



# Com Systems Notes

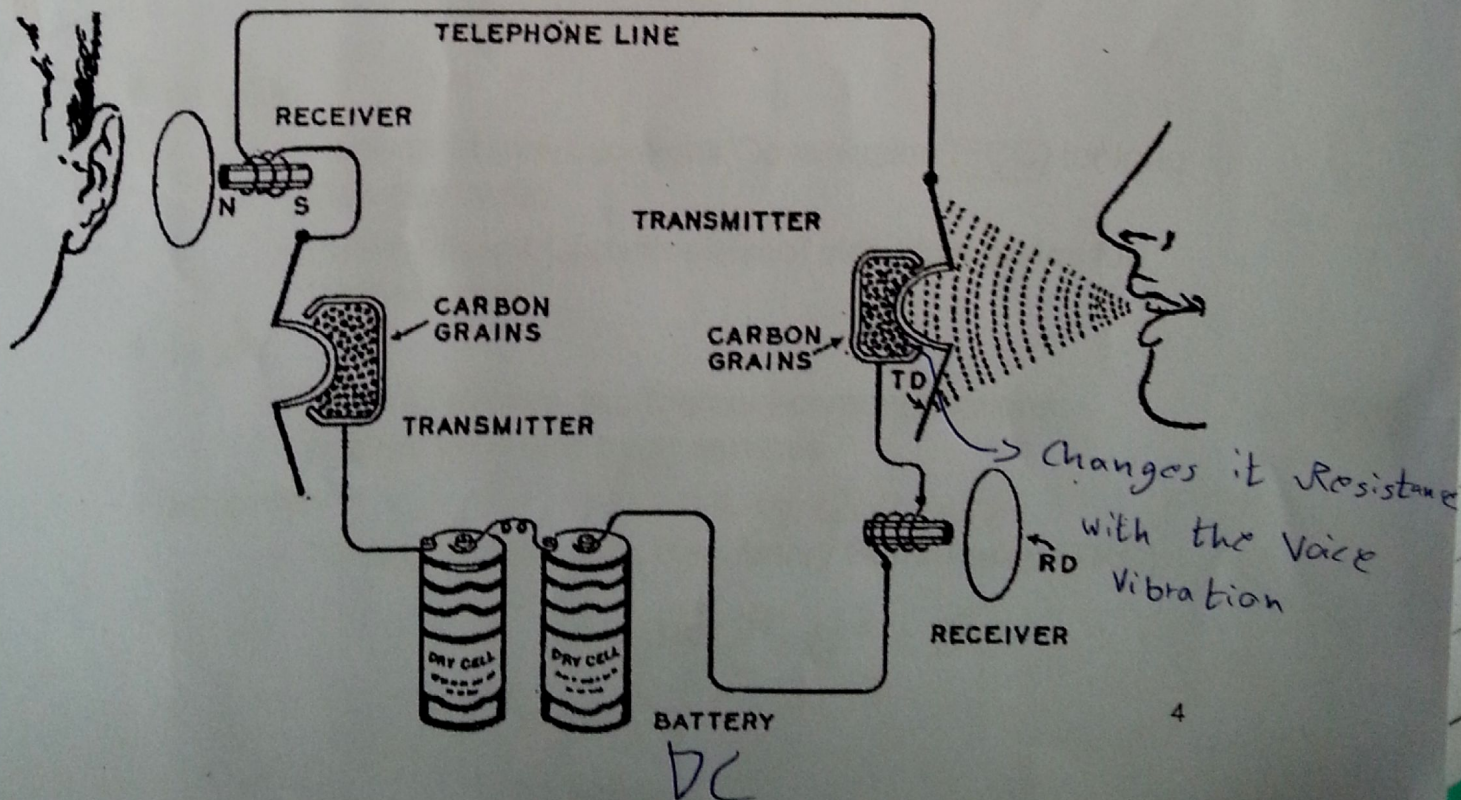


**DR . RABED ALZOBIE**  
**BY : YAMMAN KHTOUM**



# Analog Telephone Network

## Telephone Circuit

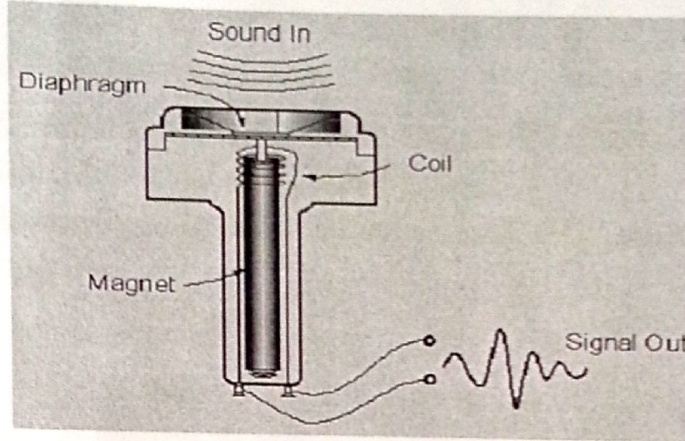




# The First Telephone

- In 1876, Alexander Graham Bell made the first Telephone, called the Bell Telephone
- The same equipment is used at TX and RX

*without Carbon Grains*



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*1876 → Alex Gram Bell*

*Yamena*

## Telecommunications Regulations

*Yamena*

- In USA
  - » Federal Communications Commission (FCC) for long distance traffic
  - » Public utilities Commissions of individual states for local services
- In UK
  - » British Telecom and Mercury communications provide local and trunk services
- In Jordan
  - » Telecommunications Regulatory Commission (TRC)

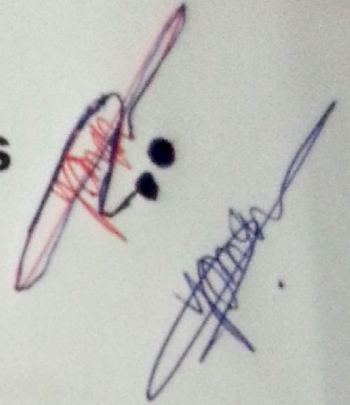
*↳ Long Distance*

*هيئة تنظيم الاتصالات*

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# Telecommunications Standard Organizations



- In North America:
- Bell Telephone Laboratories and Western Electric.
- The US Telephone Association (USTA).
- Exchange carriers standards Association (ECSA).
- Electronic Industries Association (EIA).
- Institute of Electrical and Electronic Engineers (IEEE). *→ makes too many standards*
- Bell communications Research (Bellcore).
- The Federal communications commission (FCC): controls the radio spectrum in USA.

*research*

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**TABLE 1.2 IEEE Local Area Network/Metropolitan Area Network (LAN/MAN) Data Communications Standards**

*important for the manufacturer and the researcher*

IEEE 802.1	Overview and Architecture, Bridging, Virtual bridged LAN (VLAN)
802.2	Logical Link Control (LLC)
802.3	Carrier Sense Multiple Access (CSMA) with Collision Detection (CD) (Ethernet)
802.4	Token Bus (Arcnet)
802.5	Token Ring (IBM Ring)
802.6	Queued Packet Synchronous Exchange (QPSX)
802.7	Broadband
802.8	Optical Fiber Technologies
802.9	Integrated Services
802.10	Security
802.11	Wireless
802.12	Demand Priority
802.14	Cable TV

*can be found on the internet*

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America → IEEE  
world → ITU

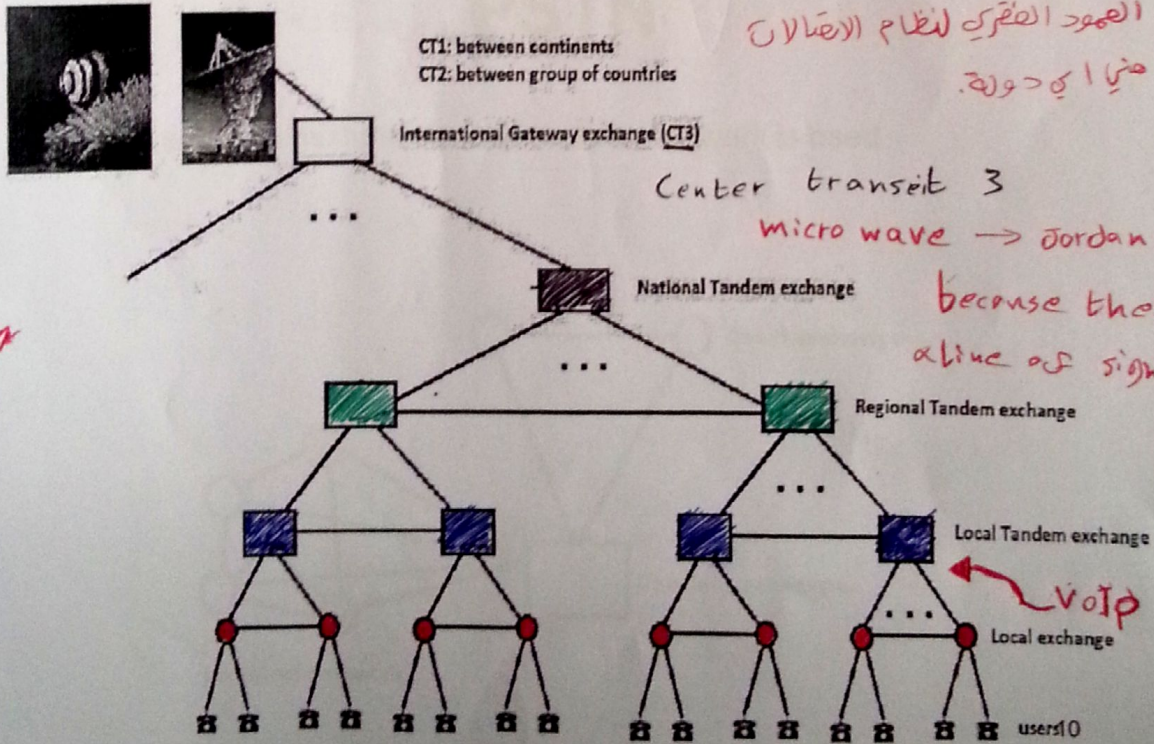
# Telecommunications Standard Organizations

- Outside North America:
- The International Telecommunication union (ITU):
  1. International Telegraph and Telephone Consultative committee (CCITT, now ITU-T): established recommendations for telephone, telegraph, and data transmission circuits and Equipments.
    - French word FAX → wire
  2. International Radio consultative committee (CCIR, now ITU-R): coordinating the use of the radio spectrum.

Radio waves

→ wireless

## Public Switched Telecommunication (Telephone) network- PSTN









# Terminology

↳ not for memorize

USA	UK (Jordan)
Customer loop	Local network
Central office	Exchange
End office	Local exchange
Inter-office trunk	Junction
Junctor	Trunk
Toll office	Trunk exchange
Toll network	Trunk network

الد  
عاشق

↳

toll quality → enough quality to be connected over long distance

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## The Analog Network Hierarchy

- **Bell System Hierarchy:**
- Alexander Graham Bell invented the first practical Telephone in 1876.
- **Central office (or end offices):** switching office in the center of a service area.
- **Trunks** were used between the central offices.
- The analog public telephone network in the United States evolved to a total of five levels.

