

Lecture 1: Introduction to Communication Systems

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EE421: Communications I.

A Communication System

- **Purpose** of a communication system:
Carry information from one point to another.
- A typical communication system consists of **three main components**:
 - Source
 - Channel
 - Destination

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How to build it?

Three basic blocks:

Simple example:

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Channel Impairments تلف

Impairments:
→ Attenuation, Distortion, Noise, etc

$P_{avg} \text{ For DC} = V^2$
 $P = (5)^2$

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Channel Impairments

Power Loss ←

1. Attenuation: As the signal travels through the channel it loses some of its energy (*power*) as *heat* in the *internal resistance* of the channel. We say the signal is attenuated.

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Attenuation

- Attenuation can be problematic for long distance communications (say cross-country).

ch2
att level
0.8/km

1 km
m(t) → 0.9 m(t)

out = 0.9 m(t)
in m(t)

= 0.9
(less attenuation compared to ch2)

↑ R ↑

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* 3 properties for Attenuation:-

- ① Att → signal types
- ② Att → channel types
- ③ increases as the channel length increase

- * Short - medium distance → use an amplifier at source or destination
- * long distance → multiple amplifiers at intermediate cities
- * optical fibers has small attenuation levels.

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* long distance communications → optical fiber. need an amplifier every 5-10 km

* For copper wires, you

* For optical fibers, you need an amp every 50-100 km

Amplifiers need power supply

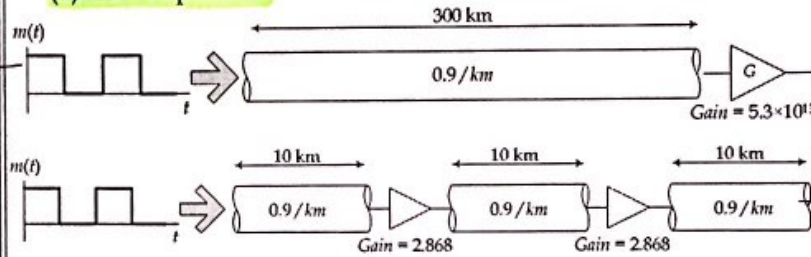
$$(0.9)^{10} m(t) \rightarrow m(t)$$

$$Gain = \frac{1}{(0.9)^{10}}$$

Attenuation is not easy to overcome

Solutions to Attenuation

(a) Use Amplifiers:



(b) Use channels with smaller attenuation levels (e.g., optical fiber) - such channels are usually more expensive.

(c) Digital signals are less susceptible to attenuation (because of threshold detection at the receiver).

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$$V_{in} = (0.9)^{300} m(t)$$

