

CIRCUIT II NOTEBOOK

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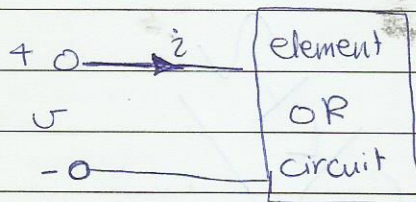
AC circuit power analysis

- ① what ??
- ② why ??
- ③ how ??

Instantaneous Power:

 $P(t)$

Definition



by definition

$P(t) \triangleq \textcircled{1} * \textcircled{2} \rightarrow$ Current through the element according to passive
 \uparrow \uparrow voltage across the element or ckt (sign convention)
 power consumed by the element or ckt

P of the basic passive elements

element

P

R

$$P_R = v_R * i_R = v_R^2 / R = i_R^2 * R$$

L

$$P_L = v_L * i_L = \left(L \frac{di_L}{dt} \right) * i_L = v_L * \frac{1}{L} \int \frac{v_L}{v_L} dt$$

C

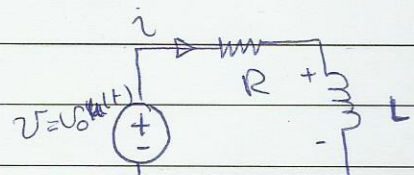
$$P_C = v_C * i_C = \left(C \frac{dv_C}{dt} \right) * v_C = \frac{1}{C} \int i_C dt * i_C$$

Illustration:

find the Power P supplied to the element in the ckt

procedure:

It can be found that



$$i = \frac{v_0}{R} (1 - e^{-\frac{R}{L}t}) u(t) = \frac{v_0}{R} - \frac{v_0}{R} e^{-\frac{R}{L}t}$$

$\frac{v_0}{R}$ is labeled as 'dc' and $\frac{v_0}{R} e^{-\frac{R}{L}t}$ is labeled as 'natural'.

i. $P_R = i^2 R \dots \textcircled{2}$ Sub $\textcircled{1}$ into $\textcircled{2}$ to find P_R

$$P_L = v_L i \quad \text{but } v_L = L \frac{di}{dt}$$

$$= L \frac{di}{dt} \times i \quad \text{--- (3) substitute (1) into (3) to find } P_L$$

P supplied by the source, P_S

$$P_S = v \times i$$

$$= v_0 \cos(\omega t) \times i \quad \text{--- (4)}$$

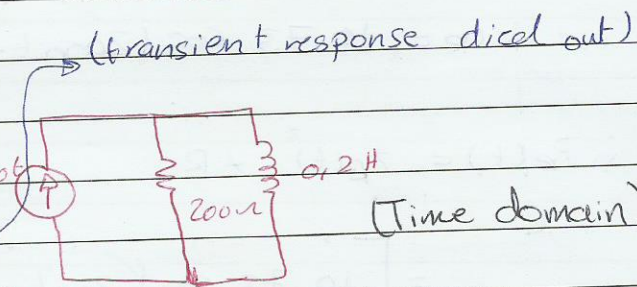
substitute (1) into (4) to find P_S

Check Power balance

$$P_S \equiv P_R + P_L$$

ex :

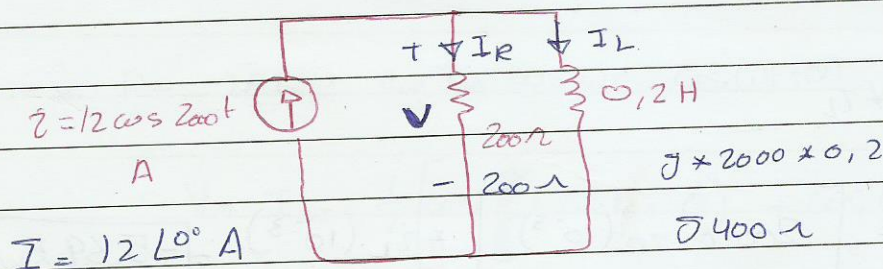
for the given ckt, $i = 12 \cos 2000t$ A and assuming (steady state) conditions, find the Power being absorbed by R, L and source at $t = 1 \text{ ms}$



~~step~~ objective Find $P_R(t)$, $P_L(t)$, $P_S(t)$ → then substitute $t = 1 \text{ ms}$

Procedure :

Transform the circuit From Time domain → frequency Domain



frequency domain

By current division:

$$I_L = 12 \Omega \frac{200}{200 + j400} = 5.4 \angle -63.4^\circ \text{ A}$$

$$i_L = 5.4 \cos(2000t - 63.4^\circ) \text{ A}$$

$$I_R = 12 \Omega \frac{j400}{j400 + 200}$$

$$= 10.73 \angle 26.76^\circ \text{ A}$$

$$i_R = 10.73 \cos(2000t + 26.76^\circ)$$

$$i P_R(t) = i_R(t)^2 \times R$$

$$= [10.73 \cos(2000t + 26.76^\circ)]^2 \times 200$$

$$i P_R (1 \times 10^{-3}) = [10.73 \cos(\overset{\text{Radians}}{\downarrow} 2 + 26.76)]^2 \times 200 = 14.06 \text{ kW}$$

$$P_L(t) = v \times i_L$$

$$= \left[L \frac{di_L}{dt} \right] \times i_L$$

OR

$$= [200 i_R] \times i_L$$

$$i P_L (1 \times 10^{-3}) = [200 \times i_R (10^{-3})] \times i_L (10^{-3}) = -5.69 \text{ kW}$$

$$P_s = v \times (-i_s) = - [P_R + P_L] = - [14.06 - 5.69] \\ = \boxed{-8.37} \text{ kW}$$

Sketch P_R , P_L and P_s



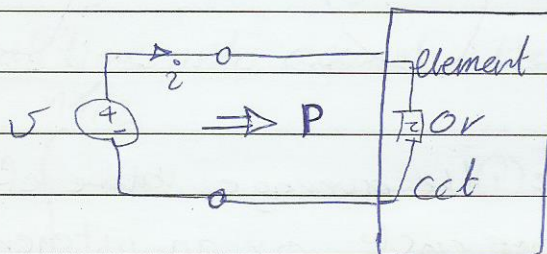
General sinusoidal case:

* let $v(t) = V_m \cos \omega t$

Objective

find p

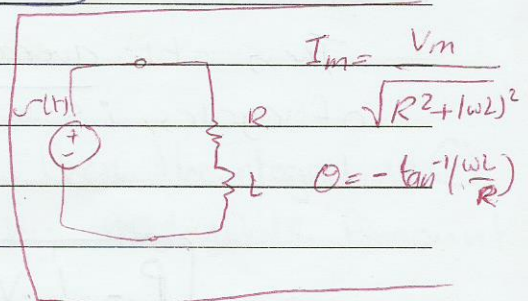
Procedure is



$$P \triangleq v \times i$$

∴ let $i = I_m \cos(\omega t + \theta)$

∴ $p = v i = V_m I_m \cos \omega t \cdot \cos(\omega t + \theta)$



$$= V_m I_m \cdot \frac{1}{2} \left[\cos(2\omega t + \theta) + \cos(\theta) \right]$$

$$= \left[\frac{1}{2} V_m I_m \cos \theta + \frac{1}{2} V_m I_m \cos(2\omega t + \theta) \right] \quad \text{--- (1)}$$

By studying (1) the followings can be deduced:

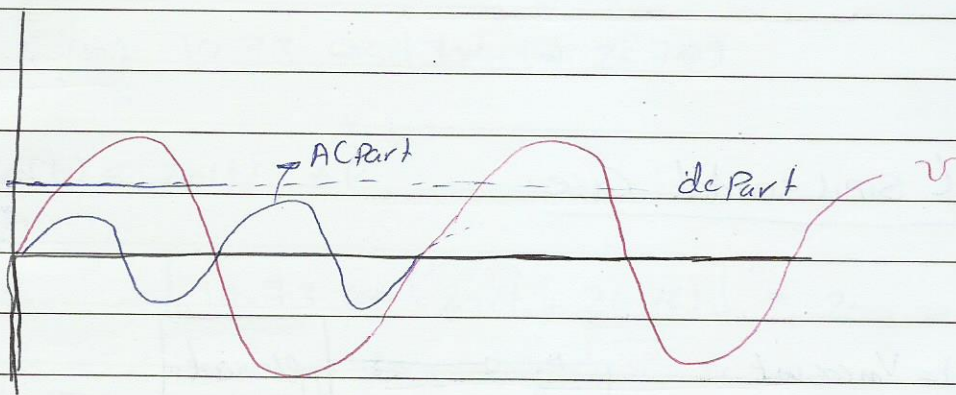
(1) P consists of 2 ~~components~~ parts &

a) a constant term = $\frac{1}{2} V_m I_m \cos \theta$

b) a sinusoidal term with a frequency twice the frequency of source = $\frac{1}{2} V_m I_m \cos(2\omega t + \theta)$

Please (2)

Sketch $v(t)$ and $P(t)$



ii) Since the average value of a pure sin wave over one cycle or an integer number of cycles = zero. Then the average value P of P in (1) over a cycle or a number of cycles, is

$$P = \frac{1}{2} V_m I_m \cos \theta \quad \text{(average power) of a periodic waveform} \quad (2)$$

Hence from (2)

a) If the element is R , then $\theta = 0^\circ$

$$\therefore P = \frac{1}{2} V_m I_m \text{ or } = \frac{1}{2} V_m^2 / R \text{ or } = \frac{1}{2} I_m^2 R$$

b) If the element is L or C

then $\theta = \pm 90^\circ$

$$\therefore \cos 90^\circ = 0$$

$$\therefore P = 0$$

\therefore The only element which consume Average power (P) is the Resistor.

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Evaluating Average value of Periodic Instantaneous Power.

Let $p(t)$ has a period of T Then $P \triangleq \frac{1}{T} \int_0^T p dt$

$$= \frac{1}{nT} \int_0^{nT} P dt \quad \text{where } n = 1, 2, 3, \dots = \frac{1}{nT} \int_{-\frac{nT}{2}}^{\frac{nT}{2}} P dt$$

In order to take all time into account, then let $n \rightarrow \infty$

$$\therefore P = \lim_{n \rightarrow \infty} \frac{1}{nT} \int_{-nT/2}^{nT/2} \dots \quad (1)$$

If n in (1) is changed slightly, then the integral in (1) and consequently P will change by negligible Amount

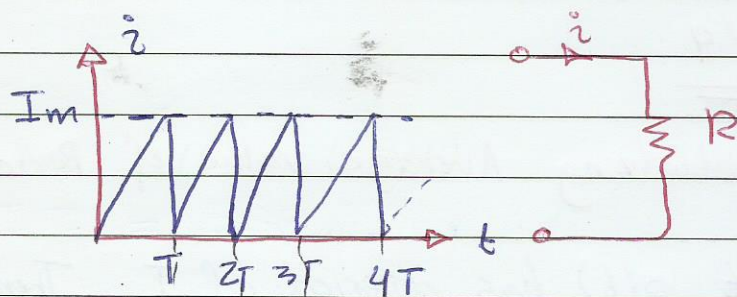
$\therefore nT$ becomes a continuous variable, say τ

Hence (1) becomes
$$P = \lim_{\tau \rightarrow \infty} \frac{1}{\tau} \int_{-\tau/2}^{\tau/2} p dt \quad (2)$$

∴ Hence (2) can be used to evaluate P for periodic and nonperiodic P by assuming that it has ∞ period.

ex: Find P supplied to R by the following sawtooth current

(limit) (∞)



Solution:

$$P = i^2 R$$

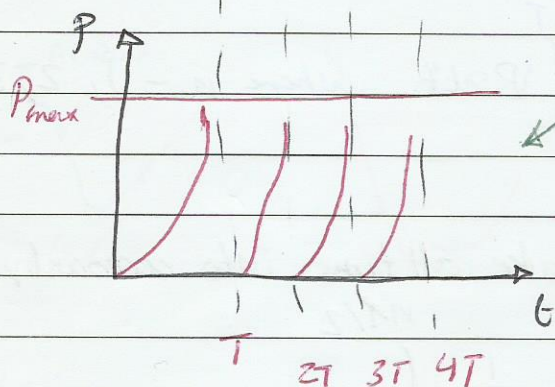


Figure (1)

∴ P is periodic with a period = T as that to the current

$$\therefore P = \frac{1}{T} \int_0^T i^2 R dt = \frac{R}{T} \int_0^T i^2 dt$$

∴ from figure (1), $i(t) = \frac{I_m}{T} t$ (2) $0 < t < T$

Sub (2) into (1)

$$\therefore P = \frac{R}{T} \int_0^T \frac{I_m^2}{T^2} t^2 dt$$

$$= \frac{R I_m^2}{3} \left[\frac{1}{3} t^3 \right]_0^T$$

$$P = \frac{1}{3} R I_m^2$$

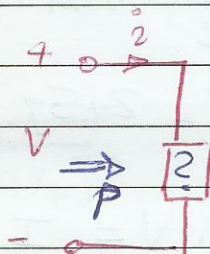
General Sinusoidal Cases

Problem

if $v = V_m \cos(\omega t + \theta)$

and $i = I_m \cos(\omega t + \phi)$

find P



Solution:

It can be found that $T_{vori} = \frac{2\pi}{\omega}$

Now, $P = v i = V_m I_m \cos(\omega t + \theta) \cdot \cos(\omega t + \phi)$

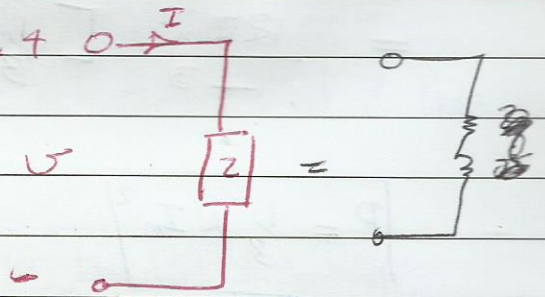
$$\therefore P = V_m I_m \frac{1}{2} \left[\cos(2\omega t + \theta + \phi) + \cos(\theta - \phi) \right]$$

$$= \frac{1}{2} V_m I_m \cos(\theta - \phi) + \frac{1}{2} V_m I_m \cos(2\omega t + \theta + \phi) \quad \dots (1)$$

$\therefore P$ is periodic with a period $T_P = \frac{1}{2} T_{vori} = \frac{\pi}{\omega}$ $\dots (2)$

$$\therefore P = \frac{1}{T_P} \int_0^{T_P} P dt \quad \dots (3) \equiv \left[\frac{1}{2} V_m I_m \cos(\theta - \phi) \right]$$

evaluate P ^{average} supplied to $Z = 6 \angle 25^\circ \Omega$ + $0 \rightarrow I$
 Z if $Z = (2 + j5) \Omega$



Sol is

$$P = \frac{1}{2} V_m I_m \cos(\theta - \phi)$$

$$Z = 2 + j5 = 5.38 \angle 68.2^\circ$$

$$V = I Z = 5.38 \angle 68.2^\circ \times 6 \angle 25^\circ = 32.28 \angle 93.2^\circ$$

V_m

$$P = 78.7 \text{ W}$$

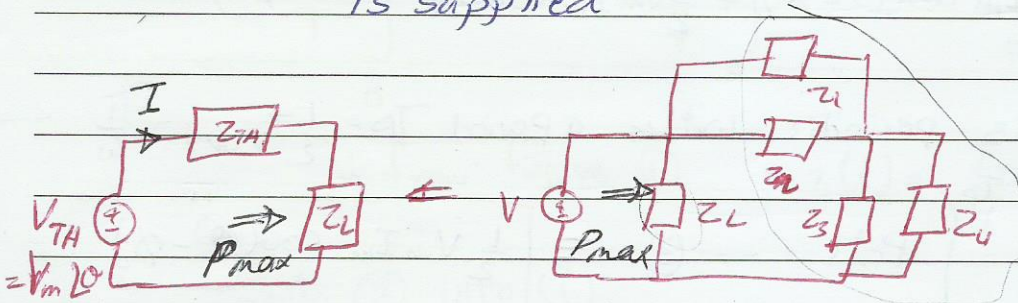
OR $P = \frac{1}{2} I_m^2 R$

$$Z = 6 \angle 25^\circ = 6 \cos 25^\circ + j 6 \sin 25^\circ$$

$$P = \frac{1}{2} \times (5.38)^2 \times 6 \cos 25^\circ = 78.7 \text{ W}$$

Maximum Power Transfer:

Objective Find Z_L in a given ckt to which max power is supplied



$$Z_{TH} = R_{TH} + j X_{TH}$$

$$Z_L = R_L + j X_L$$

Procedure: Simplify the given ckt to it's thevenin equivalent

$$i) P = \frac{1}{2} |I|^2 R_L \quad \dots (1)$$

$$\text{But } I = \frac{V_{TH}}{Z_{TH} + Z_L} = \frac{V_m \angle \theta}{(R_{TH} + R_L) + j(X_{TH} + X_L)}$$

$$ii) |I| = \frac{V_m}{\sqrt{(R_{TH} + R_L)^2 + (X_{TH} + X_L)^2}}$$

Sub (2) into (1)

$$P = \frac{1}{2} \frac{V_m^2 R_L}{(R_{TH} + R_L)^2 + (X_{TH} + X_L)^2} \quad \dots (3)$$

To find Z_L to which P is max Then solve $\frac{\partial P}{\partial R_L} = 0$ (4)

$$\frac{\partial P}{\partial X_L} = 0 \quad \dots (5)$$

Apply (4) and (5) to (3)

From (4) and (5) it can be found

$$X_L = -X_{TH}$$

$$R_L = R_{TH}$$

$$ii) Z_L = R_L + jX_L = R_{TH} - jX_{TH} = \boxed{Z_{TH}^*}$$

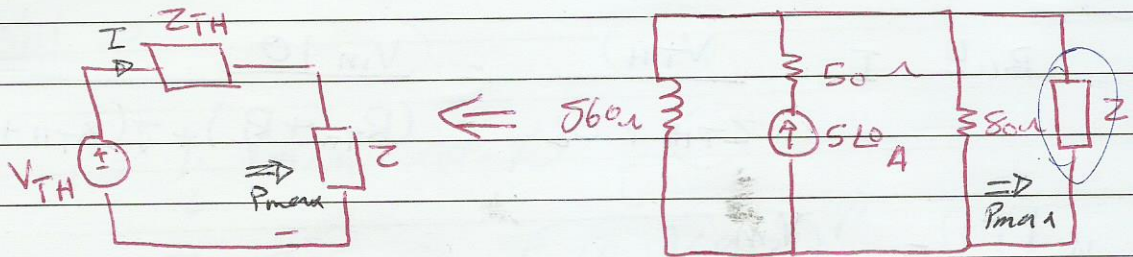
↳ Conjugate

find P_{max}

$$P_{max} = \frac{1}{2} |I|^2 R_L$$

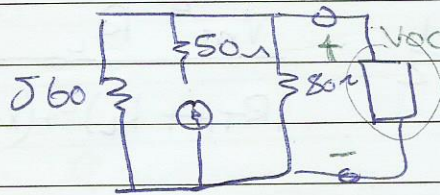
$$|I| = \frac{V_m}{2}$$

EX: 2 Evaluate in the given ckt. Z to which P_{max} is supplied.



* it is required to find Z_{TH}
we kill all the dependent sources

$$Z_{TH} = 80 \parallel j60$$



$$= \frac{80 * j60}{80 + j60} = 48 \angle 53.1^\circ$$

$$= 28.8 + j38.4$$

$$\therefore Z = Z_{TH}^* = 48 \angle -53.1^\circ = 28.8 - j38.4$$

$$V_{TH} = V_{OC} = j60 \left[5 \angle 0^\circ * \frac{80}{80 + j60} \right] = 240 \angle 53.1^\circ$$

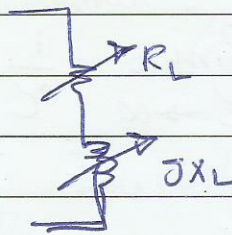
$$\therefore I = \frac{V_{TH}}{Z_{TH} + Z} = \frac{240 \angle 53.1^\circ}{2 * 28.8} = 4.17 \angle 53.1^\circ \text{ A}$$

$$\therefore P_{max} = \frac{1}{2} * |I|^2 * 28.8 = 250.4 \text{ W}$$

Solve from the book

find Z from P_{max} under the following conditions: \rightarrow

- 1) R_L fixed and $\neq R_{TH}$
- 2) $X_L \sim \sim \neq -X_{TH}$
- 3) $X_{TH} = 0$
- 4) \vdots
- 5) \vdots



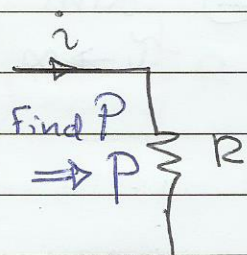
\rightarrow Evaluating P of non periodic p

(avg)

(inst)

Problem:

if $i = I_{m1} \sin \omega_1 t + I_{m2} \sin \omega_2 t$, find P



It's periodic if $mT_1 = nT_2$ where m and n are integers

find P

$$P = i^2 R = \int R I_{m1}^2 \sin^2 \omega_1 t \quad (1) + \int 2 R I_{m1} I_{m2} \sin \omega_1 t \sin \omega_2 t \quad (2) + \int R I_{m2}^2 \sin^2 \omega_2 t \quad (3)$$

$$i P = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} p dt \quad (2)$$

by substituting (1) into (2), then there are 3 integrals to be evaluated.

$$\textcircled{1} \Rightarrow \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} R I_{m_1}^2 \sin^2 \omega_1 t \, dt$$

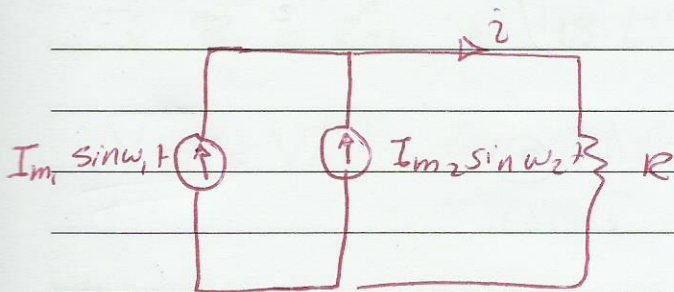
$$= \lim_{T \rightarrow \infty} \frac{1}{T} \cdot R I_{m_1}^2 \int_{-\frac{T}{2}}^{\frac{T}{2}} \frac{1}{2} [1 - \cos 2\omega_1 t] \, dt = \frac{1}{2} I_{m_1}^2 R \textcircled{3}$$

Similarly $\textcircled{3} \Rightarrow \frac{1}{2} I_{m_2}^2 R \textcircled{4}$

$$\textcircled{2} \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} R I_{m_1} I_{m_2} [\cos(\omega_1 t - \omega_2 t) - \cos(\omega_1 t + \omega_2 t)] \, dt = 0 \textcircled{5}$$

ii substitute $\textcircled{3}, \textcircled{4}, \textcircled{5}$ into $\textcircled{2}$

$$P = \frac{1}{2} I_{m_1}^2 R + 0 + \frac{1}{2} I_{m_2}^2 R$$



\Rightarrow here we can use superposition principle

Conclusion: From $\textcircled{6}$ it can be deduced that in this ~~case~~ special case (ie current consist of components with different frequencies superposition can be applied to power calculations)

(6) Can be extended to n components, irrespective of any phase angles:

e.x.:

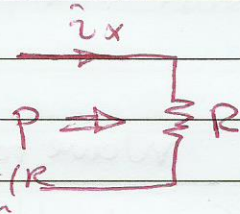
$$i_x = I_{m1} \sin(\omega_1 t - \theta) - I_{m2} \cos(\omega_2 t + \alpha) + I_{m3} \cos(\omega_3 t - \beta) + I_{m4} \sin(\omega_4 t + \phi)$$

using super S.P.

$$P = \frac{1}{2} I_{m1}^2 R + \frac{1}{2} I_{m2}^2 R + \dots + \frac{1}{2} I_{m_n}^2 R$$

OR

$$= \frac{1}{2} V_{m1}^2 / R + \frac{1}{2} V_{m2}^2 / R + \dots + \frac{1}{2} V_{m_n}^2 / R$$

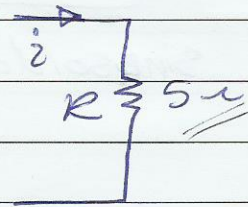


ex. 8 if $i = (2 - 3 \cos 100t)^2$, Find P

solution:

$$i = 4 - 12 \cos 100t + 9 \cos^2 100t$$

$$= 4 - 12 \cos 100t + 9 \cdot \frac{1}{2} [1 + \cos 200t]$$



$$= 4 - 12 \cos 100t + 4.5 + 4.5 \cos 200t$$

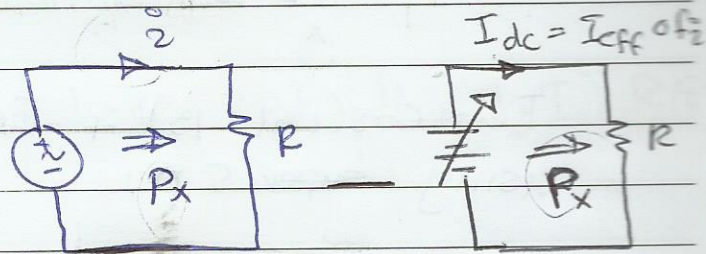
$$= 8.5 - 12 \cos 100t + 4.5 \cos 200t$$

$$P = P_1 + P_2 + P_3$$

$$= (8.5)^2 \times 5 + \frac{1}{2} (12)^2 \times 5 + \frac{1}{2} (4.5)^2 \times 5 = 227.25 \text{ W}$$

Effective value of aperiodic current (i) or periodic voltage (v)

Def: The effective value of i or v (ie I_{eff} or V_{eff}) is equal to the dc current or dc voltage which supply the same average power to a resistive R or i or v



Wave form	P_{AC}	P_{DC}	$P_{AC} = P_{DC}$
Saw tooth	$\frac{1}{3} I_m^2 R$	$I^2 R$	$\frac{1}{3} I_m^2 R = I_{eff}^2 R$ $\therefore I_{eff} = I_m / \sqrt{3}$
Sinusoidal	$\frac{1}{2} I_m^2 R$	$I^2 R$	$\frac{1}{2} I_m^2 R = I_{eff}^2 R$ $\therefore I_{eff} = I_m / \sqrt{2}$ OR $I_m = \sqrt{2} I_{eff}$

Note: The domestic distribution voltage in Jordan is 220 V (effective value)

$$\text{Peak value} = \sqrt{2} \times 220$$

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Mathematical expression for effective value is

$$P_{AC} = P_{DC}$$

$$\frac{1}{T} \int_0^T i^2 R dt = I_{eff}^2 R \Rightarrow$$

$$I_{eff} = \sqrt{\frac{1}{T} \int_0^T i^2 dt}$$

I_{eff} = square Root of the Mean of Squared current.

= RMS value

is V_{eff} OR V_{rms}

* IF $i = I_m \cos(\omega t + \theta)$ find I_{rms} !

$$* I_{rms} = \sqrt{\frac{1}{T} \int_0^T (I_m \cos(\omega t + \theta))^2 dt}$$

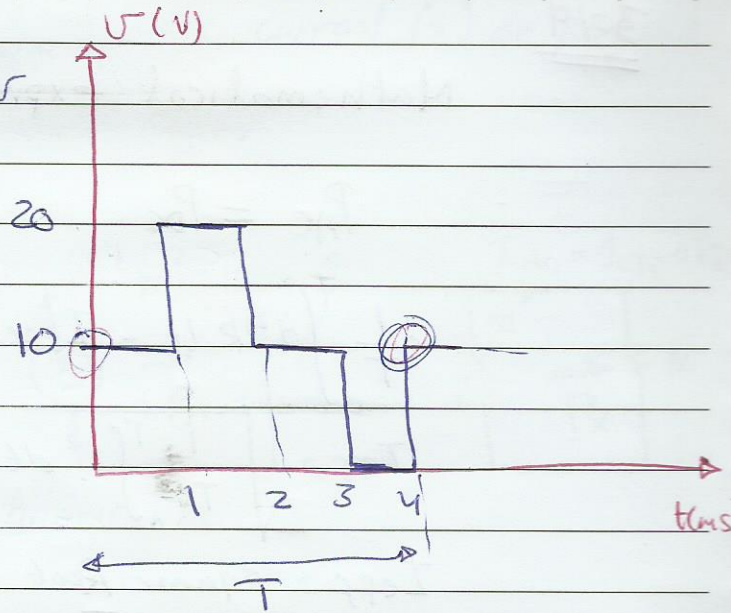
where $T = \frac{2\pi}{\omega}$

it can be found $I_{RMS} = \frac{I_m}{\sqrt{2}}$

ex: Find V_{eff} of the given V

$$V_{eff} = \sqrt{\frac{1}{4 \times 10^{-3}} \left[\int_0^{1ms} (10)^2 dt + \int_{1ms}^{2ms} (20)^2 dt + \int_{2ms}^{3ms} (10)^2 dt + \int_{3ms}^{4ms} 0 dt \right]}$$

$$= 12.25 \text{ V rms}$$



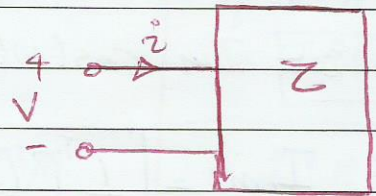
⇒ (*) Average Power in terms of effective value

It was found that

$$P = \frac{1}{2} V_m I_m \cos \theta$$

Since $Z = \frac{V}{I}$

$$\Rightarrow Z = \frac{V}{I} \Rightarrow \theta = \angle V - \angle I$$



$$\theta = \angle V - \angle I$$

$$= \frac{1}{2} (\sqrt{2} V_{eff}) * (\sqrt{2} I_{eff}) \cos \theta$$

$$P = V_{eff} I_{eff} \cos \theta$$

* Effective value of i or V with multiple frequencies

If $i = I_{m1} \sin(\omega_1 t - \beta) + I_{m2} \cos(\omega_2 t) + I_{m3} \cos(\omega_3 t - \beta) + \dots + I_{mn} \sin(\omega_n t + \phi)$

Find I_{eff}

As found before by superposition

$$P = P_1 + P_2 + \dots + P_n = I_{eff}^2 R + I_{eff_2}^2 R + \dots + I_{eff_n}^2 R \quad (1)$$

$$\text{But } P_{DC} = I_{eff}^2 R \quad (2)$$

By equating (1) and (2) \rightarrow

$$I_{eff}^2 R = I_{eff_1}^2 R + \dots + I_{eff_n}^2 R$$

$$\therefore I_{eff} = \sqrt{I_{eff_1}^2 + I_{eff_2}^2 + \dots + I_{eff_n}^2}$$

ex: if $i = (2 - 3 \cos 100t)^2$ Find I_{eff}

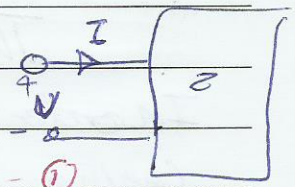
It was found $i = \underline{8.5} - \underline{12 \cos 100t} + 4.5 \cos 200t$

$$\therefore I_{eff} = \sqrt{I_{eff_1}^2 + I_{eff_2}^2 + I_{eff_3}^2}$$

$$= \sqrt{(8.5)^2 + \left(\frac{12}{\sqrt{2}}\right)^2 + \left(\frac{4.5}{\sqrt{2}}\right)^2} = 12.42 \text{ ARMS}$$

Apparent Power and Power Factor
 القوة الظاهرة القدرة الفعلية

$$P \triangleq V_{eff} I_{eff} \cos \theta = \frac{1}{2} V_m I_m \cos \theta$$



$$\text{Apparent Power} \triangleq V_{eff} I_{eff} \quad (2)$$

Since $\cos \theta$ is Dimensionless then (1) and (2) should be the same unit.
 But, they are different, then the Apparent Power is given the unit
 since Volt-Ampere (VA)

$$\text{Power factor} \triangleq \frac{\text{Average Power}}{\text{Apparent Power}}$$

$$\text{PF}$$

in For the sinusoidal case: \rightarrow

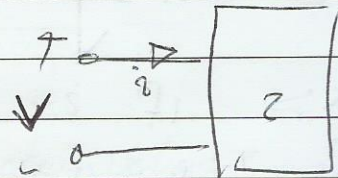
$$\text{PF} = \frac{VI \cos \theta}{VI} = \cos \theta$$

in θ is called PF angle.