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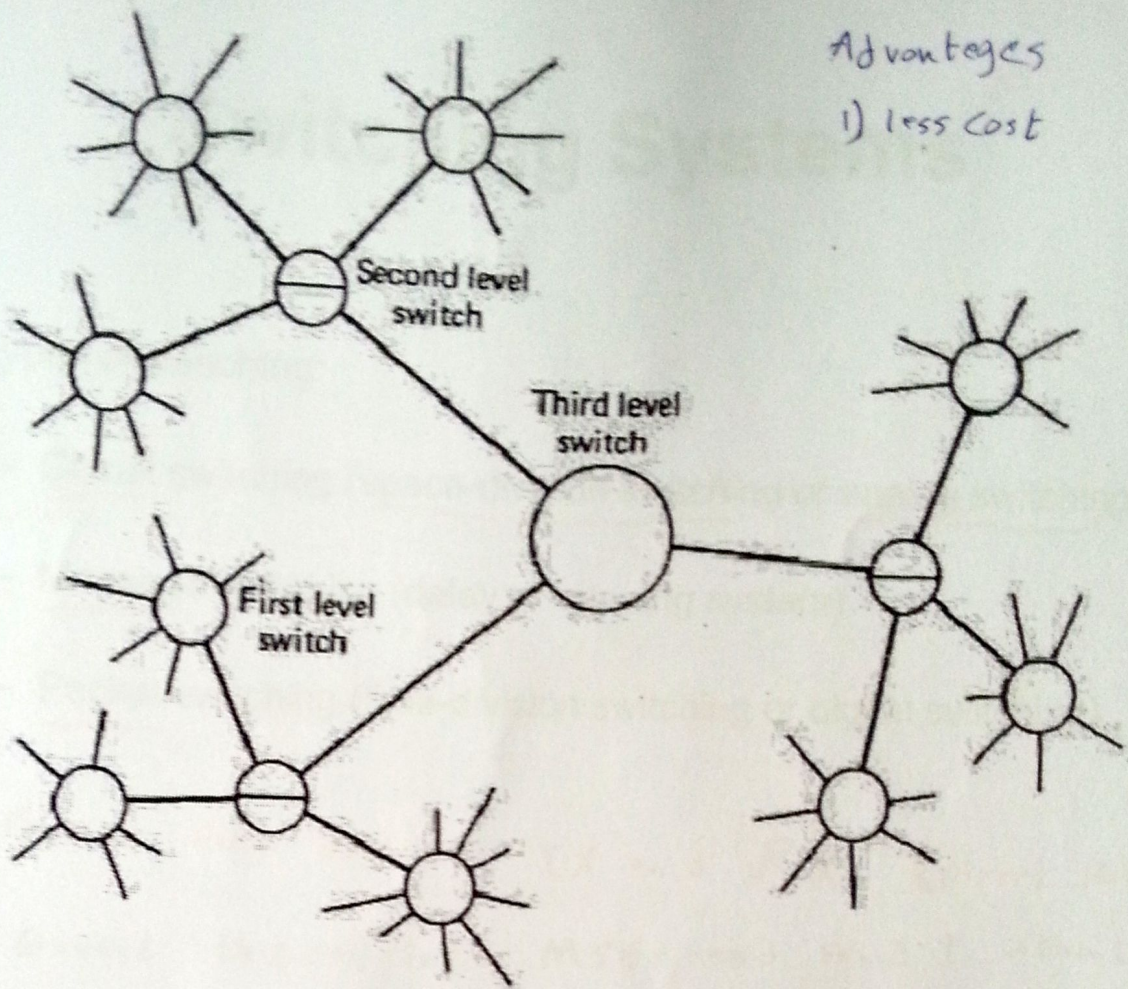
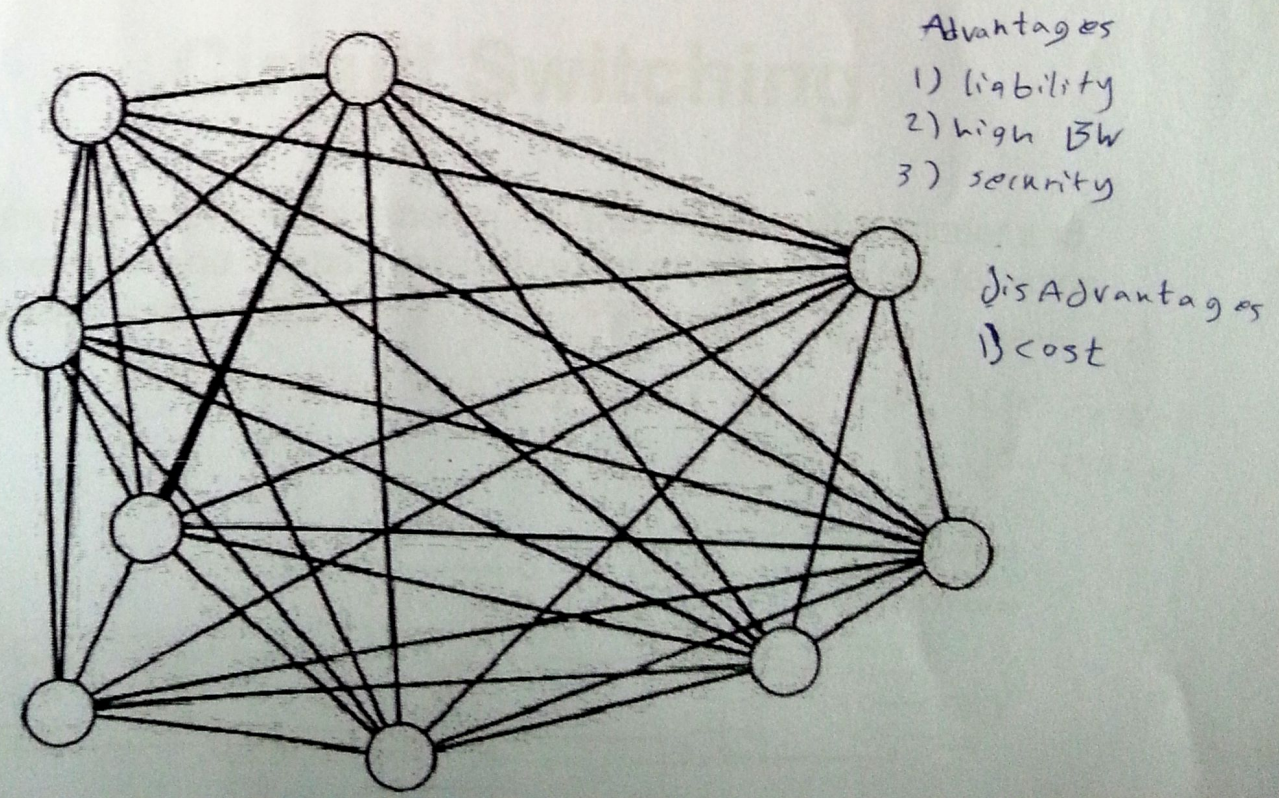


Figure 1.2 Three-level switching hierarchy.





# Switching Systems

- Types of switching:

- Circuit switching (space-division switching or analog switching)

- Message switching (delay or queuing system)

- Packet switching (time-division switching or digital switching)

→ physical path between TX and RX (direct path)

→ Convert the call into MSGs and send it without a direct path → we need a BW Available. (long MSG is divided into shorter MSGs)

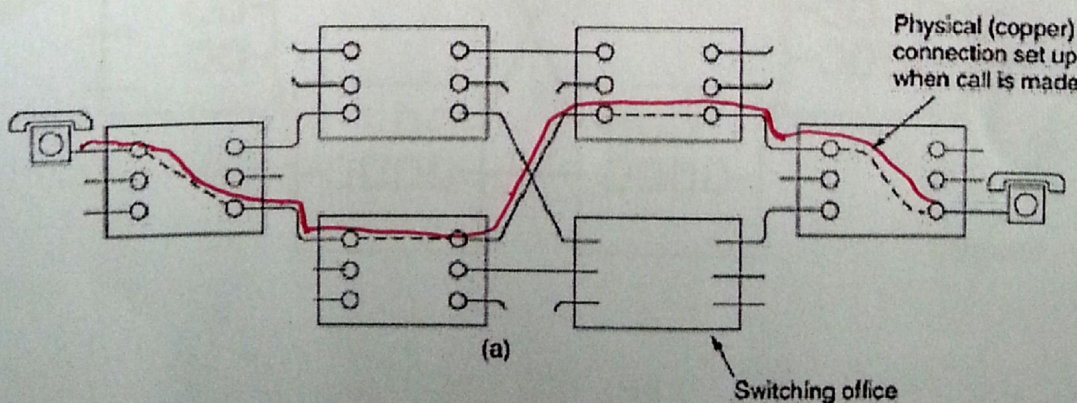
→ Divide the MSG into a fixed packets of Data and send it through the office → TDM

## Circuit Switching

- A physical path is established in advance between the sender and the receiver and this path is reserved for only one call (so, for voice network)

\* BW Reliability is Bad → (these moments)

\* Utilization of BW is Bad → Use Packet Switching



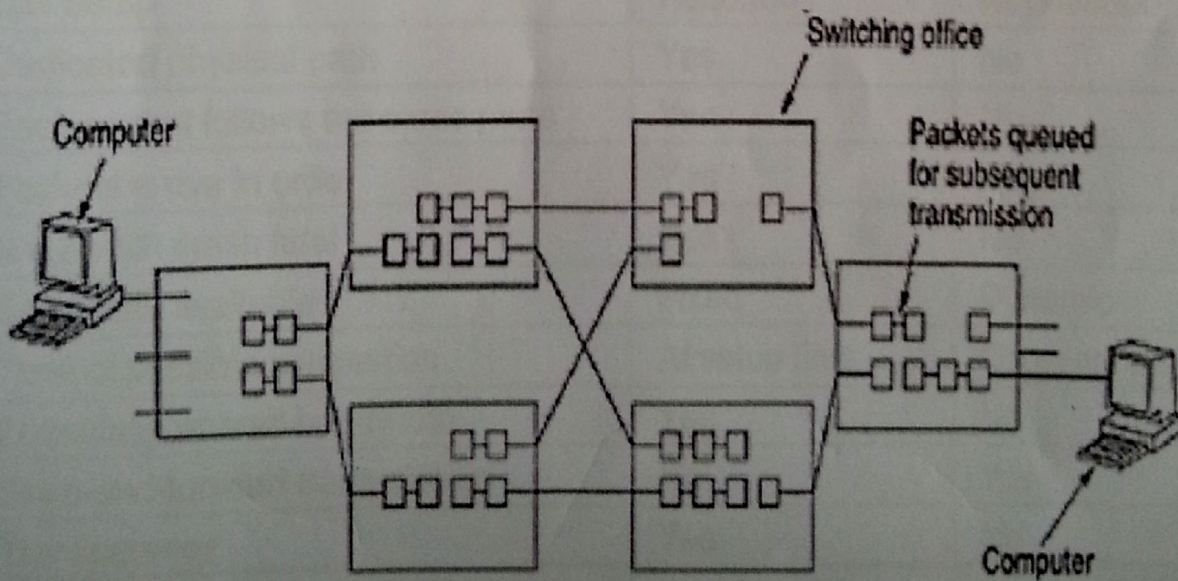


# Packet Switching

- Dividing the long messages into packets is useful to solve the problem of queuing messages with different lengths
- Used in internet
- Developed in 1969 by ARPANET (Advanced Research Projects Agency). So, ARPANET was the pioneer to today's Internet
- The Department of Defense wanted a more reliable network with route diversity capability. In a national emergency such as the September 11, 2001 attacks in the United States on the Pentagon in Washington, DC, and the World Trade Center in New York City, the Internet still functioned when many portions of the public voice and cellular networks were either out of service or so overwhelmed with traffic that people could not make calls → because the internet doesn't need a direct physical path → it just need a Routing ways to send / Receive the packets

