

University of Jordan  
 College of Engineering & Technology  
 Department of Electrical Engineering  
 Fall Term - A.Y. 2015-2016



Digital Signal Processing, second exam,

sec. 1

Number of questions :5

Name:

Student Number:

Q1. A system is described by the difference equation

$$y[n] = x[n] - 2x[n - 6]$$

6

- a) Compute  $H(e^{j\omega})$  of the system.
- b) Determine the output of the system for the following input:

$$x[n] = 3 + 6 \cos\left(\frac{\pi}{3}n\right) + 5 \sin\left(\frac{2\pi}{5}n + \frac{\pi}{2}\right) \quad -\infty < n < \infty$$

a)  $H(e^{j\omega}) = \frac{Y(e^{j\omega})}{X(e^{j\omega})}$

$$Y(e^{j\omega}) = X(e^{j\omega}) - 2e^{-j6\omega} X(e^{j\omega})$$

$$Y(e^{j\omega}) = (1 - 2e^{-j6\omega}) X(e^{j\omega})$$

$$\therefore H(e^{j\omega}) = 1 - 2e^{-j6\omega}$$

$$e^{-j\frac{12\pi}{5}} = \cos\frac{12\pi}{5} - j\sin\left(\frac{\pi}{5}\right) = 1 \angle -\frac{2}{5}\pi = 1 \angle -72$$

$$e^{-j\frac{2\pi}{5}} = \cos\frac{2\pi}{5} - j\sin\frac{2\pi}{5} = +1$$

b)  $H(0) = 1 - 2 = -1$

$$H\left(\frac{\pi}{3}\right) = 1 - 2e^{-j\frac{6\pi}{3}} = 1 - 2e^{-j2\pi} = 1 - 2(+1) = -1$$

$$H\left(\frac{2\pi}{5}\right) = 1 - 2e^{-j\frac{6(2\pi)}{5}} = 1 - 2e^{-j\frac{12\pi}{5}} = 1 - 2(1 \angle -72) = 1.94 \angle 78.65$$

$$Y[n] = -3 - 6 \cos\left(\frac{\pi}{3}n\right) + 9.7 \sin\left(\frac{2\pi}{5}n + \frac{\pi}{2} + 78.65^\circ\right)$$

168.65

Q2. For the sequence  $x[n] = \{1, 2\}$ ,

- Find the  $D_2$  matrix.
- Find  $X[k]$ ,  $k = 0, 1$ . (The DFT of  $x[n]$ ).
- Find the  $D_2^{-1}$  matrix.
- Find the IDFT of  $X[k]$ .

$$a) D_2 = \begin{bmatrix} 1 & 1 \\ 1 & W_2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$W_2 = e^{-j\frac{2\pi}{N}} = e^{-j\pi} = \cos\pi - j\sin\pi = -1$$

$$b) X[k] = D_2 x[n]$$

$$= \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1+2 \\ 1-2 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$$

$\therefore X[k] = \{3, -1\}$ .

$$c) D_2^{-1} = \frac{1}{N} D^* = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & -1/2 \end{bmatrix}$$

$$d) x[n] = D_2^{-1} X[k]$$

$$= \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & -1/2 \end{bmatrix} \begin{bmatrix} 3 \\ -1 \end{bmatrix} = \begin{bmatrix} 3/2 - 1/2 \\ 3/2 + 1/2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\therefore x[n] = \{1, 2\} \#$$

$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j\frac{2\pi}{N}nk}$$

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j\frac{2\pi}{N}nk}$$

$$N=4$$

Q3. Let  $X[k]$ ,  $0 \leq k \leq 3$ , be a 4-point DFT of a 4-length real sequence  $x[n]$ , given by:

$$X[k] = \{ 6, -1-j, 0, -1+j \}$$

Evaluate the following functions of  $x[n]$  without computing the IDFT of  $X[k]$ :

- a)  $x[0]$     b)  $x[2]$     c)  $\sum_{n=0}^3 x[n]$     d)  $\sum_{n=0}^3 e^{j\pi n} x[n]$     e)  $\sum_{n=0}^3 |x[n]|^2$

a)  $x[0] = \frac{1}{N} \sum_{k=0}^3 X[k] W_N^{0k}$

$= \frac{1}{4} \sum_{k=0}^3 X[k] = \frac{1}{4} [6 - 1 - j + 0 - 1 + j] = \frac{4}{4} = 1$

b)  $x[2] = \frac{1}{N} \sum_{k=0}^3 X[k] W_N^{2k}$

$= \frac{1}{4} \sum_{k=0}^3 X[k] (-1)^k$   
 $= \frac{1}{4} [6 + -1(-1-j) + 0 + -1(-1+j)]$   
 $= \frac{1}{4} [6 + 1 + j + 1 - j] = \frac{8}{4} = 2$