Comments,

1) For Pure resistive load $\theta = 0$

in $\text{PF} = 1$ (i.e. unity PF)



$$\theta = \angle V - \angle I = 0$$

2) For pure Inductive or capacitive load, $\theta = \pm 90^\circ$

in $\text{PF} = 0$

in In general $0 \leq \text{PF} \leq 1$

3) If it is given $\text{PF} = 0.5$

Then $\theta = 60^\circ$ (Inductive or -ve capacitive)

In order to specify PF clearly, then the concept of lagging PF or leading PF is used

Here the reference is the current with respect to voltage.

in Lagging PF means i lags v by $\theta = \cos^{-1}(\text{PF})$

Leading PF $\sim \sim$ Leads $\sim \sim \sim \sim$

(current lead) (capacitor)
 (" lag ") inductor

Illustration:

If $\angle V = 20^\circ$

and PF = 0.5 leading

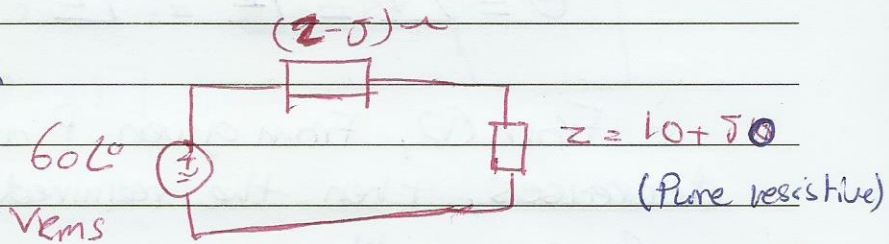


$\therefore \angle I = 20^\circ + \cos^{-1} 0.5$

$\approx 20^\circ + 60^\circ = 80^\circ$

Find for the given ckt:

- 1) Apparent power supplied source
- 2) PF of the source



Solution:

App. Power = $V_{eff} I_{eff}$

$I_{eff} = 3.54 \text{ Arms}$
 Apparent power = 212.13 W
 P.F. = $\frac{P}{V_{eff} I_{eff}} = 0.7$

$I = \frac{60 \angle 0^\circ}{(2-j) + (10+j0)} = 4.98 \angle 4.76^\circ \text{ Arms}$

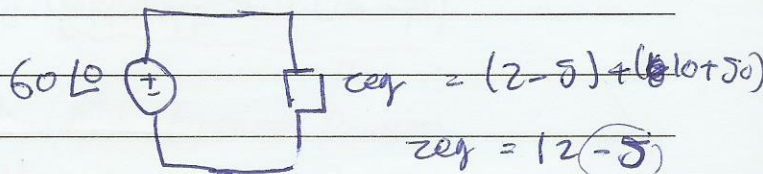
Apparent power = $60 \times 4.98 = 298.8 \text{ VA}$

ii) PF = $\cos [\angle V - \angle I]$

$\therefore \cos [0^\circ - 4.76^\circ] \text{ leading}$
 $= 0.9965$

OR: PF = $\frac{\text{Av. Power}}{\text{App. Power}}$

PF = $\cos \angle Z = \cos^{-1} (\frac{1}{12}) \text{ leading}$

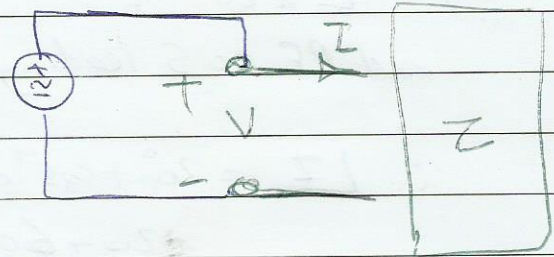


capacitive

Practical Importance of PF:

Since $P = V I \cos \theta$
_{eff eff}

i) $I_{eff} = \frac{P}{V \cos \theta}$ — (1)



$$\theta = \angle V - \angle I = \angle Z$$

i) From (1), From given P and V_{eff} as the PF decreases, then the required current (I_{eff}) increases

Consequently:

1) conductors or Lines with large cross sectional Area are required

i) Higher capital cost

2) Higher losses ($I_{eff}^2 R$) in lines.

where (1) and (2) are suffered by the Power Company or distribution company

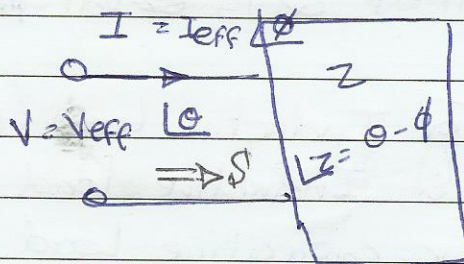
Hence \therefore the PF should not be below a certain ~~min~~ minimum acceptable level
Internationally, this level is 0.85

Complex power

Why? This is a mathematic tool or concept used to simplify power calculations in AC circuits.

Definition \Rightarrow

$$P = V_{eff} I_{eff} \cos(\theta - \phi) \dots (1)$$



(1) can be written as \Rightarrow

$$P = \text{Re} \left[V_{eff} I_{eff} e^{j(\theta - \phi)} \right]$$

Re is real part

$$\therefore P = \text{Re} \left[V_{eff} e^{j\theta} \times I_{eff} e^{-j\phi} \right] = \text{Re} \left[V_{eff} \angle\theta \times I_{eff} \angle-\phi \right]$$

$$= \text{Re} \left[\underline{V \times I^*} \right] \dots (2)$$

Complex Power
 \underline{S}

The product $(V \times I^*)$ in (2) is called complex power, \underline{S}

Comments about $\underline{S} = VI^* = V_{eff} \angle\theta - I_{eff} \angle-\phi = V_{eff} I_{eff} \angle(\theta - \phi)$

- 1) The magnitude of $\underline{S} = |\underline{S}|^* = V_{eff} I_{eff} = \text{Apparent power (VA)}$
- 2) $\angle \underline{S} = (\theta - \phi) = \text{PF angle}$
- 3) $\underline{S} = \underbrace{V_{eff} I_{eff} \cos(\theta - \phi)}_{\text{Re}} + j \underbrace{V_{eff} I_{eff} \sin(\theta - \phi)}_{\text{Im}}$

$\therefore \text{Re} [\underline{S}] = \underline{P} \equiv \text{Average Power}$

$\text{Im} [\underline{S}] = V_{eff} I_{eff} \sin(\theta - \phi) = \text{Given symbol } Q$

$$i) Q = V_{eff} I_{eff} \sin(\theta - \phi)$$

$$ii) S = P + jQ \quad Q \text{ is called Reactive Power}$$

Unit of Q is Volt-Ampere-Reactive (VAR)

iii) For Inductive load $(\theta - \phi) > 0$ $\therefore Q$ is +ve

iv) Inductive load consumes Reactive Power

For capacitive load, $(\theta - \phi) < 0$, $\therefore Q$ is -ve

(capacitive load generates -ve Reactive Power. OR it generates Reactive Power)

$$v) \text{ In general } S = P + jQ$$

* Capacitor \rightarrow generators

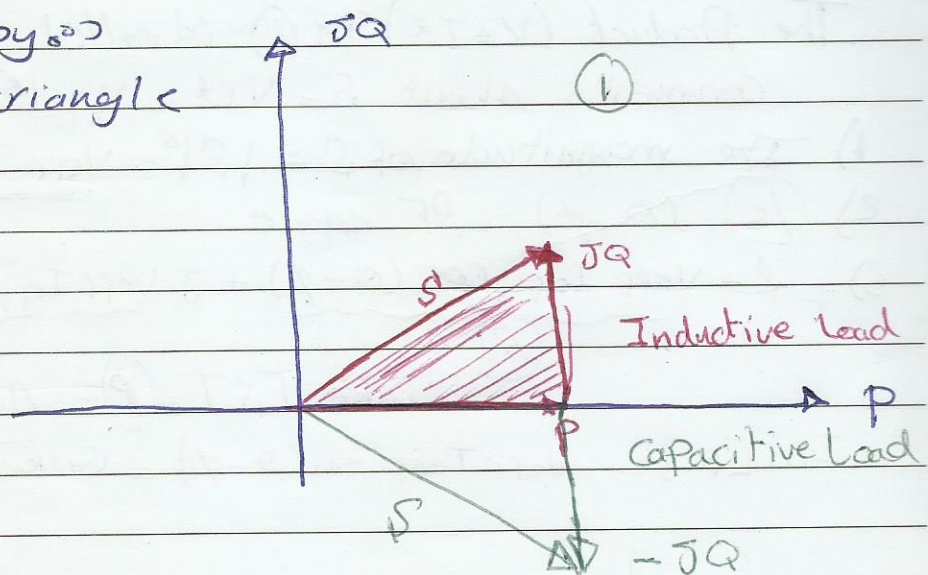
(توليد الطاقة الجارية)

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Graphical Representation of S

This is done by

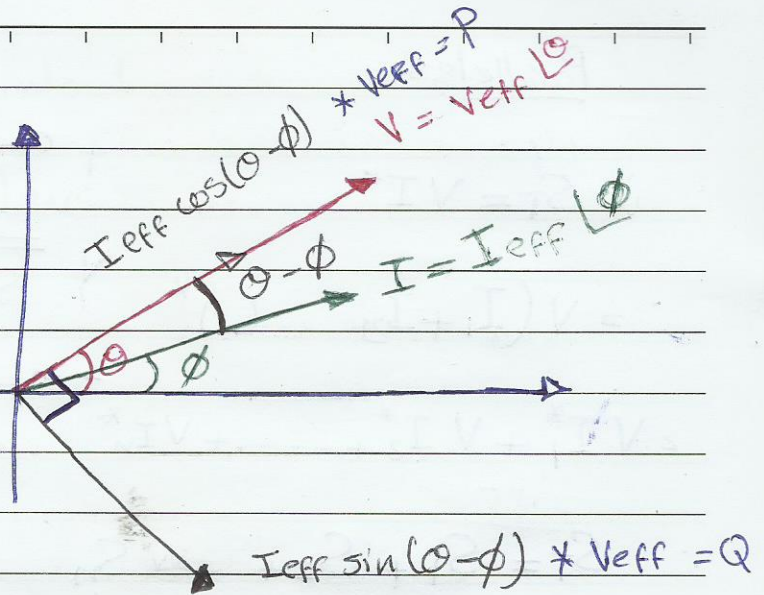
1) Power triangle



2) Phasor diagram

Q makes 90° with P

\dot{Q} is also called
Quadrature component.



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$$S = P + jQ = VI \cos \theta + jVI \sin \theta$$

$$\dot{Q} = \frac{P}{\tan \theta}$$

$$\dot{Q} = P \tan \theta$$

(*) Total complex power supplied to a set of loads =

Σ of the individual complex power irrespective of how the loads are connected.

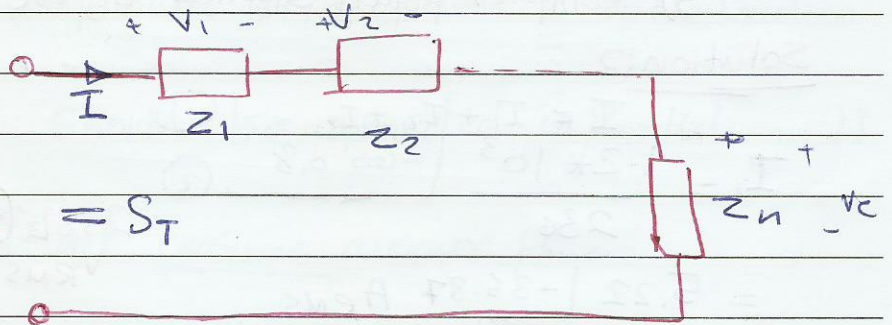
Series:

$$S_T = VI^*$$

$$= (V_1 + V_2 + \dots + V_n) I^* = S_T$$

$$= V_1 I^* + V_2 I^* + \dots + V_n I^*$$

$$S_T = S_1 + \dots + S_n$$

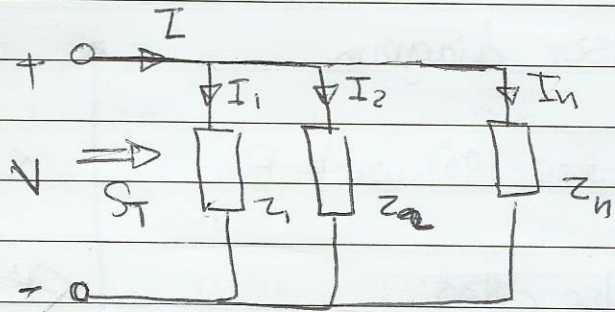


Parallel

$$i) S_T = VI^*$$

$$= V(I_1 + I_2 + \dots + I_n)^*$$

$$= VI_1^* + VI_2^* + \dots + VI_n^*$$



$$\therefore S_T = S_1 + S_2 + \dots + S_n$$

example: An Industrial company has the following 3 loads

solve for load $I = 14.35$

L_1 : A pump rated at 1.2 kVA, 0.8 PF lagging, 230 Vrms

L_2 : An Inductive motor rated at 1.6 kVA, 0.9 PF lagging, 230 Vrms

L_3 : Heater rated at 900W, unity PF, 230 Vrms

Find:

- 1) The magnitude of current supplied.
- 2) PF of source
- 3) Complex power supplied by the source

Solution

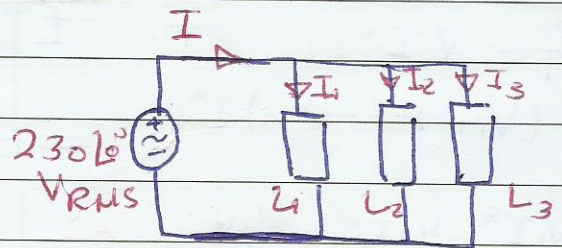
$$I = I_1 + I_2 + I_3 \quad \text{--- (1)}$$

$$I_1 = \frac{1.2 \times 10^3}{230} \angle -\cos^{-1} 0.8 \quad \text{--- (2)}$$

$$= 5.22 \angle -36.87 \text{ A}_{RMS}$$

$$I_2 = \frac{1.6 \times 10^3}{230} \angle -\cos^{-1} 0.9 = 6.96 \angle -25.84 \text{ A}_{RMS} \quad \text{--- (3)}$$

$$I_3 = \frac{900}{230 \times P.F.} \angle 0 = 3.91 \angle 0 \text{ A}_{RMS} \quad \text{--- (4)}$$



$$P = VI \cos \theta$$

$$I = \frac{P}{V \cos \theta}$$

Substitute 2, 3, 4 into 1

$$I = 15.616 \angle -23.23 \text{ ARMS}$$

↳ magnitude

$$PF = \cos(\angle V - \angle I)$$

$$\cos(0 - (-23.23))$$

$$= 0.9189 \text{ lagging}$$

$$S = V * I^*$$

$$= 230 \angle 0 * 15.616 \angle 23.23$$

$$= 3591.68 \angle 23.23 \text{ VA}$$

PF Improvement or corrections

Objective: To increase the Power Factor of a given load in order to avoid penalty or electricity bill
فانقصة التكلفة
فانقصة التكلفة

Solutions

Add a component or equipment X to the load in such way

i) X should be connected in parallel with the load.

ii) X should not consume average Power

$$P_{\text{After}} = P_{\text{Before}}$$

Ex, It's required to

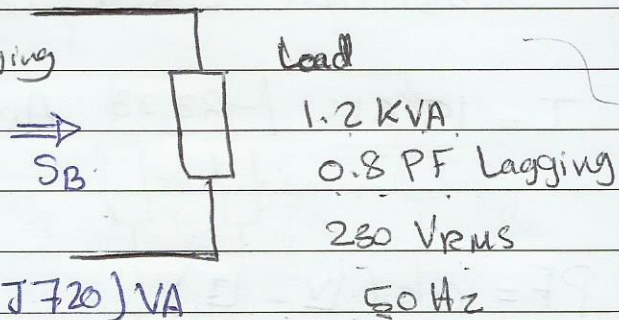
improve the PF to 0.9 Lagging

What is the solution?

Before

$$S_B = 1.2 \times 10^3 \cos^{-1} 0.8$$

$$= 1.2 \times 10^3 \cos^{-1} 0.8 = (960 + j720) \text{ VA}$$



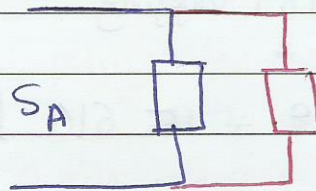
After:

$$P_A = P_B = 960 \text{ W}$$

$$\text{since } Q = P \tan \theta$$

$$\begin{aligned} \therefore Q_A &= P_A \tan \theta_A \\ &= 960 \times \tan [\cos^{-1} 0.9] \end{aligned}$$

$$\begin{aligned} &= 960 \times \tan [25.84] \\ &= 465 \text{ VAR} \end{aligned}$$



$$\therefore S_A = 960 + j465 = (S_{\text{Load}} + S_x) = (960 + j720) + S_x$$

$$\therefore (S_x) = j465 - j720 = -j255 \text{ VAR}$$

$\therefore X$ consumes pure -ve reactive power of -255 VAR

$\therefore X$ is a capacitor

Since $Q = VI \sin \theta$

for capacitor $\theta = -90^\circ$

$$\begin{aligned} \therefore |Q| &= |V| |I| \\ &= |V| \times |V| \omega C \\ &= |V|^2 \omega C \end{aligned}$$

$$i) C = |Q| / (V^2 \times \omega)$$

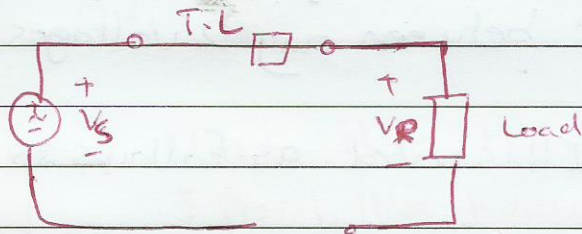
$$i) C = 255 / (230)^2 \times 2\pi(50)$$

$$= 15.4 \mu F$$

Solution: a capacitor in parallel with the load having the following specifications: \rightarrow

15.4 μF , 255 VAR, 230 V_{RMS}, 50 Hz

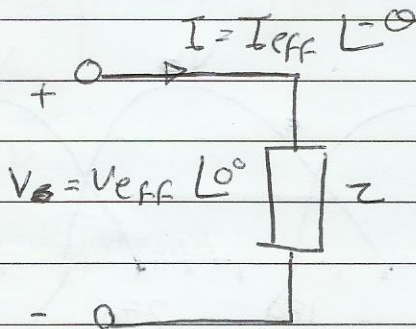
$$V_R = V_S - I Z_L$$



Current lags V by θ

$$i) \text{Shift} = |V - I|$$

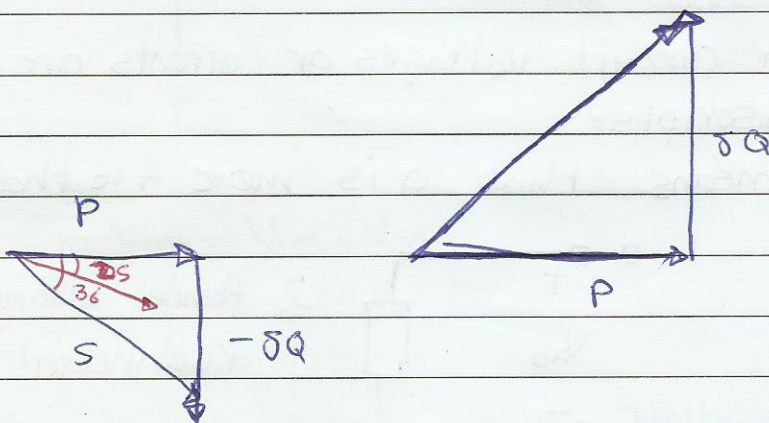
$$= 0 - (-\theta) = +\theta$$



$$Z = \frac{V}{I} = \frac{V_{eff} L^0}{I_{eff} L^{-\theta}} = |Z| L^{\theta}$$

$i)$ For inductive load $Z = +\text{PF angle}$

$$S = V \times I^* = V_{eff} L^0 \times I_{eff} L^{\theta} = V_{eff} I_{eff} L^{\theta}$$



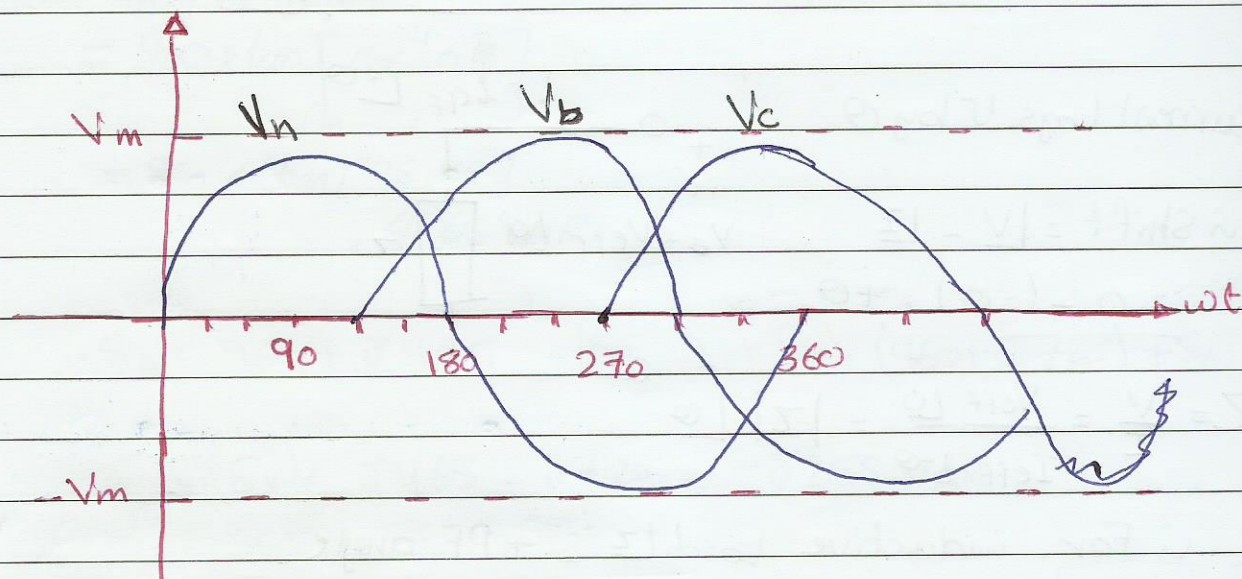
9/10:

Three phase system or circuits:

⊗ Here a 3-ph source, called 3-ph ~~syn~~

synchronous generators, generates 3 sinusoidal voltages equal in magnitude and there is a phase shift of 120° between any 2 voltages.

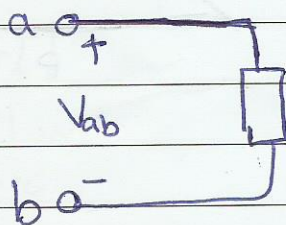
Illustrated as follows:



Double Subscript Notation

⊗ In 3-ph circuit voltages or currents are defined by double subscripts.

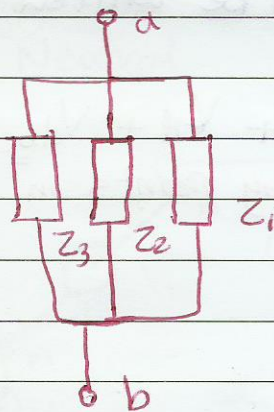
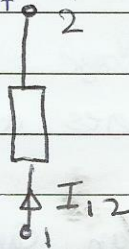
ex: V_{ab} means that a is more +ve than b



\Rightarrow Hence adding Polarity is redundant information.

⊗ Als the current $I_{12} \equiv$ means that current is flowing from Node 1 to Node 2

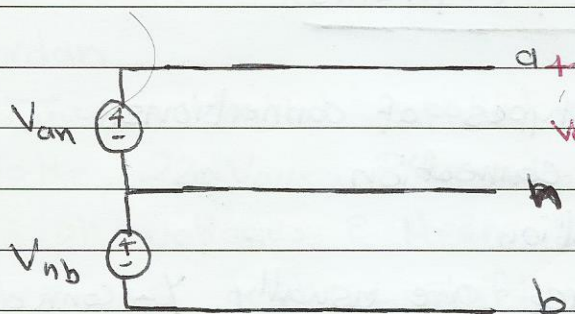
Direction of current is redundant, except when there are parallel branches between the same nodes.



$I_{ab} \equiv$ Here there are 3 possibilities hence one has to identify direction.

Single phase 3 wire system

Before analyzing the 3-ph system, an introduction about 1-ph, 3 wires given below



where
 $V_{ab} = V_{an} + V_{nb}$
 $\angle V_{an} = \angle V_{ab}$
 is one phase Angle
 b - Hence the name single phase 3 wire

by KVL:

$$V_{ab} = V_{an} + V_{nb}$$

is For $V_{an} = 120V$

is $V_{ab} = 240V$

is This system present 2 voltage levels (120 and 240)

(*) a major advantage of the Double subscript notation is that KVL can be applied directly without looking at the circuit.

Because any voltage can be written as the sum of 2 or more voltages as follows:

For e.g. V_{ab} can be written as

$$V_{ab} = V_{ac} + V_{cd} + V_{db}$$

where a, b, c and d are any points in the given circuit

$$a \begin{matrix} \bullet \\ + \end{matrix} \quad V_{ac} \quad - \quad \begin{matrix} \bullet \\ + \end{matrix} c$$

V_{ab}

V_{cd}

\Leftarrow

$$\text{in } -V_{ab} + V_{ac} + V_{cd} + V_{db} = 0$$

in KVL is satisfied

$$b \begin{matrix} \bullet \\ - \end{matrix} \quad V_{db} \quad + \quad \begin{matrix} \bullet \\ - \end{matrix} d$$

Analysis of 3-ph systems

There are two types of connections

a) γ or star connection

b) Δ connection

(*) 3-phase source are usually γ -connected.

(*) 3-phase loads can be γ or Δ connected

3-ph Y-connected source

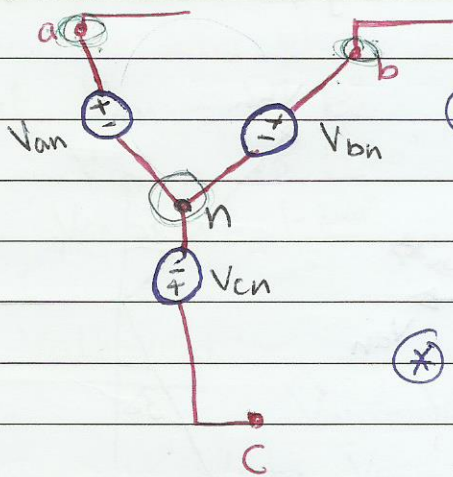
This source has

- a) 3 independent terminals called Line terminals.
- b) a common terminal called Neutral.

It is represented as follows:

a, b, c = Line Terminals ~~because~~ because they are connected to transmission line.

n = Neutral



Definitions

(*) Phase voltages

It is the voltage between a line terminal and the ~~the~~ Neutral

e.g. V_{an} , V_{bn} and V_{cn}

(*) Line voltage:

It is the voltage between any pair of line terminals

(*) The domestic distribution voltage is phase voltage.

i In Jordan

~~The~~ The residential supplied voltage is:

50 Hz, 220 V_{rms}, Phase voltage.

Balance 3-ph voltages & Means 3 voltages equal in magnitude and there is a phase shift $\approx 120^\circ$ between any 2 voltages.

Balanced 3-ph voltages: To identify such voltages as phasors, then ~~select~~ select one of them to be the Reference.

Let V_{an} to be the Ref.

$$V_{an} = V_p \angle 0^\circ$$

$$V_{bn} = V_p \angle 120^\circ$$

$$V_{cn} = V_p \angle 240^\circ$$

$V_p \equiv$ Magnitude of phase voltage usually expressed in RMS value

\rightarrow +ve phase sequence OR abc sequence

OR,

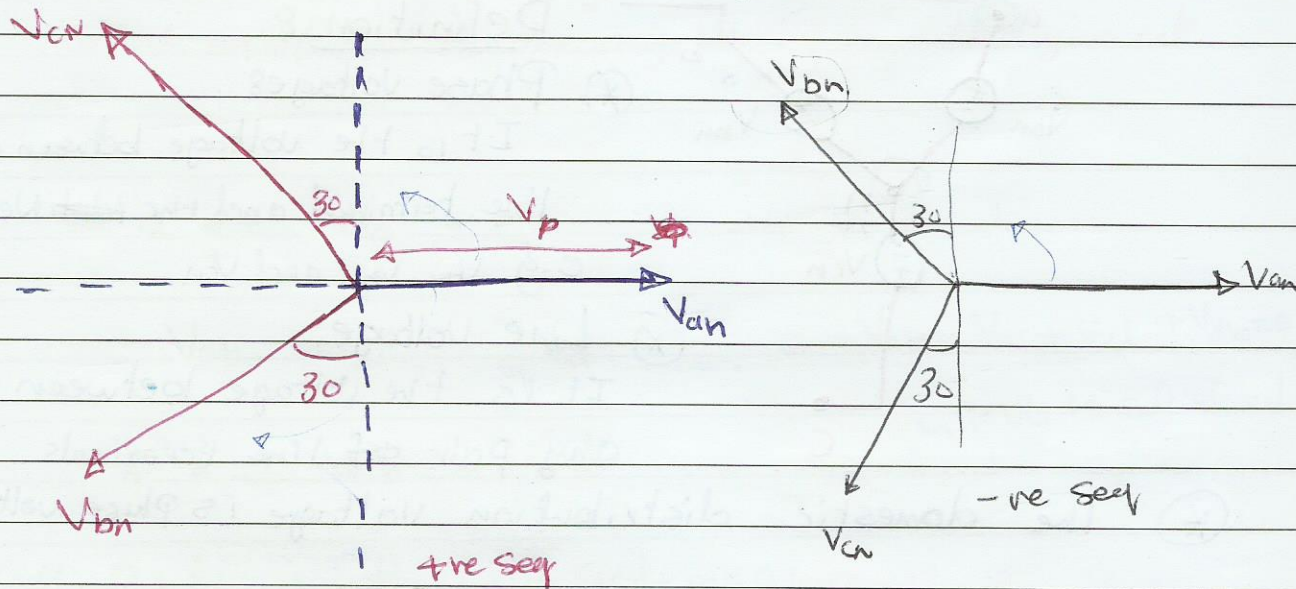
$$V_{an} = V_p \angle 0^\circ$$

$$V_{bn} = V_p \angle 120^\circ$$

$$V_{cn} = V_p \angle 240^\circ$$

\rightarrow -ve phase sequence OR cba Seq

These can be represented by phasors Diagram as follows:



Sum of Balanced Voltages

OR

currents is equal to

zero

e.g

$$V_{an} + V_{bn} + V_{cn} = 0$$

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Line Voltages

These can be evaluated by

- 1) analytical, or
- 2) graphical by using phasor diagram

i)

Assume +ve phase sequence

$$\begin{aligned} \text{Let } V_{an} &= V_p \angle 0^\circ & \text{--- (1)} \\ V_{bn} &= V_p \angle -120^\circ & \text{--- (2)} \\ V_{cn} &= V_p \angle -240^\circ & \text{--- (3)} \end{aligned} \quad \left. \vphantom{\begin{aligned} V_{an} \\ V_{bn} \\ V_{cn} \end{aligned}} \right\} \leftarrow$$

Line Voltages

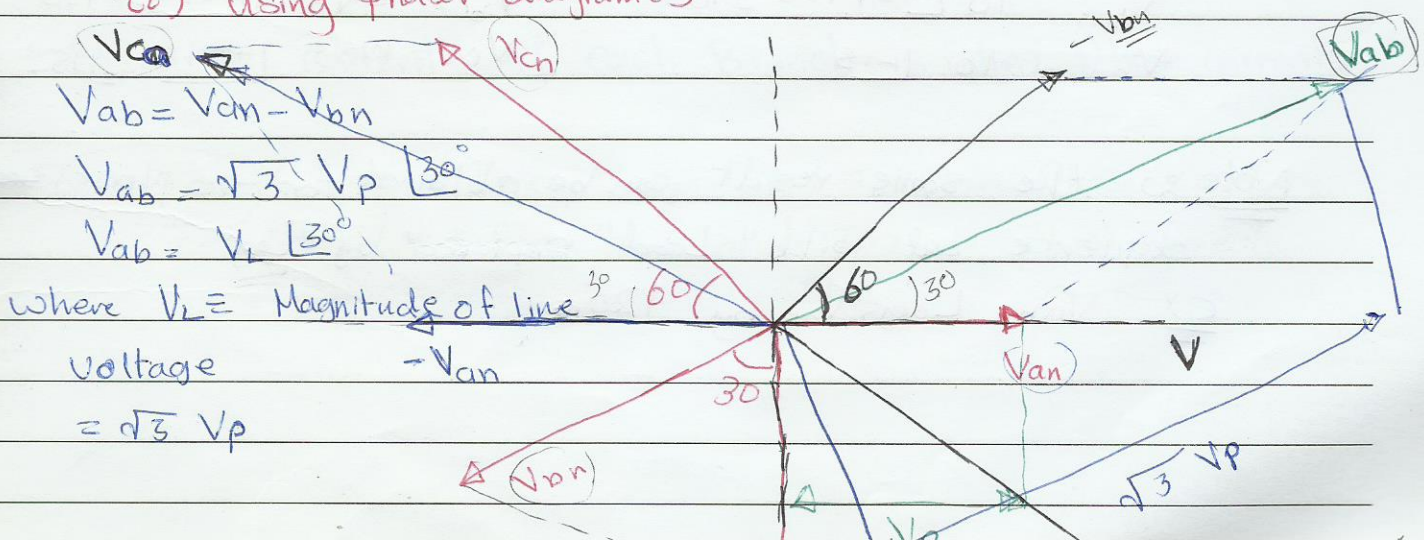
$$V_{ab} = V_{an} - V_{bn} \quad \text{--- (4)}$$

$$V_{bc} = V_{bn} - V_{cn} \quad \text{--- (5)}$$

$$V_{ca} = V_{cn} - V_{an} \quad \text{--- (6)}$$

Substitute (1), (2), (3) into (4), (5) and (6)

ii) using phasor diagram



~~XXXXXXXXXXXX~~

$$V_{bc} = V_{bn} - V_{cn}$$

$$V_{bc} = V_L \angle -90^\circ$$

$$V_{ca} = V_{cn} - V_{an}$$

$$V_{ca} = V_L \angle -210^\circ$$

(*) It can be reduced that Line voltage Leads Phase voltage by 30°

i) V_{ab} Lead V_{an} by 30°

V_{bc} " V_{bn} " "

V_{ca} " V_{cn} " "

Conclusion \Rightarrow

Hence knowing any voltage (phase) or line

then the other voltages can be derived

ex \Rightarrow If $V_{cn} = 10 \angle -15^\circ$

Find all phase and line voltages, Assuming +ve phase sequence.