$$Gain = \frac{1}{(0.9)^{300}}$$

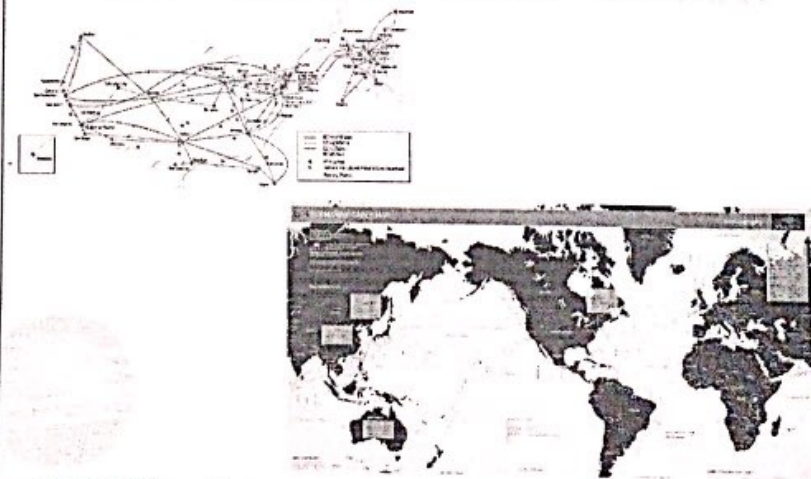
Inverse gain

$$m(t) = V_o$$

$$V_o(t) = Gain \times V_{in}(t)$$

$$m(t) = \frac{1}{(0.9)^{300}} \times (0.9)^{300} m(t)$$

Fiber Cables for Long Distance

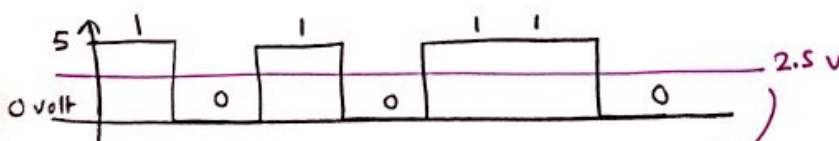


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* Using Digital signals instead of analog



(0 ← 2.5 ← 5) threshold detection
 (0 ← 2.5 ← 5) threshold detection

we don't care about the voltage, we care if it above the threshold or not!

Channel Impairments

2. Linear Distortion: The channel attenuation changes according to the transmitted signal frequency. Usually higher frequencies are attenuated more. Hence, the channel acts as a **LPF** that attenuates high frequencies, thus distorting the signal. We say the channel is a filter that has **finite (limited) channel bandwidth**.

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* Frequency transfer function:
higher frequency → higher attenuation.

$Z_R = R'$
 $Z_L = j\omega L$
 $Z_C = \frac{1}{j\omega C}$

$\omega = 0 \rightarrow Z_C = \frac{1}{j\omega C}$
 $\omega = \infty \rightarrow Z_C = \frac{1}{j\omega C}$

Linear Distortion: Cause

$|H(f)| = V_o(f) / V_i(f)$

$R / (R + R') \approx 1.0$

must be
 $= P_o / P_{in}$
 $= (V_o^2) / (V_{in}^2)$
 ↓
 but this is unitless
 So, we must use dB.

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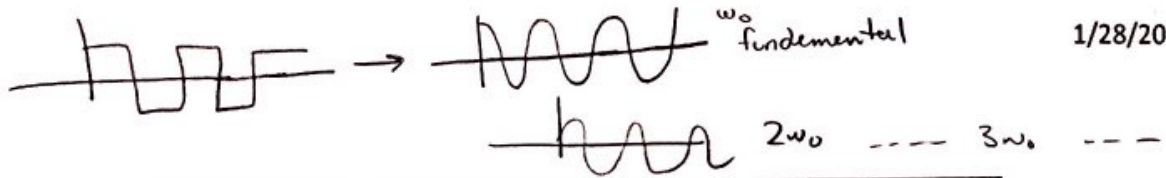
$\log 0 = -\infty$
 log goes down.

cut-off \equiv
 Bandwidth of the
 channel

$= 10 \log_{10} (P_{out} / P_{in}) \rightarrow \text{dB}$
 $= 10 \log_{10} (V_{out}^2 / V_{in}^2)$

Periodic signals:-

$$x(t) \text{ periodic} = \sum_{\infty} \text{cosines}$$



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Linear Distortion: Effects

The diagram shows a square wave $m(t)$ on the left. To its right, an equals sign is followed by a vertical stack of sine waves of increasing frequencies, separated by plus signs. The top sine wave is the largest, and the frequency increases downwards, with three dots at the bottom indicating an infinite series.

