University of Jordan Elect. Eng. Dept. Numerical Methods 903301

Second Exam Reg. No.

Wednesday 3/8/2016 Mark out of 30

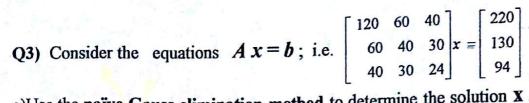
Student Name: Answers should be written in ink Exam Duration: 70 min

Dinas (Mails	
Pover unil-	then one line briefly
Q1) From numerical methods point of view, in not more	ulan one me,
answer	
	of equations over
i) The advantage of direct methods for solving system	ns of equations
iterative methods.	
	egossive substitution
ii) The advantage of the Newton method over the su	ICCESSIVE SUBSTITUTE
method	
iii) The advantage of the secant method over the Newton	n Raphson method.
iii) The advantage of the secant method over the revision	, ,)
	1000
iv) A difficulty when calculating the condition number.	\mathcal{V})
(V) A difficulty when shows 8	
v) A use of eigenvalues	
	1 E
vi) A use of matrix norms	
vii) Write down the error formula involved with the N	ewton-Raphson method relating
E_{i+1} to E_i .	3

Q2) a) Formulate the solution of $x^3 = \cos(x)$ as a zero finding problem, hence use the fixed point method to find the solution starting with $x^0=0.8$. Perform as many iteration needed to confirm convergence. What answer do you get? Now, repeat the process once more starting with $x^0=0.8$ and write down the first 5 iterations to 10 significant digits.

b) To check the result obtained above, use the Newton-Raphson method starting with $x^0=0.8$. Write down the first 5 iterations to 10 significant digits.

Inspect the numbers obtained now to comment on the rate of convergence. What is it? Is it expected?

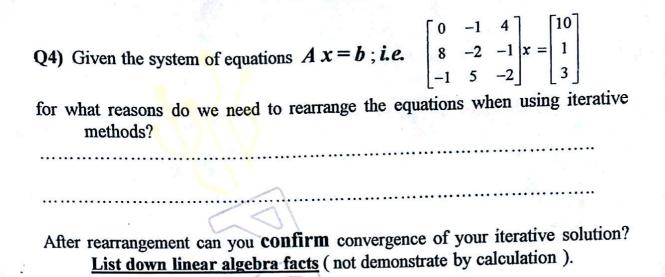


a)Use the naïve Gauss elimination method to determine the solution X.



b) Suppose now that 220 in the b matrix is changed to 200, obtain the solution once more. Note that you can avoid repeating all the calculation done before. Be wise.

Is the new solution significantly different?. If so, why is that?. You may need the fact that the infinity norm of the inverse of A is 3.4..



Now Calculate by performing two iterations only using Gauss-Seidel method starting with $x^0 = \begin{bmatrix} 0.8 & 1.8 & 2.8 \end{bmatrix}^T$.

Using vector norms, calculate the <u>relative approximate error</u> at the end of the second iteration.