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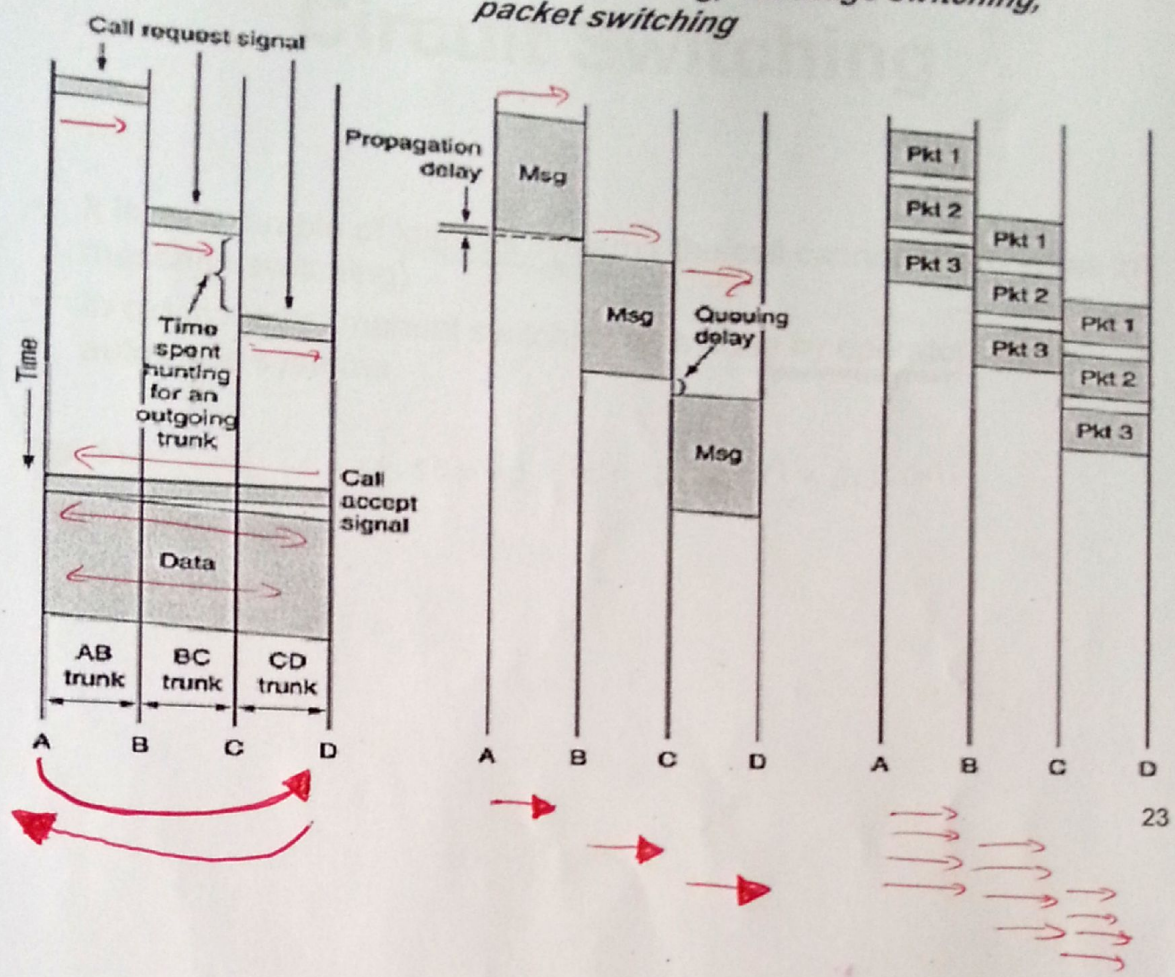
# Packet Switching



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Timing of events in circuit switching, message switching, packet switching

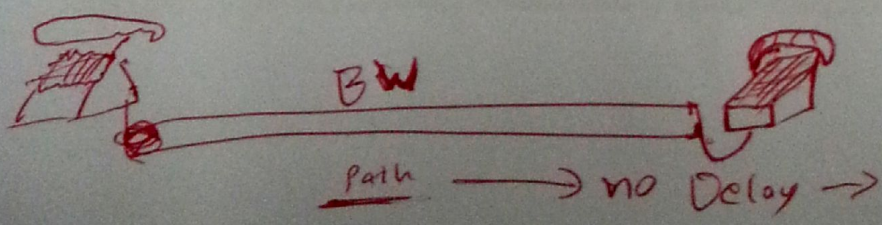


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\* in packet switching → the Application layer is responsible of re arranging the received ~~signal~~ packets and deliver it to the user

Item	Circuit switched	Packet switched
Call setup	Required	Not needed*
Dedicated physical path	Yes	No
Each packet follows the same route	Yes	No
Packets arrive in order	Yes	No
Is a switch crash fatal	Yes	No
Bandwidth available	Fixed	Dynamic
Time of possible congestion	At setup time	On every packet
Potentially wasted bandwidth	Yes	No
Store-and-forward transmission	No	Yes
Transparency	Yes	No
Charging	<u>Per minute</u>	Per packet

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TU transmission over packets



# Circuit Switching

- It is an example of lost-call system ( the call cannot be stored as in message switching)
- In old systems: manual switching was done by operator. Then, automatic systems.

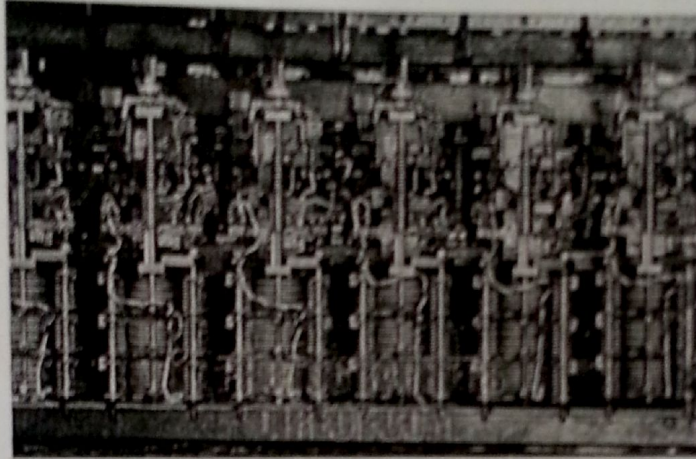
the call is not stored it's Live Audio call



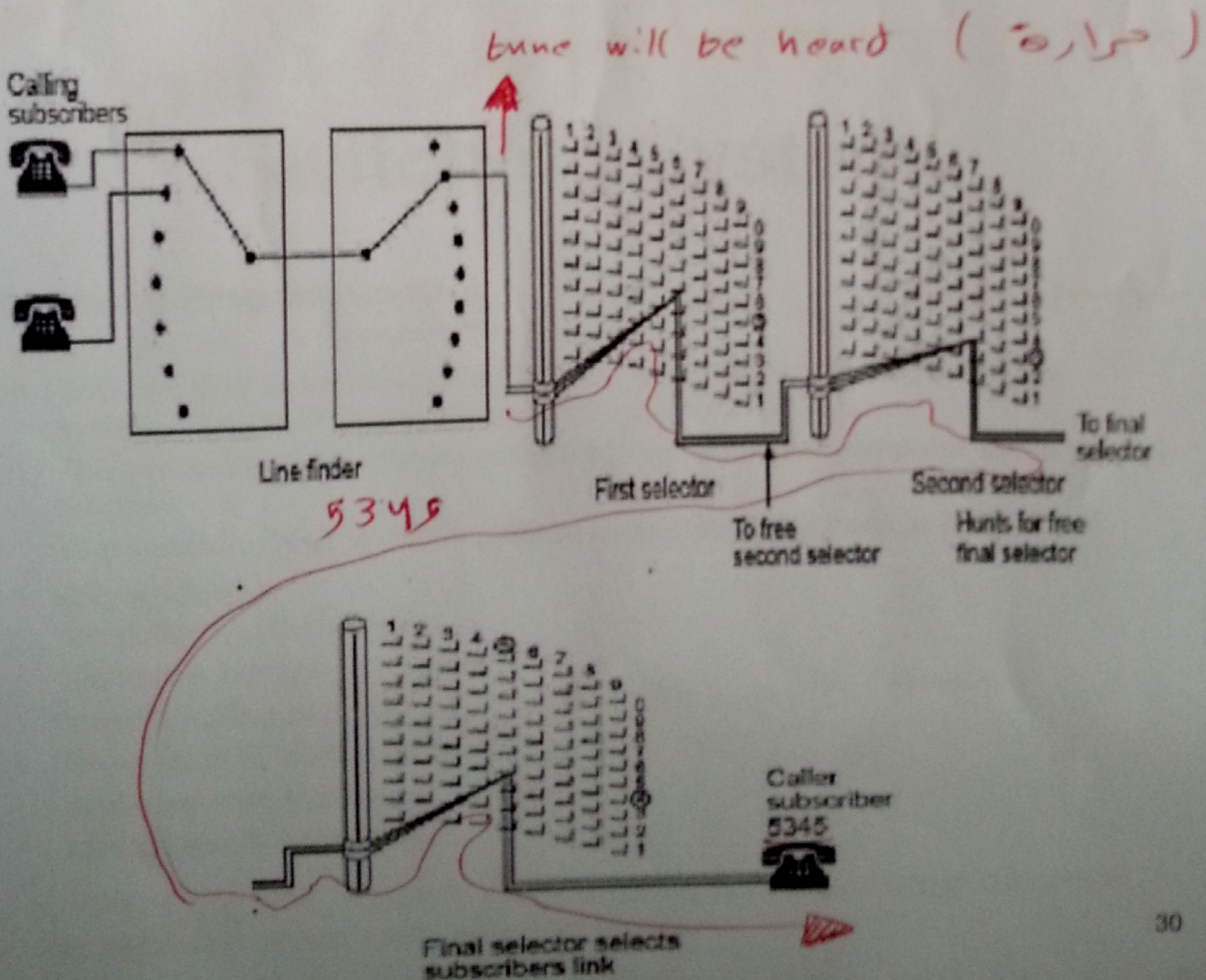
# Switching Systems

- Step-by-step switching system:
- Uses the two-motion selector which was invented by Almon B. Strowger
- Had a lifetime of nearly 100 years
- It is the first automated switching system

*After operators*



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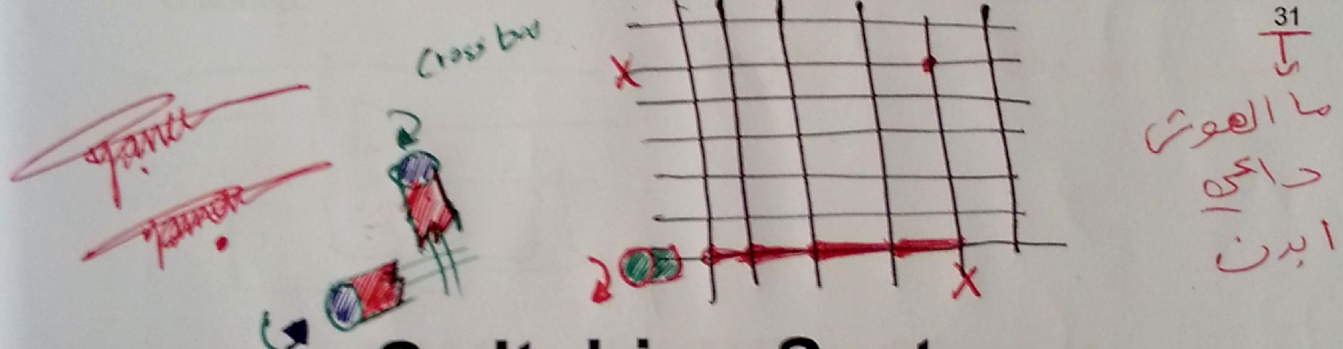
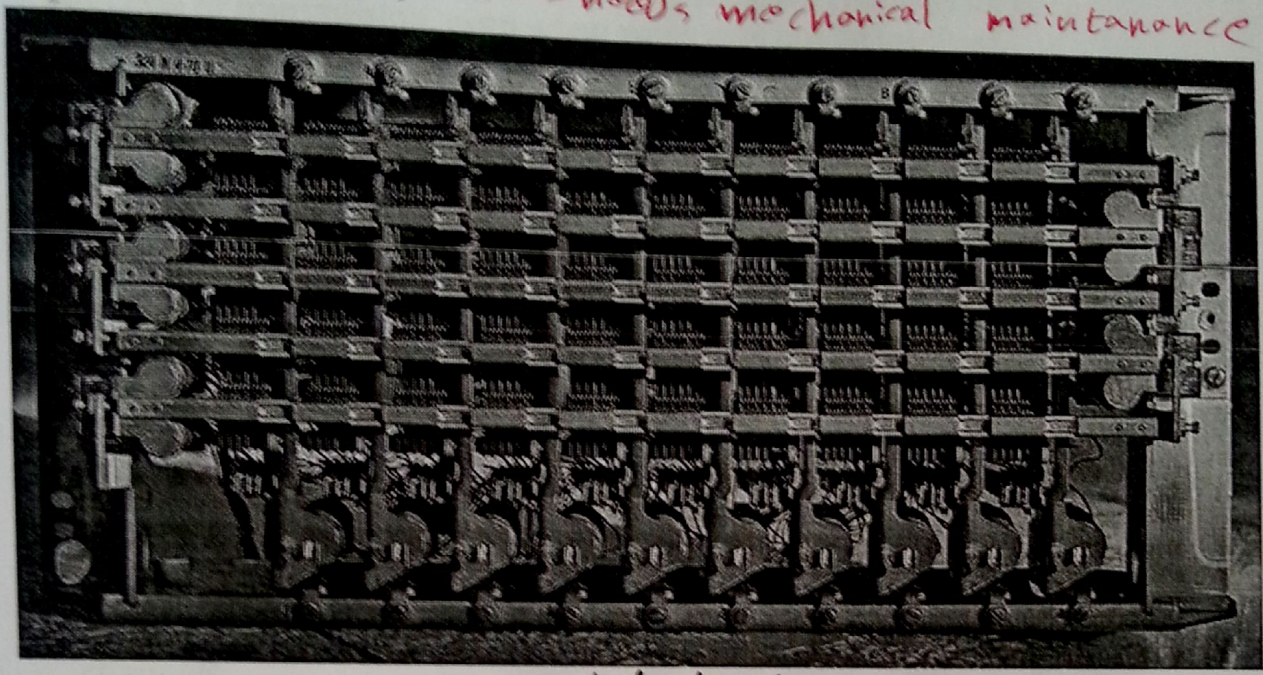


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# Switching Systems

Crossbar Switching System → needs mechanical maintenance



## Switching Systems

### b) Stored Program Control:

→ Control is computerized But the matrix Cross point was still ~~still~~ mechanical

In 1965: the Bell System installed the first computer-controlled switching system: The No.1 Electronic Switching System (ESS)

- This switching system uses a stored-program digital computer for its control function.
- The switching matrix of this system uses electromechanical reed relays
- Advantages:
- Simplified maintenance.
- Made number changes easy.
- lower blocking probabilities. → "Network Busy"
- Generation of traffic statistics.
- Automatic call tracing.
- Message unit accounting.