Phase voltage

$$V_{an} = 10 \angle 105 + 20 = 225^\circ$$

$$V_{bn} = 10 \angle -15 + 120 = 105^\circ$$

$$V_{cn} = 10 \angle -15$$

Line voltages

$$V_{ab} = 10\sqrt{3} \angle 225 + 30 = 255^\circ$$

$$V_{bc} = 10\sqrt{3} \angle 105 + 30 = 135^\circ$$

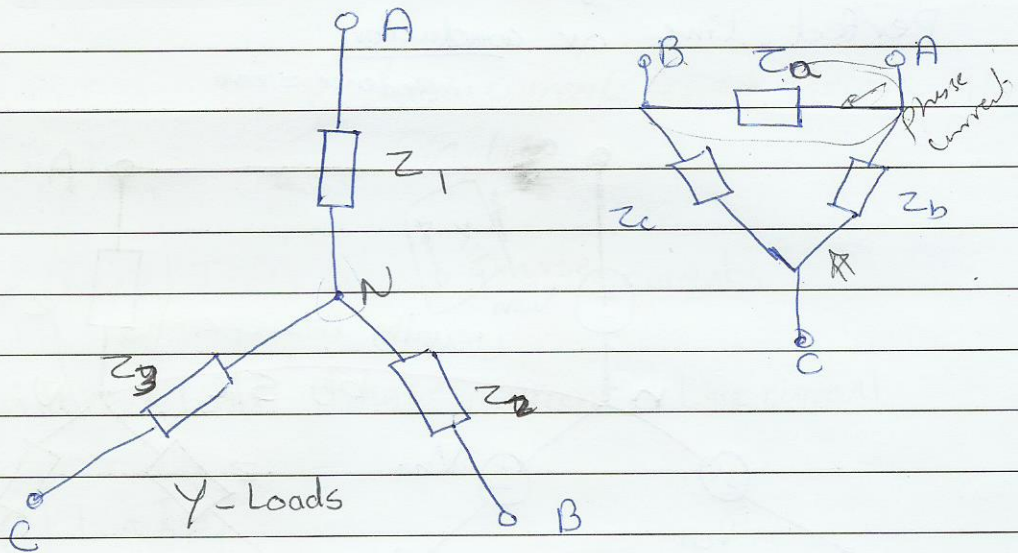
$$V_{ca} = 10\sqrt{3} \angle -15 + 30 = 15^\circ$$

Note \Rightarrow the same result can be obtained for -ve phase sequence but with "Lead" replaced by "Lag"

ex V_{ab} Lags V_{bc} by 120°

3-Phase Loads

This can be connected as Y or Δ as follows



(Balanced Loads) Means that the impedance of each Branch is the same

$$\text{For Y-load} \Rightarrow Z_1 = Z_2 = Z_3 = Z$$

$$(\Delta\text{-Load}) \Rightarrow Z_a = Z_b = Z_c = Z$$

The voltage across each Branch is called Phase voltage.

For Y-load, V_{AN} , V_{BN} and V_{CN} are phase voltages.

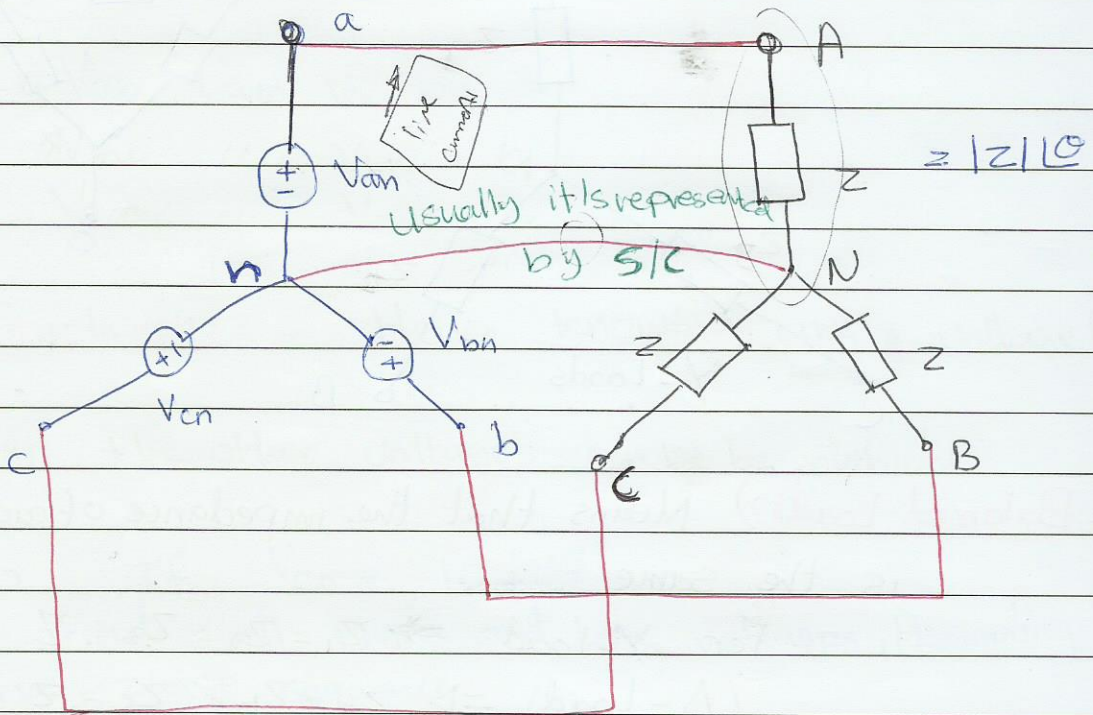
(*) The current of each Branch is called Phase current.

For Y-load: I_{AN} , I_{BN} and $I_{CN} \Rightarrow$ Phase currents

For Δ -load: I_{AB} , I_{BC} and $I_{CA} \Rightarrow$ Phase currents

3-phase system :-

(*) Consider a balance 3-ph Y-source supplying electrical energy to a balance 3-ph Y-load through Perfect line or conductors!
impedance = zero



Objective :- Evaluate various voltages and currents and find relationships between them.

∴ From Fig. 1 :-

$$I_{aA} = I_{AN} = \frac{V_{AN}}{Z} = \frac{V_{an}}{Z} = \frac{V_p \angle 0^\circ}{|Z| \angle \theta} = \frac{V_p}{|Z|} \angle (-\theta)$$

$$I_p = \frac{V_p}{|Z|} = \text{Magnitude of phase current Fig 1}$$

$$I_{bB} = I_{BN} = \frac{V_{bN}}{Z} = \frac{V_{bn}}{Z} = \frac{V_p \angle -120^\circ}{|Z| \angle \theta}$$

$$= \frac{V_p}{|Z|} \angle (-120^\circ - \theta) = I_p \angle (-120^\circ - \theta)$$

$$I_{CC} = I_{CN} = V_{CN} / Z = V_{CN} / z = \cancel{V_p} V_p \angle^{-240^\circ} / |z| \angle \theta$$

$$= \frac{V_p}{|z|} \angle^{-240^\circ - \theta} = I_p \angle^{-240^\circ - \theta}$$

I_{CA}, I_{CB}, I_{CC} Line currents ~~because~~ Because they flow in line.

I_{AN}, I_{BN}, I_{CN} ← Phase currents

∴ For Y load Phase current = Line current

$$I_L = I_p$$

∴ Phase currents

I_{AN}, I_{BN} and I_{CN} are Balanced

$$\therefore I_{AN} + I_{BN} + I_{CN} = 0$$

$$\text{By KCL} \Rightarrow I_{Nn} = I_{AN} + I_{BN} + I_{CN}$$

$$= 0$$

(*) Since $I_{Nn} = 0$

Then the Line (N_n) can be represented by any Impedance without affecting the calculation.

including star or line



Balanced

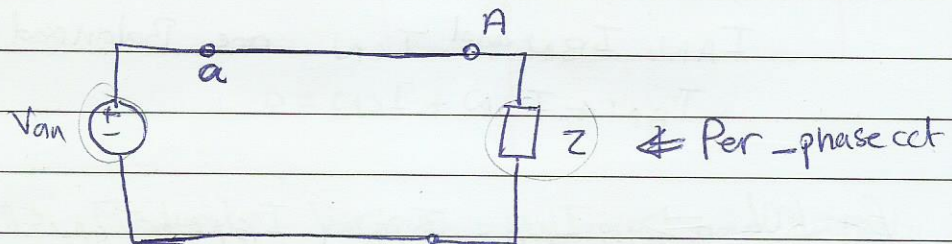
Conclusions (Y-Y System) \rightarrow

i) Since $I_{Nn} = 0$, then it line can be represented by any impedance including SL or OL usually it is represented by SL

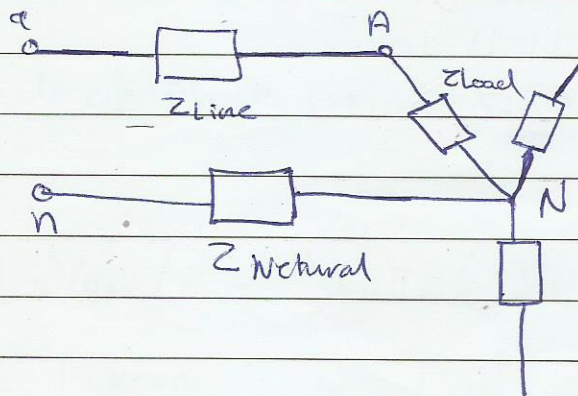
ii) $I_L = I_p$

iii) $V_L = \sqrt{3} V_p$

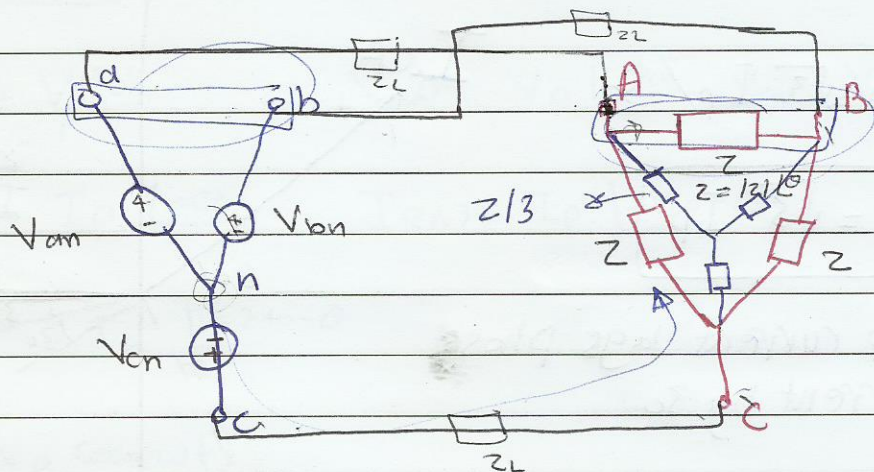
iv) Since knowing the voltage and current of one phase and then the voltages and currents of other phases can be deduced, Hence the 3-ph ckt. can be represented by a single phase ckt called per-phase ckt. as follows:



iv) The same result ($I_{Nn} = 0$) $N \rightarrow$ can be obtained if the lines are not perfect conductors, but they are balanced (i.e. have equal impedance). Because Z_{Line} can be combined with Z_{Load}



Y-Δ system



in For Δ -Load $| \text{phase voltage} | = | \text{Line voltage} |$

$$\underline{V_{AB} = V_{ab}}$$

$$\underline{V_{BC} = V_{bc}}$$

$$\underline{V_{CA} = V_{ca}}$$

Y-Δ System (Balanced)

Phase currents

Assuming the phase sequence,

By KCL \Rightarrow
line current

$$I_{aA} = I_{AB} - I_{CA} = \frac{V_{AB}}{Z} - \frac{V_{CA}}{Z} = \frac{V_L \angle 0^\circ}{|Z| \angle \theta} - \frac{V_L \angle -240^\circ}{|Z| \angle \theta}$$

$$\text{but } V_{AB} = V_L \angle 0^\circ \quad \text{in } I_{aA} = \frac{V_L \angle 0^\circ}{|Z|} - \frac{V_L \angle -240^\circ}{|Z|}$$

$$= I_p \angle 0^\circ - I_p \angle -240^\circ$$

$$I_p = \frac{V_L}{|Z|} = \text{Magnitude of phase current}$$

I_{aA} can be calculated analytical or by using phase diagram

To simplify let $\theta = 0^\circ$

$$I_{aA} = \sqrt{3} I_p \angle -30^\circ$$

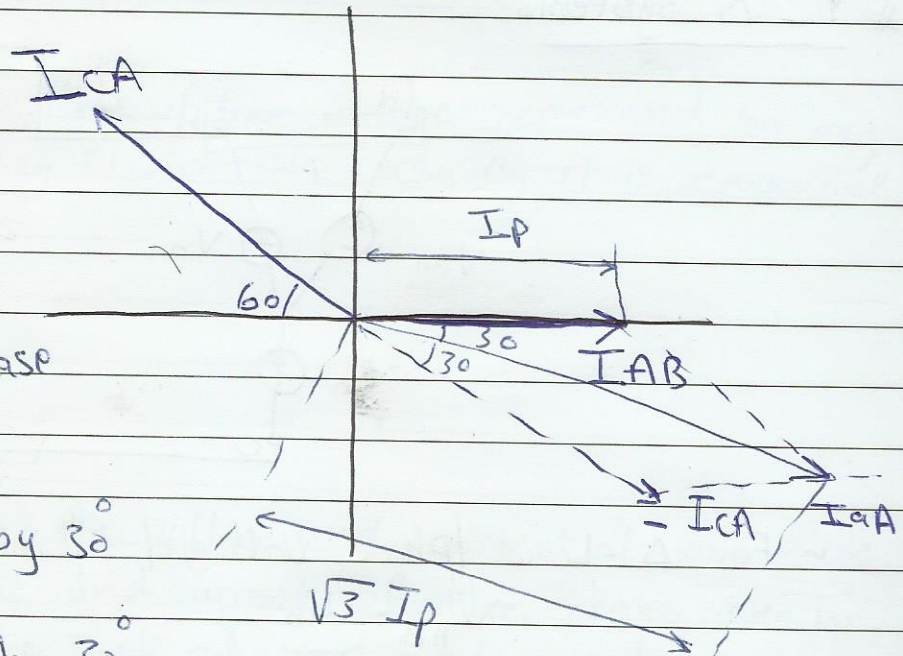
$$I_L = \sqrt{3} I_p$$

line current lags phase
current by 30°

I_{aA} lags I_{aB} by 30°

I_{bB} " I_{bC} by 30°

I_{cC} " I_{cA} by 30°



(# Power supplied to Balanced 3-ph load)

Average Power

$$P_{3-ph} = 3 \times P_{1-ph} = 3 \times V_p I_p \cos \theta$$

$\theta \equiv$ phase shift between (phase voltages) and phase current
 $= \angle Z$

$$P_{V-load} = 3 \times \frac{V_L}{\sqrt{3}} \times I_L \times \cos \theta = \sqrt{3} V_L I_L \cos \theta$$

$$P_{\Delta-load} = 3 \times V_L \times \frac{I_L}{\sqrt{3}} \cos \theta = \sqrt{3} V_L I_L \cos \theta$$

* Instantaneous Power \Rightarrow

$$\text{Let } V_{AN} = V_p \angle 0^\circ \quad \dots \quad V_{BN} = V_p \angle 120^\circ, \quad V_{CN} = V_p \angle -240^\circ$$

$$\text{in } I_{AN} = I_p \angle -\theta \quad \quad I_{BN} = I_p \angle -120^\circ - \theta$$

$$I_{CN} = I_p \angle -240^\circ - \theta$$

$$\text{in } V_{AN} = V_p \cos(\omega t)$$

$$V_{BN} = V_p \cos(\omega t - 120^\circ)$$

$$V_{CN} = V_p \cos(\omega t - 240^\circ)$$

$$i_{AN} = I_p \cos(\omega t - \theta)$$

$$i_{BN} = I_p \cos(\omega t - 120^\circ - \theta)$$

$$i_{CN} = I_p \cos(\omega t - 240^\circ - \theta)$$

$$\text{in } P_{AN} = V_{AN} \times i_{AN} = V_p I_p \cos \omega t \cdot \cos(\omega t - \theta) = \frac{1}{2} V_p I_p \cos \theta + \frac{1}{2} V_p I_p \cos(2\omega t - \theta) \quad \text{--- (1)}$$

$$V_p I_p$$

E

~~$P_{AN} = V_{AN} \times i_{AN}$~~

$$P_{BN} = V_{BN} \times i_{BN} = I_p V_p \cos(\omega t - 120^\circ) \cdot \cos(\omega t - \theta - 120^\circ)$$

$$P_{BN} = \frac{1}{2} V_p I_p \cos \theta + \frac{1}{2} V_p I_p \cos(2\omega t - 240^\circ - \theta) \quad \text{--- (2)}$$

$$P_{CN} = V_{CN} \times i_{CN} = \frac{1}{2} V_p I_p \cos \theta + \frac{1}{2} V_p I_p \cos(2\omega t - 480^\circ - \theta) \quad \text{--- (3)}$$

G

$$\hat{i} P_{3-ph} = P_{AN} + P_{BN} + P_{CN} = \textcircled{1} + \textcircled{2} + \textcircled{3} =$$

$$\frac{3}{2} V_p I_p \cos \theta + [E + F + G] = 0$$

$$\hat{i} P = \frac{3}{2} V_p I_p \cos \theta = P \quad \text{= constant value}$$

This one of the adv of 3-ph circuits

$$\# \quad P = 3 \times \frac{1}{2} V I \cos \theta = 3 V I \cos \theta = \sqrt{3} V I \cos \theta \quad \text{W}$$

Peak *RMS phase* (*RMS Line*)

$$Q = 3 \times \frac{1}{2} V I \sin \theta = 3 V I \sin \theta = \sqrt{3} V I \sin \theta \quad \text{VAR}$$

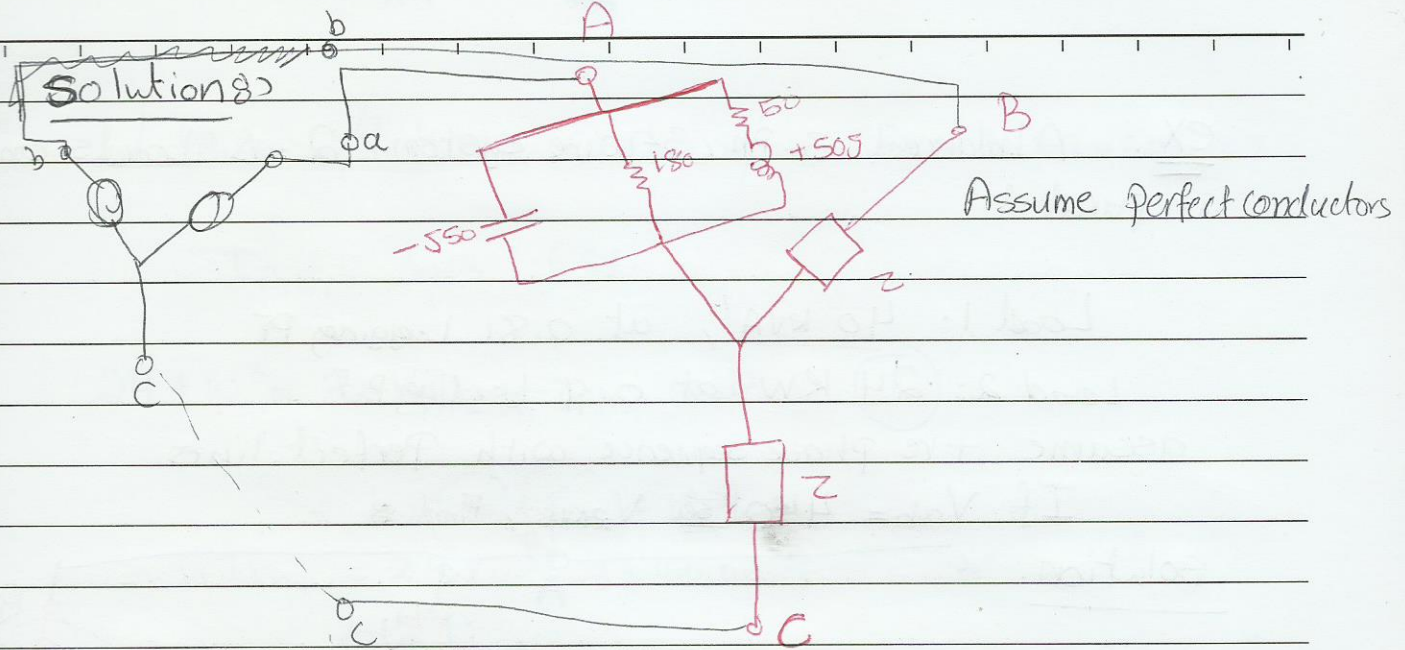
$$S = P + jQ \quad \hat{i} |S| = \sqrt{P^2 + Q^2} = 3 V I \text{ OR } \sqrt{3} V I \quad \text{(VA)}$$

ex :> If $V_{ab} = 100 \angle 0^\circ$, $V_{bd} = 40 \angle 80^\circ$ and $V_{ca} = 70 \angle 300^\circ$
find V_{bc}

$$\hat{i} V_{bc} = V_{ba} + V_{ac} = -V_{ab} - V_{ca} = -100 \angle 0^\circ - 70 \angle 200^\circ = 41.75 \angle 145^\circ$$

ex :> A balance 3-ph, 3-wire system has a Δ -connected load
Each phase contains 3 loads in parallel : $-j100 \Omega // 100 \Omega //$
(50175)

Assume +ve phase sequence with $V_{ab} = 400 \angle 0^\circ$ VRMS, Find the followings.



i) $V_{an} = \frac{400}{\sqrt{3}} \angle 0-30^\circ$

ii) $I_{aA} = I_{aB} = I_{aC} = \frac{V_{an}}{Z} \quad \text{--- (1)}$

But $V_{an} = \frac{400}{\sqrt{3}} \angle -30^\circ \text{ V RMS} \quad \text{--- (2)}$

$\frac{1}{Z} = \frac{1}{-j100} + \frac{1}{100} + \frac{1}{50+j30} \Rightarrow Z = 50 \angle 0^\circ \Omega \quad \text{--- (3)}$

∴ by substituting (2) and (3) into (1) \Rightarrow

$I_{aA} = 4.62 \angle 30^\circ$

iii) Find P supplied to Load

$P = 3VI \cos \theta = \sqrt{3} VI \cos \theta = 3I^2 R_{Ph}$

Here $\theta = 0$

$P = 3 \times (4.62)^2 \times 50 = 3201.7 \text{ W}$

$$PF = \frac{\text{Average } P}{\text{Apparent}}$$

ex: A balanced 3-ph, 3-wire system 2- Δ Loads connected in parallel

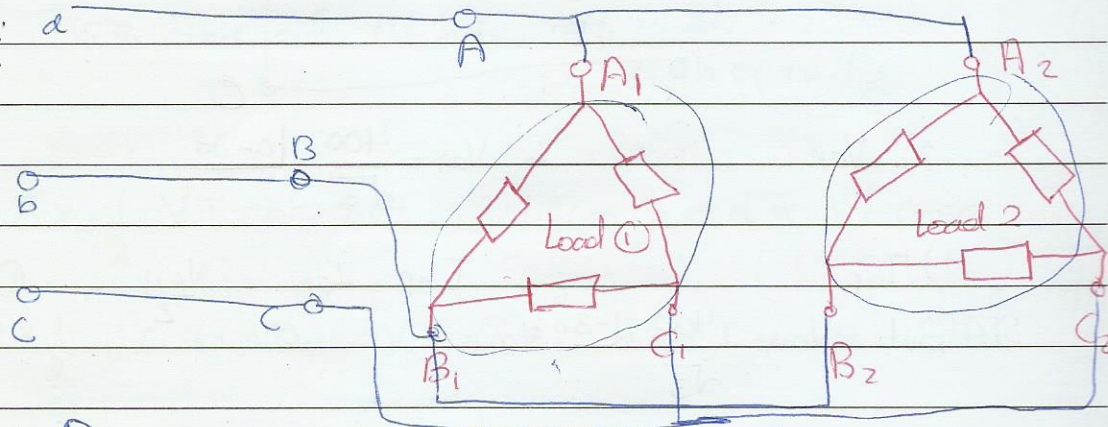
Load 1: 40 kVA, at 0.81 lagging PF

Load 2: 24 kW, at 0.9 leading PF

assume +ve phase sequence with Perfect lines

If $V_{ab} = 440 \angle 30^\circ$ V rms, Find 3

Solution: a



i) Find total P supplied by source OR to loads

$$P = P_1 + P_2$$

$$P = 40 \times 0.8 \text{ kW} + 24 = 32 + 24 = 56 \text{ kW}$$

ii) Evaluate $I_{A_1 B_1}$ and $I_{A_2 B_2}$

$$I_{A_1 B_1} = I_{ph_1}$$

$$I_{A_2 B_2} = I_{ph_2}$$

$$40 \times 10^3 = 3 V_{ph_1} I_{ph_1} = 3 \times 440 \times I_{ph_1}$$

$$\therefore I_{ph_1} = 40 \times 10^3 / 3 \times 440 = \boxed{30.3} \text{ A rms}$$

$$\angle I_{A_1 B_1} = \angle V_{A_1 B_1} - \cos^{-1} 0.8 = 30 - 36.87 = -6.87$$

$$\dot{i} I_{A_1 B_1} = 30.3 \angle -6.87$$

$$24 \times 10^3 = 3 \times V_{ph2} \times I_{ph2} \cos \theta$$

$$= 3 \times (440) \times I_{ph2} \times 0.9$$

$$\dot{i} I_{ph2} = \frac{24 \times 10^3}{3 \times 440 \times 0.9}$$

$$= 20.2 \text{ Arms}$$

$$\angle I_{A_2 B_2} = \angle V_{A_2 B_2} + \cos^{-1} 0.9 = 30^\circ + 25.8^\circ = \boxed{55.8^\circ}$$

$$\dot{i} I_{A_2 B_2} = 20.2 \angle 55.8^\circ$$

$$I_{cc} \Rightarrow I_{cA}$$

ii) Find $I_{cA} = I_{cA_1} + I_{cA_2}$

$$\sqrt{3} \times 30.3 \angle -6.87 - 30 + \sqrt{3} \times 20.2 \angle 55.8 - 30^\circ$$

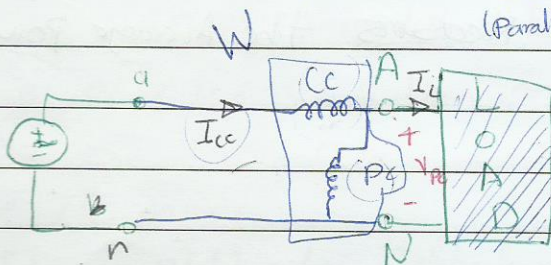
$$I_{cA} = 75.3 \angle -124.3 \text{ Arms}$$

Power Measurement: This is measured by Wattmeter

It consist of 2 coils :-

i) coil connected in series with Load, called current coil. (CC)

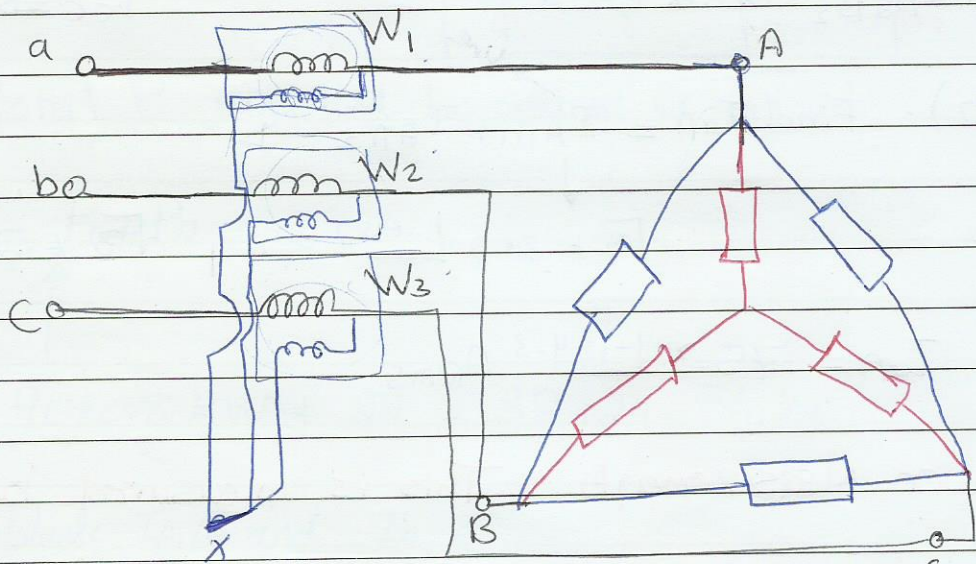
ii) ~ ~ ~ across the ~ ~ ~ potential coil. (PC)



$$\begin{aligned} \text{Wattmeter Reading} &= |I_{cc}| \times |V_{pc}| \times \cos(\angle V_{pc} - \angle I_{cc}) \\ &= |I_L| \times |V_L| \cos(\angle V_L - \angle I_L) \\ &= |I_L| |V_L| \cos \theta = P_{\text{Load}} \end{aligned}$$

Measurement of 3-ph Power

(*) Sometimes the Neutral of the Y-Load does not exist, and also in the case of Δ -Load, the current coil cannot be connected in series with each phase. Hence the Wattmeters should be connected on the line terminals as follows:



(*) The potential coil is connected between each Line and a Reference point say x where x is any point in the 3-ph system

(*) Since the Wattmeter Measures the Average Power, P

$$W_1 = \frac{1}{T} \int_0^T i_{aA} v_{Ax} dt$$

$$W_2 = \frac{1}{T} \int_0^T i_{aB} V_{Bx} dt$$

$$W_3 = \frac{1}{T} \int_0^T i_{cC} V_{Cx} dt$$

Summate the 3 Readings:

$$W = W_1 + W_2 + W_3$$

$$= \frac{1}{T} \int_0^T (i_{aA} V_{Ax} + i_{bB} V_{Bx} + i_{cC} V_{Cx}) dt \quad \text{--- (1)}$$

By using Double Notations:

$$V_{Ax} = V_{AN} + V_{Nx}$$

$$V_{Bx} = V_{BN} + V_{Nx}$$

$$V_{Cx} = V_{CN} + V_{Nx}$$

(2)

Substitute (2) into (1) \rightarrow

$$W = \frac{1}{T} \int_0^T (i_{aA} V_{AN} + i_{bB} V_{BN} + i_{cC} V_{CN}) dt + \frac{1}{T} \int_0^T V_{Nx} (i_{aA} + i_{bB} + i_{cC}) dt$$

zero because

Balanced currents



$$\therefore W = \frac{1}{T} \int_0^T (i_{aA} V_{AN} + i_{bB} V_{BN} + i_{cC} V_{CN}) dt$$

= Average Power supplied to 3-ph Reading, $P_{3\phi}$

\therefore Sum of Readings = $P_{3\phi}$

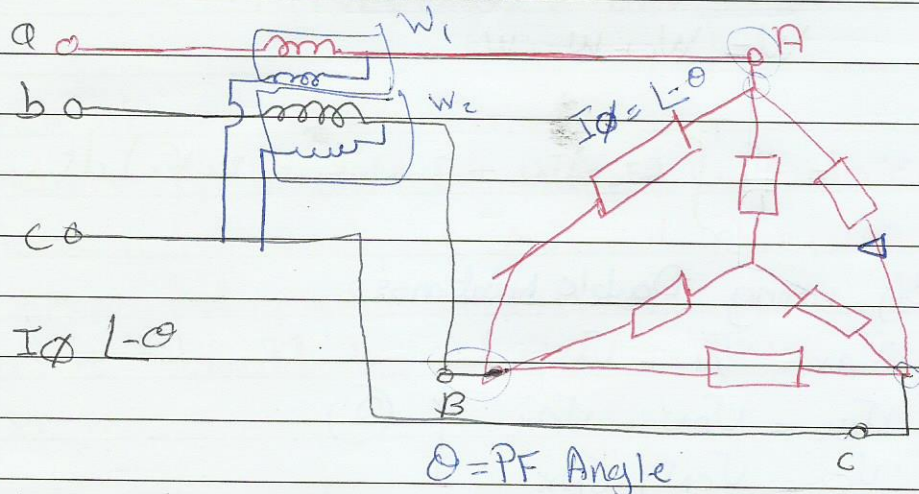
(*) If the Ref point X is taken to be one of the phases (i.e. a or b or c), Then one of the wattmeter Reading will be zero. Hence only 2 wattmeter are required.

Hence the names =

Two - wattmeter Methods:

(*) Let $V_{ab} = V \angle 0^\circ$ VRMS
and assume the phase sequence.

(*) Let the Ref. Point phase C.



(*) Let $I_{AB} = I_\phi \angle -\theta$

$$W_1 = |I_{aA}| |V_{AC}| \cos(\angle V_{AC} - \angle I_{aA}) \quad \text{--- (1) } I_\phi = \text{phase current magnitude}$$

$$W_2 = |I_{bB}| |V_{BC}| \cos(\angle V_{BC} - \angle I_{bB}) \quad \text{--- (2)}$$

$$I_{aA} = \sqrt{3} I_\phi \angle -\theta - 30^\circ \quad \text{--- (3) } \quad \text{Since } I_{AB} = I_\phi \angle -\theta$$

$$\text{But } V_{CA} = V \angle -240^\circ$$

$$V_{AC} = -V_{CA} = V \angle -60^\circ \quad \text{--- (4)}$$

$$\angle I_{bB} = \sqrt{3} I_\phi \angle -\theta - 30^\circ - 120^\circ = -\theta - 150^\circ \quad \text{--- (5)}$$

$$V_{BC} = V \angle -120^\circ \quad \text{--- (6)}$$

Substitute (3) and (4) into (1)

" (6) " (5) " (2) \Rightarrow

$$W_1 = \sqrt{3} I_\phi \times V \times \cos(-60^\circ - (-\theta - 30^\circ)) = \sqrt{3} I_\phi V \cos(\theta - 30^\circ) \quad \text{--- (7)}$$

$$W_3 = \sqrt{3} I_\phi \times V \times \cos(-120^\circ - (-\theta - 130^\circ)) = \sqrt{3} I_\phi V \cos(\theta + 30^\circ) \quad \text{--- (8)}$$

$$i) W_1 + W_2 = VI [\cos(\theta - 30) + \cos(\theta + 30)]$$

$$= VI [2 \cos \theta \cdot \cos 30 + 0]$$

$$= 2VI \cos \theta \cdot \cos 30$$

$$W_1 + W_2 = \sqrt{3} VI \cos \theta = P$$

Comments and conclusions

$$ii) W_1 - W_2 = VI [\cos(\theta - 30) - \cos(\theta + 30)]$$

$$W_1 - W_2 = 2VI \sin \theta \cdot \sin 30 = VI \sin \theta$$

$$\sqrt{3} (W_1 - W_2) = \sqrt{3} VI \sin \theta = Q \text{ Reactive Power}$$

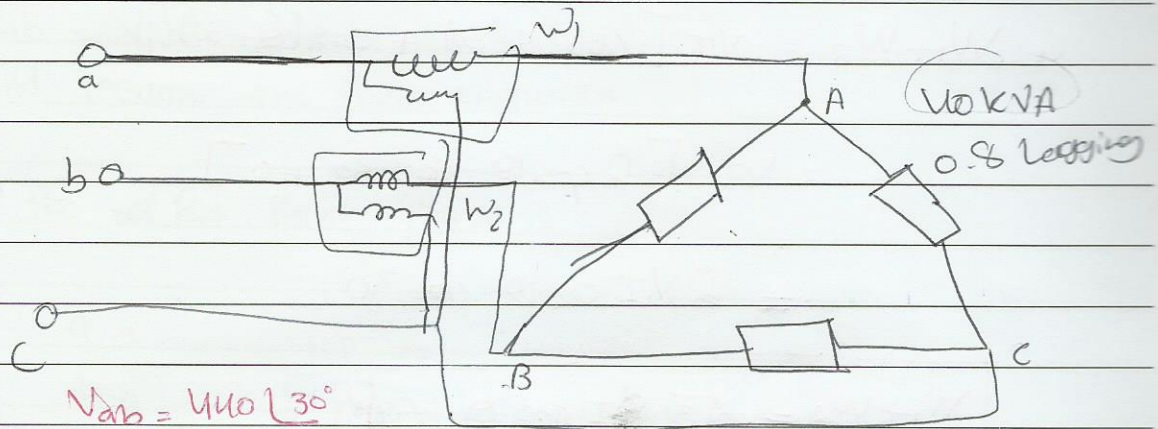
∴ Difference between Readings & Reactive Power

$$ii) \frac{\sqrt{3} (W_1 - W_2)}{(W_1 + W_2)} = \frac{\sqrt{3} VI \sin \theta}{\sqrt{3} VI \cos \theta}$$
$$= \tan \theta$$

$$\therefore \theta, \text{ Pf Angle} = \tan^{-1} \left[\frac{\sqrt{3} (W_1 - W_2)}{W_1 + W_2} \right]$$

$$\text{Pf} = \tan \theta$$

MCQ



Given $V_{ab} = 440 \angle 30^\circ$

$$W_1 = |I_{aA}| |V_{ac}| \cos(\angle V_{ac} - \angle I_{aA})$$

$$I_{aA} = \sqrt{3} \times 30.3 \angle -36.87^\circ$$

$$I_{bB} = \sqrt{3} \times 30.3 \angle -87.12^\circ$$

$$V_{bc} = 440 \angle 30 - 120 = -90^\circ$$

$$W_2 = |I_{bB}| |V_{bc}| \cos(\angle V_{bc} - \angle I_{bB})$$

$$V_{ca} = 440 \angle -210$$

$$V_{ac} = -V_{ca} = 440 \angle -30^\circ$$

By substituting

$$W_1 = 23092.7 \text{ W}$$

$$W_2 = 9070.9 \text{ W}$$

$$W_1 + W_2 = 32.2 \text{ kW}$$

Magnetic couple circuit 4||1 (We can :))

Definition :-

These are electrical circuits which are electrically isolated but coupled (or connected) by means of magnetic field.

