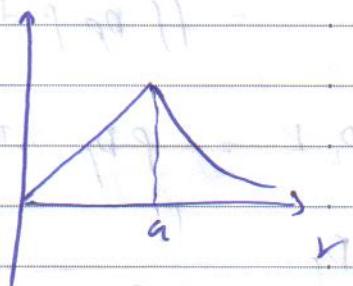
$$D_r = \frac{P_v}{3} r$$

$$\vec{E} = \frac{P_v}{3\epsilon_0} r \hat{ar}$$



radius = a

D, E





EM 1 Notebook
Dr: Omar Ghazawi
By : Amr Aljada'

بِأَمْكَانٍ_نُبَدِع

Subject

Date

No.

Exercise: Use the general formula for the resistance to obtain the resistance of a uniform conductor.

Zeeshan

Power:

$$\text{Power} = \text{force} * \text{velocity} \quad \theta = 0^\circ$$

\vec{F}, \vec{v} are in the same direction

$$= \text{force} \cdot \text{velocity}$$

"dot product"
when \vec{F}, \vec{v} are not
in the same direction $\theta \neq 0^\circ$

$$P = q \vec{E} \cdot \vec{U}$$

Power is scalar

$$dP = P v dV \vec{E} \cdot \vec{U}$$

$$dP = \vec{E} \cdot \rho_v \vec{U} dV$$

$$dP = \vec{E} \cdot \vec{J} dV$$

$$P = \int dP = \int \vec{E} \cdot \vec{J} dV$$

$$= \sigma \int |\vec{E}|^2 dV \quad \left\{ \vec{J} = \sigma \vec{E} \right.$$

$$\left\{ \begin{array}{l} \text{energy} = \text{force} \times \text{displacement} \\ \text{Power} = \text{force} \times \frac{d}{dt} (\text{displacement}) \\ = \text{Power} \times \text{velocity} \end{array} \right.$$

$$\left\{ \begin{array}{l} w = F \cdot d \\ \frac{w}{t} = \frac{F \cdot d}{t} \\ = F \cdot v \end{array} \right.$$

Exercise: ① Use the general formula for the power to obtain the power in a uniform conductor.
② prove that $P = I V$ "in uniform"

Solution:-

$$P = \int_V E \cdot J \, dv$$

$$= \int_L E \cdot dl \int_S J \cdot ds$$

$$= V I$$

Example:

$$\text{let } \vec{J} = \frac{1}{r^3} (2\cos\theta \hat{a}_r + \sin\theta \hat{a}_\theta) \text{ A/m}^2$$

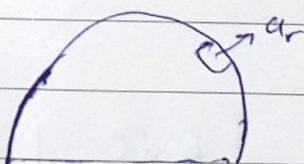
calculate current through :

- i) hemispherical shell of radius 20 cm
- ii) spherical shell of radius 10 cm

Solution:

$$I = \int_S \vec{J} \cdot d\vec{s}$$

$$d\vec{s} = r^2 \sin\theta \, d\theta \, d\phi \, \hat{a}_r$$



hemisphere $\leftrightarrow \frac{\pi}{2} \times 2\pi$

$$I = \int_0^r \int_0^{\frac{\pi}{2}} \frac{2}{r} \cos\theta \sin\theta \, d\theta \, d\phi$$

$$I = \frac{R}{0.2} (2\pi) \int_0^{\frac{\pi}{2}} \cos \theta \sin \theta d\theta$$

$$= 20 \text{ ft} \cdot \frac{\sin^2 \theta}{2} \Big|_0^{\frac{\pi}{2}}$$

$$= 10\pi \text{ A}$$

ii) Second case:

$$I = \int_0^{\pi} \int_0^{2\pi} \frac{2}{r} \cos \theta \sin \theta d\theta d\phi$$

$$= \frac{2}{0.1} \cdot 4 \cdot 2\pi \int_0^{\pi} \cos \theta \sin \theta d\theta$$

$$= 20\pi \cdot \frac{2 \sin^2 \theta}{2} \Big|_0^{\pi} = 0 \text{ A}$$

check: use ~~area~~ $\nabla \cdot \vec{J} = \lim_{\Delta V} \frac{\int \vec{J} \cdot d\vec{s}}{\Delta V}$

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$$\Rightarrow \int_S \vec{J} \cdot d\vec{s} = \int_V \nabla \cdot \vec{J} dv$$

$$I = \int_V \nabla \cdot \vec{J} dv = 0A$$

$$= 0 A$$

Subject

Date

No.

Polarisation of Dielectrics :

Metals



Dielectrics

Stable insulators
insulators "die"

electrons are not free
to move

"Unstable" dielectrics
electrons are bound to the
nucleus

To Reckham off: just write about it

Metals are highly as the is very low.

In dielectrics , charges are tightly bound to the crystalline structure , unable to move freely as is the case in metals

If an external electric field is applied , the positive & negative charges are displaced of their original positions , resulting in the creation of dipoles.

$$\vec{P} = Q \vec{d}$$

dipole
moment.

Polarisation is defined as :

$$\vec{P} = \lim_{\Delta V \rightarrow 0} \frac{\sum_{k=1}^n Q_k \vec{d}_k}{\Delta V}$$

also is also

It can be shown that

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P}$$

" Dielectric ~~medium~~ "
 ↪ Polarisation

$$\vec{P} = 0 \quad \text{in free space \& in metals}$$

in free space

$$\left. \begin{array}{l} \vec{D} = \epsilon_0 \vec{E} \\ \vec{P} = 0 \quad \{ Q = 0 \} \end{array} \right\} \text{no charges}$$

also \vec{P} depends on \vec{E}

through :

$$\vec{P} = \epsilon_s \chi_e \vec{E}$$

χ_e : is the susceptibility of the dielectric
that we will talk about

hence :

~~bullet~~

$$\vec{D} = \epsilon_0 (1 + \chi_e) \vec{E}$$

$$= \epsilon_0 \epsilon_r \vec{E}$$

$$\left. \begin{array}{l} \epsilon_r = 1 + \chi_e \\ \epsilon_r > 1 \end{array} \right\}$$

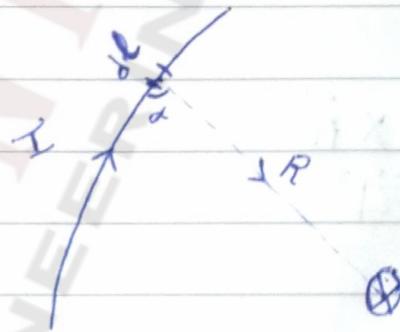
also : $\epsilon_r = \frac{\epsilon}{\epsilon_0} \Rightarrow \epsilon = \epsilon_0 \epsilon_r$

Magnetostatics (Ch 7)

The Biot-Savart's Law

The magnitude of the magnetic field due to an elemental current:

$$\frac{dH \propto I dl \sin\alpha}{|R|^2}$$



Since the field has direction:

$\left\{ \begin{array}{l} I dl: \text{elemental current} \\ \end{array} \right.$

$$d\vec{H} = K \frac{I |dl| \sin\alpha}{|R|^2} \hat{a}_n$$

$$d\vec{H} = \frac{K I |dl| \sin\alpha}{|R|^2} \hat{a}_n = K I \frac{d\vec{l} \times \hat{a}_R}{|R|^2}$$

Perpendiculair
to the plane

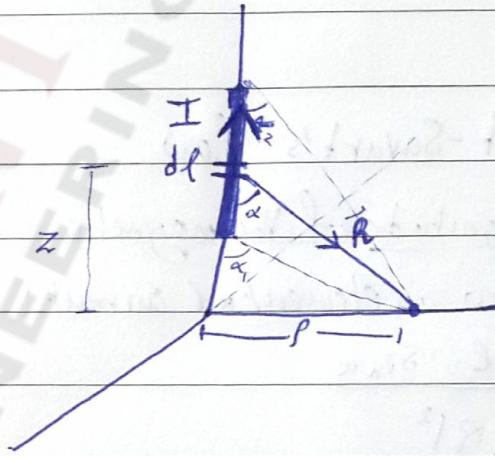
$$= K I \frac{d\vec{l} \times |R| \hat{a}_R}{|R|^3} = \frac{1}{4\pi} I \frac{d\vec{l} \times \vec{R}}{|R|^3}$$

$$K = \frac{1}{4\pi} \quad \text{in SI unit system}$$

Example:

$$d\vec{H} = \frac{I}{4\pi} \frac{dl \times \vec{R}}{|\vec{R}|^3}$$

$$= \frac{I}{4\pi} \frac{dz a_z \times (p a_p - z a_z)}{(p^2 + z^2)^{\frac{3}{2}}}$$