In 1976: AT&T's No. 4 ESS is a high-capacity switch used computer control and digital electronics for its switching matrix.

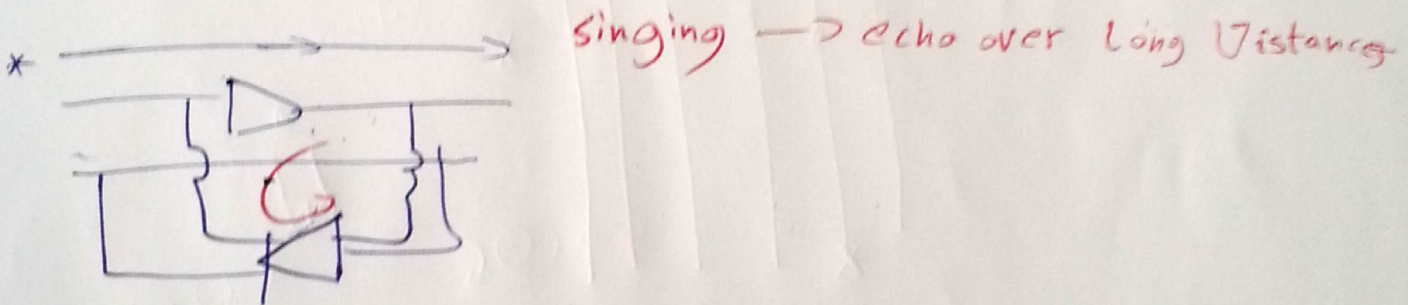
All computer Based controlled



# Four-wire System

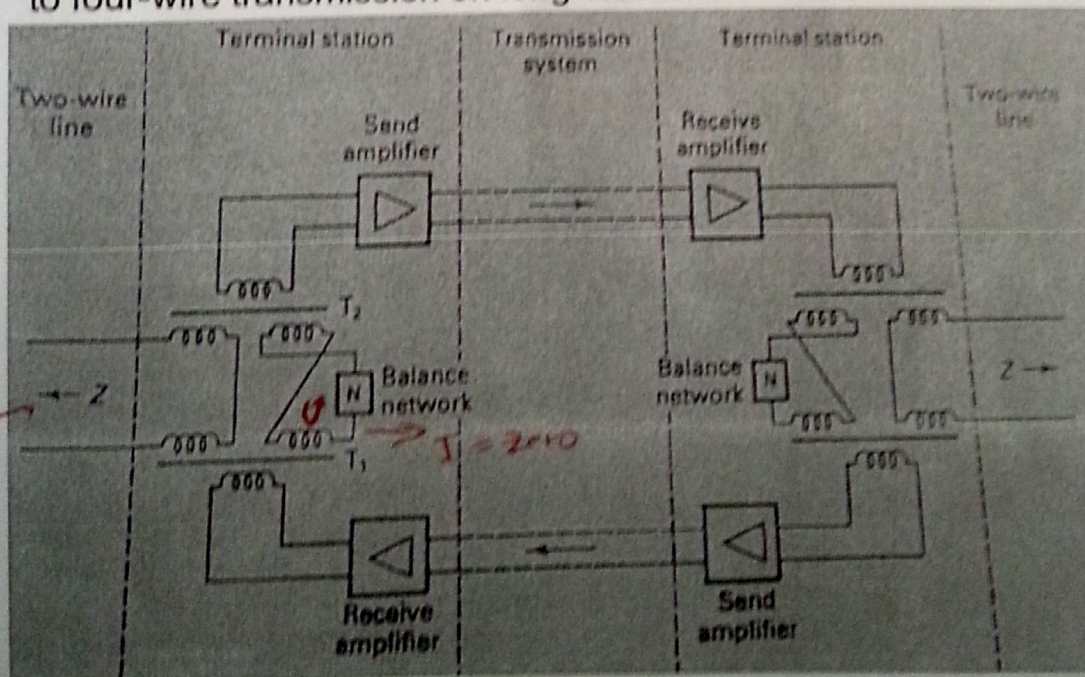
- The term four-wire has evolved to imply separate channels for each direction of transmission, even when wires may not be involved.
- For example, fiber optic and radio systems that use separate channels for each direction are also referred to as four-wire systems.
- Long distance transmission requires amplification and most often involves multiplexing.
- These operations are implemented most easily if the two directions of transmission are isolated from each other.
- Thus interoffice trunks typically use two pairs of wires or two fibers and are referred to as four-wire systems.
- a net savings in copper could result from multiplexing more channels.

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## 2-Wire / 4-Wire Circuit

- It is necessary to convert from two-wire transmission of local loops to four-wire transmission on long-distance trunks.

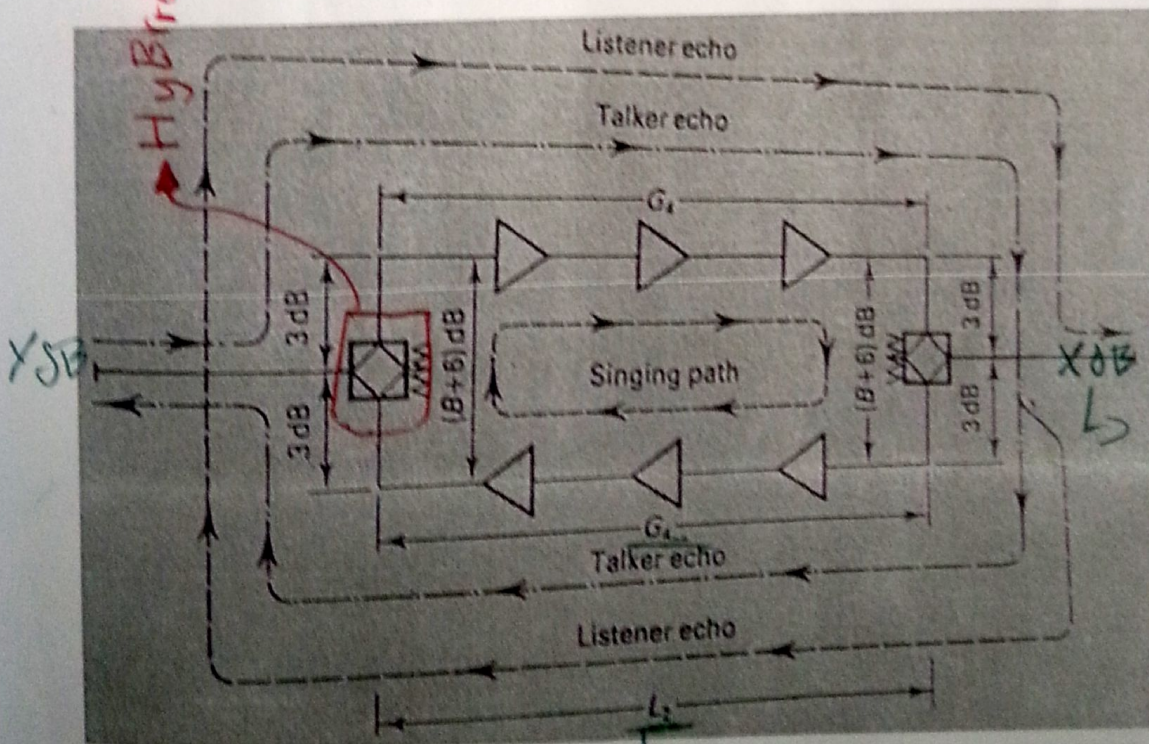


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# 2-wire / 4-wire circuit

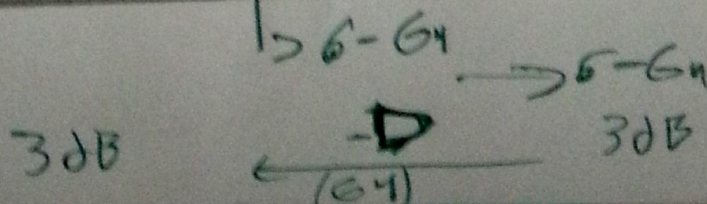
Hybrid transformer



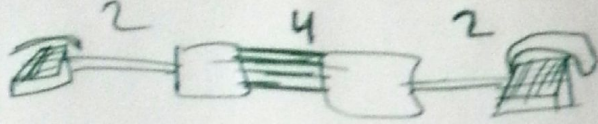
Power at Y

$$Y = X - 6 + G_4$$

$$= X + G_4 - 6$$







## 2-wire / 4-wire circuit

↗ In case of mismatch between  $N$  and  $Z$

- Total attenuation from one two-wire circuit to the other is

$$L_2 = 6 - G_4$$

- Transhybrid loss (TL): is the attenuation through the hybrid transformer from one side of the 4-wire circuit to the other.

$$TL = 6 + B \text{ dB}$$

$$B = 20 \log \left| \frac{N + Z}{N - Z} \right| \text{ dB} \quad \rightarrow N = Z \rightarrow \infty \text{ loss} \rightarrow \text{no echo}$$

22.5ms is the Max accepted Delay 37

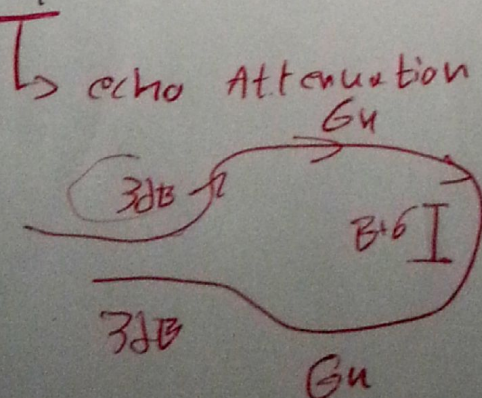
~~to~~

## 2-wire / 4-wire circuit

- B: balance return loss due to impedance mismatch between 2-wire line and the balance network
- Z: impedance of the 2-wire line
- N: impedance of the balance network

- The attenuation of the echo that reaches the talker's 2-wire line

$$L_t = 3 - G_4 + (B + 6) - G_4 + 3 = 2L_2 + B \text{ dB}$$





# 2-wire / 4-wire circuit

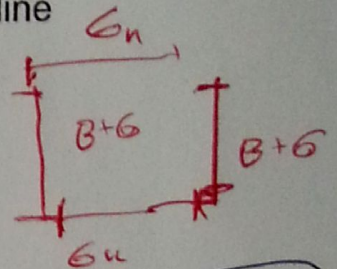
صوت مرئى

- The attenuation of the echo that reaches the listener's 2-wire line

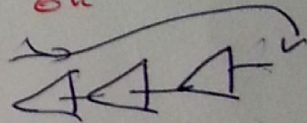
بیشتر شود

should be huge

$$L_1 = (B + G) - G_4 + (B + G) - G_4 = 2L_2 + 2B \text{ dB}$$



- We can control echo by applying loss when  $2T_4 < 45 \text{ msec}$  (increasing  $L_2$  by increasing the length but this increases delay)



want  $L_1$   $L_2$  to be big  $\rightarrow$  high loss of echo  
 $L_1$

Attenuation  
 by length  
 in the  
 echo/listener  
 path

$\rightarrow L_1 = 2L_2 + 2B \rightarrow$  increase the line length

\* can't add resistance because that will change the coaxial cable characteristics