Principle of operations

any current i → Generates Magnetic flux ϕ
 $\phi \propto i$ | if i is dc the ϕ will be dc, if i is ac then ϕ is ac → if ϕ cut a conductor or a coil, then a voltage e will be induced in this conductor or coil, where by Faraday's Law

$$e \propto \frac{d\phi}{dt}$$

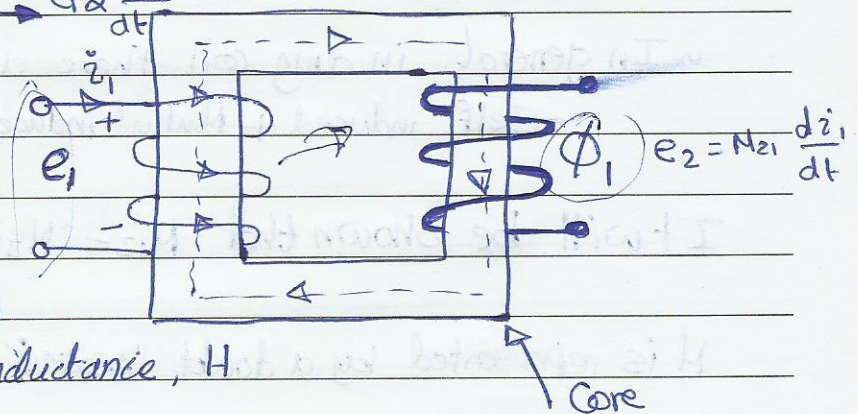
$$e \propto \frac{di}{dt}$$

Induced voltage e Consider the following case

$$i \rightarrow \phi_1 \rightarrow e_1 \rightarrow e_1 \propto \frac{d\phi_1}{dt} \rightarrow e_1 \propto \frac{di_1}{dt}$$

$$e_1 \propto \frac{di_1}{dt}$$

$$e_1 = L_1 \frac{di_1}{dt} \quad ; \quad L_1 \equiv \text{constant of proportionality called self Inductance, H.}$$



Polarity of e_1 is defined by Passive sign convention.

⊗ Consider a 2nd coil, installed on the same ~~coil~~ core.
 Hence due to ϕ_1 a voltage e_2 will be induced in this 2nd coil.

$$e_2 \propto \frac{d\phi_1}{dt} \propto \frac{di_1}{dt}$$

$$e_2 = M_{21} \frac{di_1}{dt}$$

$$e_2 = M_{21} \frac{di_1}{dt}$$

M_{21} = constant of proportionality called Mutual Inductance
↑ Its unit is Henry

↳ voltage in the 2nd coil due to current in the first coil

The Polarity of the Mutually Induced voltage, e_2 can be found by means of Dot convention which will be explained later on.


(*) If now a current i_2 flow in the 2nd coil → it will generate flux Φ_2 → Φ_2 will

1) induce a self voltage in the 2nd coil = $L_2 \frac{di_2}{dt}$
and

2) induce a mutual voltage in the 1st coil = $M_{12} \frac{di_2}{dt}$

↳ In general in any coil there are 2 induced voltages: \Rightarrow
Self induced + Mutual induced.

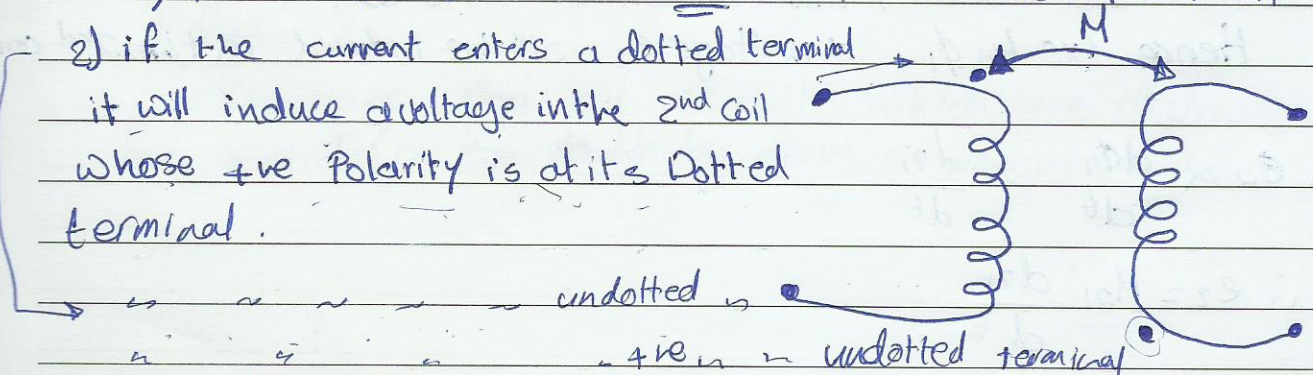
It will be shown that $M_{12} = M_{21} = M$

M is represented by a double headed arrow 

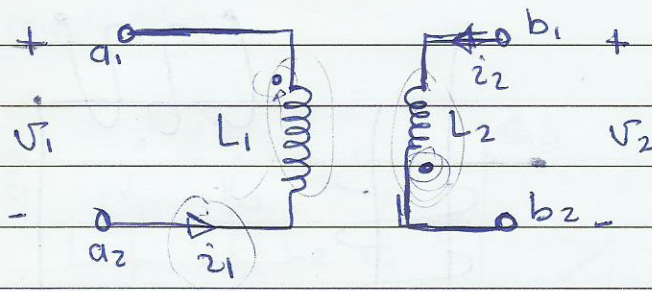
Dot conventions

1) A dot is located at one of the terminals of each coil

2) if the current enters a dotted terminal it will induce a voltage in the 2nd coil whose +ve Polarity is at its Dotted terminal.



$v_1, v_2 \equiv$ Terminal Voltages
 Apply KVL \Rightarrow



1st Loop

$$-v_1 - L_1 \frac{di_1}{dt} - M_{12} \frac{di_2}{dt} = 0 \quad \text{--- (1)}$$

2nd Loop \Rightarrow $-v_2 + L_2 \frac{di_2}{dt} + M_{21} \frac{di_1}{dt} = 0 \quad \text{--- (2)}$

(1), (2) are written in time domain.

Frequency domain is also applicable to $M \Rightarrow j\omega m$

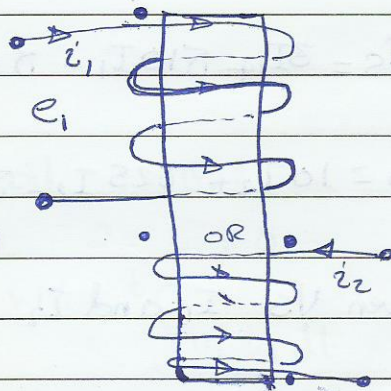
$$(1) \Rightarrow -v_1 - j\omega L_1 I_1 - j\omega m I_2 = 0 \quad \text{--- (3)}$$

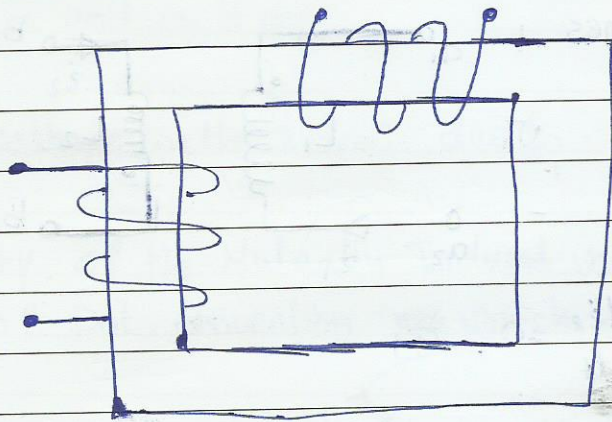
$$(2) \Rightarrow -v_2 + j\omega L_2 I_2 + j\omega m I_1 = 0 \quad \text{--- (4)}$$

Physical Meaning of Dot convention

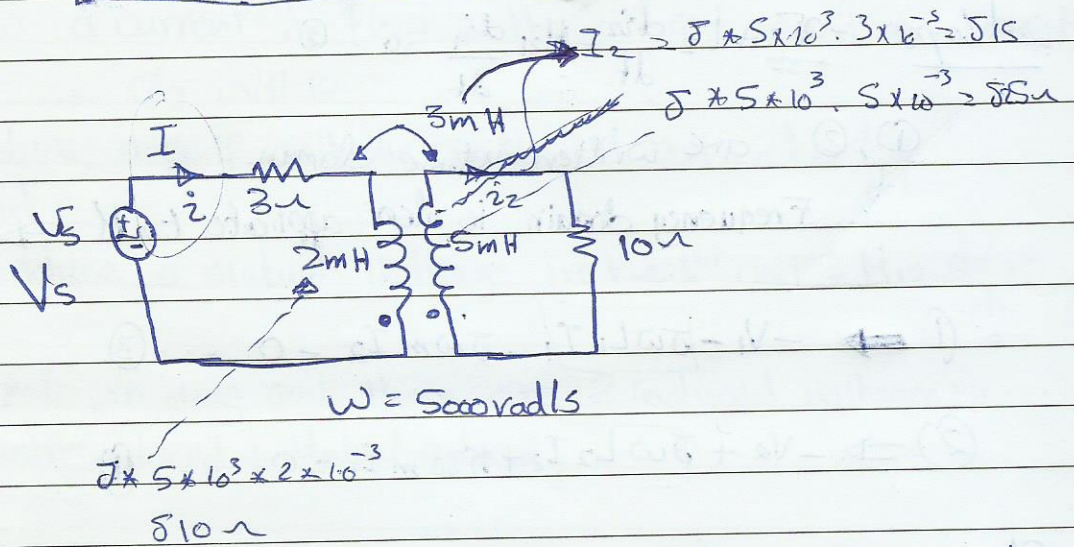
\rightarrow ϕ \rightarrow $\frac{d\phi}{dt}$ \rightarrow i_2, i_1 \rightarrow $\frac{dI_1}{dt}$

Hence : Dots are located at the terminals at which entering currents produce Aiding flux (flux in the same direction)





G11:3



eg for the given circ. write the mesh equation in Frequency domain

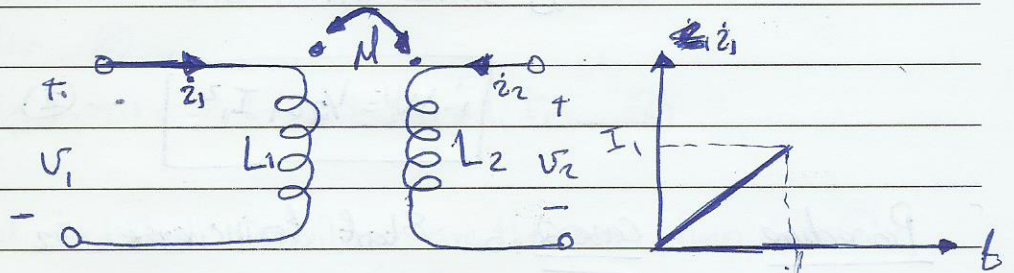
BKVL

$$V_s = 3I_1 + 510I_1 - 15I_2 \quad \text{--- (1)}$$

$$0 = 10I_2 + 25I_2 - 15I_1 \quad \text{--- (2)}$$

For a given V_s I_1 and I_2 can be evaluated.

Energy stored in Mutually couple coils



Objective :- i) To find expression for such energy. Because it has many practical Applications

ii) To show that $M_{12} = M_{21} = M$

iii) Find an upper Limit For M .

Procedure :- Case 1:

coil 2 is O.C. (i.e. $i_2 = 0$)

Start to increase i_1 from zero to a certain value I_1 at $t = t_1$, and then keep it constant at this value.

Find the energy stored in this case

$$i) v_1 = L_1 \frac{di_1}{dt} + 0$$

$$v_2 = 0 + M \frac{di_1}{dt}$$

i) Power supplied to coil 1 = $v_1 i_1$

ii) Power supplied to coil 2 = $v_2 i_2 = 0$

i) Energy stored in coil 1 = $W_1 = \int_0^t v_1 i_1 dt$

$$i) W_1 = \int_0^t L_1 \frac{di_1}{dt} \cdot i_1 dt$$

$$= \int_0^{I_1} L_1 i_1 di_1 = \boxed{\frac{1}{2} L_1 I_1^2} \quad \text{--- (1)}$$

Energy stored in coil 2 = 0

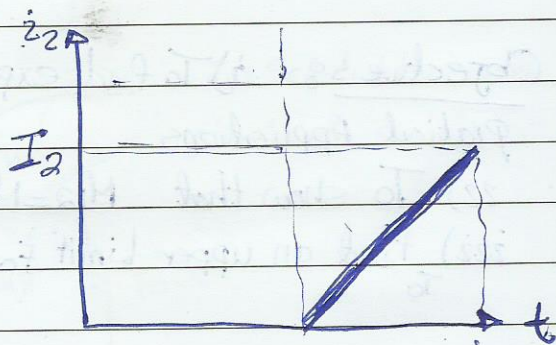
∴ Energy stored in this case = $W_1' + W_2'$

$$\boxed{\therefore W = \frac{1}{2} L_1 I_1^2} \quad \dots (2)$$

Procedure Case 2: Start to increase i_2 From 0 at $t = t_1$ to a fixed value I_2 at $t = t_2$

$$V_1 = 0 + M \frac{di_2}{dt} = M \frac{di_2}{dt}$$

$$V_2 = L_2 \frac{di_2}{dt} + 0 = L_2 \frac{di_2}{dt}$$



Energy stored in 1st coil, $W_1 = \int_{t_1}^{t_2} V_1 i_1 dt = \int_{t_1}^{t_2} M \frac{di_2}{dt} \cdot I_1 dt = \int_0^{I_2} \frac{MI_1}{I_2} di_2$

$$\boxed{W_1 = \frac{MI_1 I_2}{2}} \quad \dots (3)$$

∴ Energy in 2nd coil $W_2'' = \int_{t_1}^{t_2} V_2 i_2 dt$

$$\therefore W_2'' = \int_{t_1}^{t_2} L_2 \frac{di_2}{dt} \cdot i_2 dt = \int_0^{I_2} L_2 i_2 di_2$$

$$\boxed{W_2'' = \frac{1}{2} L_2 I_2^2} \quad \dots (4)$$

∴ Total Energy stored, $W = (2) + (3) + (4)$

$$\boxed{W = \frac{1}{2} L_1 I_1^2 + \frac{1}{2} L_2 I_2^2 + M I_1 I_2} \quad \dots (5)$$

$$\cos^2 \theta = \frac{1 + 2\cos \theta}{2}$$

If the process of increasing current is reversed, that then \Rightarrow

Prove equation (6):

$$W = \frac{1}{2} L_1 I_1^2 + \frac{1}{2} L_2 I_2^2 + M I_1 I_2 \quad \text{--- (6)}$$

Since the initial and final condition are the same, then (5) = (6)

$$\therefore M_{12} = M_{21} = M$$

$$\therefore W = \frac{1}{2} I_1^2 L_1 + \frac{1}{2} L_2 I_2^2 + M I_1 I_2 \quad \text{--- (2)}$$

Comments and conclusions:

i) if one of the current direction is reversal, then Replace M by $(-M)$ in (7)

ii) Since t_1 and t_2 can be any values in the time domain.

then W can be written by \Rightarrow

$$W(t) = \frac{1}{2} L_1 i_1^2(t) + \frac{1}{2} L_2 i_2^2(t) + M i_1(t) i_2(t) \quad \text{--- (8)}$$

Upper Limit of M

Since W can not be -ve, because one is dealing with passive elements then \Rightarrow

if i_1 and i_2 are both +ve or -ve the form (8), the ~~possibility~~ possibility of -ve W comes from $(-M i_1 i_2)$

$$i) W(t) = \frac{1}{2} L_1 i_1^2 + \frac{1}{2} L_2 i_2^2 - M i_1 i_2 \quad \text{--- (9)}$$

(9) can be Rewritten as \Rightarrow

$$W = \frac{1}{2} (\sqrt{L_1} i_1 - \sqrt{L_2} i_2)^2 + \sqrt{L_1 L_2} i_1 i_2 - M i_1 i_2 \quad \text{(10)}$$

∴ From (10) for true $W \Rightarrow \sqrt{L_1 L_2} \epsilon_1 \epsilon_2 > M \epsilon_1 \epsilon_2$

$$\therefore M \leq \sqrt{L_1 L_2}$$

∴ upper of Maximum value of $M = M_{\max} = \sqrt{L_1 L_2}$

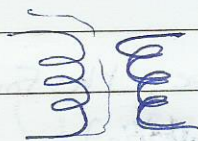
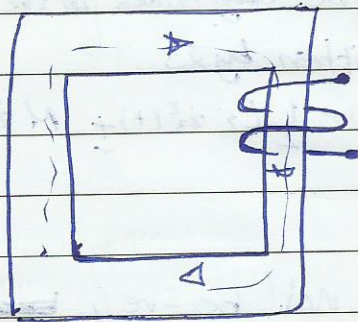
If i_1 and i_2 ~~have~~ have different signs

Then one can still have the same result $M \leq \sqrt{L_1 L_2}$

Coupling Factor, k

$$k \triangleq \frac{M}{M_{\max}} = \frac{M}{\sqrt{L_1 L_2}}$$

loosely coupled coils \uparrow $0 \leq k \leq 1 \rightarrow$ Tightly coupled coils

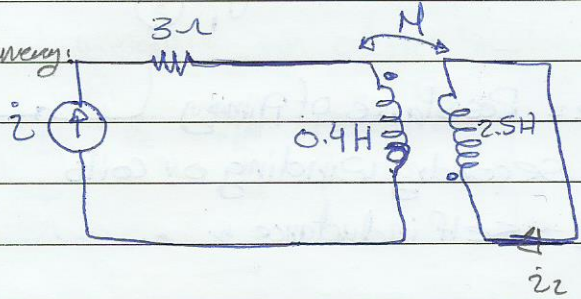


$\vec{A}, \vec{M}, \vec{B}, \vec{S}, \vec{P}$

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example 80

e.g For the given ckt. find the energy stored at $t=0$, given



$$i_1 = 2 \cos 10t \text{ A}$$

$$k = 0.6$$

(اختارنا الاتجاه)

Sol 80

$$w(t) = \frac{1}{2} L_1 i_1^2 + \frac{1}{2} L_2 i_2^2 + M i_1 i_2$$

$$L_1 = 0.4, L_2 = 2.5 \text{ H}$$

$$\omega = 10$$

$$M = k \sqrt{L_1 L_2} = 0.6 \times \sqrt{0.4 \times 2.5} = 0.6$$

$$i_1 = 2 \cos 10t \quad i_1(0) = 2$$

To find i_2 , Apply KVL to 2nd Mesh

$$\omega L_2 I_2 + \omega M I_1 = 0$$

$$i_2 L_2 I_2 = -M I_1$$

$$i_2 I_2 = \frac{-M}{L_2} I_1 = \frac{0.6}{2.5} \times 2 \angle 0^\circ = \frac{-1.2}{2.5} \angle 0^\circ = -0.48 = 0.48 \angle 180^\circ$$

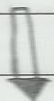
$$\therefore i_2 = 0.48 \cos(10t + 180^\circ)$$

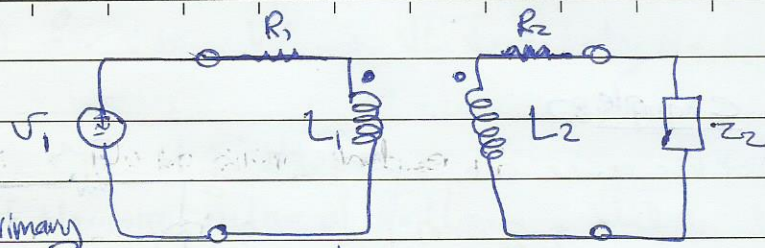
$$i_2(0) = 0.48 \cos(180^\circ) = -0.48$$

$$\text{By substitute } \Rightarrow w(0) = 0.512 \text{ J}$$

Practical Application of Mutual coupling

Transformer
Construction





$R_1, R_2 =$ Resistance of primary and secondary winding or coils

$L_1, L_2 =$ self inductance

$Z_L =$ Load Impedance

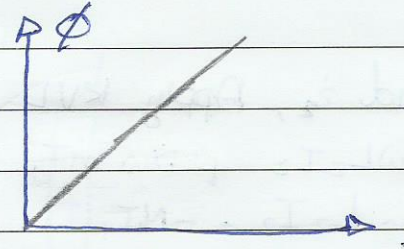
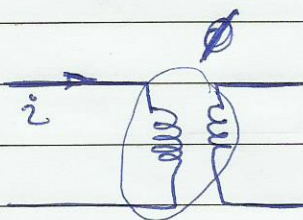
Primary winding (with the source)

Second winding (with the load)

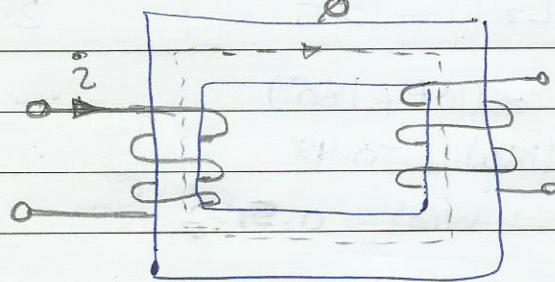
$V_1 \equiv$ Applied voltage to primary

$i_1, i_2 \equiv$ Primary and secondary currents.

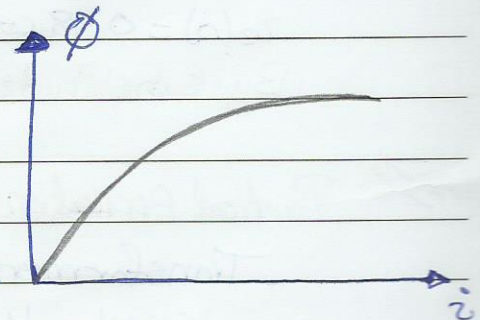
* Air core Transformer



Hence it is called Linear Transformer. Hence k is very small

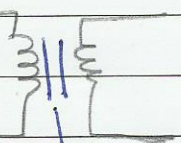


iron-core transformer



k here is very large, Ideally $= 1$

Hence the Name Ideal transformer



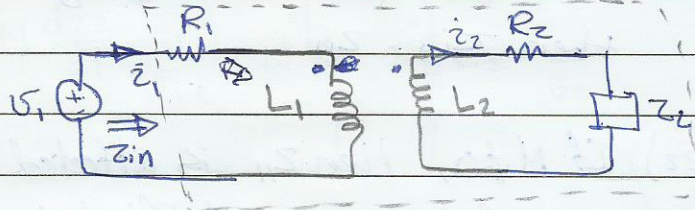
To represent Iron coil

Linear Transformer

objective: To evaluate input impedance Z_{in} of this transformer.

Procedure:

Is to find $Z_{in} = \frac{V_1}{I_1}$



Apply KVL to Primary ckt.

$$V_1 = I_1 R_1 + \delta \omega L_1 I_1 - \delta \omega m I_2$$

$$\therefore V_1 = I_1 (R_1 + \delta \omega L_1) - \delta \omega m I_2$$

$$\therefore V_1 = I_1 Z_{11} - \delta \omega m I_2 \quad \dots (1)$$

where $Z_{11} = R_1 + \delta \omega L_1$ and called Primary ckt. Impedence
second Mesh:

$$I_2 R_2 + I_2 Z_L + \delta \omega L_2 I_2 - \delta \omega m I_1 = 0$$

$$I_2 (R_2 + Z_L + \delta \omega L_2) - \delta \omega m I_1 = 0$$

$$I_2 Z_{22} - \delta \omega m I_1 = 0 \quad \dots (2)$$

$Z_{22} = R_2 + \delta \omega L_2 + Z_L$, called secondary ckt Impedence.

$$(2) \quad I_2 = \frac{\delta \omega m I_1}{Z_{22}} \quad \dots (3)$$

substitute (3) into (1)

$$\therefore V_1 = I_1 Z_{11} - \delta \omega m \left(\frac{\delta \omega m I_1}{Z_{22}} \right) = I_1 \left(Z_{11} + \frac{\omega^2 m^2}{Z_{22}} \right)$$

$$\therefore \frac{V_1}{I_1} = Z_{in} = Z_{11} + \frac{\omega^2 m^2}{Z_{22}} \quad \dots (4)$$

Comments and Conclusions

i) Z_{in} is independent of Dot location.

ii) If $M=0$ (i.e. No coupling between primary and secondary), then $Z_{in} = Z_1$

iii) If $M \neq 0$, then Z_{11} is affected by the factor $\frac{\omega^2 M^2}{Z_{22}}$. This factor is called Reflected Impedance

iv) if $Z_{22} = R_{22} + jX_{22}$

$$i) Z_{in} = Z_{11} + \frac{\omega^2 M^2}{R_{22} + jX_{22}}$$

$$ii) Z_{in} = Z_{11} + \frac{\omega^2 M^2 (R_{22} - jX_{22})}{R_{22}^2 + X_{22}^2}$$

$$Z_{in} = Z_{11} + \frac{\omega^2 M^2 R_{22}}{R_{22}^2 + X_{22}^2} - \frac{j\omega^2 M^2 X_{22}}{R_{22}^2 + X_{22}^2}$$

Resistance from losses Point of view

$$iii) jX_{22} \longrightarrow -jX_{22}$$

iv) Linear Transformer changes the type of load

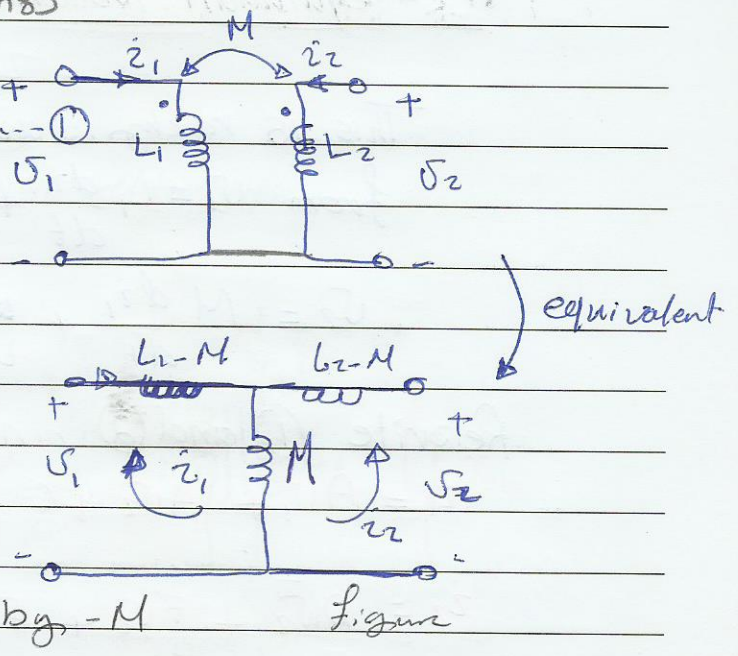
Inductance \longrightarrow capacitive



Equivalent ckt of Linear Transform

By KVL $\Rightarrow V_1 = L_1 \frac{di_1}{dt} + M \frac{di_2}{dt}$ --- (1)

$V_2 = L_2 \frac{di_2}{dt} + M \frac{di_1}{dt}$ --- (2)



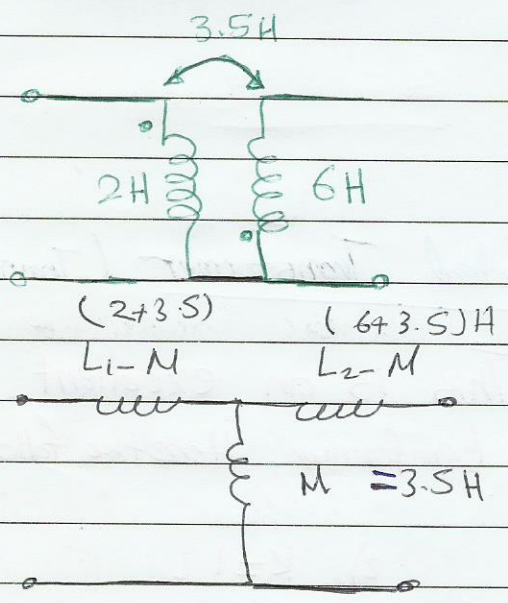
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(*) If one dot location is changed, then replace M by -M

(*) All the elements in figure are self inductance

(*) Linear transformer can be used to synthesize or materialize Negative inductance.

ex Find the equivalent T-Network



* fill in the blank
Q in the exam

π - equivalent Network

This is rarely used

$$\text{from } v_1 = L_1 \frac{di_1}{dt} + M \frac{di_2}{dt} \quad \dots (1)$$

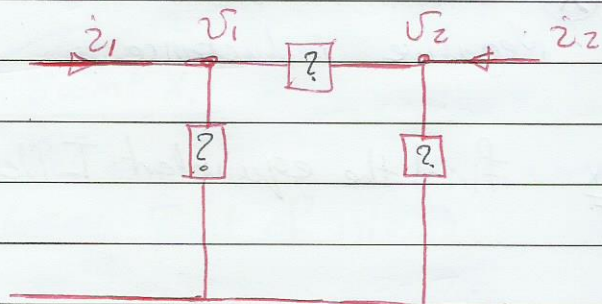
$$v_2 = M \frac{di_1}{dt} + L_2 \frac{di_2}{dt} \quad \dots (2)$$

Rewrite (1) and (2), in the following forms

$$v_1 = A v_2 + A v_2 + C \quad \dots (3)$$

$$v_2 = D v_2 + E v_2 + F \quad \dots (4)$$

Deduce the equivalent cd from (3) and (4) سوال بالکل سو



Ideal Transformer (Transformer with ideal core) ↑ Ref
π-equivalent

This is an excellent approximation for a well coupled Iron core transformer. Here the following are assumed.

i) $k=1$.

ii) It has no losses. Hence $R_1 = R_2 = 0$

iii) Inductive Reactance of primary and ~~and~~ secondary windings are \gg Load impedance (Z_L)

Objectives

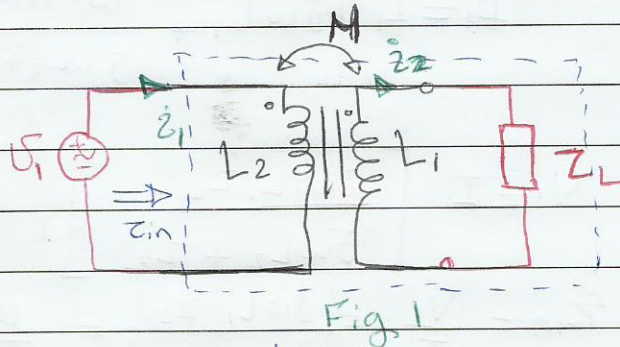
To evaluate

- i) Z_{in}
- ii) Voltage and current relationships.