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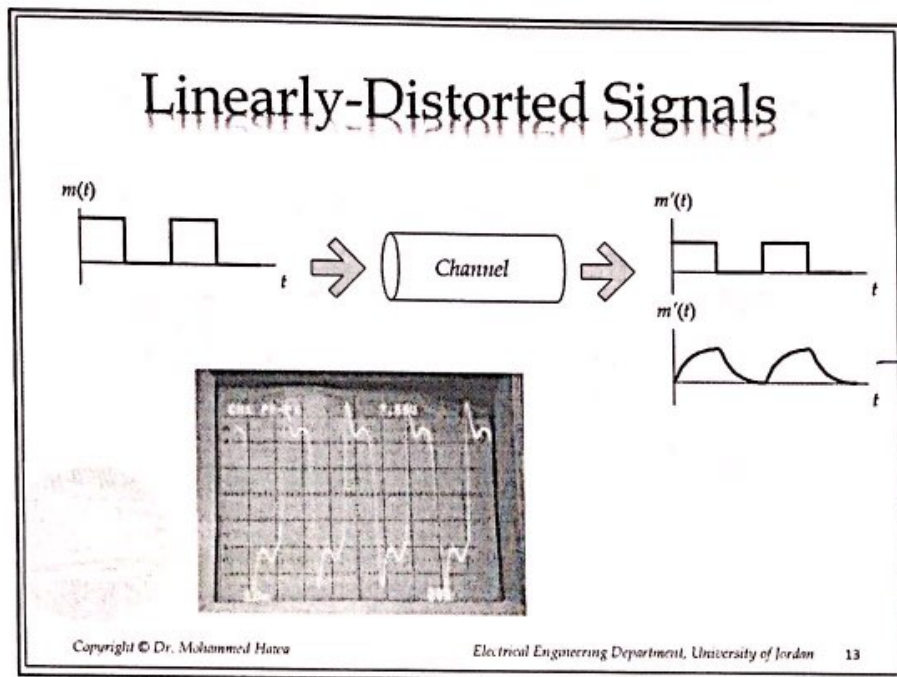
Linear Distortion: Effects

The diagram illustrates the magnitude spectrum $|M(\omega)|$ of a square wave $m(t)$. The top part shows discrete impulses at various frequencies, with a handwritten note: "every pair is a cosine". The bottom part shows a trapezoidal envelope representing the channel bandwidth, with labels $2\pi B_{channel}$ and $2\pi B$ on the x-axis.

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لازم تكونه بل Hz
بنا 5 سنت Rad/s
بفرق $2\pi * B$

message should
fit in the
channel
bandwidth



→ The shape was changed.

To Summarize:

- Channel Bandwidth $B_{channel}$:
 - A property of the channel.
 - You read it from the data sheet of the channel.
 - The frequency after which the channel presents very high attenuation.
- Signal Bandwidth $B_{m(t)} = B$:
 - A property of the signal.
 - You figure it out from the Fourier transform of the signal.
 - The frequency above which $m(t)$ has insignificant (negligible) harmonics.
- Rule of thumb: signal bandwidth should be less than or equal to channel bandwidth.

$$B_{m(t)} \leq B_{channel}$$

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← The message should fit in channel bandwidth.

- * Bandwidth of 1km Copper wires, is about 1-2 MHz
- * 1km of Coax cable \rightarrow 1-2 GHz
- * 1km fiber \rightarrow too big (many THz)
 \hookrightarrow more expensive.

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Compress in Time \rightarrow expand in freq and vice versa

Solutions to Linear Distortion

(a) The message should fit in the channel bandwidth (either send at smaller data rate or use a better channel)