\* limitation  $\rightarrow$  if the delay is less than  $22.5 \text{ ms}$   $\rightarrow$  then it's ok, your ears won't tell the difference

# 2-wire / 4-wire circuit

- Connections that produce more than 45 msec of roundtrip delay (representing 1800 miles of wire) require more attenuation for echo control than can be tolerated in the forward path. In these cases one of two types of devices was used to control the echo:

1. Echo suppressor
2. Echo canceller.

\* Amplifying the signal



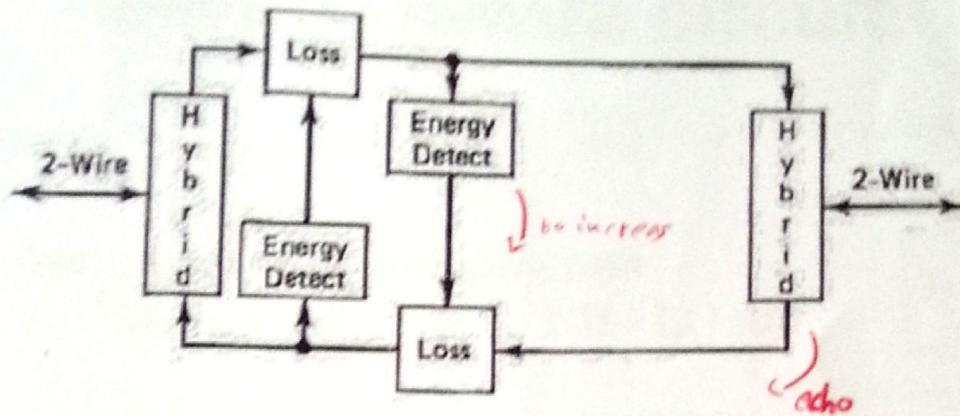


Figure 1.29 Echo suppressor.

- \* if the two (talker/listener) talk at the same time we'll face a problem
- One drawback of echo suppressor was that they might clip beginning portions of speech segments. If a party at one end of a connection begins talking at the tail end of the other party's speech.

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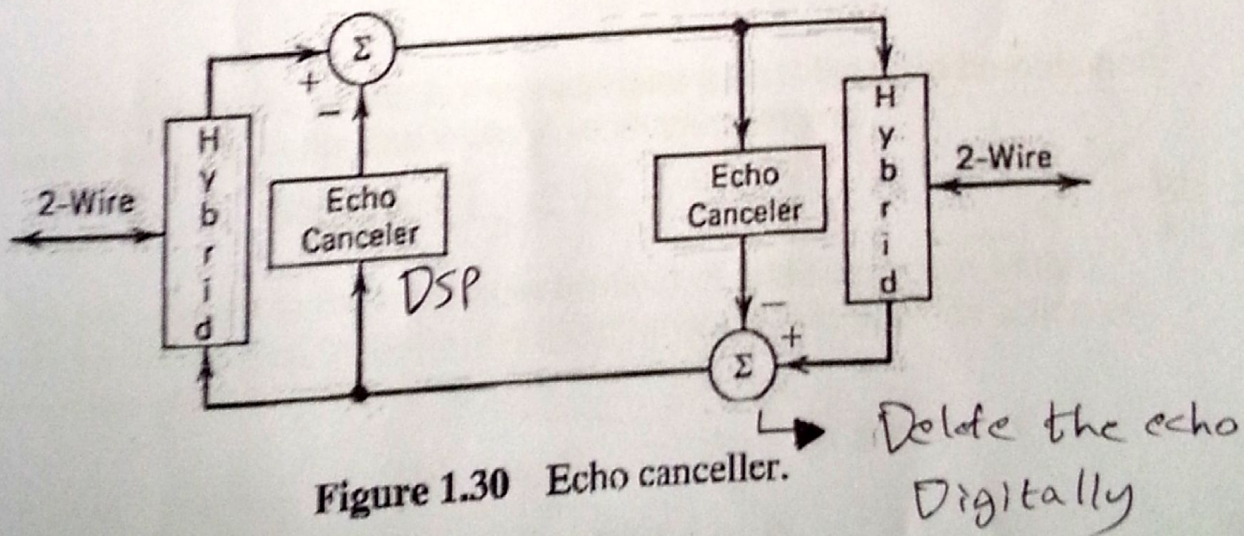


Figure 1.30 Echo canceller.

- It is better than echo suppressor.
- Because the cost of digital signal processing (DSP) technology has dropped so dramatically, echo cancellers are now used in any situation requiring echo control.

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# 2-wire / 4-wire circuit

- **Stability:** echo cancellation on) to prevent it from circulation

The net loss of the singing path

$$L_s = 2(B + \delta - G_4) \text{ dB} = 2(B + L_2) \text{ dB}$$

*singing*

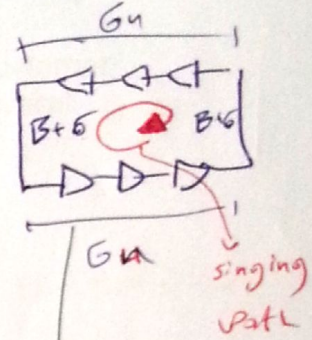
The necessary condition for stability is

$$L_s > 0$$

$$L_2 + B > 0$$

$$-L_2 < B$$

$$G_2 < B \rightarrow \text{then it's stable}$$



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# 2-wire / 4-wire circuit

- Singing point of a circuit is the maximum gain  $S$  that can be obtained from 2-wire to 2-wire line without producing singing

From  $G_2 < B$ ,  $S = B$

- Stability margin is the maximum amount of additional gain  $M$  that can be introduced (equally and simultaneously) in each direction of the transmission without causing singing

$$L_s - 2M = 0$$

$$2(B + L_2) - 2M = 0$$

$$M = B + L_2 \text{ dB}$$

الآن  
والآن

M

must be known

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in the Exam



# Telephone System

- A rating system was standardized by CCITT to grade a customer satisfaction is called Overall Loudness Rating (OLR) or Overall Reference Equivalent (ORE) in dB

$$ORE = TRE + RRE + \text{losses} \quad \text{dB}$$

*-ve value → Better than the Reference*

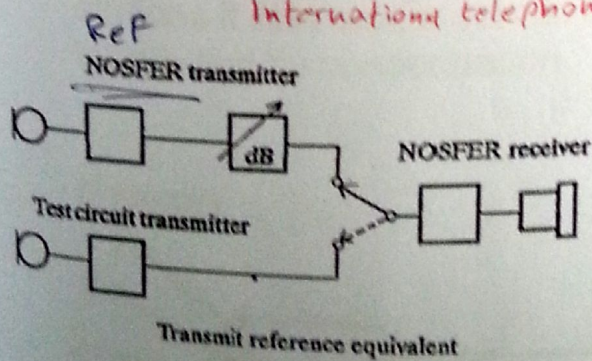
- TRE: transmit reference equivalent
- RRE: receive reference equivalent
- ve dB: the system is better than the reference

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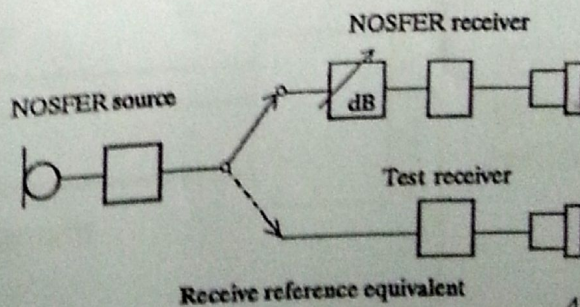
## Transmission Performance In Telephone System

- TRE and RRE is measured using a reference system called NOSFER in ITU lab in Geneva

*International telephony Union: to standardize the telephones manufacturing. (Reference)*



TRE

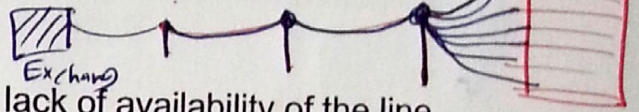


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# Pair-Gain Systems

- In the past, a common means of reducing the cost was to use party lines, which involves sharing of a wire pair among multiple households.



- But due to the lack of privacy and the lack of availability of the line, the pair-gain system was used as a solution.

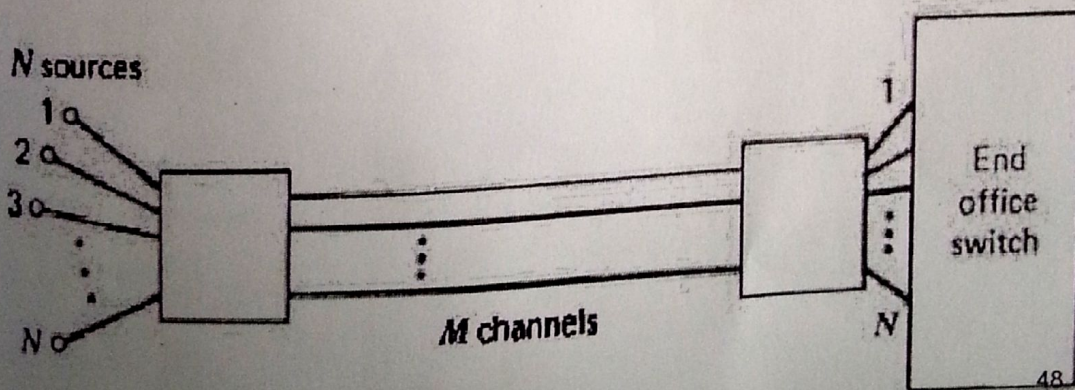
- Basic types of pair-gain systems:**

- concentrators (remote switches)
- multiplexers (carrier systems)

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# Pair-Gain Systems

- Concentrator**
- Since a concentration is in capable of simultaneously connecting all stations it services, a certain amount of blocking is necessarily introduced by concentration



$$M < N$$

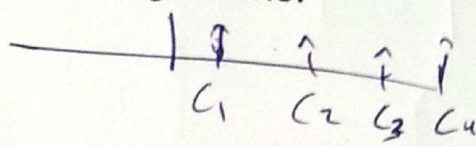
\* Good in privacy

\* → Blocking Probability → less than Party lines

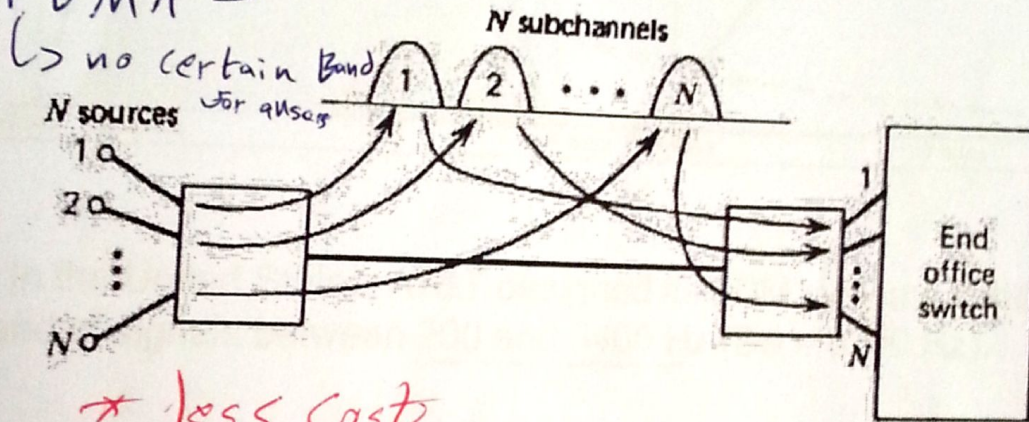


# Pair-Gain Systems

- **Multiplexing:**
- Space division multiplexing involves nothing more than bundling more than one pair of wires into a single cable.
- FDM  $\rightarrow$  Carriers
- In digital systems (TDM)