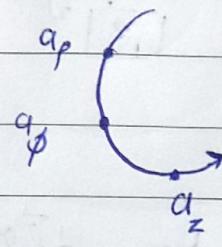
$$\left. \begin{aligned} dl &= dz a_z \\ \vec{R} &= p a_p - z a_z \end{aligned} \right\}$$

$$|\vec{R}| = (p^2 + z^2)^{\frac{1}{2}}$$

$$\vec{H} = \int_L d\vec{H} = \int_L \frac{I}{4\pi} \frac{p dz a_\phi}{(p^2 + z^2)^{\frac{3}{2}}} = 0$$

$$= \frac{I}{4\pi} \int_L \frac{p dz}{(p^2 + z^2)^{\frac{3}{2}}} a_\phi$$

$$= \frac{I p a_\phi}{4\pi} \int_L \frac{1}{(p^2 + z^2)^{\frac{3}{2}}} dz$$



Subject

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By Trigonometric Substitution:

$$\text{let } z = \rho \cot \alpha$$

$$dz = -\rho \csc^2 \alpha \, d\alpha$$

$$\rho^2 + z^2 = \rho^2 (1 + \cot^2 \alpha) = \rho^2 \csc^2 \alpha$$

$$\Rightarrow \vec{H} = -\frac{I \rho \alpha_\phi}{4\pi} \int_{\alpha_1}^{\alpha_2} \frac{\rho \csc^2 \alpha}{\rho^3 \csc^3 \alpha} \, d\alpha$$

$$\vec{H} = -\frac{I \alpha_\phi}{4\pi \rho} \int_{\alpha_1}^{\alpha_2} \sin \alpha \, d\alpha = -\frac{I}{4\pi \rho} (\cos \alpha_1 - \cos \alpha_2) \alpha_\phi$$

$$\left\{ \vec{H} = \frac{I}{4\pi \rho} (\cos \alpha_2 - \cos \alpha_1) \alpha_\phi \right\}$$

Special case : Semi-infinite wire :

$$\alpha_1 = 90^\circ \quad \alpha_2 = 0$$

$$\vec{H} = \frac{I}{4\pi\rho} a_\phi$$

Special case, infinite wire:

$$\alpha_1 = +180^\circ \quad \alpha_2 = 0$$

$$\vec{H} = \frac{I}{2\pi\rho} a_\phi$$

Ampere's ~~law~~ circuit law:

Briefly: The circulation of \vec{H} is equal to the sum of enclosed currents.

H : magnetic field intensity

Circulation: line integral over a closed path

$$\oint_L \vec{H} \cdot d\vec{l} = I_{enc} = \sum_{i=1}^N I_i$$

I is scalar

using Stokes theorem

$$\oint_L \vec{H} \cdot d\vec{l} = \int_S (\nabla \times \vec{H}) \cdot ds = I_{enc}$$

$$I_{enc} = \int_S J \cdot ds = \int_S (\nabla \times \vec{H}) \cdot ds$$

$$\Rightarrow \nabla \times \vec{H} = \vec{J} \quad \text{Maxwell's Third equation in point form}$$

$$\nabla \times \vec{H} = \vec{J}$$

$$J \neq 0 \Rightarrow \nabla \times \vec{H} \neq 0$$

i.e. The magnetic field is not conservative

Magnetic field is $\frac{\partial \Phi_B}{\partial r}$ or "Work done (closed path) $\oint \vec{B} \cdot d\vec{l}$ "
↓
Potential

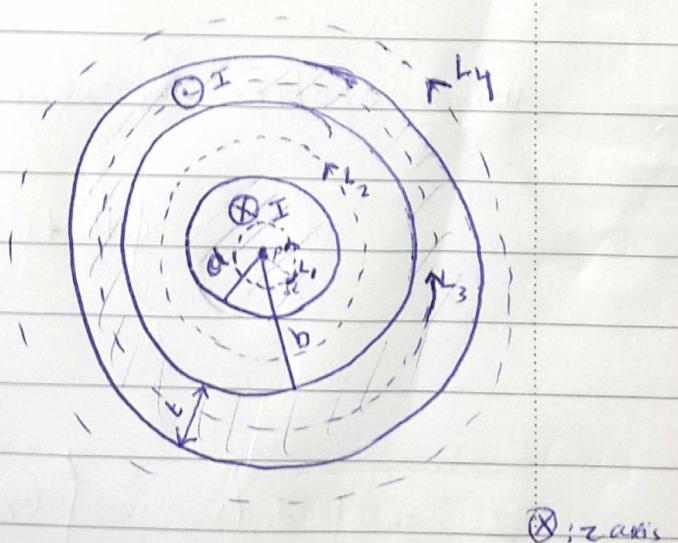
Example: Consider Infinite length coaxial transmission line.

Infinite length: uniform magnetic field

for

$R_0 < r < a$

$$\oint_{L_1} H \cdot d\vec{l} = I_{enc} = \int_S \vec{J} \cdot d\vec{s}$$



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$$\vec{J} = \frac{I}{\pi a^2} a_z$$

$$ds = dr r d\phi a_z$$

$$d\vec{l} = r d\phi a_\phi$$

$$\vec{H} = H_\phi a_\phi$$

$$\int_L \vec{H} \cdot d\vec{l} = \int_S \vec{J} \cdot ds$$

$$\int_{\phi=0}^{2\pi} H_\phi a_\phi \cdot r d\phi a_\phi = \int_{r=0}^r \int_{\phi=0}^{2\pi} \frac{I}{\pi a^2} a_z \cdot r dr d\phi a_z$$

$$H_\phi P(2\pi) = \frac{I}{\pi a^2} (2\pi) \frac{r^2}{2}$$

$$H_\phi = \frac{I}{2\pi a^2} r$$

$$\vec{H} = \frac{I r}{2\pi a^2} a_\phi$$

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When $\rho \geq b+t$

$$\int H_\phi a_\phi \cdot \rho d\phi a_\phi = I + (-I) = 0$$

$$2\pi \rho H_\phi = 0$$

Since $\rho \neq 0$

$$\Rightarrow H_\phi = 0$$

for the case $b \leq \rho \leq b+t$

$$\int H_\phi a_\phi \cdot \rho d\phi a_\phi = I + \int_{\bar{s}}^{\bar{J}_b} \bar{J}_b \cdot d\bar{s}$$

~~REMARKS~~

$$2\pi \rho H_\phi = I - \frac{I}{\pi} \left\{ \int_0^{2\pi} \int_b^{\rho} \frac{1}{t^2 + 2bt} a_z \cdot d\rho d\phi a_z \right\}$$

$\left. \begin{aligned} \bar{J}_b &= \frac{I}{\pi(b+t)^2 - \pi b^2} (-a_z) \\ &= \frac{-I}{\pi(t^2 + 2bt)} a_z \end{aligned} \right\}$

"negative reactance" due to load

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$$2\pi\rho H_\phi = I - \frac{2I}{2} \frac{1}{t^2 + 2bt} \rho^2 b^2$$

$$2\pi\rho H_\phi = I \left(1 - \frac{(t^2 - b^2)}{t^2 + 2bt} \right)$$

$$H_\phi = \frac{I}{2\pi\rho} \left(1 - \frac{(t^2 - b^2)}{t^2 + 2bt} \right)$$

Magnetic Flux Density : (\vec{B})

Defined as

$$\vec{B} = \mu_0 \vec{H}$$

μ_0 is the Permeability of free space.

The ~~parallel~~ magnetic flux through a surface S is

$$\Psi = \int_S \vec{B} \cdot d\vec{s}$$

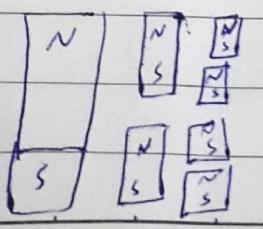
also

$$\Psi = \oint_S B \cdot ds = 0$$

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يجب ان يكون "المagnetic" مكتوب

implying the non-existence of separate magnetic charges



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Using the divergence theorem:

$$\oint_S \vec{B} \cdot d\vec{s} = \iiint_V (\nabla \cdot \vec{B}) \cdot dV = 0$$

$$\nabla \cdot \vec{B} = 0$$

one of Maxwell equations



Electromagnetics I

NoteBook

By: Ahmad Ghzawi
Dr. Omar Ghzawi

بآفكارنا نبدع

electromagnetics

* the gradient of a scalar field

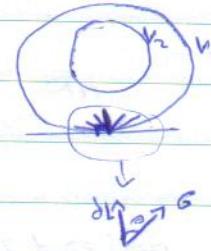
$$\delta V = \frac{\partial V}{\partial x} dx + \frac{\partial V}{\partial y} dy + \frac{\partial V}{\partial z} dz$$

$$= \underbrace{\left(\frac{\partial V}{\partial x} \hat{a}_x + \frac{\partial V}{\partial y} \hat{a}_y + \frac{\partial V}{\partial z} \hat{a}_z \right)}_{\vec{G}} \cdot \underbrace{(dx \hat{a}_x + dy \hat{a}_y + dz \hat{a}_z)}_{\delta L}$$

$$\text{so } \delta V = \vec{G} \cdot \delta L = |\vec{G}| |\delta L| \cos \theta$$

$$\frac{\delta V}{|\delta L|} = |\vec{G}| \cos \theta$$

$$\max \left| \frac{\delta V}{|\delta L|} \right| \text{ when } \theta = 0^\circ = G$$



* the gradient \vec{G} gives the direction of maximum increase in V .

$$\text{so } \vec{G} \cdot \delta L = \nabla V = \left(\frac{\partial}{\partial x} dx + \frac{\partial}{\partial y} dy + \frac{\partial}{\partial z} dz \right) \underset{\substack{\text{must be} \\ \text{a scalar} \\ \text{field}}}{V}$$

* The Electric potential :

Defined as work per unit charge.