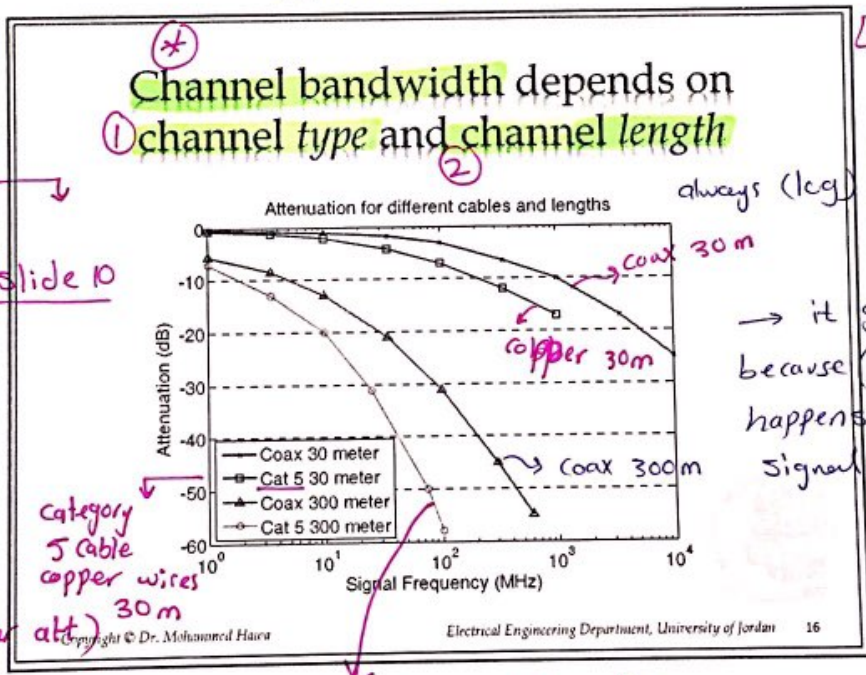
(b) Use an Equalizer at the receiver

(c) Pre-distortion at the transmitter

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- ① device used in Rx
- ② equalizer tries to do the opposite job of the channel expensive solutions (very complex)
- ③ complex and expensive

- ① complex and expensive
- ② used at Tx
- ③ does the opposite job of channel



More realistic data sheet than that in slide 10

(14) Record

always (log) goes down \rightarrow it goes down because (more power loss) happens when the signal is higher frequency.

category 5 cable copper wires 30m (has higher att)

higher attenuation

why all the numbers is negative ?!

$$10 \log_{10} \left(\frac{P_o}{P_i} \right) < 1 \text{ because of power loss}$$

$$= -ve$$

so we apply:

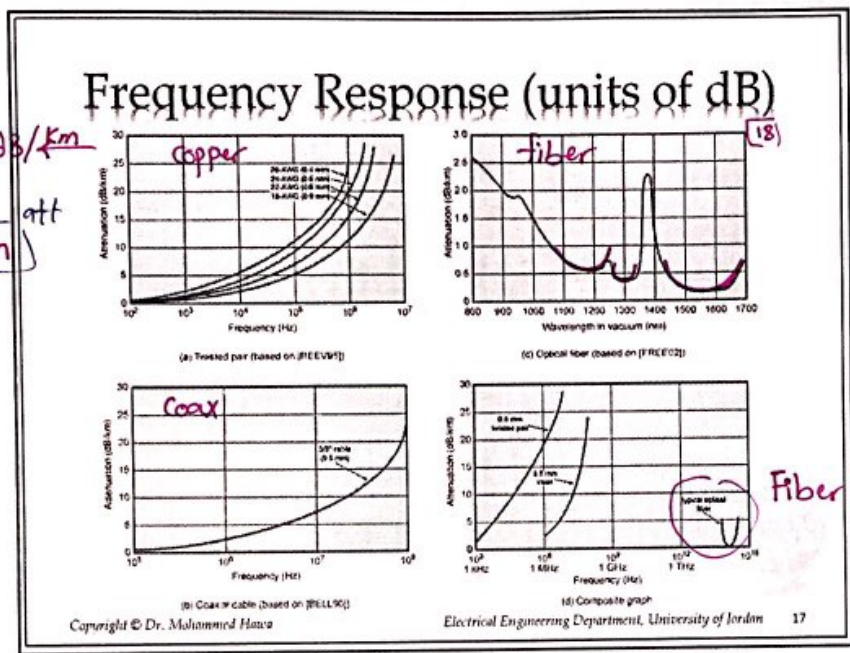
$$10 \log_{10} \left(\frac{P_o}{P_i} \right)$$

8

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LPF should act like this

مع زيادة التردد
 $10^5 \text{ Hz} \rightarrow \text{att} = 5 \text{ dB/km}$
 $= 100 \text{ KHz}$
 actually -5 dB/km