CDMA  $\rightarrow$  in cell  
 OFDMA  $\rightarrow$  in cell

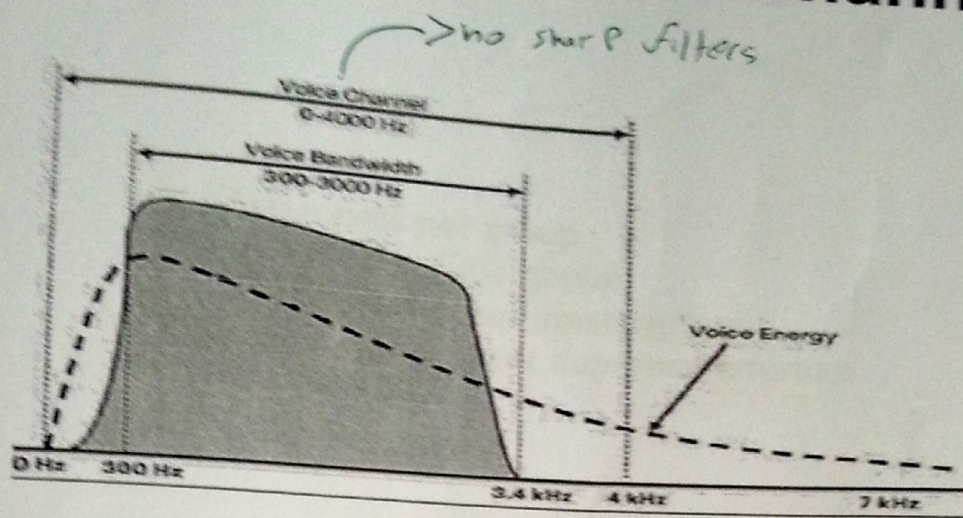


\* less cost

\* less blocking probability



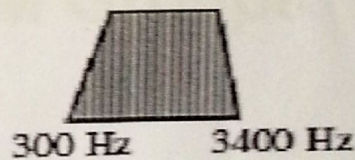
# 4 KHz Human Voice Channel



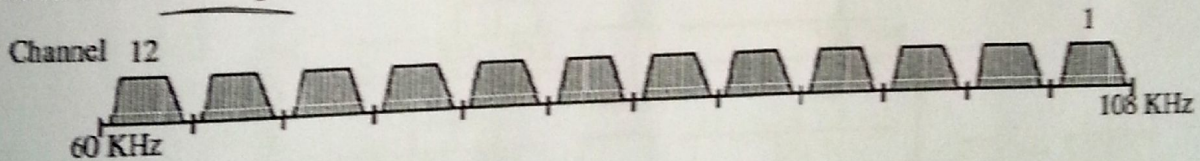
Note: In the United States, AT&T designed its FDM systems to handle the band of signals between 200 and 3400 Hz ( $B_w = 3200 \text{ Hz}$ ).

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## A Single Voice Channel [SSB]



## A 12 Channel Group



- 900 Hz guardband between channels
- Single Sideband suppressed carrier modulation SSB

1) Less power in transmission ← Less power Utilization

2) less Bandwidth

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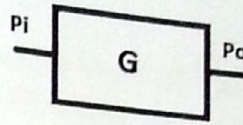


# Power Levels

$$G = 10 \log \frac{P_o}{P_i} \text{ dB}$$

$$G = 10 \log \frac{P_o}{1 \text{ mW}} \text{ dBm}$$

$$G = 10 \log \frac{P_o}{1 \text{ W}} \text{ dBW}$$



Handwritten notes:

$$1 \text{ dB} = 10 \log \frac{x}{y}$$

$$\frac{1}{10} = \log \frac{x}{y}$$

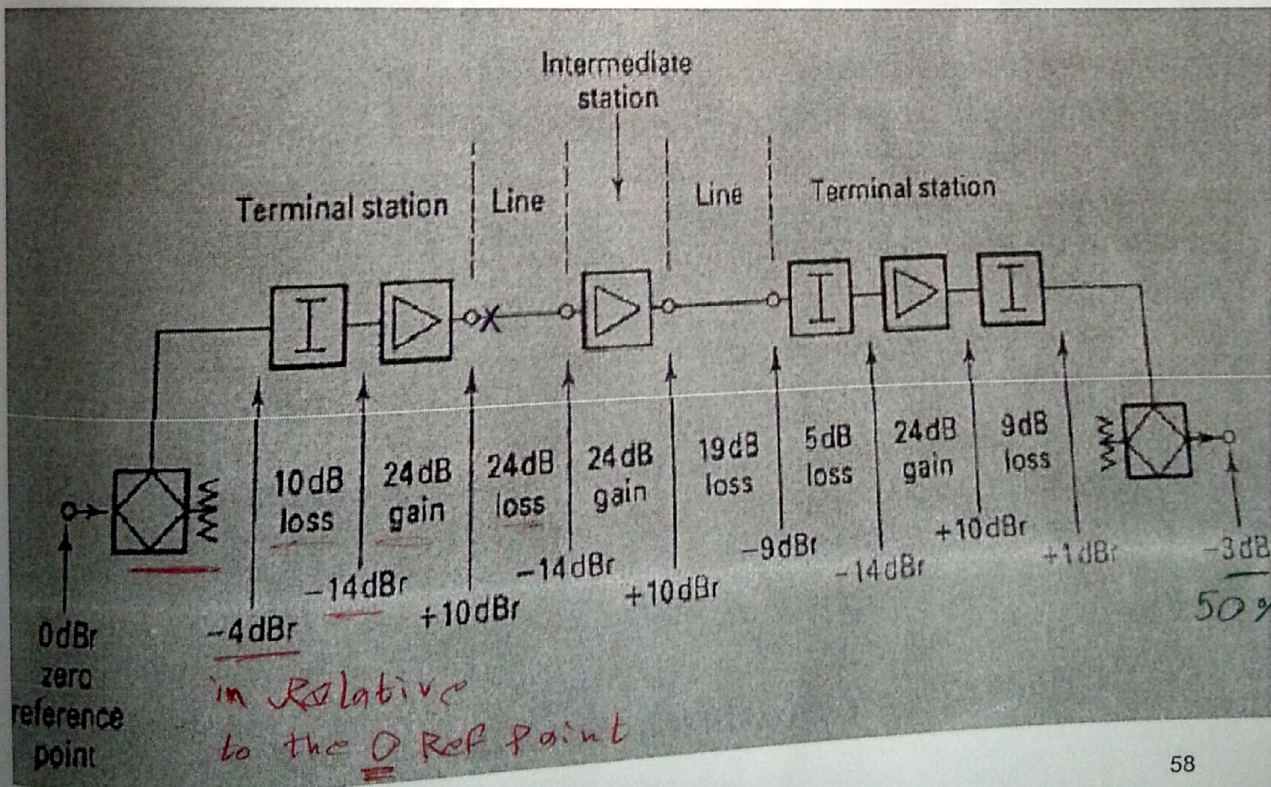
used to indicate power levels relative to 1 mW  
 Example: 1 W = 30 dBm

used to indicate power levels relative to 1 W

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Handwritten note:

$$10 \log 1000$$



Handwritten note: dBm0 → is the same



# Power Levels

- Relative level of a signal at any point in the system with respect to its level at the reference point is denoted by dB<sub>r</sub>
- Signal level in terms of the corresponding level at the reference point is denoted by dB<sub>mO</sub>:  $dB_{mO} = dB_m - dB_r$

at x  $P_x = 10 \text{ mW} \rightarrow 10 \text{ dB}_m$

*its the same*

$dB_r \text{ at } x \rightarrow +10 \text{ dB}$

$dB_{mO} = dB_m - dB_r = 10 - 10 = 0$

$P_{ref} = 1 \text{ mW}$

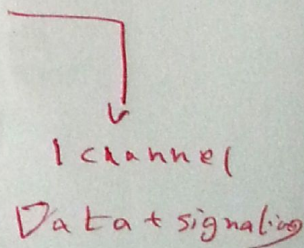
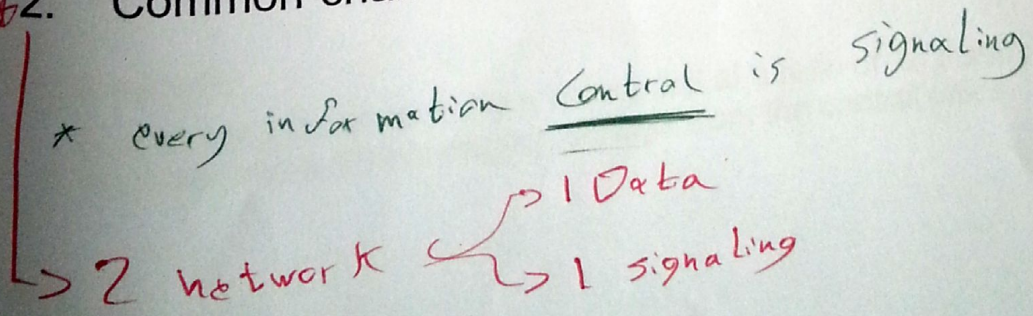
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# Signaling

Types of signaling:

- In-channel signaling or called Channel Associated Signaling (CAS): used in old telephone network.
- Common-channel signaling (CCS).

*handy*



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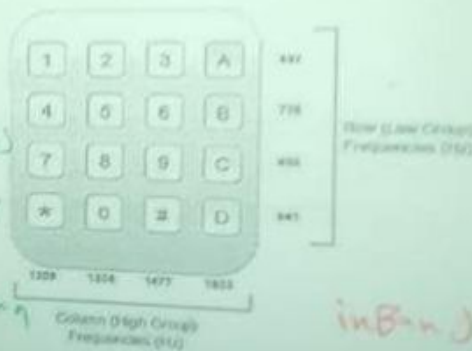


# Channel Associated Signaling

a) In-band: called voice frequency signaling (VF).

- The main advantage of in-band signaling is that it can be used on any transmission medium.
- The main disadvantage is the need to eliminate mutual interference between the signaling waveforms and a user's speech.

Example: Dual-tone multi-frequency (DTMF) signals from push-button telephone.



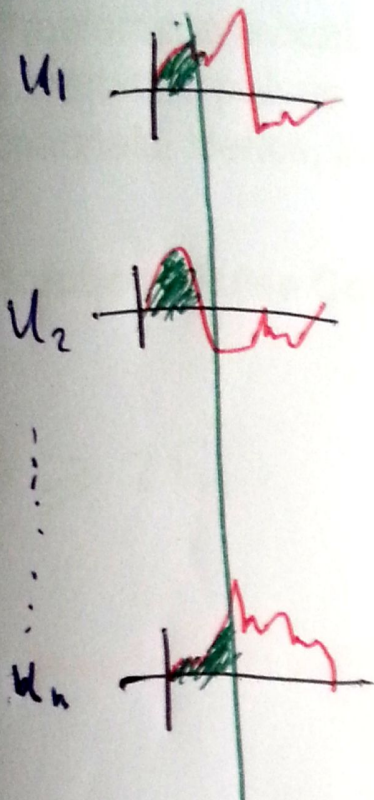
\* those two signals are unique → when added together you can tell the difference between it and the voice/noise signal

in-band

Channel Associated



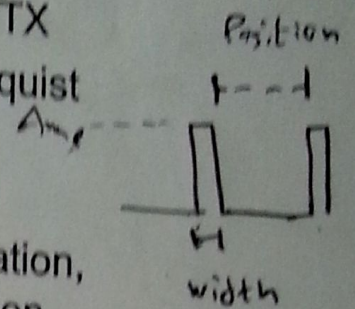
# Digital Telephone Network





# Time Division Multiplexing

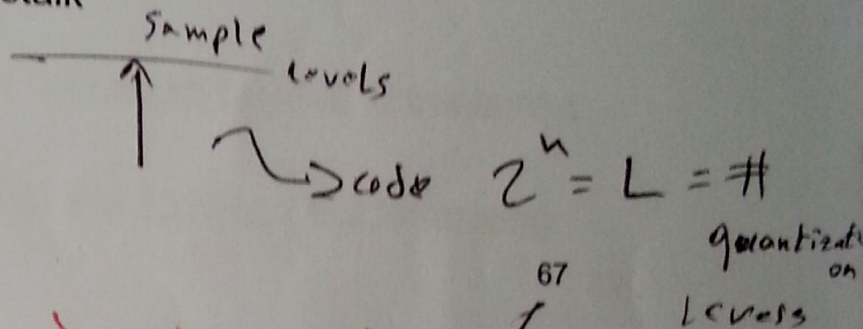
In RX: sampling pulses should be synchronized with that in TX  
 In Telephone system: sampling rate is 8KHz (2 x 4 KHz, Nyquist frequency). So 8k pulses/second



Possible modulation methods: PAM-pulse amplitude modulation, PWM-pulse width modulation, PPM-pulse position modulation

Problems: attenuation and delay causes dispersion of the transmitted pulses. So pulses interfere with other pulses of adjacent channels. Hence, inter-channel crosstalk

Solution: Pulse Code Modulation



$$f_s \geq 2f_m$$

$$\text{Frame duration} = \frac{1}{8k}$$

1 sample from each user / sample

easy to recover the signal

## PCM

\* threshold



# PCM

- A/D: an analog level of voltage is converted to a group of bits (word=32 bits or byte= 8 bits)

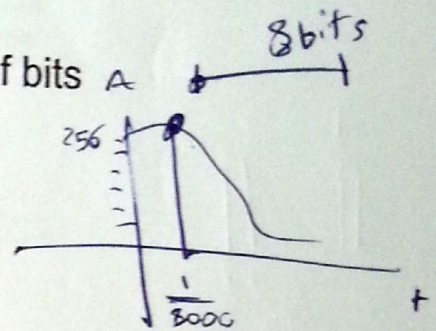
- In telephone system: 8 bit encoding is used (256 levels).