If a charge Q is moved within an electric field,

then along a certain path L .

Then work done is :

$$dW = \cancel{QE} - Q\vec{E} \cdot d\vec{L}$$

$$W = -Q \int_L \vec{E} \cdot d\vec{L}$$

$$V = \frac{W}{Q} = - \int_L \vec{E} \cdot d\vec{b}$$

Ex: Consider potential due to a point charge.

$$\vec{E} = \frac{Q}{4\pi\epsilon_0 r^2} \hat{a}_r$$

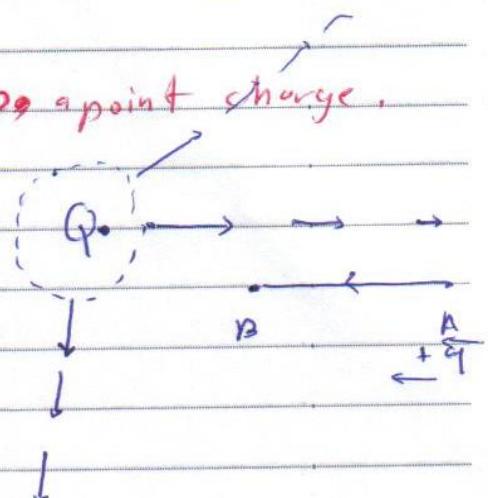
$$d\vec{l} = +dr \hat{a}_r$$

$$V(r) = - \int_A^B \vec{E} \cdot d\vec{l}$$

$$V(r) = - \int_A^B \frac{Q}{4\pi\epsilon_0 r^2} dr$$

$$V(r) = - \int_{r=r_A}^{r=r_B} \frac{Q}{4\pi\epsilon_0 r^2} dr$$

$$V(r) = \frac{Q}{4\pi\epsilon_0} \cdot \frac{1}{r} \Big|_{r=r_A}^{r=r_B} = \frac{Q}{4\pi\epsilon_0} \left[\frac{1}{r_B} - \frac{1}{r_A} \right]$$



* Curl of a vector field

* an operation on vector field results in a vector quantity

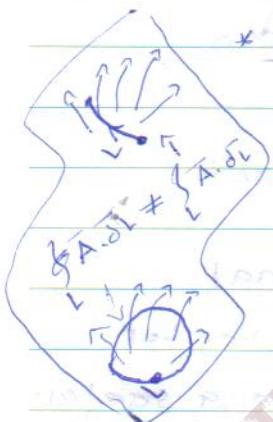
* it gives a measure of rotation in the field, so $\text{curl } \vec{E} = 0 \leftarrow \uparrow\uparrow\uparrow\uparrow\uparrow \vec{E}$

(no rotation)

$$\left(\begin{array}{c} \curvearrowleft \\ \curvearrowright \\ \curvearrowleft \end{array} \right) \Rightarrow \text{curl } \vec{E} \neq 0$$

* Definition

$$\text{curl } (\vec{A}) = \nabla \times \vec{A} = \lim_{\Delta s \rightarrow 0} \frac{\oint \vec{A} \cdot d\vec{l}}{\Delta s} \hat{a}_n$$



* it can be shown that in cartesian coordinate

$$\text{curl } \vec{A} = \nabla \times \vec{A} = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix}$$

$$\text{ex: vet } \vec{A} = K \hat{a}_x$$

$$\xrightarrow{\substack{\longleftarrow \\ \longrightarrow \\ \uparrow \\ \downarrow}}$$

$$\text{so } \text{curl } \vec{A} = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ K & 0 & 0 \end{vmatrix} = 0$$

$$\text{div } \vec{A} = 0$$

~~curl A = 0~~

if $\nabla \cdot \mathbf{A} = 0$ then

$$\text{ex: } \bar{A} = r\bar{a}_r$$

curl $\bar{A} = 0$ but \bar{A} is not zero

$$\nabla \cdot \bar{A} \neq 0$$

and \bar{A} is not zero so $\nabla \cdot \bar{A} \neq 0$

$$\text{ex: } \bar{A} = \bar{r}\bar{\theta}\bar{a}_\theta \Rightarrow \nabla \cdot \bar{A} \neq 0$$

$$\text{curl } \bar{A} \neq 0$$

$$\nabla \cdot \bar{A} \neq 0$$

* it can be shown that

relating curl $\mathbf{E} = \nabla \times \mathbf{E} = 0$ adirotational

$$\& \bar{E} = -\nabla V \text{ getting a vector}$$

A \times field through a scalar field

* ∇ is easier to calculate than \bar{E}

$$\nabla \times (\mathbf{A} \times \mathbf{B}) = \mathbf{A}(\nabla \cdot \mathbf{B}) - \mathbf{B}(\nabla \cdot \mathbf{A}) + \mathbf{A} \times (\nabla \times \mathbf{B}) - \mathbf{B} \times (\nabla \times \mathbf{A})$$

$$\mathbf{B} = \mathbf{A} \times \mathbf{V}$$

* in conservative fields, the potential difference does not depend on the path taken.

it depends on the starting & ending points.

* V_{AB} is the same irrespective of the path taken.

so, in calculation choose

a path which simplifies the calculations.

$$\therefore V_{AB} = V_B - V_A, \quad V_{A'B} = -V_{BA} \Rightarrow V_{AB} + V_{BA} = 0$$

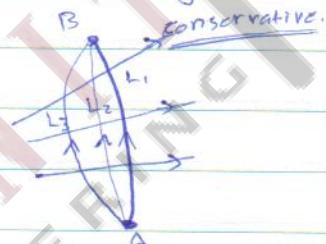
i.e. $\oint \vec{A} \cdot d\vec{l} = 0$ if the field is conservative.

$$\text{Ex: let } V(r) = \frac{10}{r^2} \sin \theta \cos \phi$$

$$\text{consider that } \nabla V = \frac{\partial V}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial V}{\partial \theta} \hat{\theta} + \frac{1}{r \sin \theta} \frac{\partial V}{\partial \phi} \hat{\phi}$$

$$\vec{E} = -\nabla V$$

$$= - \left[\frac{-20}{r^3} \sin \theta \cos \phi \hat{r} + \frac{10}{r^3} \cos \theta \cos \phi \hat{\theta} - \frac{10 \sin \theta \sin \phi}{r^3 \sin \theta} \hat{\phi} \right]$$





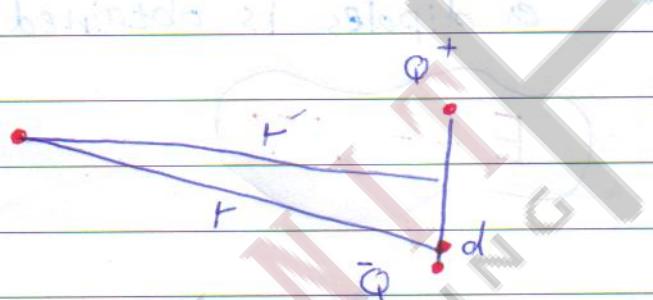
ElectroMagnaticsI

NoteBook

Dr. Omar Ghzawii

بآفاق كارنا_نبذع

* Electric Dipole moment * "P142"



* A dipole is two equal and opposite changes displacement by a distance "d"

* The product $\bar{P} = Q\bar{d}$ is shown as it can be shown (see book) that:

$$V(r) = \frac{\bar{P} \cdot \bar{a}_r}{4\pi\epsilon_0 r^2}$$

* If the center of Dipole is the position at F. then:

$$V(r) = \frac{\bar{P} \cdot (\bar{r} \cdot \bar{F})}{4\pi\epsilon_0 |\bar{r} \cdot \bar{F}|^3}$$

* The Electric field intensity due to a dipole is obtained through:

$$\boxed{E = -\nabla V}$$

Ex) calculate "E" For the dipole (see book)