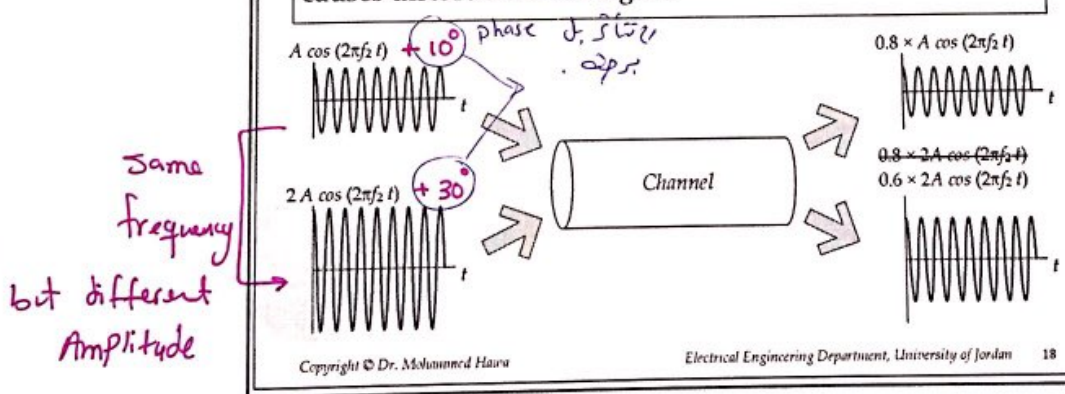


Fiber is less attenuation.

Channel Impairments

3. Non-Linear Distortion: The channel attenuation changes according to the transmitted signal amplitude and/or phase. Usually higher amplitudes are attenuated more. This causes distortion to the signal.

Linear distortion
 ↓
 Frequency



there is no rule of thumb for the change of phase, it depends on the channel itself.

Fourier Transform Again!

** Bigger cosines will be attenuated more*

$|M(\omega)|$
magnitude spectrum density
(every pair is a cosine)

ω (rad/s)

$\angle M(\omega)$
phase spectrum density

ω (rad/s)

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Non-Linearly-Distorted Signals

$m(t)$

Channel

$m'(t)$

Attenuation &
Linear Distortion

$m'(t)$

Attenuation &
Linear Distortion &
Nonlinear Distortion

$m'(t)$

The shape has changed (problem)

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Distorted signals are not desired!



• **Solutions to Non-Linear Distortion:** Use an Equalizer ^{① Rx} at the receiver or Pre-distortion ^{② Tx} at the transmitter.

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expensive and complex.

* attenuation, linear and Non-linear distortion work on ~~the~~ your signal.

but Noise adds another part to the original signal.

Channel Impairments

4. Noise: All the undesired signals (not part of the original signal) that are added by the channel. Noise is a random (non-deterministic) signal generated by external and internal sources.

- **External Sources:** interference from signals transmitted on nearby channels (crosstalk), interference generated by contact switches, automobile ignition radiation, fluorescent lights, natural noise from lightning, solar radiation, etc.

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you cannot write an equation.

Land line telephony :- channels behave like LPF



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Example External Noise: Crosstalk

$m_1(t)$
 $m_2(t)$
 $m_1(t) + k m_2(t)$
 the magnetic field produces
 caused by the electromagnetic force (EMF)
 $m_2(t) \times i_3 + i_4$
 external noise because of nearby channels
 And it's Random.

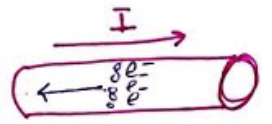
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many cables were put together to save money but it causes noise (Crosstalk) because of the magnetic field.

Noise

- Internal Sources:** thermal noise (random motion of electrons in conductors, random diffusion and recombination of charged carriers in electronic devices).