- 8 K pulse /sec (1 pulse = 8 bits)

- Bit rate =  $8 \text{ k} \times 8 / \text{sec} = 64 \text{ kbps}$  (= baud rate, since bit is one symbol).

- Nyquist showed that the minimum bandwidth needed to transmit a digital signal at B bauds is  $B/2$ .

- So, in telephone system: minimum BW= 32 KHz. ( but for analog BW =4 KHz)



Exam

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# PCM

- PCM introduces quantization distortion which is not found in analog transmission.
- If quantization is done using uniform size steps, then high quantization error. So, non-uniform size steps are needed (problem).
- It is better to assign small quantization interval for small signals and large signals. (and then expanding)



Examples: if a signal has an Absolute level of  $-5 \text{ dBm}$  at a point where the Relative level is  $-10 \text{ dB}$ , find the signal level referred back to the zero reference point ( $\text{dBm}_0$ )

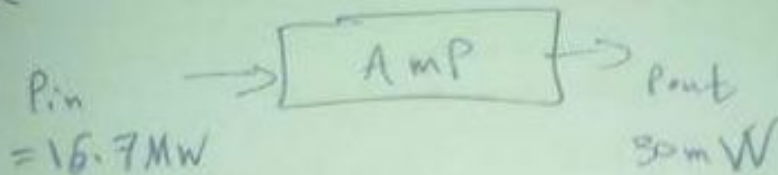
Sol:

$$\text{dBm}_0 = \text{dBm} - \text{dB}$$

$$-5 - (-10) = 4 \text{ dBm}$$

Example

2



Sol: Find Gain in dB

$$G = \frac{P_{out}}{P_{in}} = \frac{30 \text{ m}}{16.7 \text{ M}} = 1.8 \times 10^3$$

$$\text{Gain}_{\text{dB}} = 10 \log (1.8 \times 10^3) = 32.6 \text{ dB}$$

Example: express the following power levels in  $\text{dBm}$

① and  $\text{dBW}$

$1 \text{ mW} \rightarrow 0 \text{ dBm}$   
 $\rightarrow -30 \text{ dBW}$

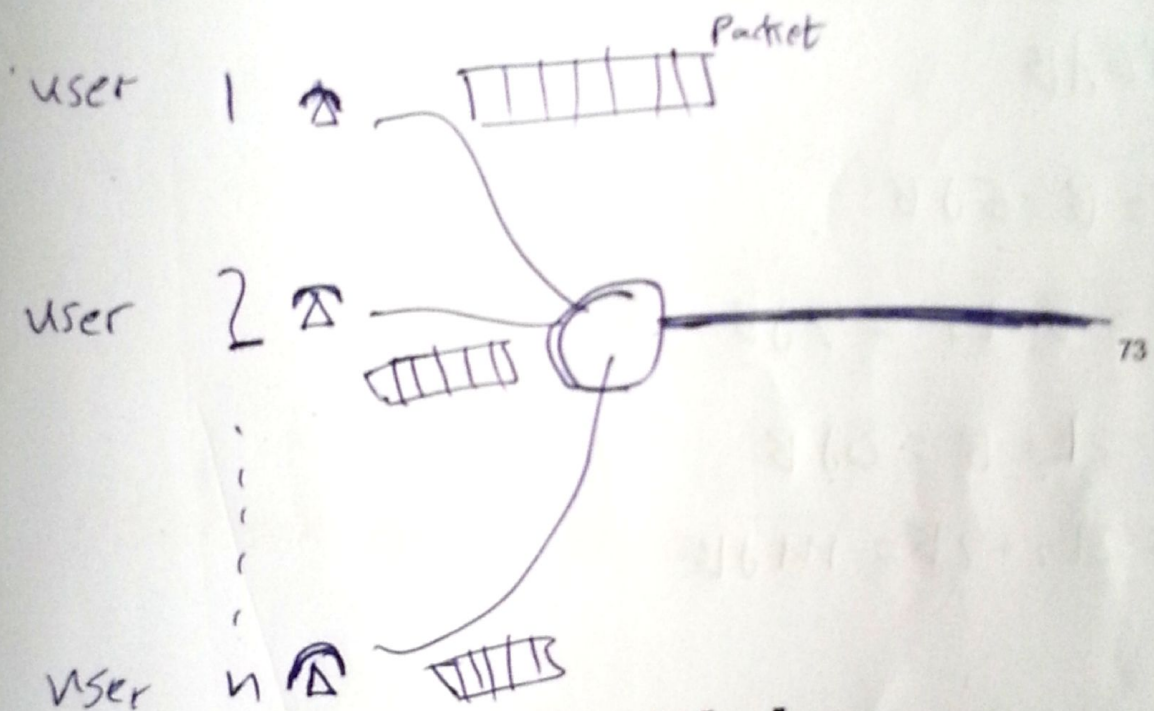
$100 \text{ mW} \rightarrow 20 \text{ dBm}$   
 $\rightarrow -10 \text{ dBW}$

②  $1 \text{ W} \rightarrow 30 \text{ dBm}$   
 $\rightarrow 0 \text{ dBW}$



# TDM and VoIP

- Once a connection is established, capacity is saved even when the device is not sending information.
- But there are small slices of silence in voice (wasting network capacity).
- This is the reason TDM is being gradually replaced in high-traffic portions of networks by Voice over Internet Protocol (VoIP) technologies



## Statistical Multiplexers

do not guarantee capacity for



Ex; A Four wire has an over All loss (two wire to two-wire)  
of  $1 \text{ dB}$  and the Balance Return loss at each End  
is  $6 \text{ dB}$

- 1) the signaling point
- 2) the stability Margin
- 3) the attenuation of talker and listener side

$$L_2 = 1 \text{ dB}$$

$$B = 6 \text{ dB}$$

$$\textcircled{1} S = B = 6 \text{ dB}$$

$$\textcircled{2} m = B + L_2 = 7 \text{ dB}$$

$$\textcircled{3} L_t = 2L_2 + B = 8 \text{ dB}$$

$$L_r = 2L_2 + 2B = 14 \text{ dB}$$



# PCM Primary Multiplex Group

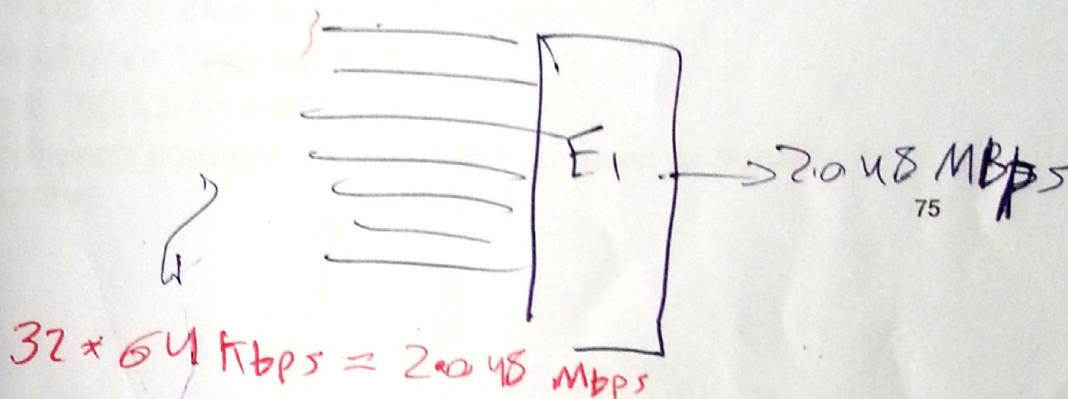
- European 30-channel system (E1-European system 1)
- 24- channel system (T1-*transmission system* 1) used in North America and Japan.
- Note: T0 and E0- are used for one channel (64 Kbps)
- What about E2, E3, or T2, T3 ?

E1

T1

30 Users is ~~using 30~~ channels in the multiplexer

E1



## E1 System

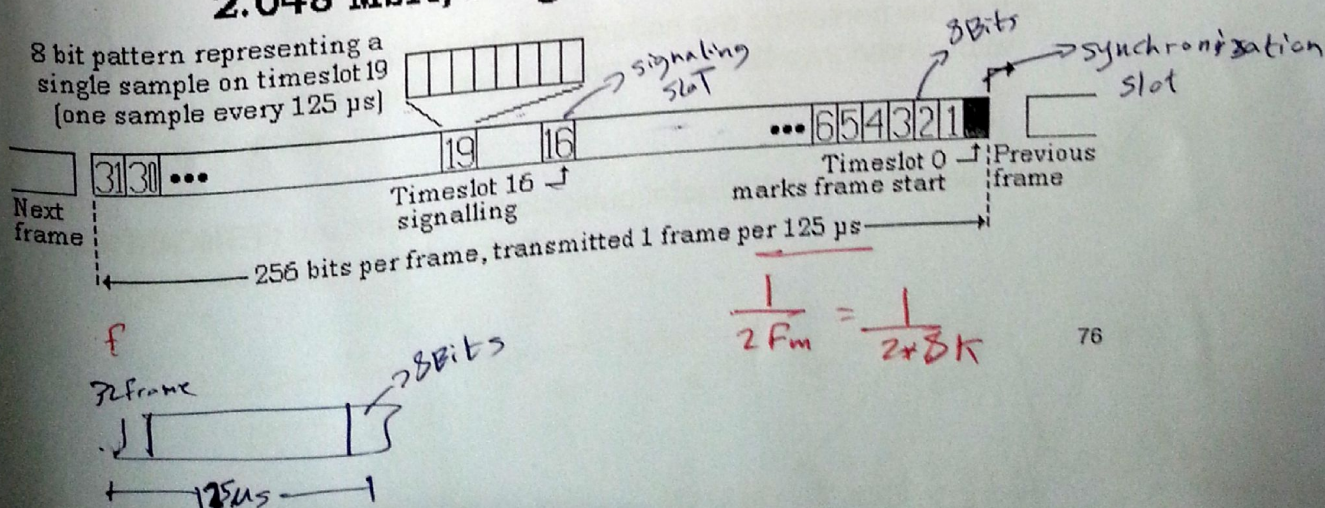
- Uses A-law companding
- Bit rate =  $32 * 8 / 125 = 2.048$  Mbps

$$F_s = 2F_m = 2 * 8 \text{ kHz} = 16 \text{ K samples/s}$$

$$\text{Bit Rate} = 16 * 8 = 128 \text{ Kbps}$$

$$\text{Frame Rate} = \frac{1}{8 \text{ K}} = 125 \mu\text{s}$$

### 2.048 Mbit/s digital frame format



$$\frac{1}{2F_m} = \frac{1}{2 * 8 \text{ K}}$$



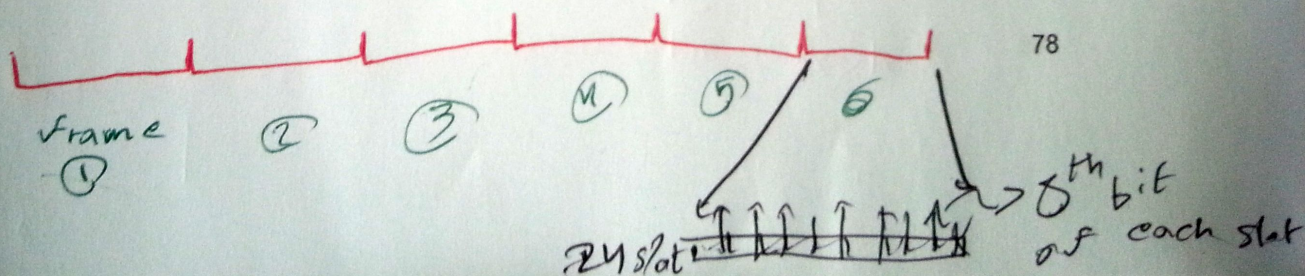
# Digital Hierarchy in E1 and T1

- The plesiochronous digital hierarchy-PDH (old)
- The synchronous digital hierarchy-SDH (new)
- The synchronous optical network -SONET (new)

**PDH:** the timing and clocking information are contained within the digital bit stream and thus this system is self-synchronized or asynchronous.