Finding: $E \propto \frac{1}{r^2}$

* Equipotential Surfaces *

Are contours of equal Potential

all Point distance V
have the same Potial



$$V_3 > V_2 > V_1$$

\vec{E} Line are Perpendicular
to the equipotential surface

Ex) study the electric field line due to dipole (see book)

* Energy stored in an Electric field Due to distance charge

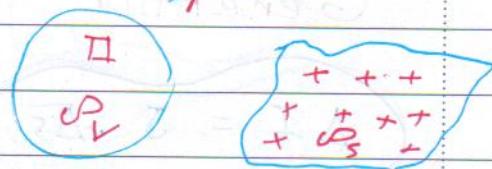
$$W = \frac{1}{2} \sum_{k=1}^N Q_k V_k$$



* Due to Continus distribution of charges

$$W = \frac{1}{2} \int \bar{D} \cdot \bar{E} dv$$

$$= \frac{1}{2} \int \epsilon_0 |E|^2 dv$$



* Energy density we is:

$$\frac{dW}{dv} = \frac{1}{2} \bar{D} \cdot \bar{E}$$

* These, distribution of charges altogether result in a certain electric field "E"

* condition in Material Space *

for conductor $\sigma \gg 1$

for insulator $\sigma \ll 1$

Current:

$$I = \frac{dQ}{dt}$$

Normal

current density:

$$J_n = \frac{\Delta T}{\Delta s}$$

$$\Rightarrow \Delta I = J_n \times \Delta s$$

Generally

$$\Delta I = J \cdot \Delta s$$

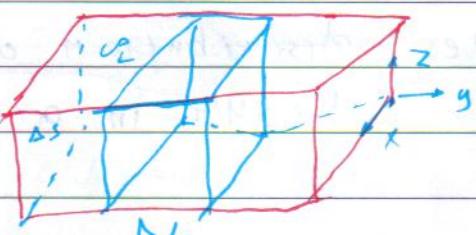
$$I = \int_S J \cdot ds$$

* Consider a Uniform material

$$\Delta I = \frac{\Delta Q}{\Delta t}$$

$$= \rho_v \Delta s \frac{\Delta L}{\Delta t}$$

$$J_{ny} = \frac{\Delta I}{\Delta s} = \rho_v n_y$$



$$J_{ny} = \rho_v u_y$$

Generally: ~~Electric current in a conductor~~

$$\bar{J} = \rho_v \bar{u}$$

* In the presence of an electric field

$$F = -e \bar{E}$$

$$m \frac{\bar{u}}{x} = -e \bar{E}$$

$$u = -\frac{e x}{m} E$$

$$\text{also } J = \rho_v \bar{u}$$

$$= -e n * -\frac{e x}{m} \bar{E}$$

$$J = \frac{n e^2 x}{m} E$$

σ for material = 10^7

σ for insulator = 10^{-17}

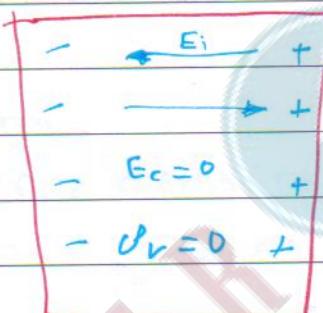
$$J = \sigma \bar{E}$$

→ Conductivity of material

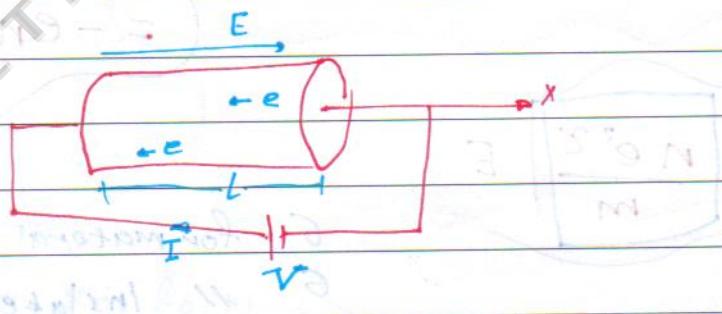
$$\bar{J} = \sigma \bar{E}$$

is known as the Point form
of ohm's Law.

* Electric Field in Conductors:



* Defining the Resistance:



* for uniform Conductor:

$$E_x = V/L$$

also

$$J_x = \frac{I}{S} = \sigma E_x$$

$$\sigma * \frac{V}{L} = \frac{I}{S}$$

* The resistance is "R" & find a:

$$R = \frac{V}{I}$$

$$R = \frac{1}{\sigma} \frac{L}{S} = \frac{\rho L}{S}$$

where " ρ " is the resistivity

* In the case where the conductor is not uniform:

$$R = \frac{V}{I} = \frac{\rho \bar{E} \cdot \bar{d}L}{\sigma \bar{S} \bar{E} \cdot \bar{d}s}$$

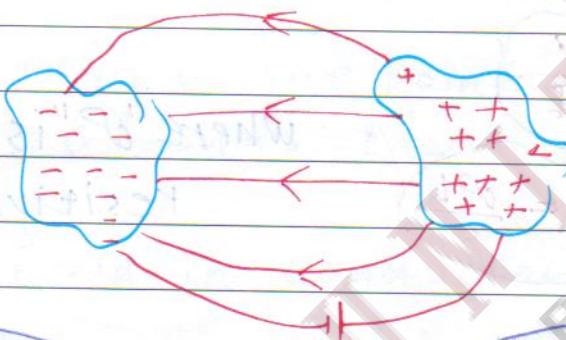
* it can be shown that that the power is given by "see book"

$$P = \int E \cdot J dv$$

* for a uniform conductors "derive"

$$P = VI = I^2 R = \frac{V^2}{R}$$

* Defining the Capacitance *



$$\text{Capacitance } (C) = \frac{Q}{V} = \frac{E \cdot \epsilon_0 \cdot A}{d}$$

Ex) shown that:

$$D = -\epsilon_0 \sigma_a x = \sigma_a C(-a x)$$

Sol.,,

assuming the fringing is negligible

Due to uniformity $C_p = \frac{Q}{S}$

$$E = \frac{-\sigma_a}{\epsilon_0} a x = \frac{Q}{\epsilon_0 S} a x$$

$$V = - \int_{-d}^0 E \cdot dL = - \int_{-d}^0 \frac{Q}{\epsilon_0 S} a x \cdot dx$$

$$= \frac{Q d}{\epsilon_0 S} = V$$

$$C = \frac{Q}{V} = C = \frac{Q}{\frac{Q d}{\epsilon_0 S}} = \frac{\epsilon_0 S}{d}$$

* Energy stored in a capacitor

$$W = \frac{1}{2} \int U \cdot E dV$$

$$= \frac{1}{2} \epsilon \cdot \int |E|^2 dV$$

$$= \frac{1}{2} \epsilon \int \frac{Q^2}{\epsilon^2 S^2} dV$$

* due to uniformity of the parallel plate capacitor:

$$= \frac{1/2 G \cdot Q^2}{\epsilon^2 S^2} \int dV$$

$$= \frac{1}{2} \epsilon \frac{G^2}{\epsilon^2 S^2} = \frac{1}{2} \frac{Q^2}{\epsilon S}$$

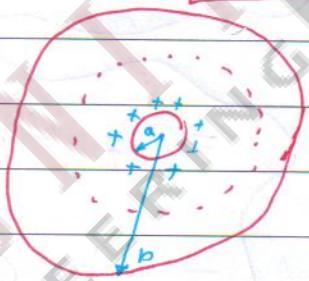
$$= \frac{1}{2} \frac{Q^2}{C}$$

$$= \frac{1}{2} C V^2 ; \frac{1}{2} Q V$$

* Coaxial Capacitor (cylindrical capacitor)

* it can be shown (see book) "P 227"

$$C = \frac{2\pi \epsilon L}{\ln(\frac{b}{a})}$$



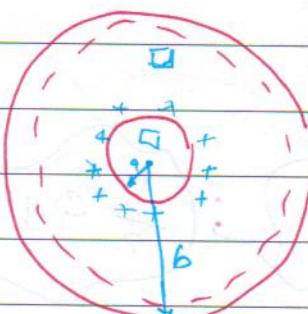
* Spherical Capacitor *

* It can be shown: "P 228"

$$C = \frac{4\pi \epsilon}{\frac{1}{a} - \frac{1}{b}}$$

AEG3

* IF "b → ∞" $\Rightarrow C = 4\pi \epsilon a$



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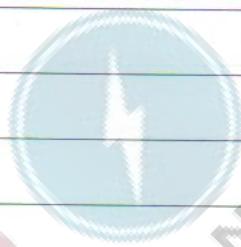
* RC Product *

$$R_C = \frac{E}{\sigma}$$

* It can be used to calculate:

C_{uR} , if R_{uC} is known

Ex)





Electromagnetics I

NoteBook

Dr. Omar Ghzawi

By: Abdelrahman Bahboh

بِالْمَكَارِنَاتِ_نُسُخَة #

Maxwell's Equation :- (CH#7)

A compact formulations for the EM.