~~Procedure~~

Procedure

The circuit is as shown in Fig. 1



* $N_1, N_2 \equiv$ Number of turns of Primary and secondary windings

$$N_1 : N_2$$

$$1 : \frac{N_2}{N_1}$$

$$1 : a$$

* $a = \frac{N_2}{N_1}$ is called Turns Ratio

* $L \propto N^2$

$$\text{i) } \frac{N_2^2}{N_1^2} = \frac{L_2}{L_1} = a^2$$

$$\text{Since } k = \frac{M}{\sqrt{L_1 L_2}}$$

$$\text{i) } M = \sqrt{L_1 L_2}$$

Apply KVL \rightarrow (Fig. 1)

$$\text{Primary ckt } \rightarrow V_1 = j\omega L_1 I_1 - j\omega M I_2 \quad \dots (1)$$

$$\text{secondary ckt } \rightarrow j\omega L_2 I_2 + I_2 Z_L - j\omega M I_1 = 0 \quad \dots (2)$$

To find Z_{in} , find Ratio of $\frac{V_1}{I_1}$

$$\textcircled{2} \Rightarrow I_2 = \frac{\delta \omega m I_1}{\delta \omega L_2 + Z_L} \quad \textcircled{3}$$

substitute $\textcircled{3}$ in $\textcircled{1} \Rightarrow$

$$V_1 = \delta \omega L_1 I_1 - \delta \omega \left(\frac{\delta \omega m I_1}{\delta \omega L_2 + Z_L} \right) = L_1 L_2 \leftarrow$$

$$V_1 = I_1 \left[\delta \omega L_1 + \frac{\omega^2 m^2}{\delta \omega L_2 + Z_L} \right] = \left[-\omega^2 L_1 L_2 + \delta \omega L_1 Z_L + \omega^2 m^2 \right] I_1$$

$$\therefore V_1 = I_1 \left[\frac{\delta \omega L_1 Z_L}{\delta \omega L_2 + Z_L} \right]$$

$$Z_{in} = \frac{V_1}{I_1} = \frac{\delta \omega L_1 Z_L}{\delta \omega L_2 + Z_L} = \frac{\delta \omega L_1 Z_L}{\delta \omega L_2} \quad \text{since } \omega L_2 \gg Z_L$$

$$\therefore Z_{in} = \frac{L_1}{L_2} Z_L = \frac{N_1^2}{N_2^2} Z_L = \left(\frac{Z_L}{a^2} \right) \quad \textcircled{4}$$

+ Reflected impedance

From $\textcircled{4}$ so

(it can change the ^{magnitude} of the impedance)

III] I. transformer change the Magnitude of Z_L

\otimes Note: Maximum Power of ~~Spee~~ Amplifier (speaker)

\therefore This concept can be used in maximum power transfer. see the eg in textbook.

$\textcircled{2}$ To Reflected secondary impedance Z_L to Primary $\text{ct. } \frac{Z_L}{a^2}$ by a^2

OR

// // Primary impedance Z_{in} to Secondary \times by a^2

$$a = 10$$

* Current Relationship

$$(3) \Rightarrow \begin{cases} I_2 = \frac{j\omega M I_1}{j\omega M L_2} \quad \text{since } \omega L_2 \gg Z_L \\ \therefore \frac{I_2}{I_1} = \frac{M}{L_2} = \frac{\sqrt{L_1 L_2}}{L_2} = \sqrt{\frac{L_1}{L_2}} = \frac{N_1}{N_2} = \frac{1}{a} \end{cases}$$

Voltage Relationships

$$\text{Since } Z_{in} = \frac{Z_L}{a^2}$$

$$\frac{V_1}{I_1} = \frac{1}{a^2} \cdot \frac{V_2}{I_2}$$

$$\therefore \left(\frac{V_1}{V_2} \right) = \frac{1}{a^2} \frac{I_1}{I_2} = \frac{1}{a^2} \times a = \frac{1}{a} = \frac{N_1}{N_2}$$

$$\therefore \frac{V_1}{V_2} = \frac{I_2}{I_1} = \frac{1}{a}$$

$$\therefore V_1 I_1 = V_2 I_2$$

∴ Both windings have the same (Apparent Power rating)

Conclusion

It was found that

$$\frac{V_2}{V_1} = \frac{I_1}{I_2} = \frac{N_2}{N_1} = a$$

$$\therefore V_2 = a V_1 \quad \text{--- (1)}$$

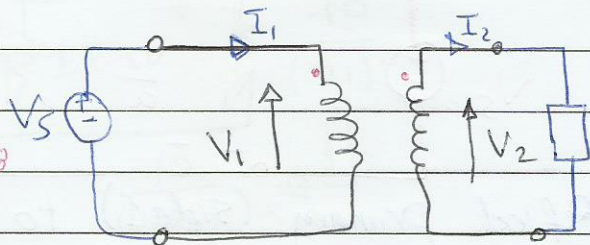
$$I_2 = I_1 / a \quad \text{--- (2)}$$

$$V_1 = V_2 / a \quad \text{--- (3)}$$

$$I_1 = a I_2 \quad \text{--- (4)}$$

$$Z_{in} = Z_L / a^2 \quad \text{--- (5)}$$

$$Z_L = a^2 Z_{in} \quad \text{--- (6)}$$



$$N_1 \propto N_2$$

$$1 \propto \frac{N_2}{N_1} = a$$

side 1 = Primary

side a = Secondary

To Reflect Primary voltage to secondary multiply by a
 current $\div a$

OR

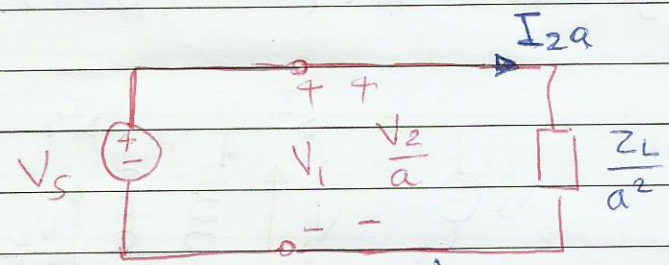
To Reflect secondary voltage to primary $\times \frac{1}{a}$ by a
 current $\times a$

To Reflect primary impedance to secondary $\times a^2$
 secondary $\div a^2$ Primary

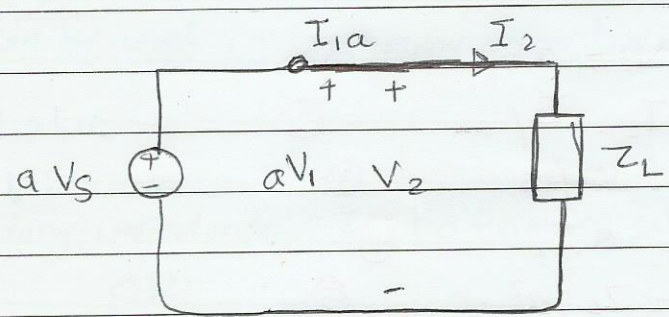
Application

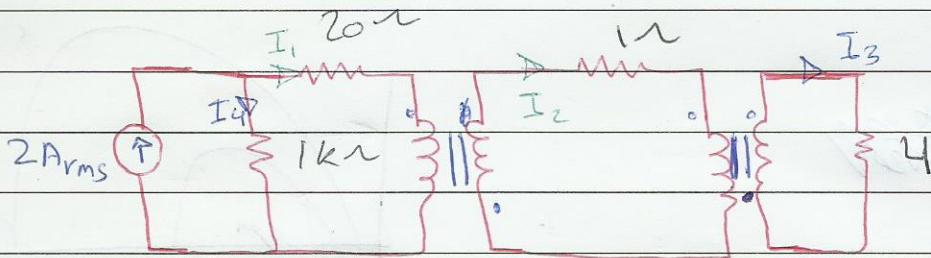
The concept of Reflection can be used to find the equivalent ckt of a system which contain a transformer as follows:

Reflect secondary (side a) to primary (side 1)



Reflect primary (side 1) to secondary (side a)



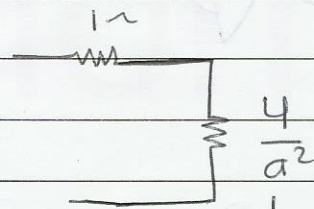


$$1: \frac{1}{5} = a_1 \quad 1: \frac{2}{3} = a_2$$

(e.g) for a given ckt evaluate the Average ~~Power~~ Power Supplied to each resistance

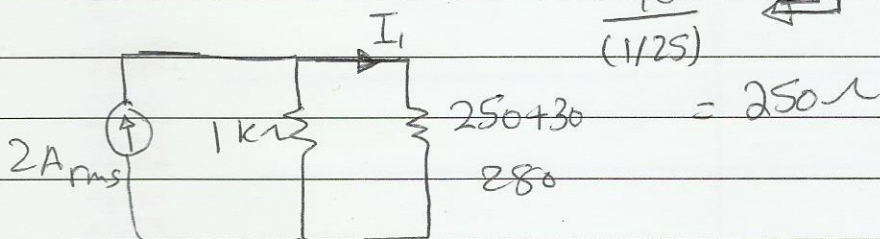
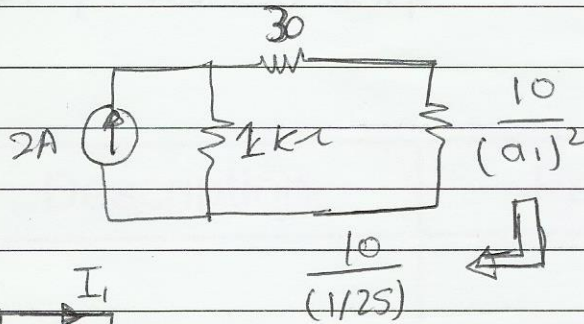
$$a_1 = \frac{1}{5} \quad a_2 = \frac{2}{3}$$

Find the equivalent ckt by Reflecting towards source



$$= 9 + 1 = 10$$

$$\downarrow \frac{4}{(1/9)} = 9 \Omega$$



By current division:

$$I_1 = 2 \times \frac{10^3}{10^3 + 20} = 1.56 \text{ A}$$

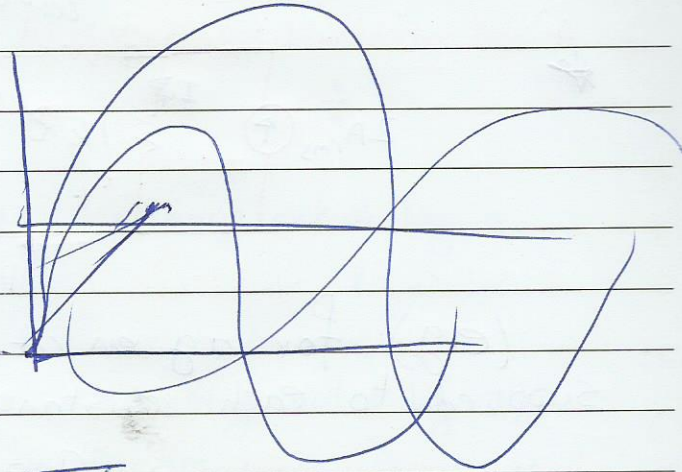
$$\frac{I_1}{-I_2} = \frac{1}{5}$$

$$\therefore I_2 = -5 I_1 = -5 \times 1.56 = -7.8 \text{ Arms}$$

$$\frac{I_2}{I_3} = \frac{2}{3}$$

~~v_1~~

~~v_2~~



~~$v_1^2 + (v_2 + v_3)^2$~~

السؤال 11

$$\Rightarrow I_4 = 2 - I_1 = 2 - 1.56 = 0.44$$

sense $p = I^2 \times R$

then evaluate P for each resistance

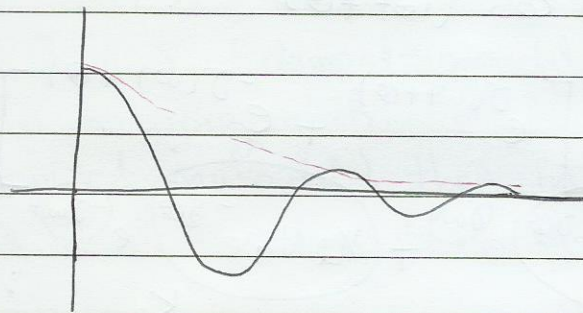
$10 \times \frac{1}{2} + 20 \times \frac{1}{2} - 20 \times \frac{1}{2}$

Complex ~~frequency~~ s

→ s is introduced by using the concept of Damped sinusoidal function and defined as follows:

$$v(t) = V_m e^{\sigma t} \cos(\omega t + \theta)$$

σ is a real number and usually, it's +ve



V_m , ω and θ as defined before.

Consider the following cases:

1) let $\sigma = \omega = 0$

∴ $v(t) = V_m \cos \theta = \text{DC voltage}$

2) let $\sigma = 0$

∴ $v(t) = V_m \cos(\omega t + \theta)$ Sinusoidal

3) let $\omega = 0$, ∴ $v(t) = V_m e^{\sigma t} \cos \theta = \text{exponential}$

Q in exam Define s in 1

∴ ① contain the 3 special cases of DC, sin, exponential

Definition: A function $f(t)$ is said to have a complex frequency, s if it can be written as:

$$f(t) = k e^{st} \quad \text{when } k \text{ and } s \text{ are constants } s \text{ Real or complex}$$

Find s of the previous special cases

i) DC voltage

$$v(t) = V_0$$

$$v(t) = V_0 e^{0t}$$

$$s = 0 + j0$$

ii) Sinusoidal voltage

$$v(t) = V_m \cos(\omega t + \theta)$$

$$v(t) = V_m \frac{1}{2} \left[e^{j(\omega t + \theta)} + e^{-j(\omega t + \theta)} \right]$$

$$v(t) = \underbrace{\left(\frac{1}{2} V_m e^{j\theta} \right)}_{k_2} e^{j\omega t} + \underbrace{\left(\frac{1}{2} V_m e^{-j\theta} \right)}_{k_1} e^{-j\omega t}$$

$$v(t) = k_1 e^{s_1 t} + k_2 e^{s_2 t}$$

$$s_1 = s_2^* = j\omega$$

$$s = 0 + j\omega$$

Real
= 0

iii)

Exponential, $v(t) = V_m e^{st}$ or $A e^{st}$

$$s = \sigma$$

$$\text{or } s = \sigma + j0$$

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iv) Damped sinusoidal

$$v(t) = V_m e^{\sigma t} \cos(\omega t + \theta)$$
$$= V_m e^{\sigma t} \frac{1}{2} \left[e^{j(\omega t + \theta)} + e^{-j(\omega t + \theta)} \right]$$

$$= \underbrace{\frac{1}{2} V_m e^{j\theta}}_{k_1} e^{(\sigma + j\omega)t} + \underbrace{\frac{1}{2} V_m e^{-j\theta}}_{k_2} e^{(\sigma - j\omega)t}$$

$$s_1, s_2 = \sigma \pm j\omega$$

i) The s of damped sinusoidal is the general case.

ii) In solving electrical circuits, one apply the general source (i.e. Damped sinusoidal), then in the final answer substitute the value of s according to the type of source.

eg: Find all complex frequencies in the following functions

$$f(t) = \left(2e^{-100t} + e^{-200t} \right) \times \sin 2000t$$

$$= k_1 \frac{1}{j} e^{(-100 + j2000)t} - \frac{1}{j} e^{(-100 - j2000)t} + \frac{1}{2j} e^{(-200 + j2000)t} - \frac{1}{2j} e^{(-200 - j2000)t}$$

$s_1 = -100 + j2000$, $s_2 = -100 - j2000$, $s_3 = -200 + j2000$, $s_4 = -200 - j2000$

$$s_1, s_2 = -100 \pm j2000$$

$$s_3, s_4 = -200 \pm j2000$$

Application of Damped sinusoidal function to electrical cts.

(*) Consider the following series RLC ckt

$$\text{If } v = V_m e^{\sigma t} \cos(\omega t + \theta)$$

find i



Procedure, since the ckt is linear, then

$$\text{Let } i = I_m e^{\sigma t} \cos(\omega t + \phi) \dots (2)$$

Transform (1) and (2) into complex forcing function and complex response.

$$\begin{aligned} \dot{v} &= \text{Re} \left[V_m e^{\sigma t} e^{j(\omega t + \phi)} \right] = \text{Re} \left[V_m e^{j\phi} e^{(\sigma + j\omega)t} \right] \\ &= \text{Re} \left[V_m e^{j\phi} e^{st} \right] \quad \text{since } s = \sigma + j\omega \end{aligned}$$

Corresponding complex forcing function,
 $v(t) = V_m e^{j\phi} e^{st} \dots (3)$

$$i = \text{Re} \left[I_m e^{\sigma t} e^{j(\omega t + \phi)} \right] = \text{Re} \left[I_m e^{j\phi} e^{st} \right]$$

Corresponding complex response is

$$i = I_m e^{j\phi} e^{st} \dots (4)$$

By KVL

$$v(t) = Ri + L \frac{di}{dt} + \frac{1}{C} \int i dt \dots (5)$$

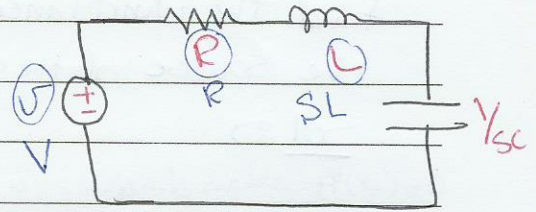
Substitute (3) and (4) into (5)

$$\cancel{V_m} e^{j\phi} e^{st} = R I_m e^{j\phi} e^{st} + L I_m e^{j\phi} s e^{st} + \frac{1}{C} I_m e^{j\phi} \cdot \frac{1}{s} e^{st} \dots (6)$$

$$\dot{v} = V_m e^{j\phi} = I_m e^{j\phi} \left[R + sL + \frac{1}{sC} \right]$$

$$\therefore I_m e^{j\phi} = \frac{V_m e^{j\theta}}{R + sL + \frac{1}{sC}}$$

$$\therefore I_m \angle \phi = \frac{V_m \angle \theta}{R + sL + \frac{1}{sC}}$$



Comments and Conclusion 8)

i) It can be deduced that R , sL and $\frac{1}{sC}$ have the unit of Ω .
 These terms represent the general expression for impedance of the basic passive elements.

ii) Hence in solving ckt. Transform it from time domain \rightarrow s domain.
 Find the answer as a function of s .
 Then Transform it to time domain.

forced response \Rightarrow response by source

Transient response \equiv natural response = free source circuit

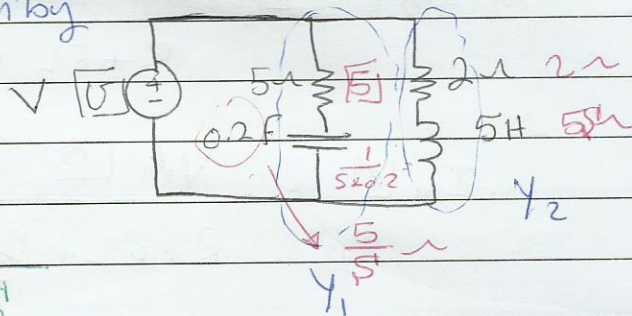
eg) if $V = \underbrace{12}_{V_L} \angle \underbrace{35^\circ}_{\theta}$ and $s = \underbrace{(-20)}_{\sigma} + j \underbrace{5}_{\omega}$ find $v(t)$

$$\therefore v(t) = V_m e^{\sigma t} \cos(\omega t + \theta)$$

Note All ckt techniques, ckt. laws and Impedance combination (Series, Parallel, Δ -Y) are applicable to cts in the s domain.

Find the admittance $Y(s)$ seen by the source of the given circuit

Sol: 3)



$$Y(s) = \frac{1}{5 + \frac{5}{s}} + \frac{1}{2 + 5s}$$

$$Y(s) = \frac{5s^2 + 7s + 5}{(5s + 5)(2 + 5s)}$$

Transfer function is

This concept is used in solving electrical circuits, by finding Transient, forced and complex Response.

Also used in other subjects

The T.F is the Ratio of 2 functions of s and Represented by a Capital letter

e.g. E, F, G, H

For e.g. $H(s) = \frac{F_1(s)}{F_2(s)}$

F_1 and F_2 can be voltage or current

$H(s)$ can be

Impedance, Z or admittance, Y

or (Voltage, Current) ratio

$F_1(s), F_2(s)$ may be written as polynomials

(In factorized forms)

$$H(s) = K \frac{(s+z_1)(s+z_2) \dots (s+z_n)}{(s+p_1)(s+p_2) \dots (s+p_n)}$$

where z_1, \dots, z_m and
 p_1, \dots, p_n constant

Zeros \Rightarrow these are the value of s' which make $H(s) = 0$

Poles \Rightarrow ∞

$\therefore -z_1, -z_2, \dots, -z_m \equiv$ Zeros of $H(s)$
 $-p_1, -p_2, \dots, -p_n \equiv$ Poles \checkmark

(e.g.) Find the zeros and poles of the T.F. $y(s) = \frac{V(s)}{V(s)}$ in \ast
the previous e.g. \ast

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\ast ~~Graphical~~ Graphical Representation of poles and zeros \Rightarrow

On the complex plane \Rightarrow

zeros are represented by a small circle.

poles \checkmark \checkmark a cross \checkmark

(e.g.) In the previous e.g. of $y(s')$ it was found that \Rightarrow

$$z_1, z_2 = -0.7 \pm j 0.714$$

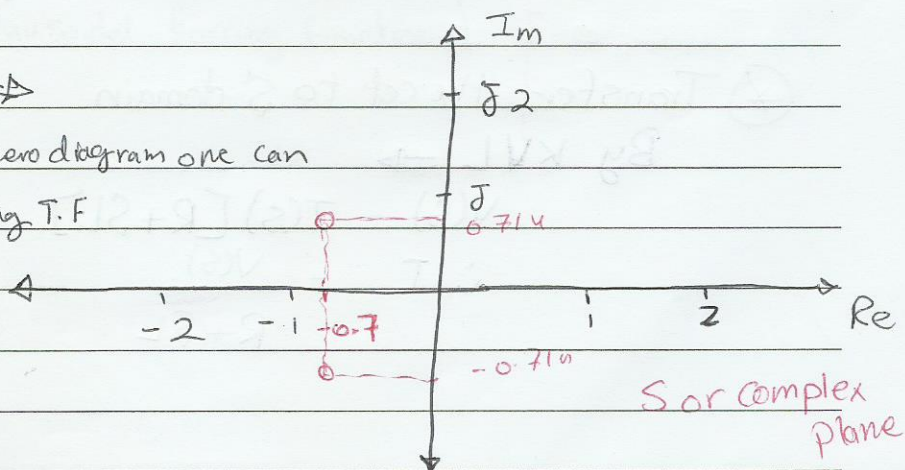
$$p_1 = -1, p_2 = -0.4$$

solutions \Rightarrow



\ast Hence given the pole zero diagram one can

Find the corresponding T.F



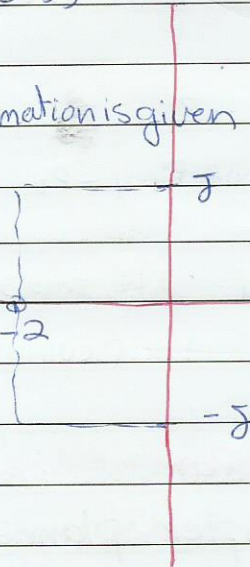
(e.g) Evaluate $H(s)$ which have the following Pole-zero diagram

$$H(s) = k \frac{s(s+3)}{(s+2+j)(s+2-j)}$$

k can be evaluated if another information is given
 Say, $H(1) = 4$

$$H(1) = 4 = k \frac{1 \times (4)}{(3+j)(3-j)}$$

$$k = \frac{4}{10} \quad \therefore k = 0.4$$



Complex Frequency Response

↳ (voltage or current)

Objective is to find the variation of Response (current or voltage) with s

Procedure Consider the following RL ckt.

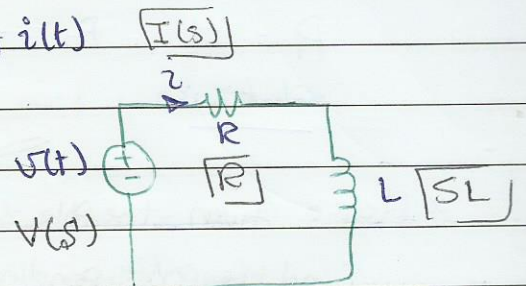
Let the Response by $i(t)$ $I(s)$

(*) Transfer the ckt to s domain

By KVL \Rightarrow

$$V(s) = I(s) [R + sL]$$

$$\therefore I = \frac{V(s)}{R + sL}$$



* To sketch $|I|$ with σ , Consider the following cases of s

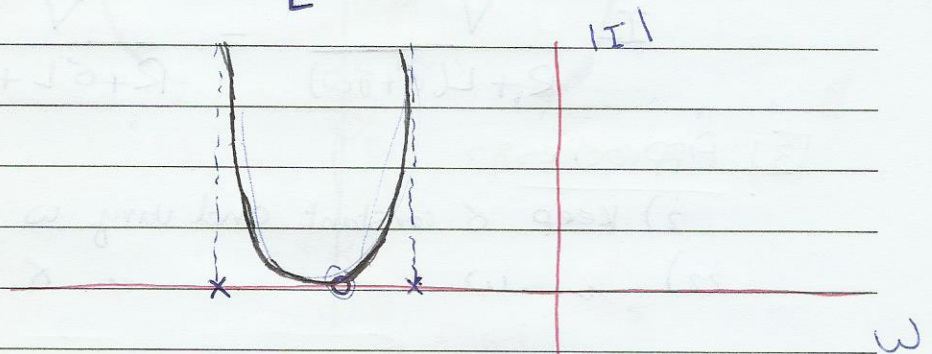
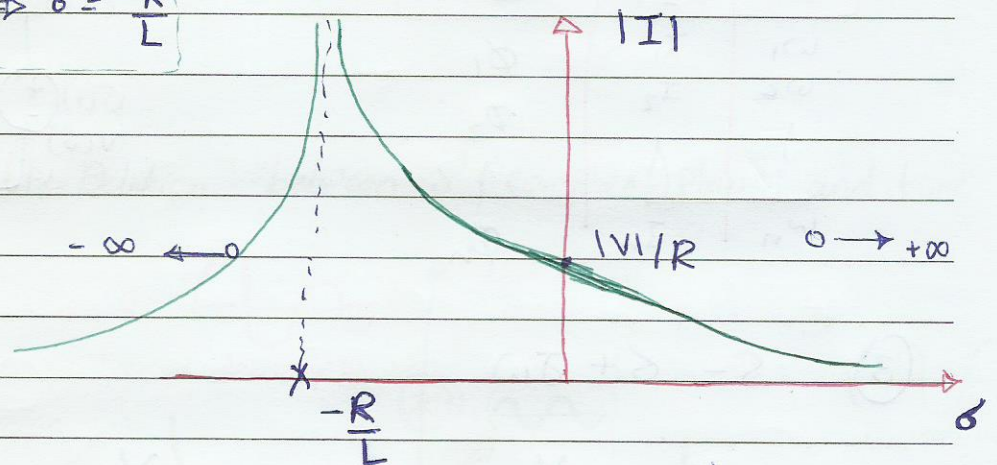
① $s = \sigma + j\omega$ (i.e. exponential forcing function)

$$\hat{i}I = \frac{V}{R + sL}$$

$$\text{Pole} = -\frac{R}{L}$$

Zeros = $+\infty$

$$\text{Poles} \Rightarrow \sigma = -\frac{R}{L}$$

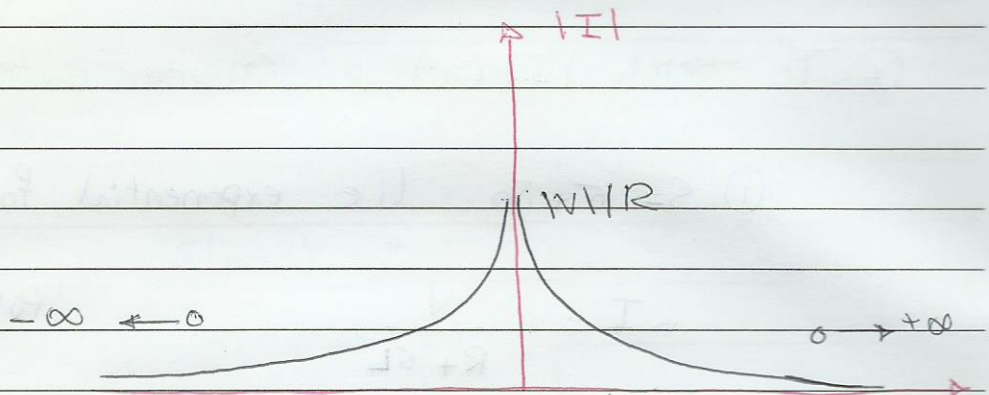


② $s = 0 \pm j\omega$ (i.e. sinusoidal forcing functions)

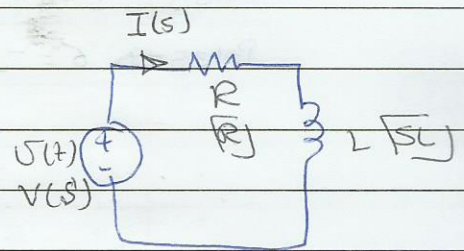
$$I = \frac{V}{R + j\omega L}$$

$$|I| = \frac{|V|}{\sqrt{R^2 + (\omega L)^2}}$$

$$\angle I = \angle V - \tan^{-1} \frac{\omega L}{R}$$



ω	$ I $	$\angle I$
ω_1	I_1	ϕ_1
ω_2	I_2	ϕ_2
\vdots	\vdots	\vdots
ω_n	I_n	ϕ_n



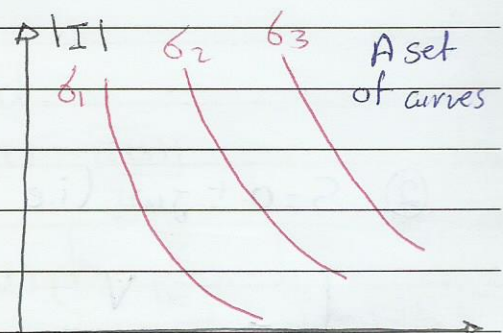
(3) $S = \sigma + j\omega$

$$I = \frac{V}{R + L(\sigma + j\omega)} = \frac{V}{R + \sigma L + j\omega L}$$

[3] Approaches

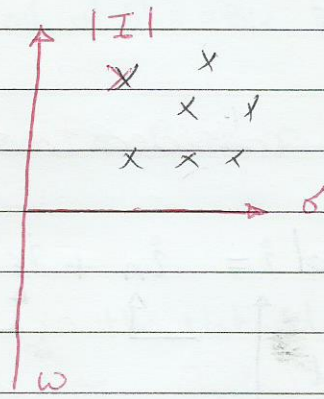
- i) Keep σ constant and vary ω
- ii) $\omega \rightarrow \sigma$

These 2 approaches give little information



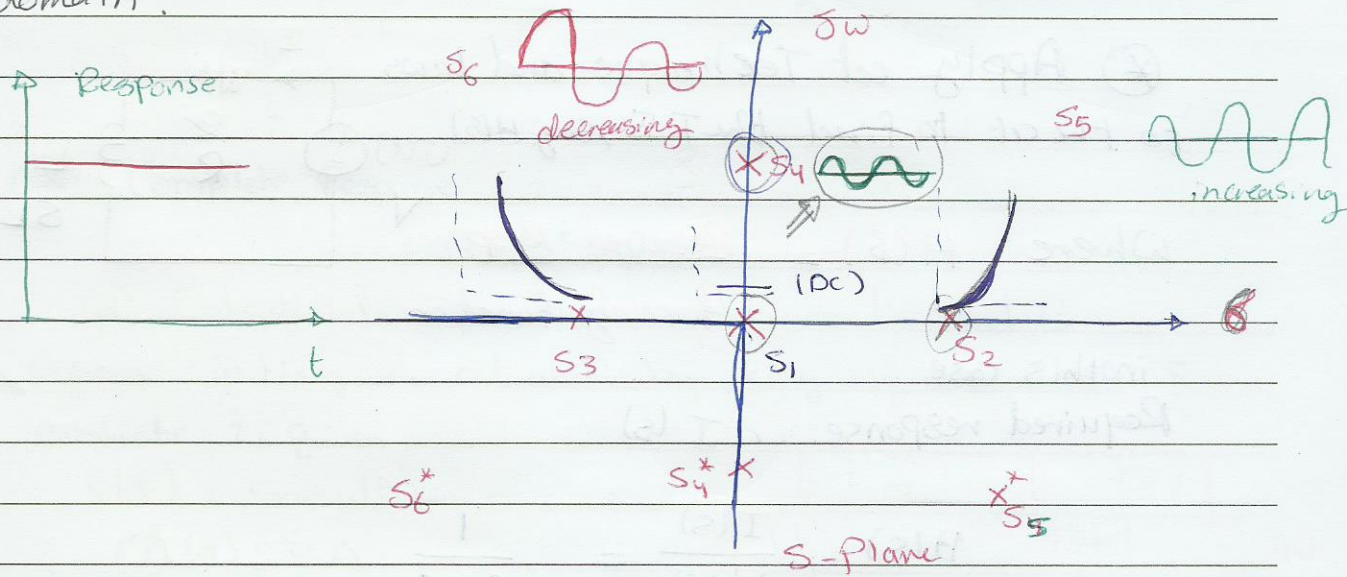
c) Three dimension sketch

A set of points
are obtained



(*) If one join the points
which have the same
magnitude then the S
called equipotential lines
are obtained.

OR using the Relation between S (complex) plane and time domain.