→ large networks

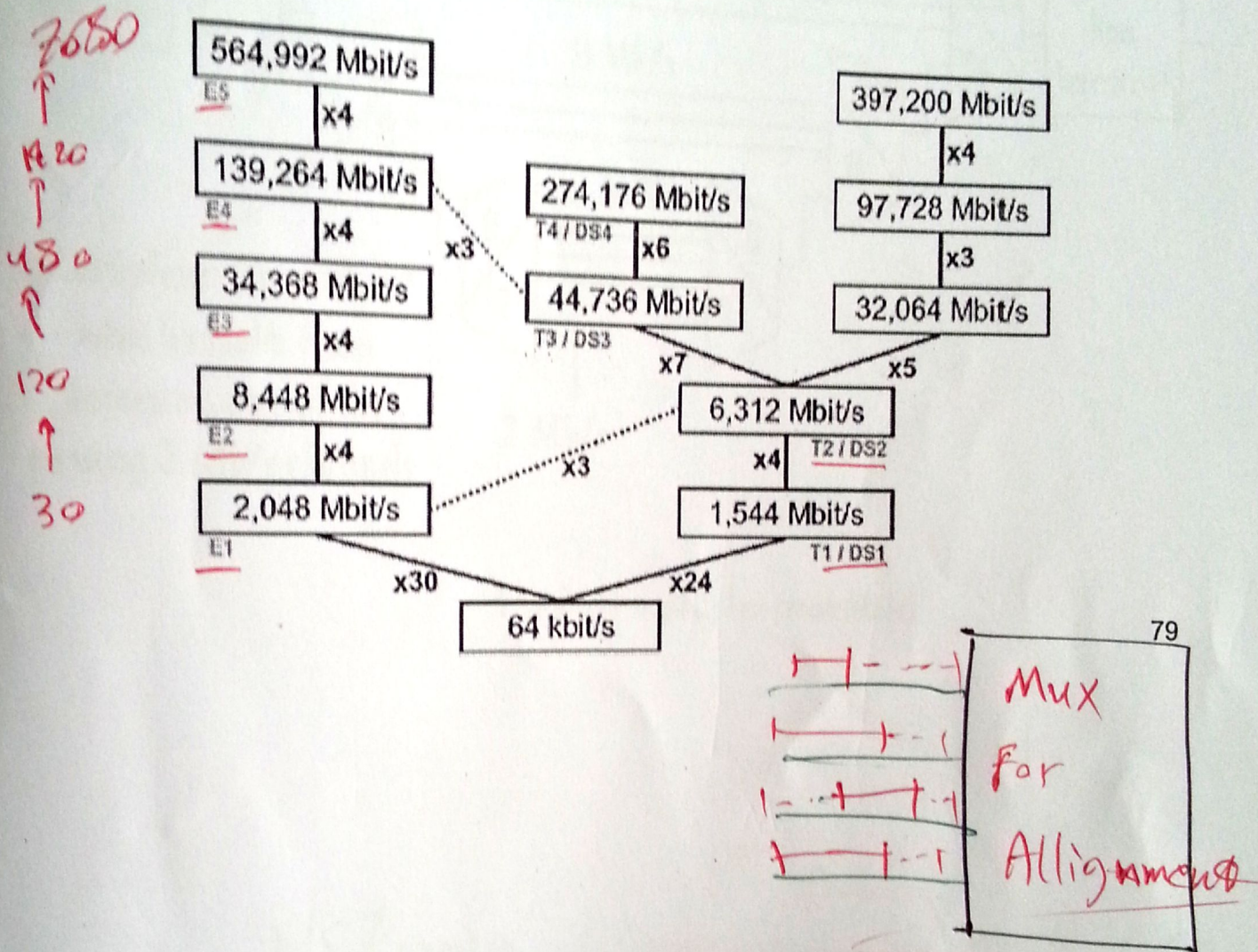
**SDH/SONET:** the timing and clocking information are obtained from a highly accurate master clock





# PDH

- European PDH (Ex)
- North American PDH (Tx or DSx)



# PDH



US/Canada <sup>1<sup>st</sup></sup> Protocol world wide  
**SDH and SONET** → protocols  
more popular

- They are standardized protocols that transfer multiple digital bit streams over optical fiber.
- Developed to replace the PDH system for transporting large amounts of telephone calls and data traffic over the same fiber without synchronization problems (synchronization sources of various circuits were different).
- SONET in the United States and Canada, and SDH in the rest of the world. Although the SONET standards were developed before SDH, it is considered a variation of SDH because of SDH's greater worldwide market penetration.



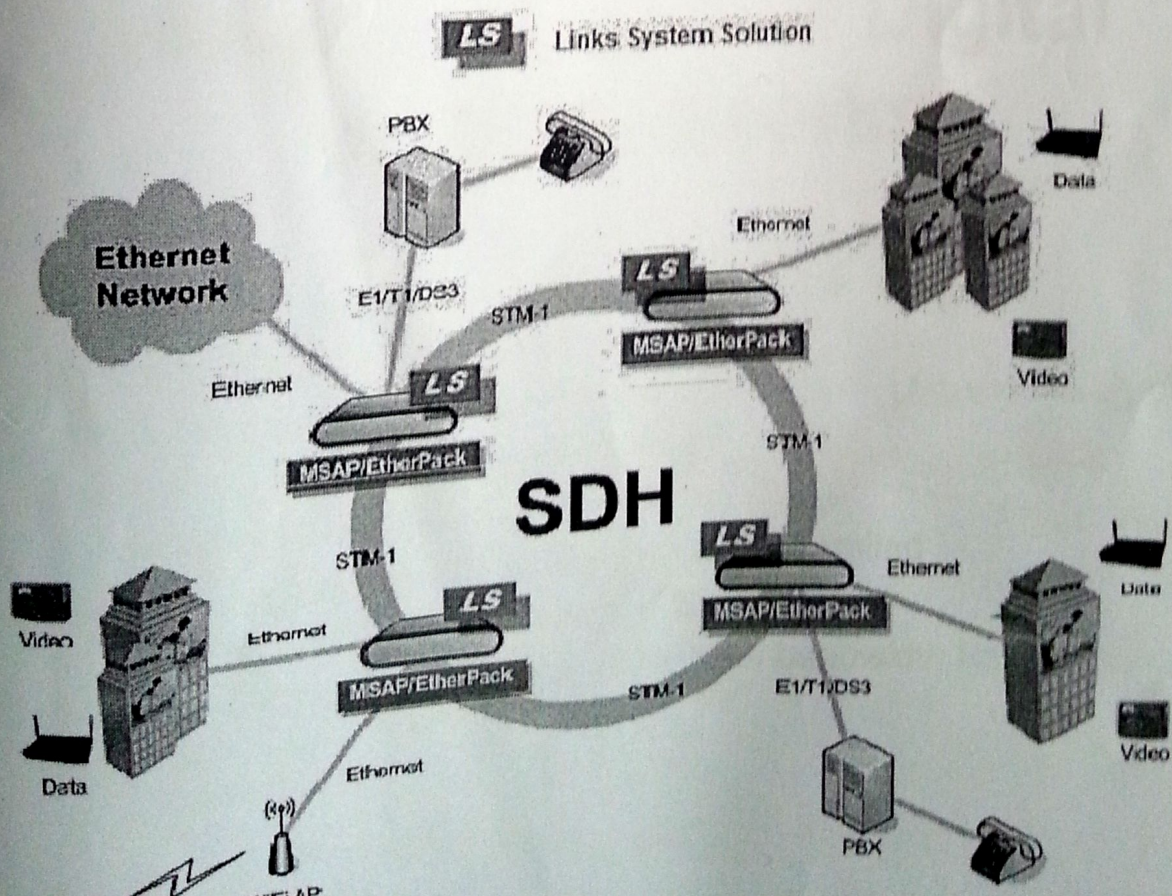
# SDH and SONET

STM-1: Synchronous Transport Module, level 1  
 STS-1: Synchronous Transport Signal, level 1

SONET and SDH transmission speeds

SONET signal	SDH signal	Bit rate [Mbps]
STS-1		51.84
STS-3	STM-1	155.52
STS-12	STM-4	622.08
STS-24		1244.16
STS-48	STM-16	2488.32
STS-192	STM-64	9953.28
STS-768	STM-256	39814.32

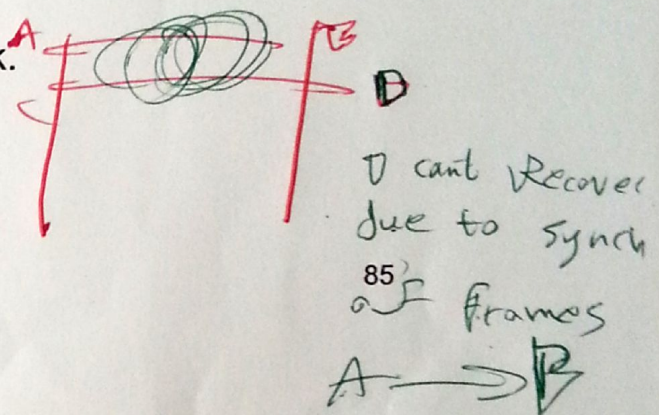
*sonet is a version of SDH*





# Advantages of Digital Voice Network

1. Ease of multiplexing → TDM Devices Cheaper than PDM Devices
2. Ease of signaling
3. Use of modern technology → Logic Gates
4. Integration of transmission and switching → Analog Voice Channels
5. Signal regeneration Repeaters → interface with signaling
6. Performance monitorability → no special devices
7. Accommodation of other services VOIP + net → in Analog SNR is higher
8. Operability at low signal-to-noise/interference ratios → Digital + Repeaters
9. Ease of encryption Scrambler
10. Digital signals are highly resistant to crosstalk.



# Disadvantages Of Digital Voice Networks

1. Increased bandwidth. 4 kHz to 64 kbps
2. Need for time synchronization.
3. Topologically restricted multiplexing. → Far Users and Near Users
4. Need for conference/extension bridges. → Ans: 100 Users
5. Incompatibility with analog facilities. → needs A/D & D/A
6. The information capacity of digital system is limited.
  - Shannon limit for information capacity
  - $C = 3.32 B \log_2 (1 + S/N)$ , C: bps, B: bandwidth Hz



# Signalling System No.7

- Uses out-band signaling and it is CCS system
- Called CCITT signaling system No. 7
- Called Common Channel Signaling System 7
- Is a set of telephony signaling protocols which are used to set up most of the world's PSTN telephone calls
- The main purpose is to start and end telephone calls but then it is used for other service such as prepaid billing mechanism and SMS

Channel Associated Signaling

CAS

90