So far they are differential (point) form or Integral form.

differential (point) form

$$\boxed{1} \quad \nabla \cdot \vec{D} = \rho_v$$

Integral form

$$\oint \vec{D} \cdot d\vec{s} = \int_v \rho_v dv$$

Gauss's Law

$$\boxed{2} \quad \nabla \cdot \vec{B} = 0$$

$$\oint \vec{B} \cdot d\vec{s} = 0$$

non-Existence of magnetic monopole.

* Magnetic Field lines are closed

* \vec{B} :- magnetic flux density.

$$\boxed{3} \quad \nabla \times \vec{E} = 0$$

$$\oint \vec{E} \cdot d\vec{l} = 0$$

conservation of the electrostatic field.

$$\boxed{4}$$

$$\nabla \times \vec{H} = \vec{J}$$

$$\oint \vec{H} \cdot d\vec{l} = \oint \vec{J} \cdot d\vec{s}$$

Ampere's Law

* Magnetic Forces :- (CH # 8)

Ex:- What are the differences between electrostatics and magnetostatic fields ??

$$\vec{F}_e = Q \vec{E} \Rightarrow \text{Force in the same direction of } \vec{E}$$

$$\vec{F}_m = Q \vec{u} \times \vec{B} \Rightarrow \text{Force is perpendicular to } \vec{u}.$$

* Due to Both Fields :-

$$\vec{F} = \vec{F}_e + \vec{F}_m = Q \vec{E} + Q \vec{u} \times \vec{B}$$

$$\boxed{\vec{F} = Q(\vec{E} + \vec{u} \times \vec{B})}$$

→ Force on a current element :-

$$I \int \vec{l} \cdot \vec{B} ds = \vec{J} dv \vec{H} \times \nabla$$

also

$$\vec{J} = \rho_i \vec{u}$$

$$\underline{Idl} = P_v \vec{u} dV = P_v dV \vec{u} = \underline{dQ \vec{u}}$$

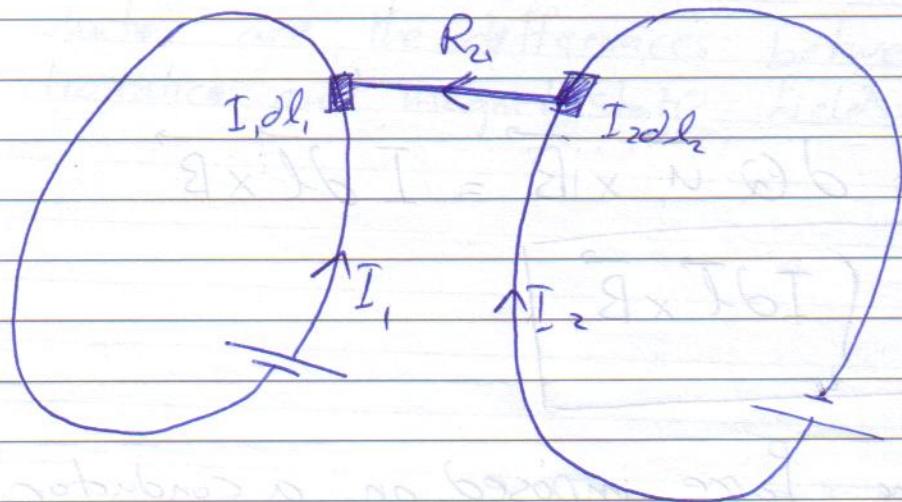
* Hence :-

$$\oint \vec{F}_m = \int Q \vec{u} \times \vec{B} = I \vec{dl} \times \vec{B}$$

$$\boxed{\vec{F}_m = \int_L I \vec{dl} \times \vec{B}}$$

* giving the Force imposed on a conductor due to an external magnetic field.

→ Force Between Two Current Elements :-



$$d(F_{m1}) = I_1 d\vec{l}_1 \times \vec{B}_2$$

$$d\vec{B}_2 = \frac{\mu_0}{4\pi} \frac{I_2 d\vec{l}_2 \times \vec{a}_{R2}}{|R_{12}|^2}$$

$$F_m = \iiint \frac{\mu_0 I_1 I_2 d\vec{l}_1 \times (d\vec{l}_2 \times \vec{a}_{R2})}{4\pi |R_{12}|^2}$$

Example 8.1 - a charged particle of mass 2 Kg and a charge 3 C starts at point (1, -2, 0) with velocity $4a_x + 3a_z$ & Electric field $2a_x + 10a_y$ V/m. At time $t=1$ sec. determine

- [1] the acceleration of particle
- [2] the velocity.
- [3] its Kinetic energy.
- [4] its position

11^m. Aug. 2021

III $\vec{F}_e = Q\vec{E} = m\vec{a}$

$$\vec{a} = \frac{Q\vec{E}}{m} = \frac{3}{2}(12a_x + 10a_y)\hat{z}$$
$$\boxed{\vec{a} = 18a_x + 15a_y \text{ m/s}^2}$$

[2] $\vec{a} = \frac{d\vec{u}}{dt} = \frac{du_x}{dt}\hat{a}_x + \frac{du_y}{dt}\hat{a}_y + \frac{du_z}{dt}\hat{a}_z$
 $= 18a_x + 15a_y$

$$\frac{du_x}{dt} = 18 \Rightarrow u_x = 18t + A$$

$$\frac{du_y}{dt} = 15 \Rightarrow u_y = 15t + B$$

$$\frac{du_z}{dt} = 0 \Rightarrow u_z = C$$

$$u(t=0) = 4a_x + 3a_y$$

$$18 \times 0 + A = 4 \Rightarrow A = 4, \quad 15 \times 0 + B = 0 \Rightarrow B = 0$$
$$C = 3$$

$$u(t) = (18t + 4)a_x + 15t a_y + 3 a_z$$

$$u(t=1) = 22a_x + 15a_y + 3a_z \text{ m/s}$$

[3] K.E. $= \frac{1}{2} m |\vec{u}|^2 \quad |\vec{u}|^2 = 2484 + 225 + 9$
 $= 2718 \text{ J}$

11th Aug. 2014

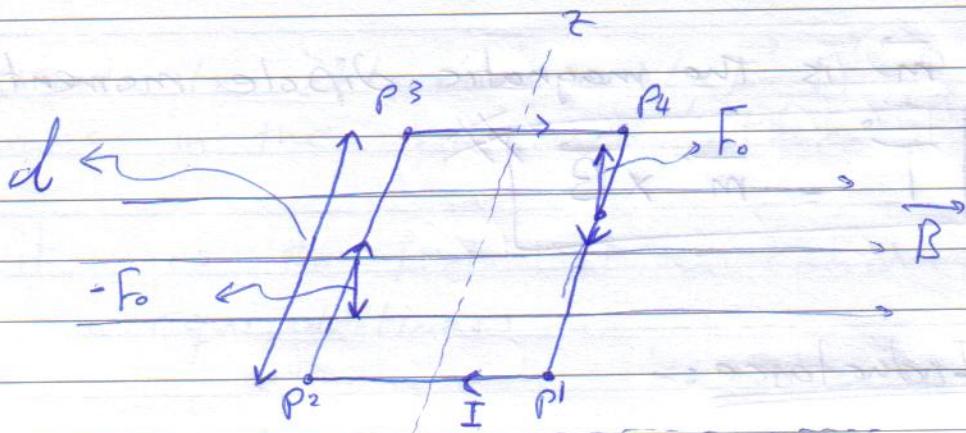
Q1 Integrate the velocity and substitute the initial conditions we obtain:-

$$(x, y, z) = (9t^2 + 4t + 1, 7.5t^2 - 2, 3t)$$

$$\text{at } t=1 \quad (x, y, z) = (14, 5.5, 3)$$

Example 8.2 :- Study this example.