Evaluating Natural, forced and Complete Response by using the concept of T.F

(*) To Illustrate consider the following RL ckt

Objective \Rightarrow find $i = i_n + i_f$
Natural or Transient \uparrow \uparrow \uparrow forced
Complete \uparrow

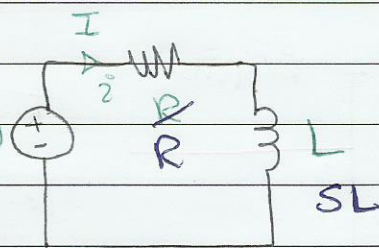
$\frac{I}{V}$

Y/N

Procedure \Rightarrow Transfer the ckt To S domain

(*) Apply ckt Technique and laws to the ckt to find the T.F, say $H(s)$

Where $H(s) = \frac{\text{Required Response}}{\text{forcing function}}$



in this case
Required response $\therefore I(s)$

$$H(s) = \frac{I(s)}{V(s)} = \frac{1}{R + sL} \quad (1)$$

$$iI = G(s) * V(s) \quad (2)$$

By knowing the forcing function (i.e $V(s)$) and its type (i.e the value of s), then the forced response $iI(s)$ can be evaluated from (2)

Then transform $I_f(s) \rightarrow i_f(t)$

(*) If $V(s)$ is applied at $s' = \text{pole of } G(s)$ and in the limit when $V(s) \Rightarrow 0$

Go to

Then a finite Response say H will be obtained

at $s = \text{pole}$

This Response is the Natural Response

in In this case $I_n(s) = A$ at $s = -\frac{R}{L}$

in Transform $I_n(s) \rightarrow i_n(t)$

$$i_n = A e^{-\frac{R}{L}t} \cos(\omega + \phi) = \underbrace{A}_{\downarrow} \underbrace{\cos(\omega + \phi)}_{\downarrow} e^{-\frac{R}{L}t}$$

$$i_n = \underbrace{B}_{\downarrow} e^{-\frac{R}{L}t}$$

(*) Complete Response $i = i_n + i_f$
 $= B e^{-\frac{R}{L}t} + i_f$

(*) Substitute initial conditions to find B

Ex 3 in the given ckt and by using the concept of T.F evaluate i , given

$$v(t) = 500 \cos t$$

$$i_1(0) = 5 \text{ A}$$

$$i_2(0) = 2 \text{ A}$$

~~Find~~ (*) objective

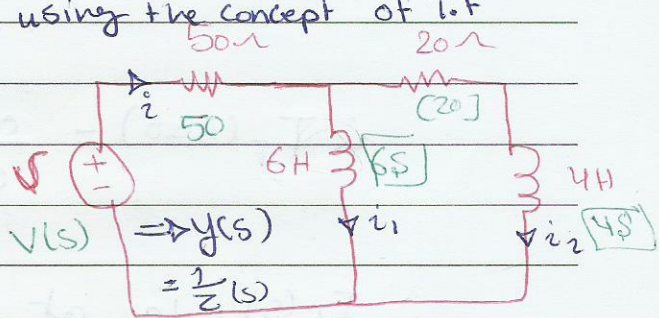
find $i = i_n + i_f$

Procedure

(*) Find $H(s) = \frac{I(s)}{V(s)} \Rightarrow Y(s) \dots (1)$

$$Z(s) = 50 + [6s \parallel (20 + 4s)]$$

$$= 50 + \frac{6s \times (20 + 4s)}{6s + 20 + 4s} \dots (2)$$



$z = z_n + z_f$ zeros & Poles

Current switch Voltage \rightarrow with series source

By Re arrangement of (2) and substituting in (1), it can be found \Rightarrow

$$= \frac{10s + 20}{24s^2 + 620s + 1000} \quad (3)$$

finding in

find Poles of $H(s)$

Solve $24s^2 + 620s + 1000$

$$s_1 = -1.728 \quad s_2 = -24.1$$

$\uparrow P_1 \qquad \qquad \qquad \uparrow P_2$

$$i_n(t) = A e^{P_1 t} + B e^{P_2 t} = A e^{-1.728 t} + B e^{-24.1 t}$$

$i_f(s) = H(s) V(s)$

since $v(t) = 500 u(t)$



$V(s) = 500$ and $s=0$ since $v(t)$ dc

$$i_f(s=0) = \frac{0 + 20}{0 + 0 + 1000} * 500 = 10$$

$i_f(s) = 10$ at $s=0$

$$i_f = 10 e^0 \cos(0) = 10$$

$$i(t) = A e^{-1.728 t} + B e^{-24.1 t} + 10$$

$$i = i_n + i_f$$

$$i = A e^{-1.728 t} + B e^{-24.1 t} + 10$$

$i(0) =$

$$A + B + 10 = 7$$

$$A + B = -3$$

Find A and B using initial condition

Find $i(t)$

$$\text{and } \frac{di}{dt} \Big|_{t=0}$$

From the given ckt

By KCL $\Rightarrow i = i_1 + i_2$

$$\frac{di}{dt} = \frac{di_1}{dt} + \frac{di_2}{dt}$$

$$i(0) = i_1(0) + i_2(0) = 5 + 2 = 7$$

Apply KVL to 1st Mesh

$$V = 5i + 6 \frac{di_1}{dt}$$

$$V(0) = 50i(0) + 6 \frac{di_1}{dt} \Big|_{t=0}$$

$$= 500 = 50 \times 7 + 6 \frac{di_1}{dt} \Big|_{t=0}$$

$$\frac{di_1}{dt} \Big|_{t=0} = \frac{150}{6}$$

Apply KVL to large loop

$$V(0) = 50i(0) + 20i_2(0) + 4 \frac{di_2}{dt} \Big|_{t=0}$$

$$500 = 50 \times 7 + 20 \times 2 + 4 \frac{di_2}{dt} \Big|_{t=0}$$

$$\frac{di_2}{dt} \Big|_{t=0} = \boxed{27.5}$$

$$\frac{di(t)}{dt} = \boxed{\quad}$$

$$A + B = 7$$

$$2A - 3B = -5$$

$$A + B = -3$$

$$\frac{di}{dt} = \frac{di_1}{dt} + \frac{di_2}{dt}$$
$$A + B = 3$$

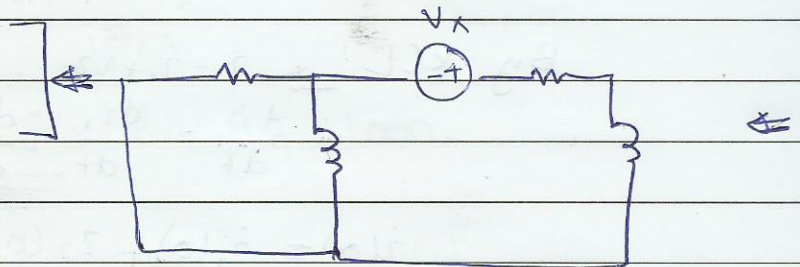
$$\frac{dz_1}{dt} \Big|_{t \rightarrow \infty} = \frac{180}{6} + 27.5$$

$$A = 2.35$$

$$B = -5.35$$

another question

جواب السؤال
Poles في المعادله

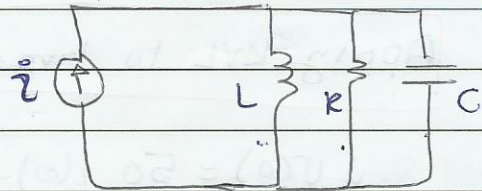
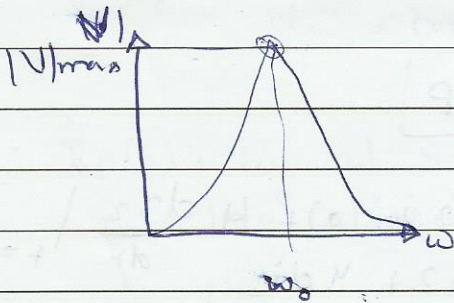


Frequency Responses

Resonance is the condition which occurs in a system when a fixed amplitude sinusoidal forcing function \rightarrow electrical cts.

Producing Maximum Response (voltage or current)

Consider the following
Parallel RLC circuit



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Parallel Resonance:

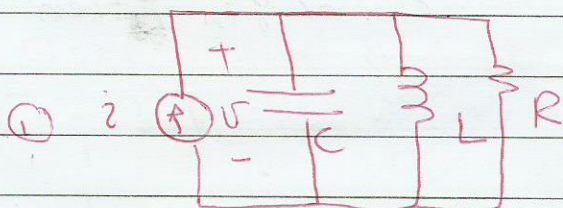
Objective \Rightarrow Find the conditions for Resonance

Let the forcing function be i

and the Resonance is V

$$V = \frac{I}{Y}$$

$$V = \frac{I}{\frac{1}{2} + j\left[\omega C - \frac{1}{\omega L}\right]}$$



$\therefore |V|_{\max}$ is when $|Y|$ is minimum

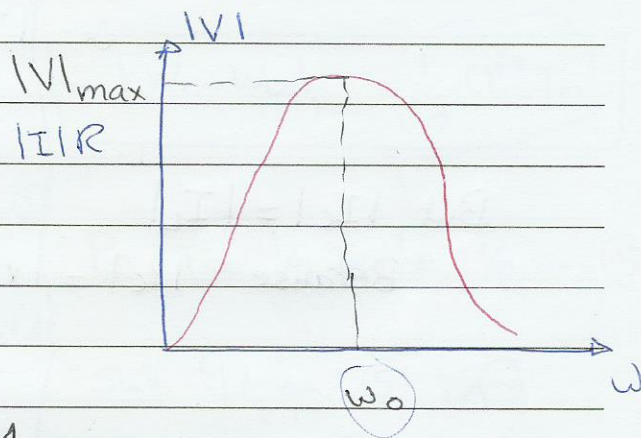
\therefore For a given $|I|$, R , L and C is minimum when

$$\left[\omega C - \frac{1}{\omega L}\right] = 0 \quad \text{--- (2)}$$

$$\therefore \text{Im}[Y] = 0$$

$$\therefore \omega C = \frac{1}{\omega L}$$

$$\therefore \omega = \frac{1}{\sqrt{LC}}$$



at Resonance $\omega = \omega_0 = \frac{1}{\sqrt{LC}}$

Comments at $\omega = \omega_0$

i) $\omega L = \frac{1}{\omega C}$ $\therefore X_L = X_C$

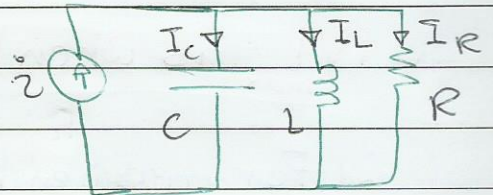
ii) $Y = 1/R$ (i.e. Pure Real) \therefore Input voltage (V) and current (i) are in phase.

\therefore To find ω_0 for any ckt, then one may find Z_{in} or Y_{in} , then solve $Im[Z_{in}] = 0$
OR

$Im[Y_{in}] = 0$

iii) $|V|_{max} = \frac{|I|}{|Y|_{max}} = \frac{|I|}{1/R}$

$\therefore |V|_{max} = |I|R$



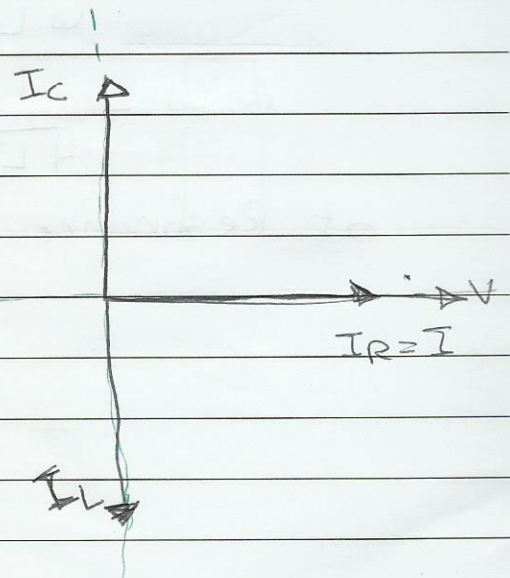
$|V|_{max} = |I|R$

$\therefore |I_R| = \frac{|V|_{max}}{R}$

$= |I|R / R = |I|$

But $|I_C| = |I_L|$

Because $|X_C| = |X_L|$



Quality Factor Q

For any ckt

$$Q \triangleq \frac{2\pi \times \text{maximum energy stored in the circuit}}{\text{Energy lost in one period}}$$

introduced For Mathematical simplification

Objective is Evaluate Q of a parallel RLC ckt at $\omega = \omega_0$
For $\omega = \omega_0 \Rightarrow [i.e. Q_0]$ ~~Derive~~ Derive

Procedure let $i = I_m \cos(\omega_0 t)$

$$v = iR = RI_m \cos(\omega_0 t)$$

$$Q_0 = 2\pi \frac{[W_C + W_L]_{\max}}{PR \times T}$$

~~$$W_C + W_L = \frac{1}{2} CR^2 I_m^2$$~~

$$W_C + W_L = (2) + (3) = \frac{1}{2} CR^2 I_m^2 [\cos^2 \omega_0 t + \sin^2 \omega_0 t] \text{ since } I_m, R \text{ and } C \text{ are constants \#}$$

$W_C, W_L =$ Energy stored in cap and L respectively

PR = Power dissipated in R

$$W_C + W_L = \frac{1}{2} CR^2 I_m^2$$

T = Periodic time

$$i [W_C + W_L]_{\max} = \frac{1}{2} CR^2 I_m^2 \quad \text{--- (4)}$$

$$W_C = \frac{1}{2} V^2 = \frac{1}{2} CR^2 I_m^2 \cos^2(\omega_0 t) \quad \text{--- (2)}$$

$$PR \times T = \frac{1}{2} I_m^2 R \frac{1}{f_0} \quad \text{--- (5)}$$

$$W_L = \frac{1}{2} i^2 L \Rightarrow i_L = \frac{1}{L} \int v dt = \frac{1}{L} \int \cos \omega_0 t dt$$

Sub (4) and (5) in (1)

$$\Rightarrow i_L = \frac{RI_m}{L\omega_0} \sin(\omega_0 t)$$

$$W_L = \frac{1}{2} LR^2 I_m^2 \frac{\sin^2(\omega_0 t)}{L^2 \omega_0^2} \text{ (i.e. } \omega_0^2 = \frac{1}{LC} \text{)}$$

$$\Rightarrow W_L = \frac{1}{2} LR^2 I_m^2 \frac{LC}{L^2} \sin^2(\omega_0 t)$$

$$Q_0 = 2\pi \frac{\frac{1}{2} CR^2 I_m^2 \cdot f_0}{\frac{1}{2} I_m^2 R}$$

$$\Rightarrow Q_0 = 2\pi f_0 CR \text{ (i.e. } 2\pi f_0 = \omega_0 \text{)}$$

$$Q_0 = \omega_0 CR$$

$$\Rightarrow W_L = \frac{1}{2} R^2 I_m^2 C \sin^2(\omega_0 t) \quad \text{--- (3)}$$

Comments on Q_0

$$i) Q_0 = \omega_0 CR = \frac{1}{\sqrt{LC}} CR = \sqrt{\frac{C}{L}} R$$

$$ii) Q_0 = \frac{R}{X_C} = \frac{R}{X_L}$$

$$iii) |I_C| = |I_L| = \omega_0 C |V| = \underbrace{(\omega_0 CR)}_{Q_0} I_m$$

$$\therefore |I_C| = |I_L| = Q_0 I_m$$

** Drive Q_0 ??

for series and
parallel RLC

If for e.g. $I_m = 2 \text{ mA}$ and $Q_0 = 50$

Then $|I_C| = |I_L| = 2 \times 50 = 100 \text{ mA}$

\therefore Parallel RLC ct can be used as a current

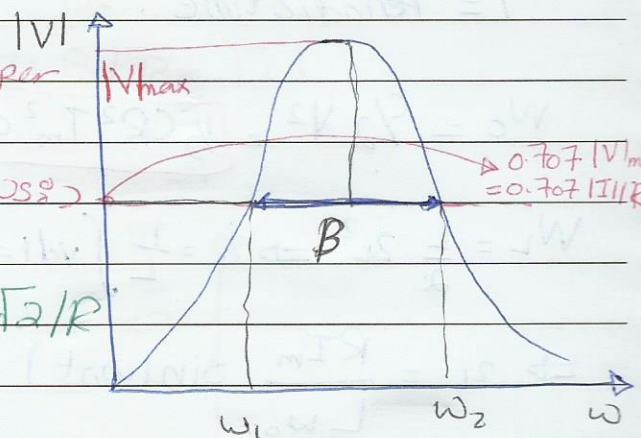
Width of the Response Curves

This is measured by the Bandwidth β

when $\beta \triangleq \omega_2 - \omega_1$

where ω_2 and ω_1 are called upper
and lower Half-power frequency
respectively and defined as follows:

$$|Y(\omega_1)| \text{ or } |Y(\omega_2)| \triangleq \frac{1}{\sqrt{2}} |Y|_{\text{max}} = \frac{1}{\sqrt{2}} I/R$$



$$\therefore |V| \text{ at } \omega_1 \text{ or } \omega_2 = |I|/|Y| = I / \frac{1}{\sqrt{2}} R = \frac{1}{\sqrt{2}} |I| R$$

$$= 0.707 |I| R$$

$$= 0.707 |V|_{\text{max}}$$

in Pat ω_1 or $\omega_2 =$

$$\frac{(0.707|I|R)^2}{R} = 0.5|I|^2 R$$

≈ 0.5 of Pat ω_0

in The Name Half Power frequency

→ Evaluation of ω_1 and ω_2 as

$$|Y(\omega_1 \text{ or } \omega_2)| \triangleq \sqrt{2} |Y|_{\min} = \sqrt{2} \cdot \frac{1}{R}$$

Procedure $Y(j\omega) = \frac{1}{R} + j \frac{1}{R} \left[\frac{\omega_0 \omega C R}{\omega_0} - \frac{R \omega_0}{\omega L \omega_0} \right]$

$$= \frac{1}{R} + j \frac{1}{R} \left[\frac{Q_0 \omega}{\omega_0} - \frac{Q_0 \omega_0}{\omega} \right] \quad \text{--- (1)}$$

Since $Q_0 = \frac{\omega_0 C R}{\omega_0 L} = \frac{R}{\omega_0 L}$

Derive ω_1, ω_2

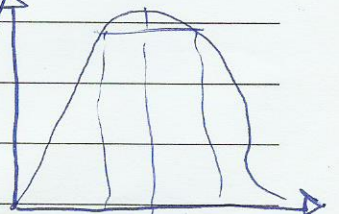
in from (1) at ω_1 or ω_2 $\left[\quad \right] = \pm 1$

$$\text{in } \frac{Q_0 \omega_2}{\omega_0} - \frac{Q_0 \omega_0}{\omega_2} = 1 \quad \text{--- (2)}$$

$$\frac{Q_0 \omega_1}{\omega_0} - \frac{Q_0 \omega_0}{\omega_1} = -1 \quad \text{--- (3)}$$

By ~~substituting~~ solving (2) and (3) it can be found as

$$\omega_2, \omega_1 = \omega_0 \left[\sqrt{1 + \left(\frac{1}{2Q_0}\right)^2} \pm \left(\frac{1}{2Q_0}\right) \right] \quad \text{--- (4)}$$



From (4)

$$i) \beta = \omega_2 - \omega_1 = \frac{\omega_0}{Q_0}$$

$$ii) \omega_0 = \sqrt{\omega_1 \omega_2}$$

Approximations

i) At high Q_0 , usually $Q_0 \geq 5$

$$\omega_2, \omega_1 \approx \omega_0 \left[1 \pm \frac{1}{2Q_0} \right] \approx \omega_0 \pm \frac{1}{2} \frac{\omega_0}{Q_0}$$

$$\approx \omega_0 \pm \frac{1}{2} \beta$$

$\therefore \omega_2$ and ω_1 are symmetrical around ω_0 .

ii) at high Q_0 , it can be found that

$$Y(j\omega) = \frac{1}{Q_0} [1 + jN]$$

$$\text{Where } N = \frac{\omega - \omega_0}{\frac{1}{2}\beta}$$

\rightarrow Number of $\frac{1}{2}$ Bandwidth between ω and ω_0

Conclusions

The smaller the value of β \rightarrow The sharper the response curve \rightarrow The more selective the parallel RLC ckt is \rightarrow hence it is more selective \rightarrow consequently it can be used as a filter.

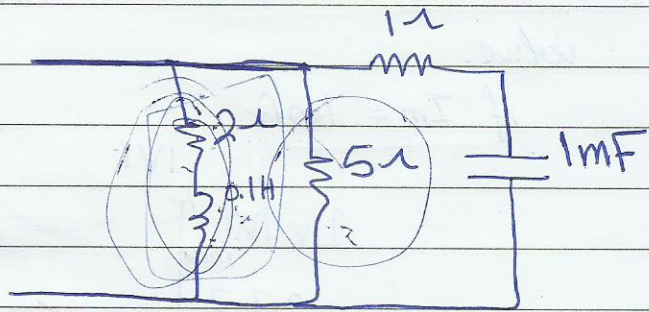
* * * * * ω^2 simple Parallel

(eg) for the given circuit find ω_0

Solution :-

i) find Y or Z

ii) solve



$$\text{Im} [Y \text{ or } Z] = 0$$

imaginary part

$$iY = \frac{1}{2 + 0.15\omega} + \frac{1}{5} + \frac{1}{1 - \frac{\delta}{\omega \times 0.001}}$$

Find $\text{Im}[Y]$

\therefore It can be found $\text{Im}[Y] = 0$

$$0.1\omega(\omega^2 + 10^6) + \omega \cdot 10^3(4 + 0.001\omega^2) = 0$$

$$\Rightarrow \omega = 98.47 \text{ Rad/s}$$

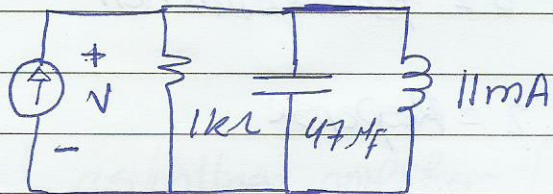
ex 200

for the given ckt, $i = I_m \cos \omega t$
evaluate the following :-

i) $Q_0 \Rightarrow Q_0 = \omega_0 CR$

$$= \frac{1}{\sqrt{LC}} \times C \times R$$

$$= 6537$$



Parallel Q_0 is the ratio of energy stored to energy dissipated

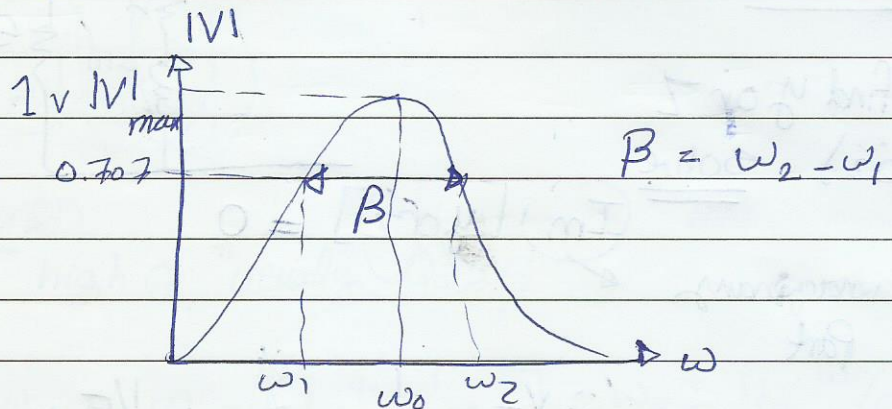
ii) Find f_0

$$\therefore \omega_0 = 2\pi f_0 \Rightarrow f_0 = \frac{\omega_0}{2\pi}$$

$$= \frac{1}{2\pi\sqrt{LC}} = 221.3 \text{ Hz}$$

ii) sketch the response curve and show on it the main parameters value.

if $I_m = 1 \text{ mA}$



$$|V|_{\max} = I_m R = 10^{-3} \times 10^3 = 1 \text{ V}$$

$$\omega_2, \omega_1 = \omega_0 \pm \left[\sqrt{1 + \left(\frac{1}{240}\right)^2} \pm \frac{1}{240} \right]$$

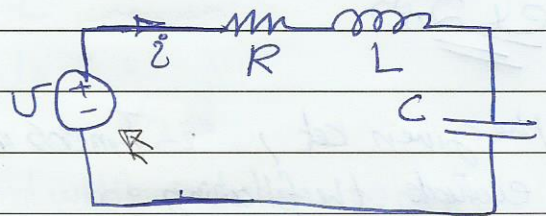
$$\omega_2 = 1402$$

$$\omega_1 = 1380$$

Series RLC circuit

$v =$ forcing function

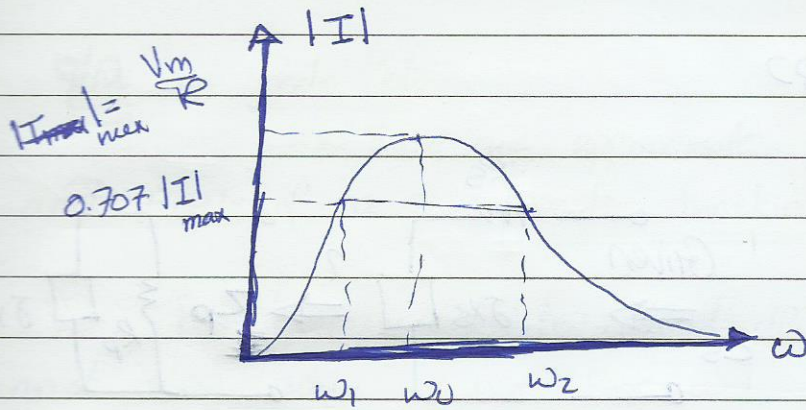
$i =$ Response



$$I = \frac{V}{Z} \rightarrow \frac{V}{R + j(\omega L - \frac{1}{\omega C})}$$

$$(I)_{\max} \text{ when } |Z|_{\min} \rightarrow \omega L = \frac{1}{\omega C} = \omega_0$$

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

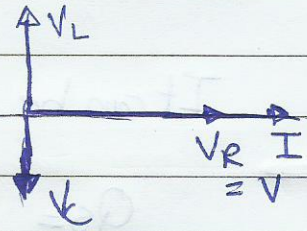


By KVL

$$V = V_R + (V_C + V_L)$$

res

$$V = V_R$$



Note the same expression of ω_1 , ω_2 , ω_0 and Q of the parallel RLC circuit is applicable to ~~the~~ series RLC circuit

But $Q_0 = \frac{\omega_0 L}{R} \Rightarrow$ ~~derivative~~ (derivative)

$$Q_0 = \frac{1}{\omega_0 CR}$$

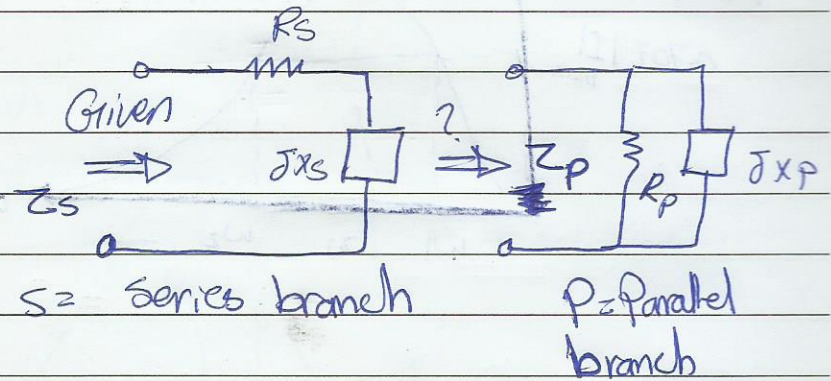
(*) Series (RLC) circuit can be used as voltage amplifier.

a.

() state the application of (RLC) //

Other Resonant ckt's

Objectives



It can be found that

$$Q_s = \frac{X_s}{R_s} \quad \text{and} \quad Q_p = \frac{R_p}{X_p}$$

The ~~2~~ ckt are equivalent if $Z_s = Z_p$

$$R_s + jX_s = \frac{R_p \cdot (-jX_p)}{R_p + (-jX_p)} \quad \text{--- (1)}$$

By equating R_e and I_m parts of (1)

$$X_p = \frac{R_s^2 + X_s^2}{X_s} = \frac{R_s^2}{X_s} + X_s = X_s \left[1 + \left(\frac{R_s}{X_s} \right)^2 \right] = X_s \left[1 + \frac{1}{Q_s^2} \right]$$

$$R_p = \frac{R_s^2 + X_s^2}{R_s} = R_s + \frac{X_s^2}{R_s} = R_s \left[1 + \left(\frac{X_s}{R_s} \right)^2 \right]$$

$$= R_s [1 + Q_s^2]$$

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Bode Plots

→ These are approximate plots of the magnitude and Angle of a given transfer function with frequency (ω)

But here, a log scale, called dB scale is used for the magnitude and alog scale is used for (ω)

Definition of dB scale

Given a transfer function, say $G(s)$

Then let $s' = j\omega$

$\therefore G(s) \Rightarrow G(j\omega)$

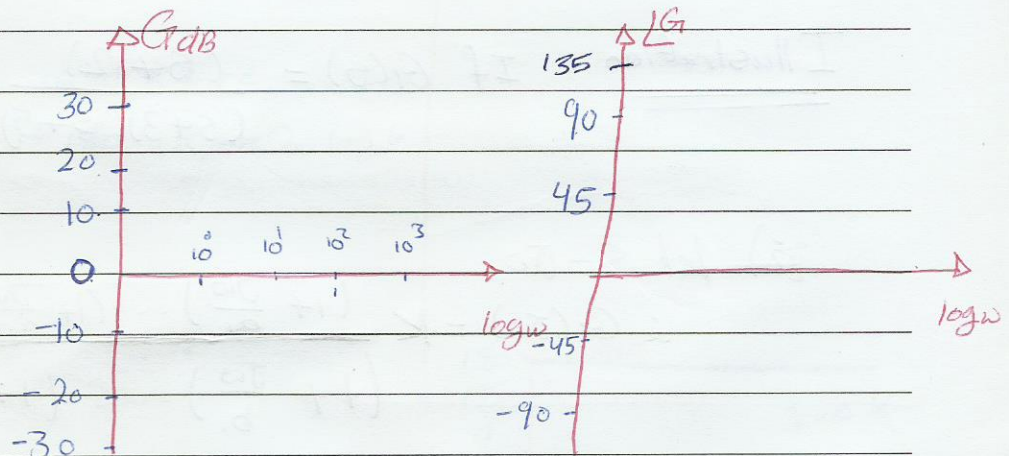
$\therefore G_{dB} \triangleq 20 \log |G(j\omega)|$

Illustration

If a semilog graph paper is used, then the values of ω can be written on the log ω axis.

$ G(j\omega) $	G_{dB}
1	0
2	6
10	20
$10^{\pm n}$	$\pm 20n$

in Two required curves



Note: If the Ratio of 2 frequencies, say ω_2 and ω_1 , equal to 10, then it is said that there is one Decade between ω_2 and ω_1 , e.g. $\frac{\omega_2 = 1000}{\omega_1 = 100}$

If the Ratio of 2 frequencies, say ω_2 and ω_1 , equal to 2, then ~~then~~ it is said that there is one octave between ω_2 and ω_1 .

e.g. $\frac{\omega_2 = 20}{\omega_1 = 10} = 2$

→ Procedure:

i) Rewrite the given transfer function in the following Factorized form:

(do not do this)

$$G(s) = K \frac{(1 + \frac{s}{a_1})(1 + \frac{s}{a_2}) \dots (1 + \frac{s}{a_n})}{(1 + \frac{s}{b_1})(1 + \frac{s}{b_2}) \dots (1 + \frac{s}{b_n})}$$

Where: K is a real number $-a_1, -a_2, \dots, -a_n \equiv$ zeros of $G(s)$

$-b_1, -b_2, \dots, -b_n \equiv$ poles of $G(s)$

Illustration If $G(s) = \frac{(s+2)}{(s+3)(s+5)} = \frac{2(1 + \frac{s}{2})}{3(1 + \frac{s}{3})5(1 + \frac{s}{5})}$

ii) let $s = j\omega$

$G(j\omega) = K \frac{(1 + \frac{j\omega}{a_1}) \dots (1 + \frac{j\omega}{a_n})}{(1 + \frac{j\omega}{b_1}) \dots (1 + \frac{j\omega}{b_n})}$ $\therefore K = \frac{2}{3 \cdot 5} = \frac{2}{15}$

$$222) \quad G_{dB} = 20 \log |G(j\omega)|$$

$$G_{dB} = 20 \log k + 20 \log \left| 1 + \frac{j\omega}{a_1} \right| + 20 \log \left| 1 + \frac{j\omega}{a_2} \right| + \dots + 20 \log \left| 1 + \frac{j\omega}{a_m} \right| - \left[20 \log \left| 1 + \frac{j\omega}{b_1} \right| + 20 \log \left| 1 + \frac{j\omega}{b_2} \right| + \dots + 20 \log \left| 1 + \frac{j\omega}{b_n} \right| \right]$$

∴ to obtain (G_{dB} versus $\log \omega$) curve, plot the individual curves of k , zeros and poles and then summate them.

$$\rightarrow \text{iv) } |G(j\omega)| = \underbrace{|k|}_{\text{circled}} + \left| 1 + \frac{j\omega}{a_1} \right| + \dots + \left| 1 + \frac{j\omega}{a_m} \right| - \left[\left| 1 + \frac{j\omega}{b_1} \right| + \dots + \left| 1 + \frac{j\omega}{b_n} \right| \right]$$

∴ Hence plot the ~~the~~ individual curves of k , zeros, and poles and then summate them to find $|G(j\omega)|$ viz ω

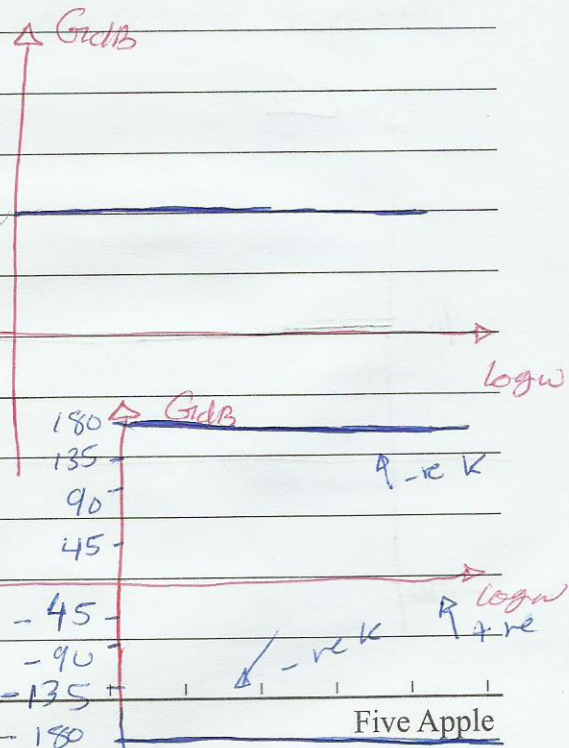
Considered the following cases of $G(s)$ 8)

i) $G(s) = k$

$$\therefore G_{dB} = 20 \log |G(j\omega)| = 20 \log k$$

ii)

$$\therefore |G(j\omega)| = |k| \begin{cases} \angle 0^\circ & \text{if } k \neq re \\ \angle \pm 180^\circ & \text{if } k = re \end{cases}$$