$W_N = e^{-j\frac{2\pi}{N}}$   
 $W_N^{-2k} = e^{j\frac{2\pi}{4} \cdot -2k}$   
 $= e^{j\pi k}$   
 $= \cos(k\pi) + j\sin(k\pi)$   
 $= (-1)^k$   
 $e^{j\frac{2\pi}{4}(2)k} = e^{j\pi k} \checkmark$

c)  $X[0] = \sum_{n=0}^3 x[n] W_N^{0n}$   
 $\therefore \sum_{n=0}^3 x[n] = X[0] = 6$

$\frac{-\pi}{2} k = \pi$   
 $\therefore k = -2$

d)  $X[k] = \sum_{n=0}^3 x[n] e^{-j\frac{2\pi}{4}nk}$

$X[k] = \sum_{n=0}^3 x[n] e^{-j\frac{\pi}{2}nk}$

$\therefore \sum_{n=0}^3 e^{j\pi n} x[n] = X[-2] = 0!$  (not defined  $0 < k < 4$ )

$-1-j = \sqrt{2} \angle -135$   
 $-1+j = \sqrt{2} \angle 135$

e)  $\sum_{n=0}^3 |x[n]|^2 = \frac{1}{4} \sum_{k=0}^3 |X[k]|^2$   
 $= \frac{1}{4} (6^2 + (\sqrt{2})^2 + 0 + (\sqrt{2})^2)$   
 $= 10$



Q5. The transfer function of a causal LTI discrete-time system is given by

$$H(z) = \frac{0.5 - 0.3z^{-1}}{1 + 0.3z^{-1}}$$

- a) Determine the impulse response  $h[n]$  of the system.  
 b) Determine the output of the system  $y[n]$  if the input  $x[n] = (0.2)^n \mu[n]$ .

$$\frac{1 + 0.3z^{-1}}{1 + 0.3z^{-1}} \left[ \frac{-1}{0.5 - 0.3z^{-1}} - \frac{-1}{-1 - 0.3z^{-1}} \right] = \frac{1.5}{1 + 0.3z^{-1}}$$

$$\Rightarrow \mathcal{Z}^{-1} \{ H(z) \} = -1 + \frac{1.5}{1 + 0.3z^{-1}}$$

$$h[n] = -\delta[n] + 1.5(-0.3)^n \mu[n]$$

$$b) x(z) = \frac{1}{1 - 0.2z^{-1}}$$

$$Y(z) = H(z) \cdot X(z) = \left( -1 + \frac{1.5}{1 + 0.3z^{-1}} \right) \frac{1}{1 - 0.2z^{-1}}$$

$$= \frac{-1}{1 - 0.2z^{-1}} + \frac{1.5}{(1 + 0.3z^{-1})(1 - 0.2z^{-1})} = \frac{-1}{1 - 0.2z^{-1}} + \frac{A_1}{(1 + 0.3z^{-1})} + \frac{A_2}{(1 - 0.2z^{-1})}$$

$$A_1 \Big|_{z = -\frac{10}{3}} = \frac{1.5}{1 - 0.2 \left( -\frac{10}{3} \right)} = \frac{9}{10} = 0.9$$

$$A_2 \Big|_{z = 5} = \frac{1.5}{1 + 0.3(5)} = \frac{3}{5} = 0.6$$

$$\therefore Y(z) = \frac{-1}{1 - 0.2z^{-1}} + \frac{0.9}{1 + 0.3z^{-1}} + \frac{0.6}{1 - 0.2z^{-1}}$$

$$y[n] = -(0.2)^n \mu[n] + 0.9(-0.3)^n \mu[n] + 0.6(0.2)^n \mu[n]$$

Q5. The transfer function of a causal LTI discrete-time system is given by

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 b) Determine the output of the system  $y[n]$  if the input  $x[n] = (0.2)^n \mu[n]$ .

$$\frac{1 + 0.3z^{-1}}{1 + 0.3z^{-1}} \left[ \frac{0.5 - 0.3z^{-1}}{-1 - 0.3z^{-1}} \right] = \frac{-1}{1.5 \quad 0}$$

$$\Rightarrow \cancel{H(z)} \quad H(z) = -1 + \frac{1.5}{1 + 0.3z^{-1}}$$

$$h[n] = -\delta[n] + 1.5(-0.3)^n \mu[n]$$

b)  $x(z) = \frac{1}{1 - 0.2z^{-1}}$

$$Y(z) = H(z) \cdot X(z)$$

$$= \left( -1 + \frac{1.5}{1 + 0.3z^{-1}} \right) \frac{1}{1 - 0.2z^{-1}}$$

$$= \frac{-1}{1 - 0.2z^{-1}} + \frac{1.5}{(1 + 0.3z^{-1})(1 - 0.2z^{-1})} = \frac{-1}{1 - 0.2z^{-1}} + \frac{A_1}{(1 + 0.3z^{-1})} + \frac{A_2}{(1 - 0.2z^{-1})}$$

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$$y[n] = - (0.2)^n \mu[n] + 0.9 (-0.3)^n \mu[n] + 0.6 (0.2)^n \mu[n] \quad \neq$$