Magnetic Torque :-



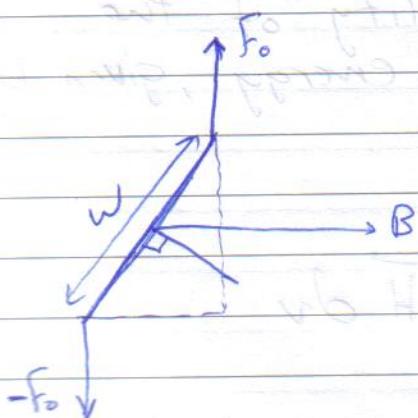
$$\vec{dF} = I \vec{dl} \times \vec{B}$$

$$\vec{F} = I \int_{P_2}^{P_3} dz \vec{a}_z \times \vec{B} + I \int_{P_4}^{P_1} dz \vec{a}_z \times \vec{B}$$

$$= I \int_{P_2}^{P_3} dz \vec{a}_z \times \vec{B} - I \int_{P_1}^{P_4} dz \vec{a}_z \times \vec{B} = 0$$

$$= F_o - F_o$$

where $|F_o| = IBl$ when \vec{B} is uniform.



$$|T| = |F_o| w \sin \alpha$$

$$= IBl w \sin \alpha$$

$$|T| = IBS \sin \alpha$$

13th Aug. 2014

Define $\vec{m} = I S$ an

where \vec{m} is the magnetic dipole moment.

hence

$$\boxed{\vec{T} = \vec{m} \times \vec{B}}$$

~~* The Inductance :-~~

$$\text{Magnetic flux } \Psi = \int \vec{B} \cdot d\vec{s}$$

If the circuit has N identical turns, then the flux linkage is

$$\lambda = N\Psi$$

It turns out that $\lambda \propto I$

$$\lambda = L I \Rightarrow L = \frac{\lambda}{I} = \frac{N\Psi}{I}$$

L is known as the inductance.

* it is a measure of the ability of the conductor to store magnetic energy, given by

$$W_m = \frac{1}{2} LI^2$$

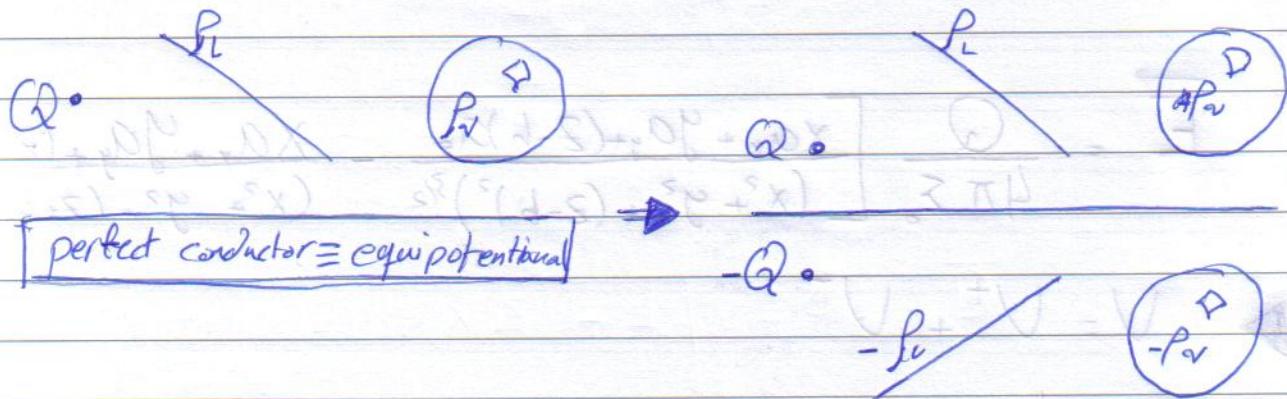
$$\text{or generally } W_m = \frac{1}{2} \int_V \vec{B} \cdot \vec{H} dv$$

14th Aug. 2014

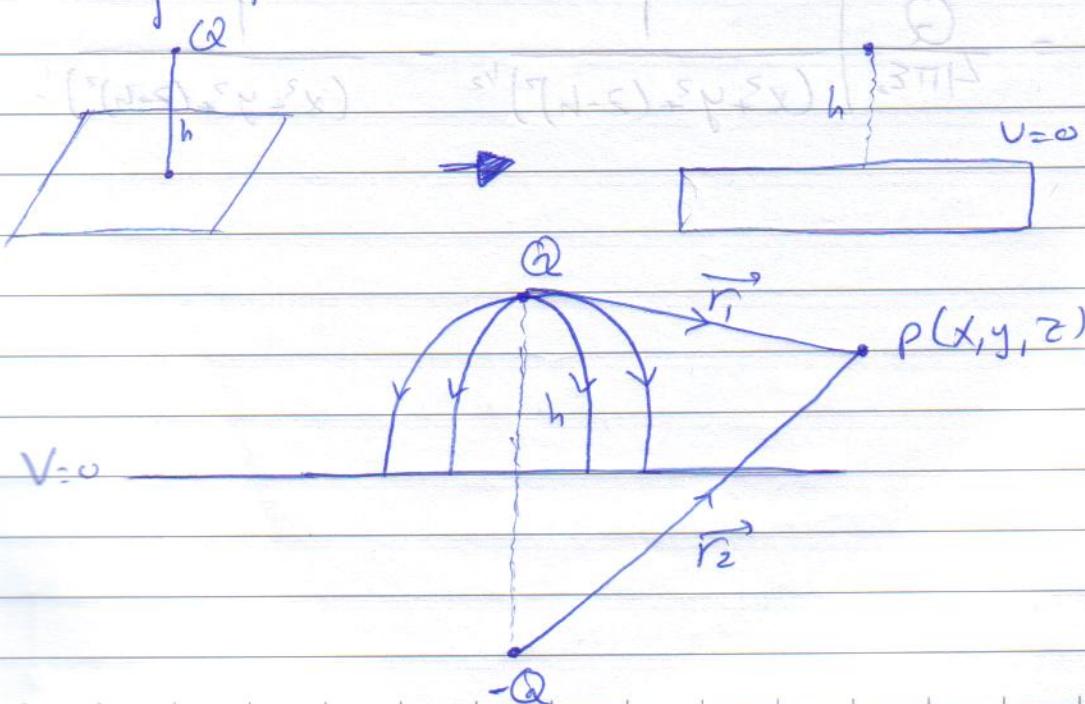
* The Method of Images :- (CH #6)

* used to determine V, \vec{E}, \vec{D}, P_s due to charges in the presence of conductors.

* it uses the fact that a conducting surface is an equipotential.



Example :- a point charge above a grounded conducting plane.



14th Aug. 2014

$$\rightarrow \vec{E} = \vec{E}_+ + \vec{E}_-$$

$$= \frac{Q \vec{r}_1}{4\pi\epsilon_0 |\vec{r}_1|^3} - \frac{Q \vec{r}_2}{4\pi\epsilon_0 |\vec{r}_2|^3}$$

$$\vec{r}_1 = (x, y, z) - (0, 0, h) = (x, y, z-h)$$

$$\vec{r}_2 = (x, y, z) - (0, 0, -h) = (x, y, z+h)$$

$$\vec{E} = \frac{Q}{4\pi\epsilon_0} \left[\frac{x a_x + y a_y + (z-h) a_z}{(x^2 + y^2 + (z-h)^2)^{3/2}} - \frac{x a_x + y a_y + (z+h) a_z}{(x^2 + y^2 + (z+h)^2)^{3/2}} \right]$$

$$\rightarrow V = V^+ + V^-$$

$$V = \frac{Q}{4\pi\epsilon_0 |\vec{r}_1|} - \frac{Q}{4\pi\epsilon_0 |\vec{r}_2|}$$

$$= \frac{Q}{4\pi\epsilon_0} \left[\frac{1}{(x^2 + y^2 + (z-h)^2)^{1/2}} - \frac{1}{(x^2 + y^2 + (z+h)^2)^{1/2}} \right]$$

14th. Aug. 2011

* Example:- a line charge above a conducting plane
(See book)

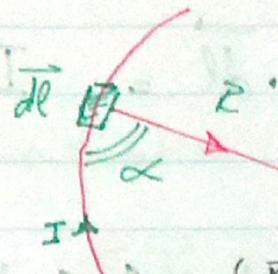
EM ظواقياً

CH7 : Magneto statics :

→ Biot - Savart's Law:

$$\rightarrow d\vec{H} \propto \frac{I d\vec{l}}{R^2} \sin\alpha$$

$$\therefore d\vec{H} = \frac{k \cdot I \vec{dl} \sin\alpha}{R^2} = \frac{I dl \cdot 1 \cdot \sin\alpha}{4\pi R^2}$$



(Right-hand Rule)

thumb in
direction of
current and
magnetic field
with other
finger

$$d\vec{H} = \frac{I \vec{dl} \times \vec{ar}}{4\pi R^2} \cdot \frac{\vec{R}}{R} = \frac{I \vec{dl} \times \vec{R}}{4\pi |R|^3}$$

$$\rightarrow \vec{H} = \int_L \frac{I \vec{dl} \times \vec{R}}{4\pi |R|^3} \quad \text{or} \quad \int_S \frac{k ds \times \vec{R}}{4\pi |R|^3}$$

(Double Integral)

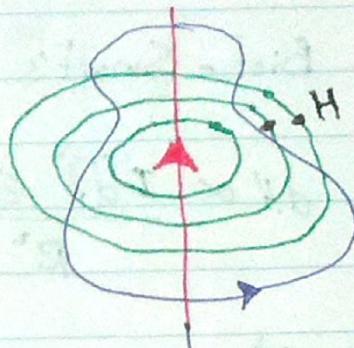
$$dR = \int_V \frac{J dl \times \vec{R}}{4\pi |R|^3}$$