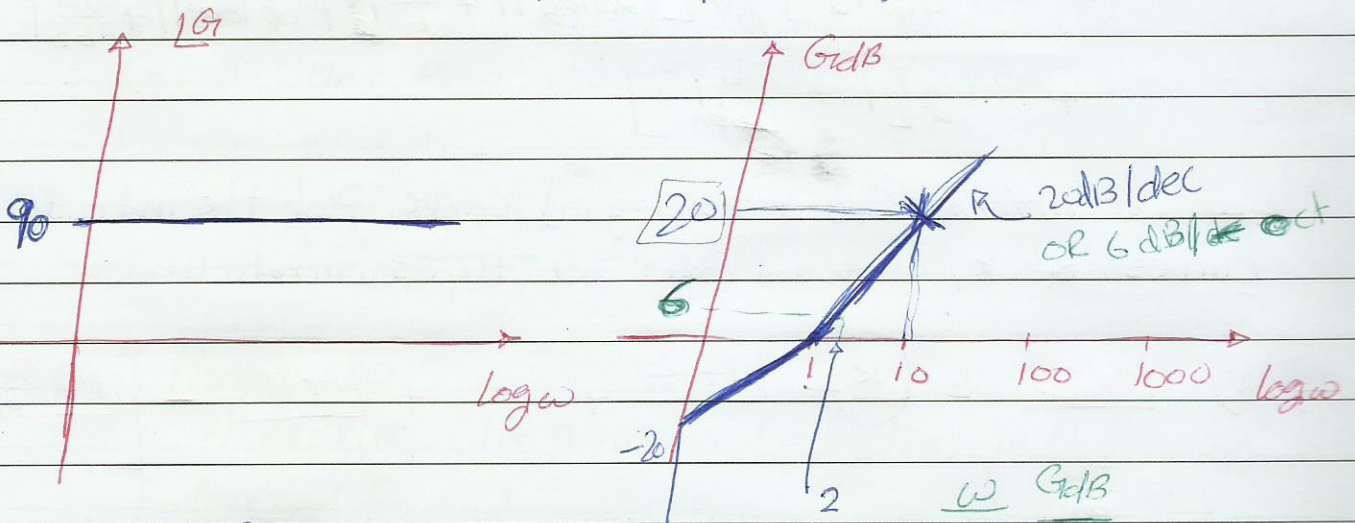


7.5 اس کا بode Plot کھینچنا - اس کا حل دیا گیا ہے

ii) $G(s) = s^2$

$G(j\omega) = \mathbf{J\omega^2}$

$G_{dB} = 20 \log |G(j\omega)| = 20 \log (\mathbf{J\omega^2}) = 20 \log \omega$



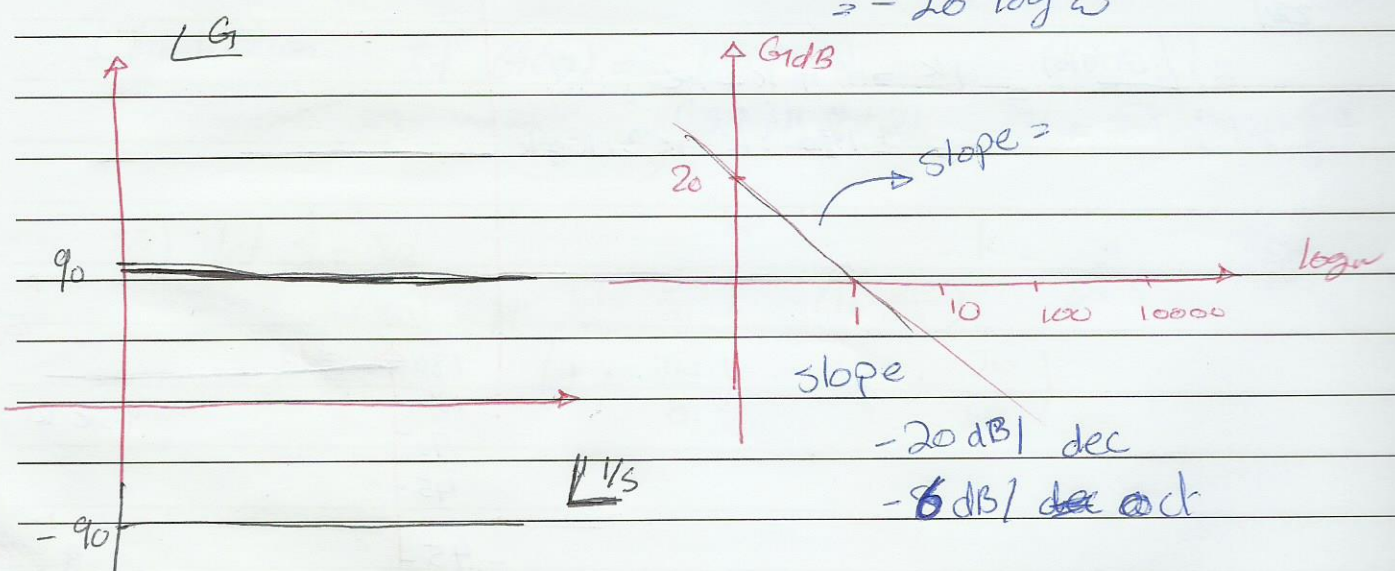
$\angle G(j\omega) = \angle \omega^2 = 90^\circ$

ω	G_{dB}
4	7
8	13

iii) $G(s) = \frac{1}{s}$
 $G(j\omega) = \frac{1}{j\omega}$

$G_{dB} = 20 \log |G(j\omega)| = 20 \log \left| \frac{1}{j\omega} \right| = 20 \log 1 - 20 \log \omega$

$= -20 \log \omega$



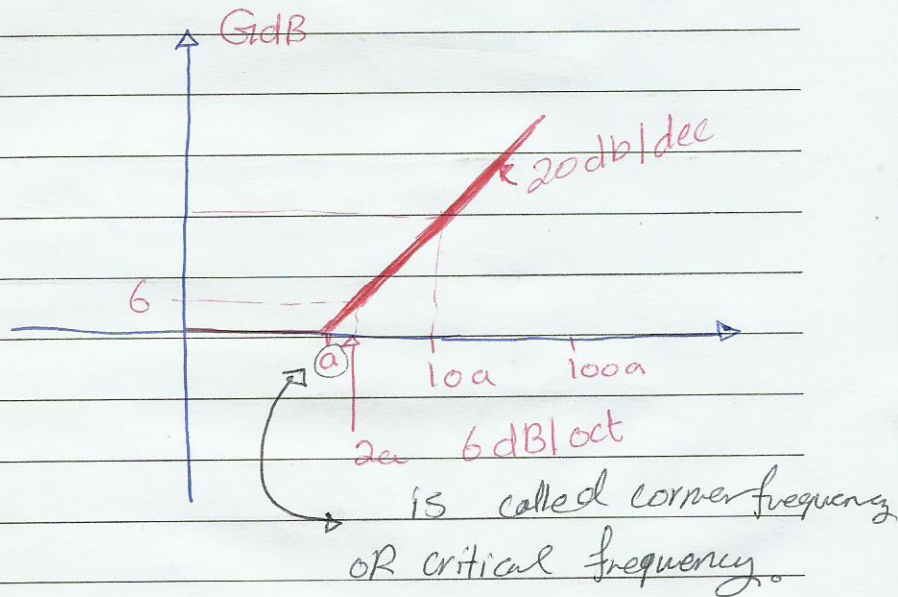
iv) $G(s) = \left(1 + \frac{s}{a}\right)$ is a zero at $s = -a$

ii $G(j\omega) = \left(1 + \frac{j\omega}{a}\right)$

ii $G_{dB} = 20 \log |G(j\omega)| = 20 \log \sqrt{1 + \left(\frac{\omega}{a}\right)^2}$
 $20 \log \sqrt{1 + \frac{\omega^2}{a^2}} \quad \left\{ \begin{array}{l} \omega \gg a \text{ (i.e. } |s| \gg 1) \\ \frac{\omega}{a} \approx 0 \quad \left\{ \begin{array}{l} a \gg \omega \text{ (i.e. } |s| \ll 1) \end{array} \right. \end{array} \right.$

If $\omega \ll a$, Taken when $\omega < a$, $G_{dB} = 20 \log 1 = 0$
 // $\omega \gg a$, // // $\omega > a$, $G_{dB} = 20 \log \frac{\omega}{a}$

$\Rightarrow |G(j\omega)| = \tan^{-1}\left(\frac{\omega}{a}\right)$



11/12

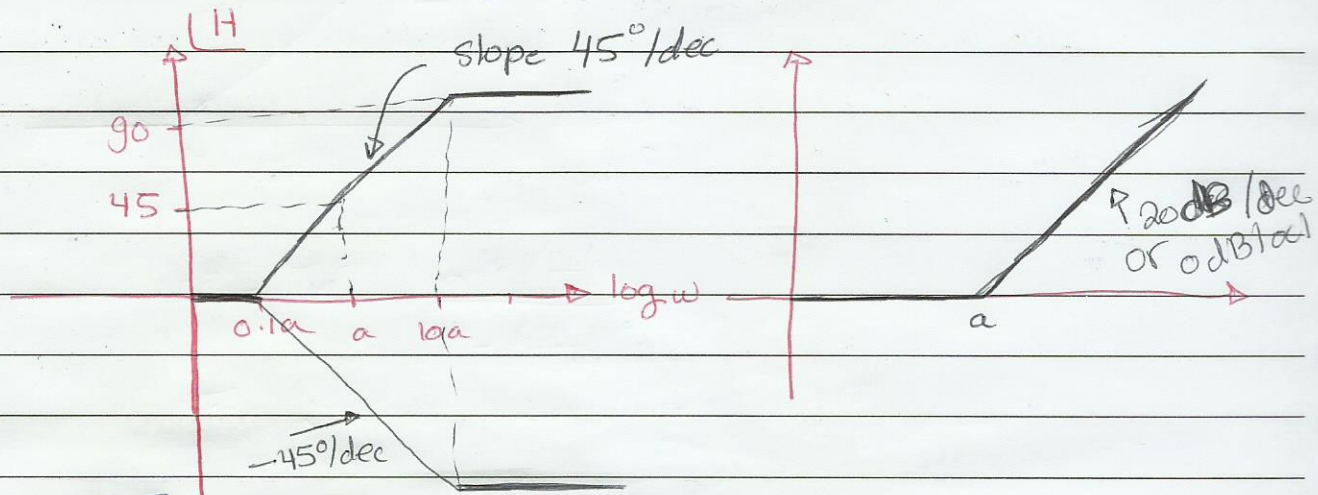
$$H(s) = \left(1 + \frac{s}{a}\right)$$

$$\angle H(j\omega) = \tan^{-1}\left(\frac{\omega}{a}\right)$$

⊗ for $\omega \ll a$, Taken $\omega < 0.1a$, $\angle H = 0$

// $\omega \gg a$, // $\omega > 10a$, $\angle H = 90$

$\omega = a$, $\angle H = 45$

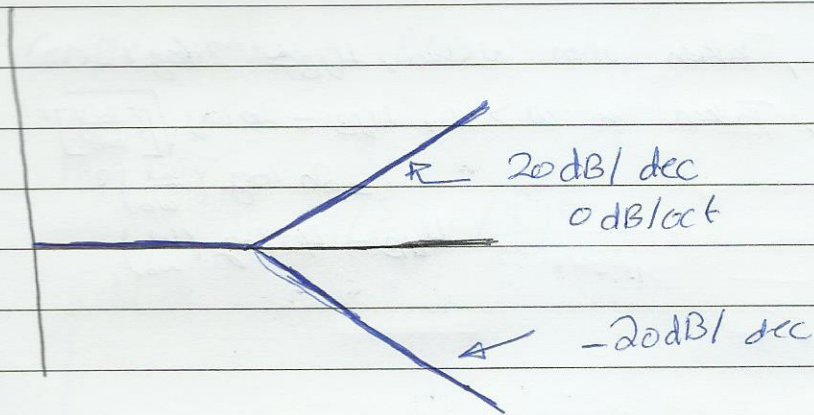


⊗ Simple Pole.

$$H(s) = \frac{1}{\left(1 + \frac{s}{a}\right)}$$

$$\angle H(j\omega) = \frac{1}{1 + \left(\frac{j\omega}{a}\right)}$$

$$H_{dB} = 20 \log 1 - 20 \log \sqrt{1 + \left(\frac{\omega}{a}\right)^2} = -20 \log \sqrt{1 + \left(\frac{\omega}{a}\right)^2}$$



(*) Complex conjugate poles and/or zeros

If there is a quadratic expression whose roots are complex (i.e. $b^2 < 4ac$) then rewrite it in the following form(s)

$$1 + 2\zeta \left(\frac{s}{\omega_0} \right) + \left(\frac{s}{\omega_0} \right)^2$$

where $0 < \zeta < 1$, $\omega_0 = \text{Real constant No.}$

Illustration 80

$$H(s) = 3 + 7s + 5s^2$$

$$= 3 \left[1 + \frac{7}{3}s + \frac{5}{3}s^2 \right]$$

$$H(s) = 3 \left[1 + \underbrace{\frac{7}{3} \cdot \frac{\sqrt{3}}{\sqrt{5}}}_{2\zeta} \left(\frac{s}{\sqrt{315}} \right) + \left(\frac{s}{\sqrt{315}} \right)^2 \right]$$

$\omega_0 = \sqrt{315}$

$$\omega_0 H(j\omega) = 3 \left[1 + 2\zeta \left(\frac{j\omega}{\omega_0} \right) + \left(\frac{j\omega}{\omega_0} \right)^2 \right]$$

$$= 3 \left[1 - \left(\frac{\omega}{\omega_0} \right)^2 + 2\zeta \left(\frac{j\omega}{\omega_0} \right) \right]$$

$$\therefore H_{dB} = 20 \log |H(j\omega)|$$

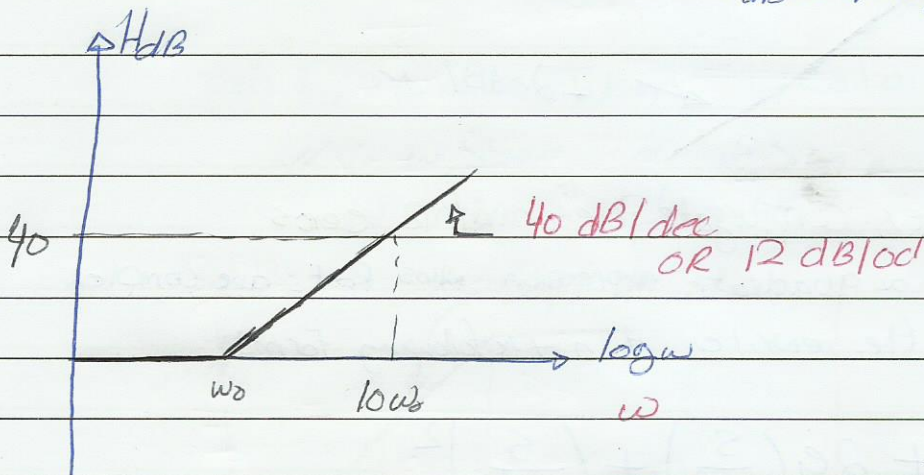
$$= 20 \log \sqrt{\left[1 - \left(\frac{\omega}{\omega_0} \right)^2 \right]^2 + \left[2\zeta \left(\frac{\omega}{\omega_0} \right) \right]^2}$$

in for $\omega \ll \omega_0$, taken when $\omega < \omega_0$, $H_{dB} \approx 20 \log 1 = 0$

$$\omega \gg \omega_0, \text{ taken } \approx \omega > \omega_0, H_{dB} = 20 \log \left[\left(\frac{\omega}{\omega_0} \right)^2 \right]^2$$

$$= 20 \log \left(\frac{\omega}{\omega_0} \right)^4$$

$$H_{dB} = 40 \log \left(\frac{\omega}{\omega_0} \right)$$

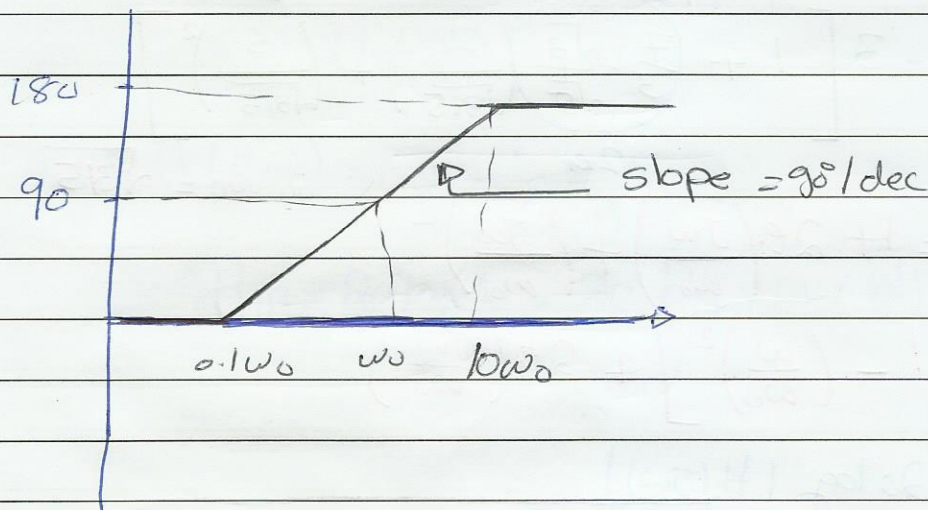


$$\angle H = \tan^{-1} \frac{2\omega \left(\frac{\omega}{\omega_0} \right)}{1 - \left(\frac{\omega}{\omega_0} \right)^2}$$

For $\omega \ll \omega_0$, taken when $\omega < 0.1 \omega_0$, $\angle H = 0$

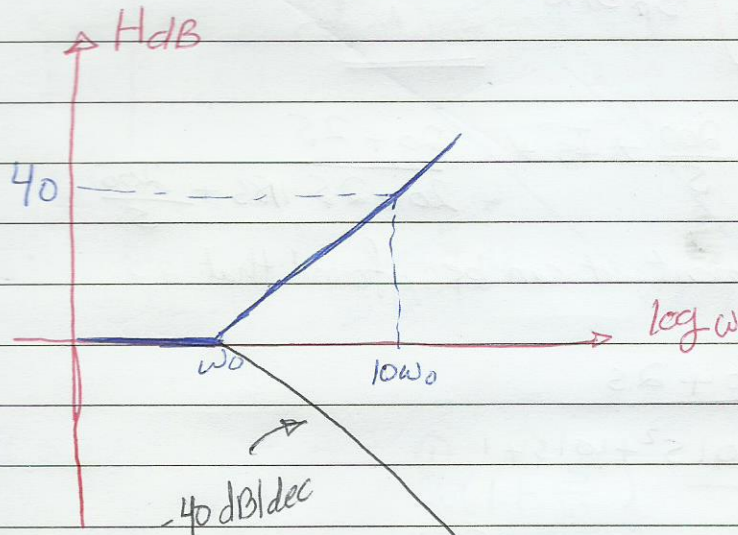
" $\omega \gg \omega_0$, " " $\omega > 10\omega_0$, $\angle H = 180^\circ$

" $\omega \approx \omega_0$, $\angle H = 90^\circ$



* Complex Conjugate Poles

$$H(s) = \frac{1}{1 + 2\zeta\left(\frac{s}{\omega_0}\right) + \left(\frac{s}{\omega_0}\right)^2}$$



* Multiple Poles and zeros

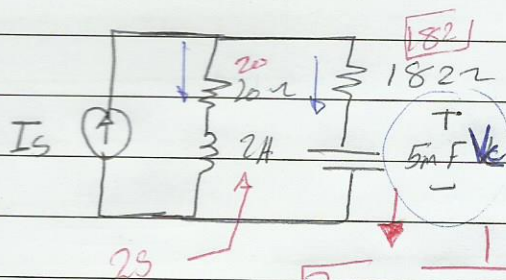
$$H(s) = \left(1 + \frac{s}{a}\right)^{\pm m} \quad m = 2, 3$$

In this case corner frequency = a

But the slopes are

1) $\pm 20m$ dB/dec

2) $\pm 45^\circ m$ /dec



(eg) Draw the Bode plot of t.c
T.f, $G(s) = \frac{V_c}{I_s}$

Solution

$$i.e. V_c = \frac{200}{s} \times I_s \times \frac{20 + 2s}{20 + 2s + 18s + \frac{200}{s}}$$

By rearrangement it can be found that

$$\frac{V_c}{I_s} = \frac{20 + 2s}{0.01s^2 + 101s + 1}$$

$$i.e. G(s) = \frac{V_c}{I_s} = \frac{20(1 + \frac{s}{10})}{0.01(s^2 + 101s + 100)}$$

$$= \frac{2000(1 + \frac{s}{10})}{(s+100)(s+1)}$$

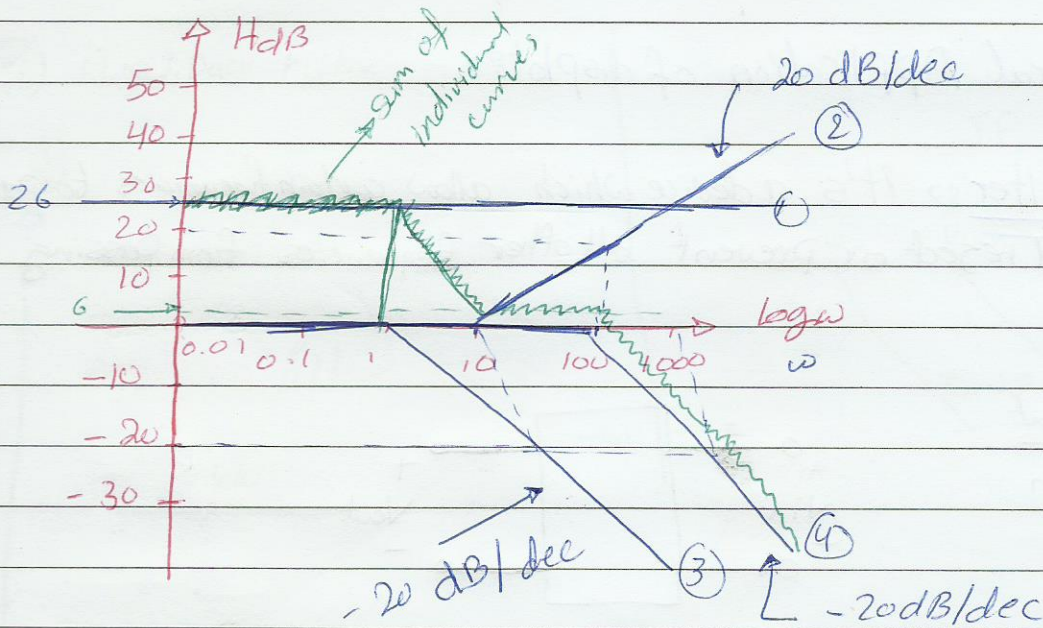
لا تفسر الواحد \rightarrow

$$= 200 \left(1 + \frac{s}{10} \right)$$

$$\frac{100(1+s)(1 + \frac{s}{100})}{(s+100)(s+1)}$$

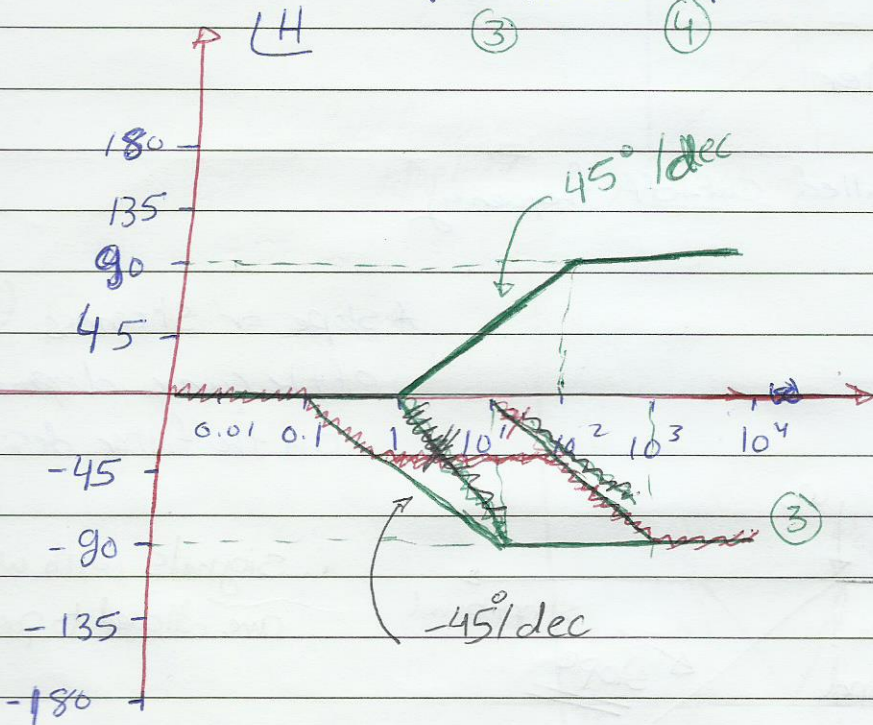
$$= \frac{20(1 + \frac{s}{10})}{(1+s)(1 + \frac{s}{100})}$$

$$\frac{20(1 + \frac{s}{10})}{(1+s)(1 + \frac{s}{100})}$$



23/2 = 11.5

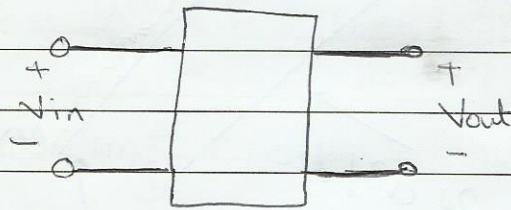
$$H(s) = \frac{\overset{\textcircled{1}}{20} \overset{\textcircled{2}}{\left(1 + \frac{s}{10}\right)}}{\underset{\textcircled{3}}{\left(1 + \frac{s}{100}\right)} \underset{\textcircled{4}}{\left(1 + \frac{s}{1}\right)}}$$



* Practical Application of plots

Filter is a device which allow certain frequencies to pass and reject or prevent all other frequencies from passing

$$H(s) = \frac{V_{out}}{V_{in}}$$



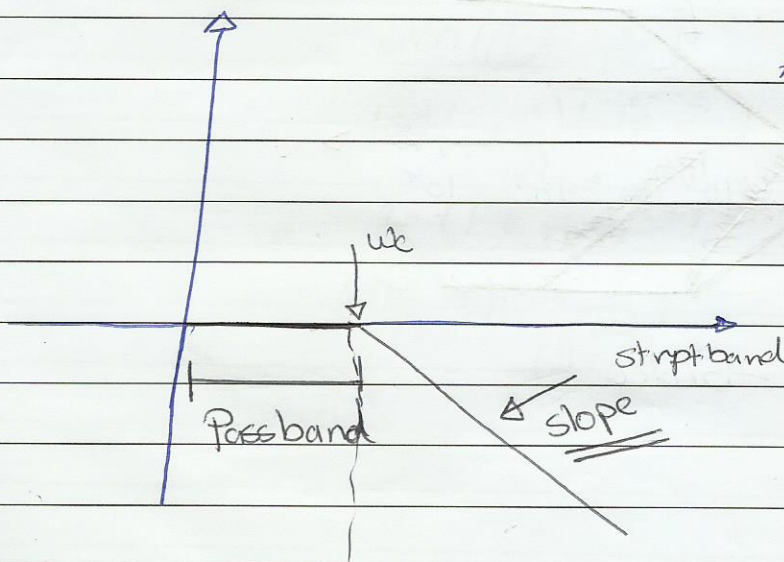
(*) When frequencies are allowed to pass, then $V_{out} = V_{in}$

$$H(s) = 1 \quad A_{dB} = 20 \log |H| = 20 \log 1 = 0$$

(*) Hence by using the dB plot, filters can be classified into

i) Low Pass Filter

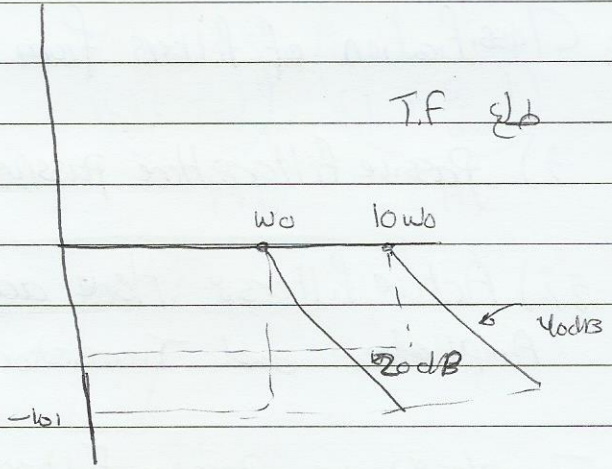
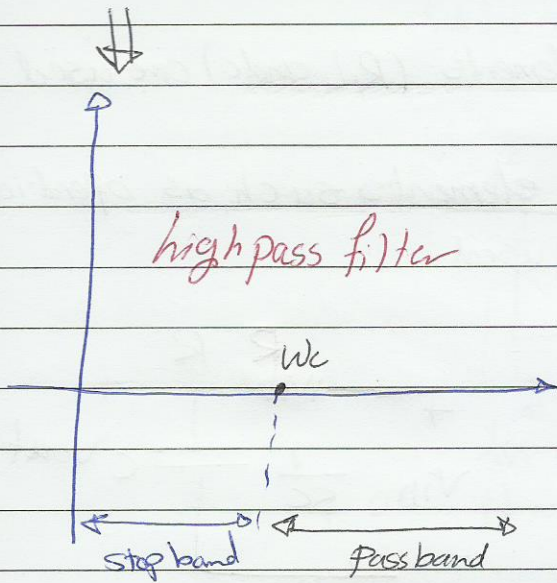
ω_c is called cut-off frequency



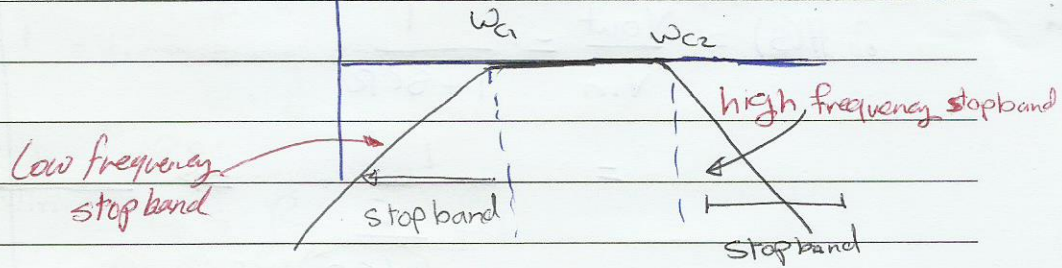
A slope or steepness of the curve depend on the filter design

signals with $\omega \leq \omega_c$ are allowed to pass

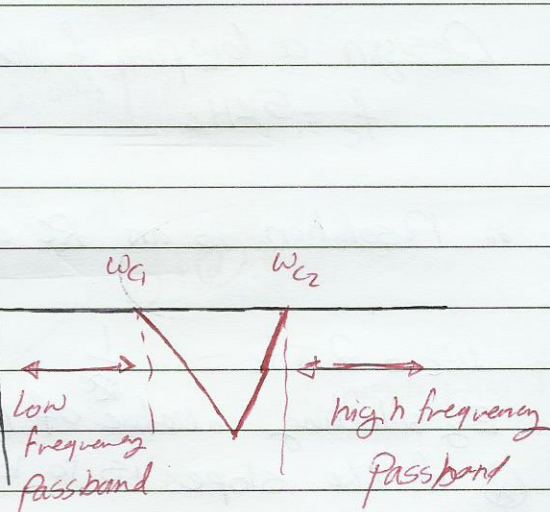
ii) Highpass Filter



iii) Band pass



iv) Band stop



final exam:

Question about op-amp *
design passive filter in the book

Classification of filters from construction point of view:

i) Passive filters: Here passive elements (R, L, and C) are used

ii) Active filters: Here active elements such as operational Amplifier and Transistor are used.

Examples in passive filters

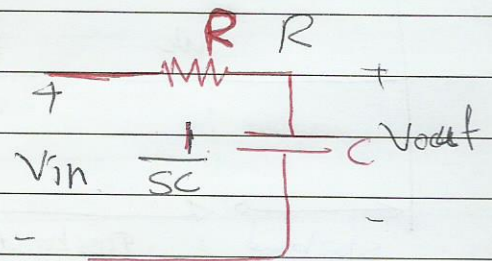
* consider the following RC ckt

By voltage Division

$$V_{out} = V_{in} \frac{1/SC}{R + 1/SC} = \frac{1}{SCR + 1}$$

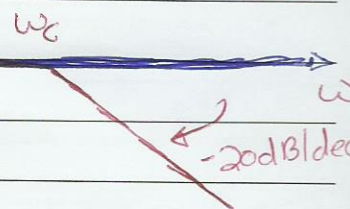
$$H(s) = \frac{V_{out}}{V_{in}} = \frac{1}{1 + sCR}$$

$$= \frac{1}{1 + \frac{s}{1/CR}} \omega_c$$



This ckt is a low pass Passive filter

when $\omega_c = 1/RC$



ex 80 Design a low pass filter with $f_c = 5\text{kHz}$

A solution is an RC ckt with output taken across C

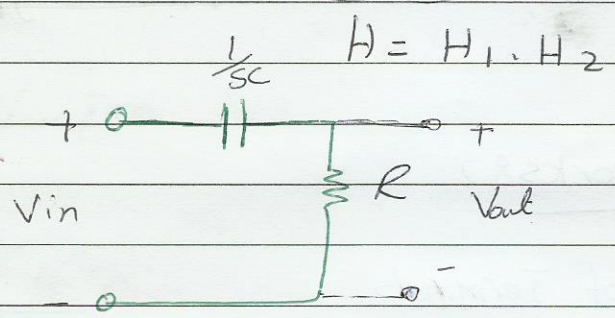
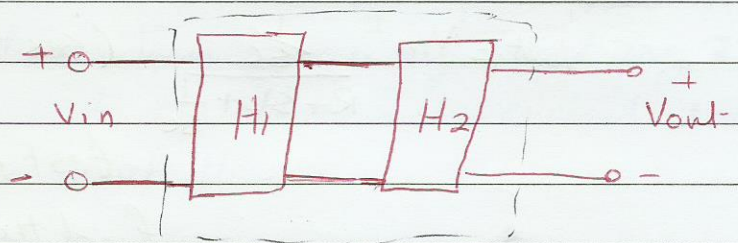
$$\omega_c = 2\pi f_c = \frac{1}{RC}$$

By selecting a value of R, then C can be evaluated.