(Triple Integral)

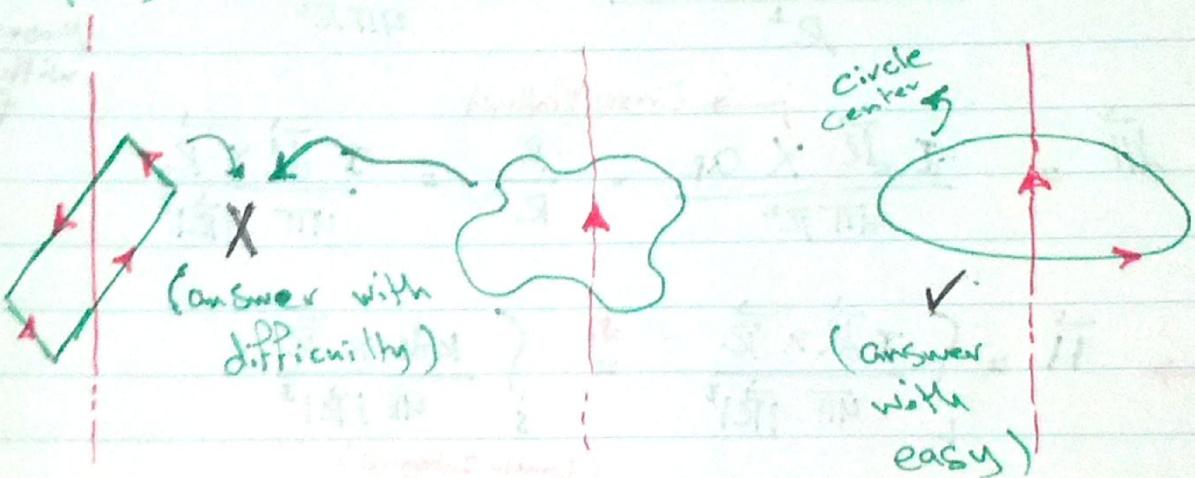
* For $L = a$, $J_{ave} = I$

* Ampere's Circuit Law :

$$\oint \vec{H} \cdot d\vec{l} = I_{\text{enc}}$$



* Suitable Contour together with utilization of Symmetry, Simplify the Calculation Considerately

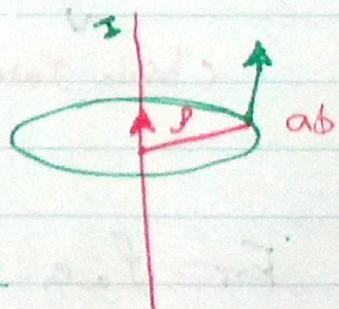


* Example : Consider the infinite Filamentary Straight Conductor

→ In this Case :

$$\vec{H} = H_\phi \hat{a}_\phi$$

• Suitable Contour (Path) is a Circle



$$\rightarrow d\vec{l} = \oint d\phi \hat{a}_\phi$$

$$I_{\text{enc}} = \oint_{\text{circle}} H_\phi \cdot a_\phi \cdot dl = \oint_{\text{circle}} H_\phi a_\phi \cdot \oint d\phi \hat{a}_\phi$$

$$H \cdot I_{\text{enc}} := \intop_{\phi=0}^{2\pi} H_\phi P d\phi = 2\pi H_\phi P$$

$$H_\phi = \frac{I}{2\pi P}$$

\therefore a generalization is

$$\sum I_i = \oint \vec{M} \cdot \vec{dl}$$

$$\vec{H} = \frac{I}{2\pi P} \alpha_\phi$$

Special Cases :

① Semi-infinite Conductor :

$$\alpha_1 = 90^\circ \quad \alpha_2 = \text{Zero}$$

$$H = \frac{I}{4\pi P} \alpha_\phi$$

② infinite Conductor :

$$\alpha_1 = 180^\circ \quad \alpha_2 = \text{Zero}$$

$$\vec{H} = \frac{I}{2\pi P} \alpha_\phi$$

* See the two example in Book
(Determine H for a Current loop)



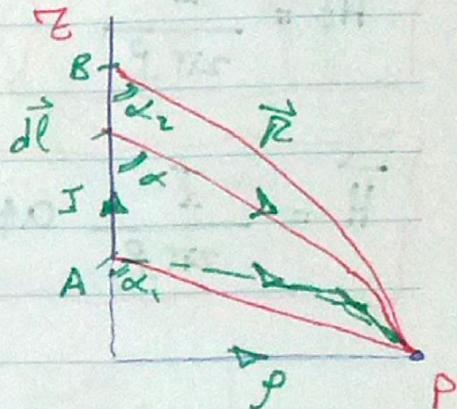
* Example : Straight Filamentary Conductor (P264)

$$d\vec{H} = \frac{I}{4\pi} \frac{dz \alpha_Z \times (+\rho \alpha_\phi - Z \alpha_Z)}{[\rho^2 + Z^2]^{3/2}}$$

$$= \frac{I}{4\pi} \cdot \frac{\rho dz \alpha_\phi - Z \alpha_Z}{[\rho^2 + Z^2]^{3/2}}$$

~~$$d\vec{H} = \frac{I}{4\pi} = \frac{dz \alpha_Z \times (+\rho \alpha_\phi - Z \alpha_Z)}{[\rho^2 + Z^2]^{3/2}}$$~~

$$\vec{H} = \frac{I}{4\pi} \rho \alpha_\phi \int_A^B \frac{1}{[\rho^2 + Z^2]^{3/2}} dz$$



Let $Z = f \cos \alpha$ (see Book) $dz = f - \csc^2 \alpha$

$$H = \frac{I\rho}{4\pi} [\cos \alpha_2 - \cos \alpha_1] \alpha_\phi$$

Final answer

$\rightarrow H$ is given by
Concentric circles
where the centre is
the conductor

* Example 3 Consider an infinity long coaxial transmission line, (See Book) for full solution

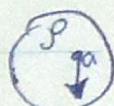
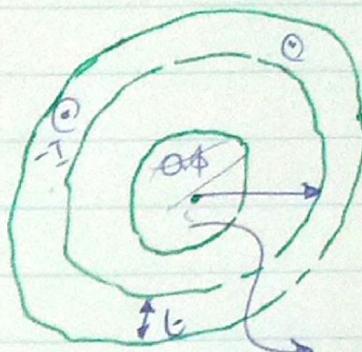
$$I = \oint \vec{J} \cdot d\vec{s}$$

$$\vec{H} = H_\phi \hat{\alpha}_\phi$$

$$d\vec{l} = \rho d\phi \hat{\alpha}_\phi$$

$$|I| = \frac{I}{\pi a^2}$$

$$I_{\text{enc}} = \frac{I \rho^2 \pi}{\pi a^2} = \frac{I \rho^2}{a^2}$$



$$\frac{I \rho^2}{a^2} = \int_{\phi=0}^{2\pi} H_\phi \alpha_\phi \cdot \rho d\phi \alpha_\phi = H_\phi \rho \int_0^{2\pi} d\phi$$

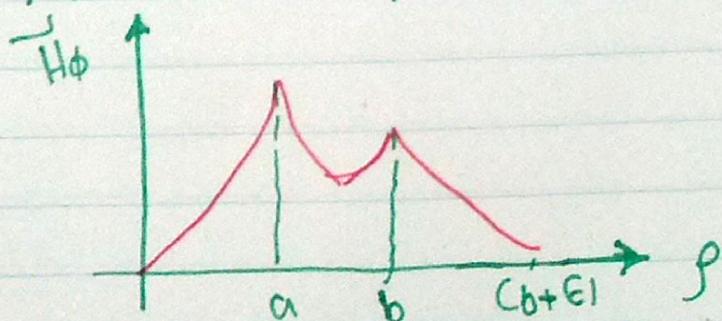
$$= 2\pi H_\phi \rho = \frac{I \rho^2}{a^2}$$

$$\therefore H = \frac{I \rho}{2\pi a^2} \alpha_\phi$$

$$0 \leq \rho < a$$

$$[\rho \uparrow \rightarrow H \uparrow]$$

$$\text{For } \rho = a, I_{\text{enc}} = I$$



(CH7)

* Maxwell's Equations *

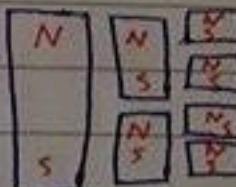
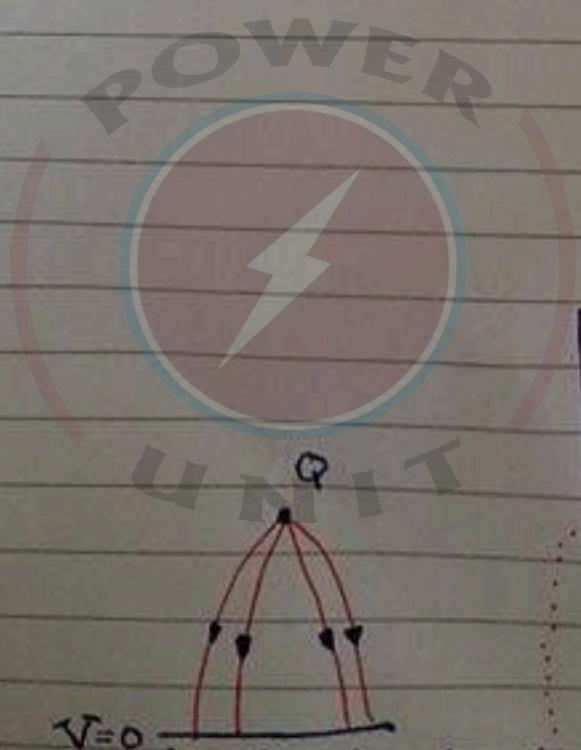
10-8-2014
Sunday

No. _____

→ A compact formulations for the "EM"

So far, They are :

differential or Point form	Integral Form	
1-) $\nabla \cdot \bar{D} = \rho_v$	$\oint \bar{D} \cdot d\bar{s} = \int \rho_v dv$	Gauss Law
2-) $\nabla \cdot \bar{B} = 0$	$\oint \bar{B} \cdot d\bar{s} = 0$	non-existance of magnetic monopole magnetic fields are closed
3-) $\nabla \times \bar{E} = 0$	$\oint \bar{E} \cdot d\bar{l} = 0$	conservation of the electrostatic
4-) $\nabla \times \bar{H} = \bar{J}$	$\oint \bar{H} \cdot d\bar{l} = \oint \bar{J} \cdot d\bar{s}$	Ampere's Law



(CH 8)

Magnetic Forces *

10-8-2014
Sunday

No. _____

Ex) what are the differences between electrostatic and the magnetostatic fields?!

(See Book)

$$F_m = Q \bar{u} \times \bar{B}$$

* Force is PerPendicular to " \bar{u} "

$$F_e = Q \bar{E}$$

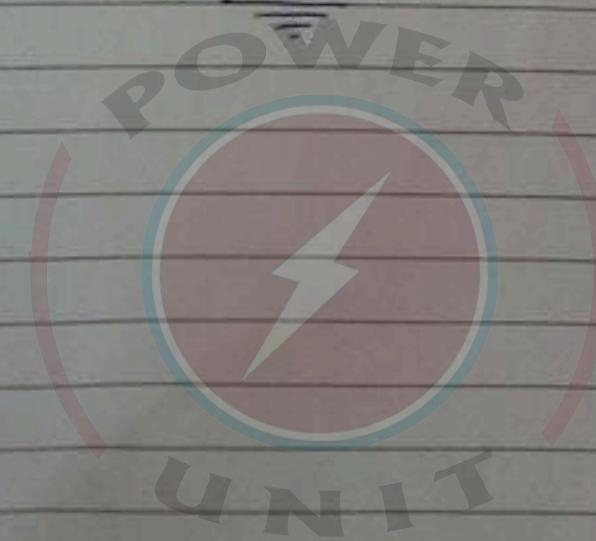
e: electrostatic

* Force is the same direction of " \bar{E} "

* Due to both fields:

$$\bar{F} = Q \bar{E} + Q \bar{u} \times \bar{B}$$

$$= Q (\bar{E} + \bar{u} \times \bar{B})$$



* Force on a Current Element *

10-8-2014
Sunday

No.

$$I d\bar{l} = K d\bar{s} = \bar{J} d\bar{v}$$

also,,,

$$\bar{J} = \rho_v \bar{u}$$

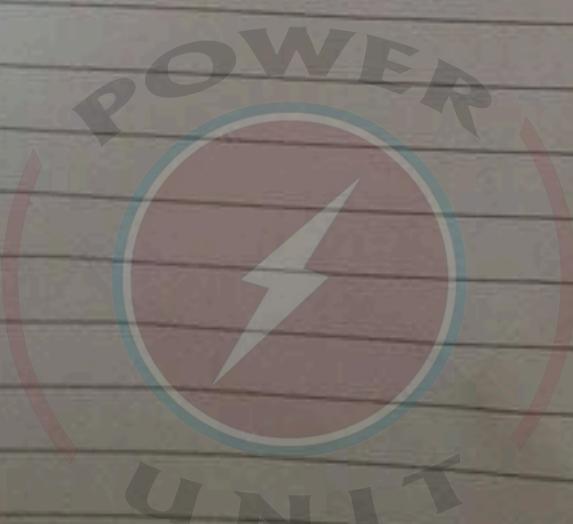
$$\Rightarrow I d\bar{l} = \rho_v \bar{u} d\bar{v} = \rho_v d\bar{v} \bar{u} = d\bar{q} \bar{u}$$

Hence,,,

$$d\bar{F}_m = d\bar{q} \bar{u} \times \bar{B}$$
$$= I d\bar{l} \times \bar{B}$$

$$\Rightarrow \bar{F}_m = \oint_L I d\bar{l} \times \bar{B}$$

→ Giving the force imposed on a conductor due to an external magnetic field.





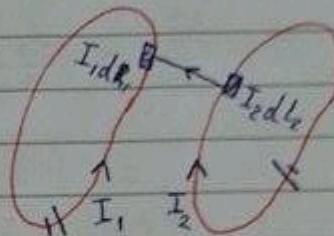
Force Between Two Current Elements

11-8-2014

monday

No. _____

$$d(dF_m) = \frac{\mu_0 I_1 I_2 d\vec{l}_1 \times d\vec{l}_2 \times \vec{a}_{R_1}}{4\pi R_{21}^2}$$



$$d(dF) = I_1 d\vec{l}_1 \times d\vec{B}_1 \quad \text{--- (1)}$$

See Examples in Book

EX 8.1

a charge particle of mass "2 kg" having a "3 C" charge at "(1, -2, 0)" with velocity "4ax + 3az" m/s in

an electric field "12ax + 10ay" V/m. at tim = "1 s" Find ?!

1-) The acceleration

2-) Velocity

3)

4-) The position

$$dB_1 = \frac{\mu_0 I_2 d\vec{l}_2 \times \vec{a}_{R_1}}{4\pi R_{21}^2} \quad \text{--- (2)}$$

$$d(dF_m) = \text{--- (2)} \text{ into (1)}$$

Sol. . .

$$1) F_e = Q \vec{E} = m \vec{a}$$

$$\vec{a} = \frac{Q \vec{E}}{m} = \frac{3}{2} (6ax + 10ay)$$

$$= [18ax + 15ay] \text{ ms}^{-2}$$

11-8-2014
Monday

2) $\vec{a} = \frac{d\vec{u}}{dt} = \frac{du_x}{dt} \vec{a}_x + \frac{du_y}{dt} \vec{a}_y + \frac{du_z}{dt} \vec{a}_z$
 $= 18 \vec{a}_x + 15 \vec{a}_y$

$$\Rightarrow \frac{du_x}{dt} = 18 \Rightarrow u_x = 18t + A$$
$$u_y = 15t + B$$
$$u_z = C$$

3) $u(t=0) = 4 \vec{a}_x + 3 \vec{a}_z = 4 \vec{a}_x + 0 \cdot \vec{a}_y + 3 \vec{a}_z$

$$8 \cdot 0 + A = 4 \Rightarrow A = 4$$

$$15 \cdot 0 + B = 0 \Rightarrow B = 0$$

$$C = 3$$

$$u(t) = (18t + 4) \vec{a}_x + 15t \vec{a}_y + 3 \vec{a}_z$$

$$u(t=1) = (18 + 4) \vec{a}_x + 15 \vec{a}_y + 3 \vec{a}_z$$

AE93

$$K.E = \frac{1}{2} m |\vec{u}|^2$$

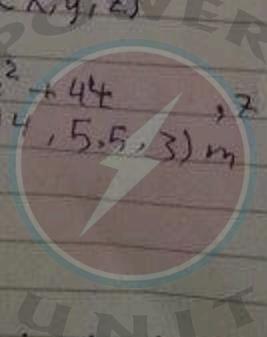
$$= \frac{1}{2} \times 2 \times (22^2 + 15^2 + 3^2)$$

$$= 718 J$$

4) Integrating the Velocity.

We obtain (X, Y, Z)

$$(X, Y, Z) = 9t^2 + 44, 15t, 3t$$
$$at(t=1) \Rightarrow (14, 15.5, 3) m$$



11-8-214

No. _____

EX 4.2 Study the example " See books"

end of second material