* if the slope is to be for example -40dB/dec

$\beta = \dots$
 $f_c = \dots$

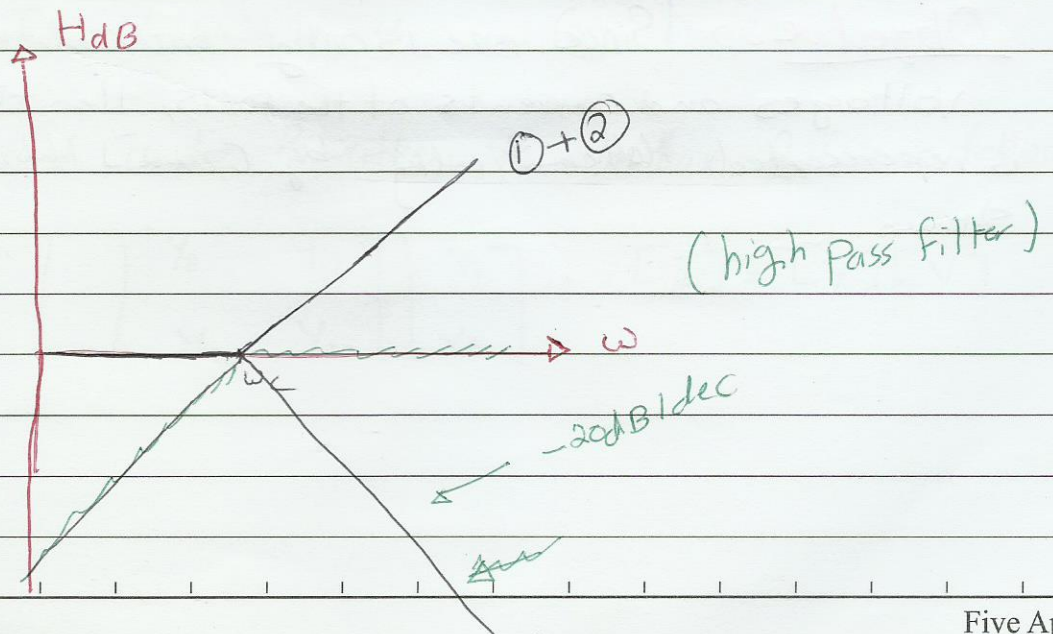
Then $H(s) = \frac{1}{\left(1 + \frac{s}{\omega_0}\right)^2} = \underbrace{\frac{1}{\left(1 + \frac{s}{\omega_0}\right)}}_{H_1} * \underbrace{\frac{1}{\left(1 + \frac{s}{\omega_0}\right)}}_{H_2}$

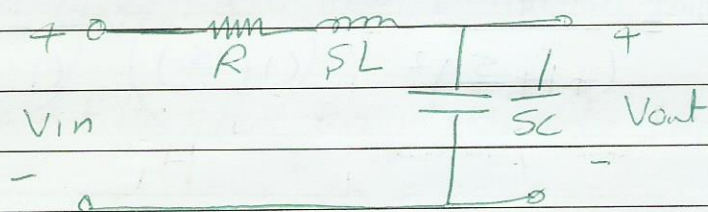


$V_{out} = V_{in} \frac{R}{R + \frac{1}{sC}}$

$\frac{V_{out}}{V_{in}} = \frac{R s C}{1 + s C R}$

$H(s) = \frac{s R C}{\left[1 + \frac{s}{\left(\frac{1}{RC}\right) \omega_0}\right]}$





$V_{out} = V_{in} \frac{\frac{1}{sC}}{R + sL + \frac{1}{sC}}$ (see the book)

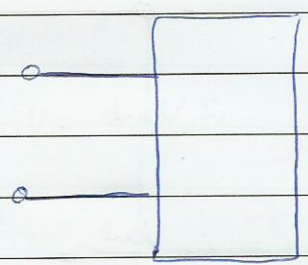
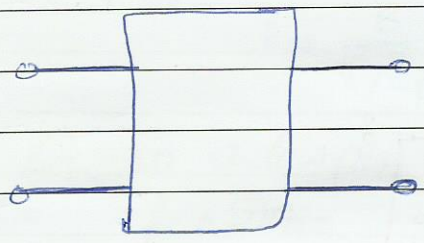
Use this circuit to find the type of filter.

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Two Port Networks

Port \equiv a pair of Terminals

* Two-port Network is a Network with 2 pairs of terminals.



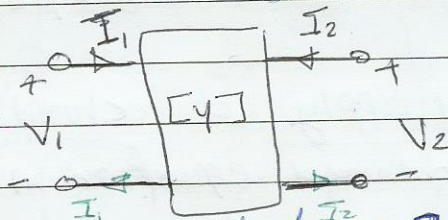
one-port network

Objective 8) Since one is only concerned with evaluation, voltages and currents of the ports, then the given Network is represented Mathematically by $[2 \times 2]$ Matrix as will be shown.

Procedure :-

Note network contain passive element and may contain dependent sources but not independent sources.

Since there are 4 variables :-



V_1, V_2, I_1 and I_2 . Then one may select any 2 to be independent variables, and the other 2 dependent variable are expressed as a function of them

Consequently, Parameters can be Classification :-

i) Y -Parameters

ii) Z - "

iii) h -Parameters

iv) t - "

Y or admittance parameters :-

Here I_1 and I_2 are expressed as functions of V_1 and V_2 as follow :-

$$\left\{ \begin{array}{l} I_1 = Y_{11} V_1 + Y_{12} V_2 \quad \text{--- (1)} \\ I_2 = Y_{21} V_1 + Y_{22} V_2 \quad \text{--- (2)} \end{array} \right. \quad \left. \begin{array}{l} \uparrow \\ \downarrow \end{array} \right.$$

\Rightarrow (1) and (2) can be rewritten in a matrix follow as follows :-

$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} Y_{11} & Y_{12} \\ Y_{21} & Y_{22} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} \Rightarrow [I] = [Y][V]$$

Methods of Evaluating [Y] Parameters

i) By apply cut techniques to the given cut. The Rearrange the obtained equation in matrix form Hence the obtained coefficients give the [Y] parameters.

ii) By applying s/c one at a time at the input and output ports, to evaluate the corresponding parameters

$$Y_{11} = \frac{I_1}{V_1} \Big|_{V_2=0}$$

$$Y_{12} = \frac{I_1}{V_2} \Big|_{V_1=0}$$

$$Y_{21} = \frac{I_2}{V_1} \Big|_{V_3=0}$$

$$Y_{22} = \frac{I_2}{V_2} \Big|_{V_1=0}$$

Y_{11} \equiv called s/c input admittance

Y_{22} \equiv " " output " "

Y_{12} & Y_{21} = called s/c Transfer Admittance.

If $Y_{12} = Y_{21}$ the network is called ~~reciprocal~~ Bilateral one

In a bilateral networks

If an ideal voltage source and an Ammeter are Interchanged

, then the Ammeter Reading will not change

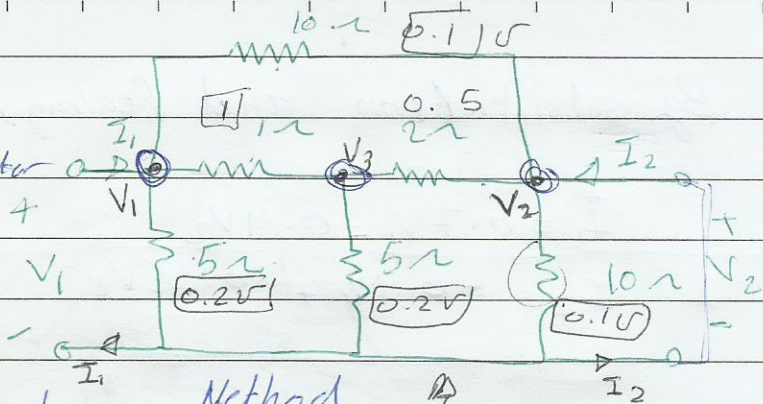
OR

current \leftrightarrow voltmeter

voltmeter \leftrightarrow current

ex 2)

evaluate the $[Y]$ Parameter of the given Network +



(1) By using cut technique Method ↑
Ref

By using nodal technique

$$\begin{bmatrix} I_1 \\ I_2 \\ 0 \end{bmatrix} = \begin{bmatrix} 1.3 & -0.1 & -1 \\ -0.1 & 0.7 & -0.5 \\ -1 & -0.5 & 1.7 \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \\ V_3 \end{bmatrix} \quad \text{--- (1)}$$

$Y_{ii} = \Sigma$ of admittance connected to i^{th} Node.

$Y_{ij} = -1 \times$ Admittance connected directly between i^{th} and j^{th} nodes.

\therefore From (1) \Rightarrow

$$I_1 = 1.3V_1 - 0.1V_2 - V_3 \quad (2)$$

$$I_2 = -0.1V_1 + 0.7V_2 - 0.5V_3 \quad (3)$$

$$0 = -V_1 - 0.5V_2 + 1.7V_3 \quad (4)$$

$$(4) \Rightarrow V_3 = \frac{V_1 + 0.5V_2}{1.7} \quad (5)$$

\therefore substitute (5) into (2) and (3)

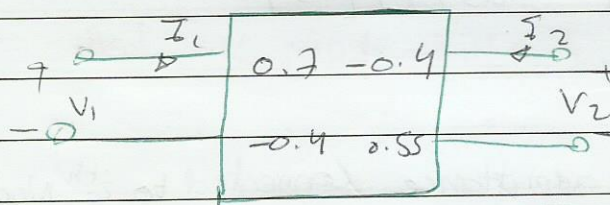
By substitution and Rearrangement it can be found:

$$I_1 = 0.7V_1 - 0.4V_2$$

$$I_2 = -0.4V_1 + 0.55V_2$$

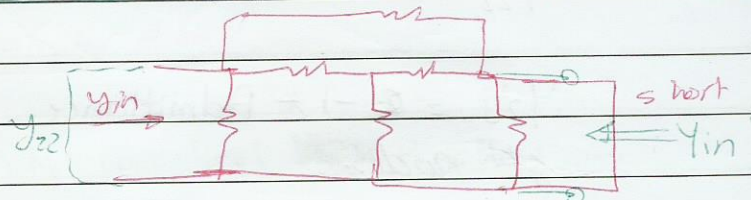
$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} \overset{y_{11}}{0.7} & \overset{y_{12}}{-0.4} \\ \underset{y_{21}}{-0.4} & \underset{y_{22}}{0.55} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$

Comment: Hence the Network is Bilateral.



• Bilateral Network

SIC Technique:



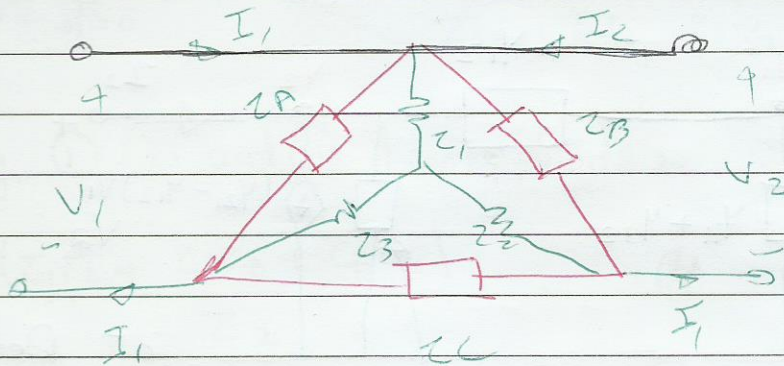
$$Y_{11} = \frac{I_1}{V_1} \Big|_{V_2=0} = y_{in} = 0.7$$

$$Y_{22} = \frac{I_2}{V_2} \Big|_{V_1=0} = y_{in}' = 0.55$$

$$Y_{12} = \frac{I_1}{V_2} \Big|_{V_1=0} = -0.4$$

Use circuit technique to find Relationship between

$$\frac{I_1}{V_2}$$



Application of $[Y]$ Parameters

Evaluating equivalent circuit of some electronic cuts

$$\text{Since } I_1 = Y_{11} V_1 + Y_{12} V_2 \quad \text{--- (1)}$$

$$I_2 = Y_{21} V_1 + Y_{22} V_2 \quad \text{--- (2)}$$

If $Y_{12} = Y_{21}$, then the equivalent circuit can be deduced directly.

If $Y_{12} \neq Y_{21}$, then equ (1) or (2) has to be modified in such a way the mutual element is the same.

For (e.g), Modify equ (2) as follows

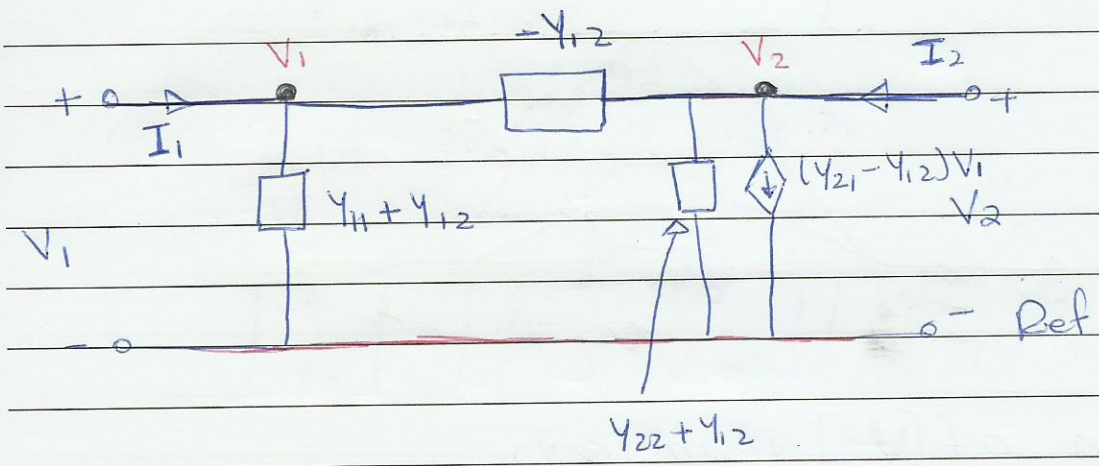
$$I_2 = Y_{21} V_1 + Y_{22} V_2 + Y_{12} V_1 - Y_{12} V_1$$

$$= Y_{12} V_1 + Y_{22} V_2 + (Y_{21} - Y_{12}) V_1$$

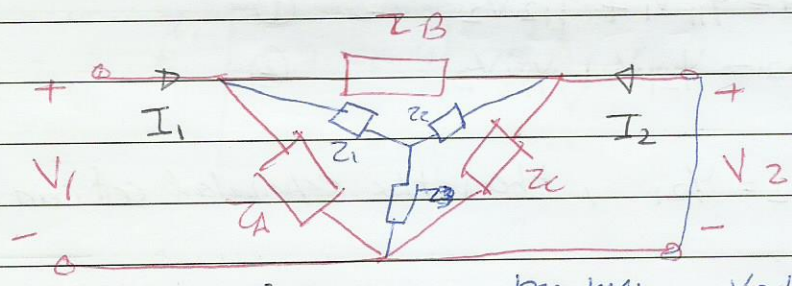
$$\therefore I_2 - (Y_{21} - Y_{12}) V_1 = Y_{12} V_1 + Y_{22} V_2 \quad \text{--- (3)}$$

$\begin{pmatrix} 5 \\ 5 \\ 10 \end{pmatrix}$
 $\begin{pmatrix} 5 \\ 5 \\ 10 \end{pmatrix}$
 $\begin{pmatrix} 25 \\ 30 \\ 10 \end{pmatrix}$
 $\begin{pmatrix} 60 \\ 70 \end{pmatrix}$

∴ Deduced the equivalent ct. for equation (1) and (3) as follows



Proof of $\Delta \rightarrow Y$ transformation. 7



for Y_{22} by KVL $-V_2 + I_1 Z_B = 0$
 $\Rightarrow \frac{I_2}{Z_B} = \frac{I_1}{Z_B}$

if the Δ and Y connection are equivalent then they should have the same parameter.

Here Evaluate, Their $[Y]$ parameter

$$Y_{11} = \frac{I_1}{V_1} \Big|_{V_2=0} = \frac{1}{Z_A} + \frac{1}{Z_B} = \frac{Y}{Z_1 + \frac{Z_2 Z_3}{Z_2 + Z_3}} \quad \text{--- (1)}$$

$$Y_{22} = \frac{I_2}{V_2} \Big|_{V_1=0} = \frac{1}{Z_B} + \frac{1}{Z_C} = \frac{1}{Z_2 + \frac{Z_1 Z_3}{Z_1 + Z_3}} \quad \text{--- (2)}$$

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$$Y_{12} = \frac{I_1}{V_2} \Big|_{V_1=0} = -\frac{1}{Z_B} = \frac{-Z_3}{Z_1 Z_2 + Z_1 Z_3 + Z_3 Z_2} \quad (3)$$

By solving (1), (2) and (3) it can be found as

$$Z_A = \frac{(Z_1 Z_2 + Z_1 Z_3 + Z_3 Z_2)}{Z_2} \quad (4)$$

$$Z_B = \frac{(Z_1 Z_2 + Z_1 Z_3 + Z_3 Z_2)}{Z_3} \quad (5)$$

$$Z_C = \frac{(Z_1 Z_2 + Z_1 Z_3 + Z_3 Z_2)}{Z_1} \quad (6)$$

(4), (5), and (6) can be used for $\Delta \rightarrow Y$ Transformation

$$\text{OR } Z_1 = \frac{Z_A Z_B}{(Z_A + Z_B + Z_C)} \quad (7)$$

$$Z_2 = \frac{Z_B Z_C}{(Z_A + Z_B + Z_C)} \quad (8)$$

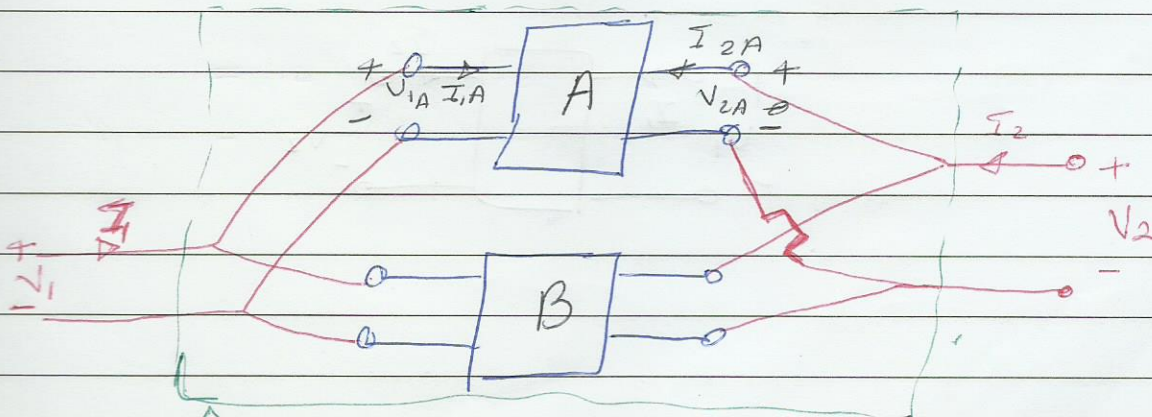
$$Z_3 = \frac{Z_A Z_C}{(Z_A + Z_B + Z_C)} \quad (9)$$

(7), (8) and (9) can be used for

$\Delta \rightarrow Y$ Transformation

Y-Parameters of Parallel connected networks

Consider the following Z Network A and B



$$I_1 = I_{1A} + I_{1B}$$

$$I_2 = I_{2A} + I_{2B}$$

$$\text{in } \begin{bmatrix} I_{1A} \\ I_{2A} \end{bmatrix} = \begin{bmatrix} Y_{12} \end{bmatrix} \begin{bmatrix} V_{1A} \\ V_{2A} \end{bmatrix} \quad \text{--- (1)}$$

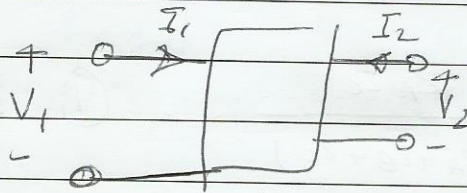
$$\begin{bmatrix} I_{1B} \\ I_{2B} \end{bmatrix} = \begin{bmatrix} Y_{1B} \\ Y_{2B} \end{bmatrix} \begin{bmatrix} V_{1B} \\ V_{2B} \end{bmatrix} \quad \text{--- (2)}$$

$$\text{in } \textcircled{1} + \textcircled{2} \Rightarrow \begin{bmatrix} I_{1A} + I_{1B} \\ I_{2A} + I_{2B} \end{bmatrix} = \begin{bmatrix} Y_{1A} + Y_{1B} \\ Y_{2A} + Y_{2B} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$



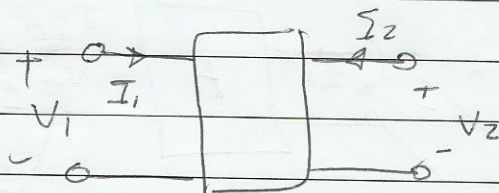
$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} Y_{1A} + Y_{1B} \\ Y_{2A} + Y_{2B} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} Y_{11} \\ Y_{21} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$

Z-Parameters



Defined as follows

$$\begin{aligned} V_1 &= Z_{11} I_1 + Z_{12} I_2 \\ V_2 &= Z_{21} I_1 + Z_{22} I_2 \end{aligned} = \begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}$$



S → App $\frac{V}{I}$
cost

Find the equivalent circuit by 2 parameter

Evaluation Techniques

- ① using cut technique as explained and illustrated in the case of [y] Parameter.
- ② by performing o/c Tests at the ports as follows:→

$$Z_{11} = \frac{V_1}{I_1} \Big|_{I_2=0}$$

$$Z_{12} = \frac{V_1}{I_2} \Big|_{I_1=0}$$

$$Z_{21} = \frac{V_2}{I_1} \Big|_{I_2=0}$$

$$Z_{22} = \frac{V_2}{I_2} \Big|_{I_1=0}$$

∴ Z parameters represent Impedances

Z_{11} & Z_{22} called the o/c Input and Output Impedances.

Z_{12} , Z_{21} called o/c Transfer Impedances.

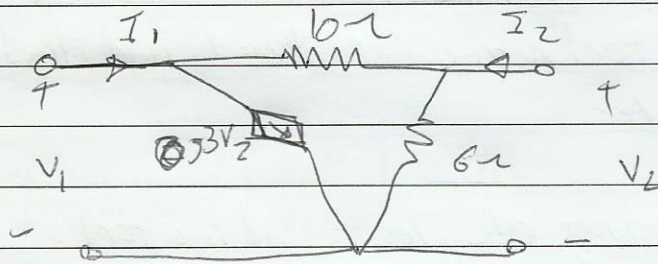
If $Z_{12} = Z_{21}$ the circuit is called bilateral.

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evaluate
the $[Z]$

Parameters

of the
given network



$$Z_{11} = \frac{V_1}{I_1} \Big|_{V_2=0}$$

$$Z_{21} = \frac{V_2}{I_1} \Big|_{I_2=0}$$

By kirchoff current laws KCL

$$I_1 = 0.3V_2 + \frac{V_2}{6} = \frac{2.8}{6} V_2 \quad \text{--- (1)}$$

By KVL

$$V_1 = \frac{V_2}{6} \times 10 + V_2 = \frac{16}{6} V_2 \quad \text{--- (2)}$$

Substitute (2) into (1) \Rightarrow

$$I_1 = \frac{2.8}{6} \times \frac{6V_1}{16}$$

$$\therefore Z_{11} = \frac{V_1}{I_1} = \frac{6 \times 16}{6 \times 2.8}$$

$$= 5.71$$

$$\textcircled{1} \Rightarrow \frac{V_2}{I_1} = \frac{6}{2.8} = Z_{21}$$

$$= 2.14$$

By similar Approach

It can be found

$$Z_{12} = -4.28$$

$$Z_{22} = 2.14$$

Equivalent ckt of [Z]

equations) add, subtract

$$V_1 = Z_{11} I_1 + Z_{12} I_2 \quad \text{--- (1)}$$

$$V_2 = Z_{21} I_1 + Z_{22} I_2 \quad \text{--- (2)}$$

in order to have the same Mutual element between 2 meshes,
then modify equ (1) or (2)

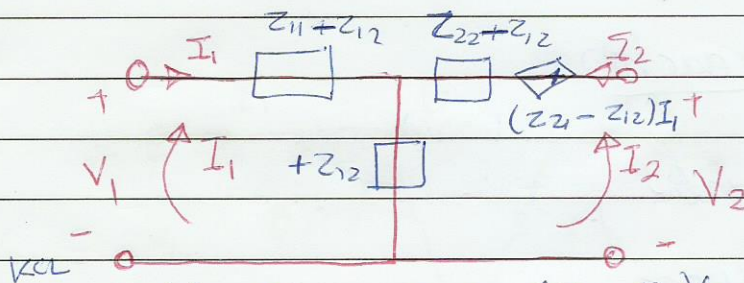
For (e.g) Modify equ. (2)

$$\text{(2)} \rightarrow V_2 = Z_{21} I_1 + Z_{22} I_2 + Z_{12} I_1 - Z_{12} I_1$$

$$\therefore V_2 = Z_{12} I_1 + Z_{22} I_2 + (Z_{21} - Z_{12}) I_1$$

$$\therefore V_2 - (Z_{21} - Z_{12}) I_1 = Z_{12} I_1 + Z_{22} I_2 \quad \text{--- (3)}$$

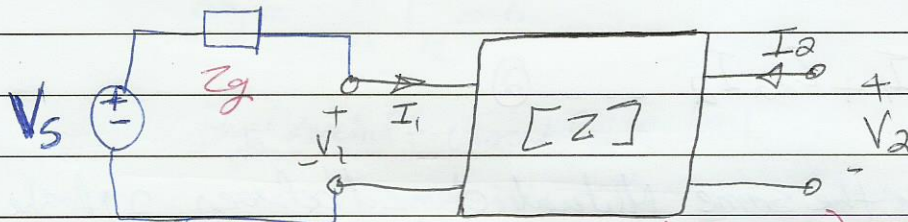
in deduce the equivalent ckt by using equs (1) and (3)



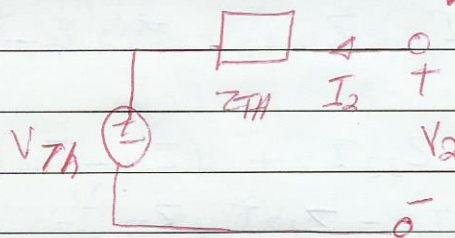
$$V_1 = I_1(z_{11} + z_{12}) + (I_1 + I_2)(-z_{12})$$

$$= I_1 z_{11} + I_1 z_{12} - I_1 z_{12} - I_2 z_{12}$$

Thevenin equivalent



objectives Find Thevenin equivalent seen from the output port.



Objectives

find An eqn

$$V_2 = I_2 Z_{TH} + V_{TH}$$

$$V_1 = z_{11} I_1 + z_{12} I_2 \quad \text{--- (1)}$$

$$V_2 = z_{21} I_1 + z_{22} I_2 \quad \text{--- (2)}$$

$$V_s = I_1 z_g + V_1 \quad \text{--- (3)}$$

$$(3) \Rightarrow V_1 = V_s - I_1 z_g \quad \text{--- (4)}$$

Sub (4) into (1) \Rightarrow

$$V_s - I_1 z_g = z_{11} I_1 + z_{12} I_2$$

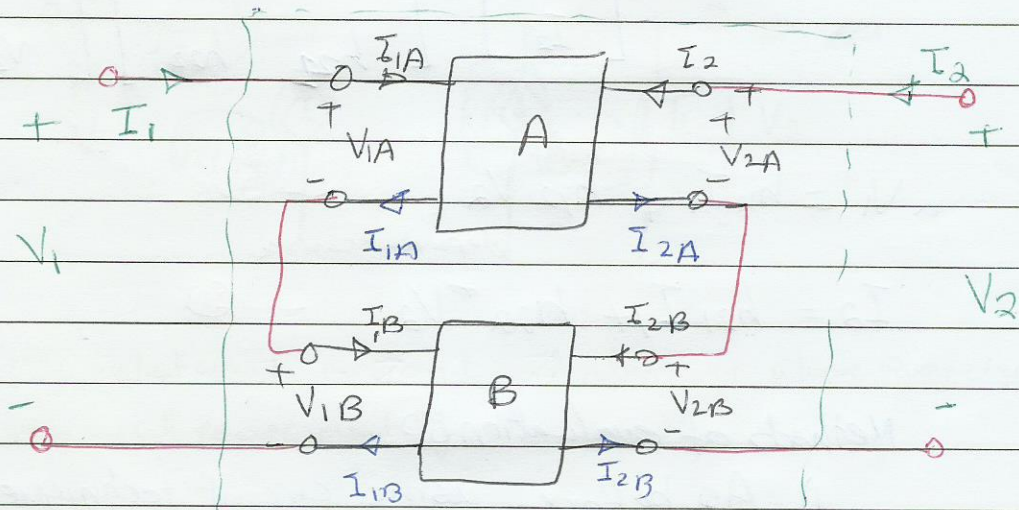
$$\therefore I_1 (z_{11} + z_g) = V_s - z_{12} I_2$$

$$\therefore I_1 = \frac{V_s - z_{12} I_2}{z_{11} + z_g} \quad \text{--- (5)}$$

Substitute (5) into (2) and Rearrange, it can be found

$$V_2 = V_s \frac{z_{21}}{z_{11} + z_g} + I_2 \left(z_{22} - \frac{z_{12} z_{21}}{z_{11} + z_g} \right) \quad Z_{TH}$$

Series Connection ^{V_{TH}} go



Objective find $[Z]$ of the equ network.

Procedure it can be found $I_1 = I_{1A} = I_{1B}$

$$I_2 = I_{2A} = I_{2B}$$

$$V_1 = V_{1A} + V_{1B}$$

$$V_2 = V_{2A} + V_{2B}$$

A

$$\begin{bmatrix} V_{1A} \\ V_{2A} \end{bmatrix} = [Z_A] \begin{bmatrix} I_{1A} \\ I_{2A} \end{bmatrix} \quad \text{--- (1)}$$

B

$$\begin{bmatrix} V_{1B} \\ V_{2B} \end{bmatrix} = [Z_B] \begin{bmatrix} I_{1B} \\ I_{2B} \end{bmatrix} \quad \text{--- (2)}$$

$$\text{in (1) + (2)} \Rightarrow \begin{bmatrix} V_{1A} + V_{1B} = V_1 \\ V_{2A} + V_{2B} = V_2 \end{bmatrix} = \underbrace{[Z_A] + [Z_B]}_{Z_{eq}} \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}$$

Hybrid or [h] Parameters

$$\begin{bmatrix} V_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix} \begin{bmatrix} I_1 \\ V_2 \end{bmatrix}$$

$$V_1 = h_{11} I_1 + \underbrace{h_{12} V_2}_{\text{dependent source}} \quad \text{--- (1)}$$

$$I_2 = h_{21} I_1 + h_{22} V_2 \quad \text{--- (2)}$$

Methods of evaluation

- 1) As before using circuit techniques
- 2) by performing short circuit and open circuit ~~test~~ as follows

$$h_{11} = \frac{V_1}{I_1} \Big|_{V_2=0} = \text{S/C input impedance}$$

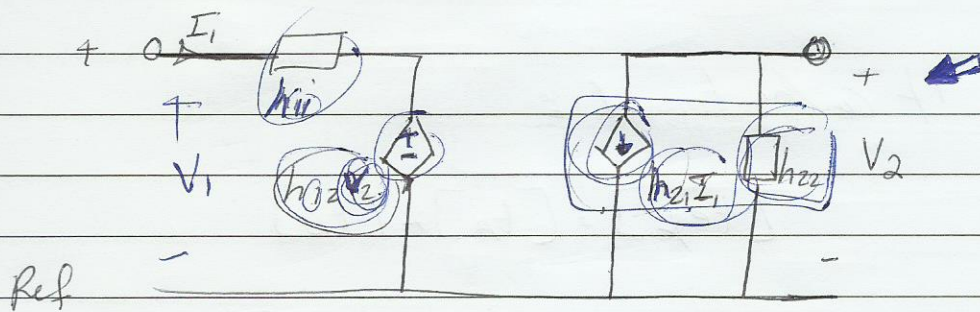
$$h_{21} = \frac{I_2}{I_1} \Big|_{V_2=0} = \text{S/C forward current gain}$$

$$h_{12} = \frac{V_1}{V_2} \Big|_{I_1=0} = \text{O/C reversed voltage gain}$$

$$h_{22} = \frac{I_2}{V_2} \Big|_{I_1=0} = \text{O/C output admittance}$$

Hence the name hybrid parameter

Equivalent circuit by using (1) and (2) is

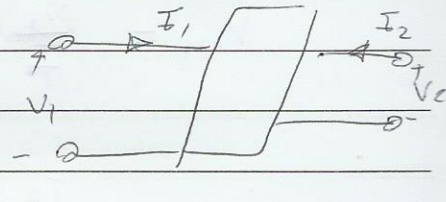


is Equivalent circuit represent of a transistor whose parameters can be measured experimentally

Parameters \leftarrow Z Parameters \rightarrow Y Parameters

Two port function in parallel \rightarrow Z Parameters \rightarrow Two port function in series \rightarrow Y Parameters

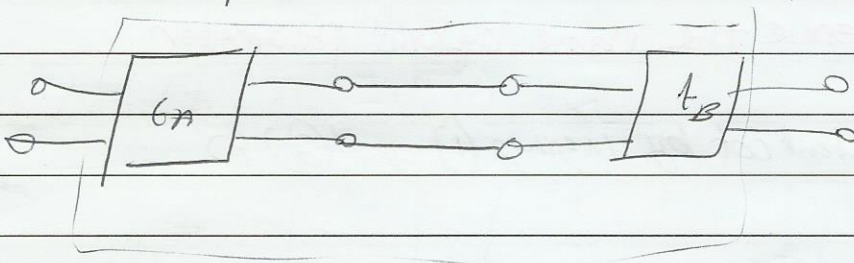
Transmission Parameters $[t]$ \rightarrow Cascade connection \rightarrow Y Parameters

$$\begin{bmatrix} V_1 \\ I_1 \end{bmatrix} = \begin{bmatrix} t_{11} & t_{12} \\ t_{21} & t_{22} \end{bmatrix} \begin{bmatrix} V_2 \\ -I_2 \end{bmatrix}$$


The same previous method can be used to evaluate $[t]$ parameter.

Cascade Connections

output of the first is the input of the second



It can be found:

$$[t_{eq}] = [t_A] \times [t_B]$$