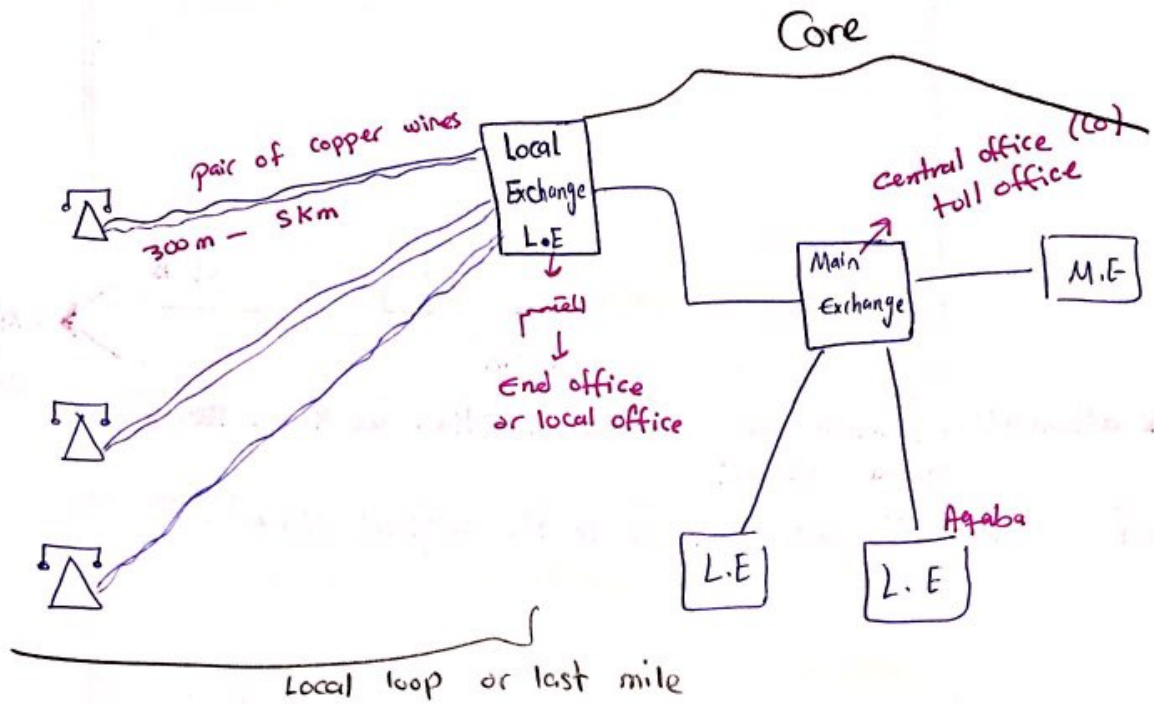
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Bandwidth for copper \rightarrow 1-2 MHz
 coax \rightarrow 1-2 GHz

Load line telephony :-

wireless channel \equiv in cellular



M.E \rightarrow to connect L.E together

L.E \rightarrow to connect users together

Fiber \rightarrow big bandwidth and very low attenuation

load line telephony $\left\{ \begin{array}{l} \rightarrow \text{PSTN : public switched telephone network} \\ \rightarrow \text{POTS : plain old telephony system.} \end{array} \right.$

Moving Electrons

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electrons move like this
Because of thermal energy
(temperature is not 0 kelvin)
gives energy to electrons.

Noisy signals are not desired!

The Internal Noise is one of the worst problems?! why?!

- The effects of external noise can be minimized or eliminated.
- The effects of internal noise can be minimized but never eliminated.

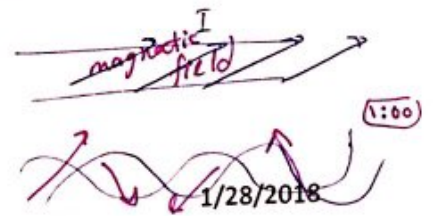
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0K = -273°C → we need temperature to be zero kelvin to eliminate internal noise and this is impossible.

why (twisting) is effective ?!

electric field is a vector (has direction)

$$\begin{aligned} \vec{s} &= \vec{10} && \text{↳ can minimize some of the vectors} \\ \vec{s} &= 0 && \text{(because they have direction)} \end{aligned}$$



Solutions for External Noise

- Shielding or twisting (very effective) But very expensive
- A different cable design (coax, fiber, wave guide).
- Proper design of the whole system.
- Using filters at the receiver side: BPF, LPF, notch filter.
- Digital transmission (threshold detection, orthogonality, FEC, etc.)

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effective and cheap

The inner wire inside the outer wire the outer one acts as conductor and shield. so that prevents interference from happen.

uses light

(It has reflected index)

Its like a mirror (reflects the light)

unshielded twisted pair UTP

cat 5 cable (used in ethernet)

covered each pair with piece of metal to avoid interference

shielded twisted pair STP

very effective and cheap

Solutions for Internal Noise

- Cooling.
- Using filters at the receiver side: BPF, LPF, notch filter.
- Digital transmission (threshold detection, orthogonality, FEC, etc.)

LNB: low Noise Block

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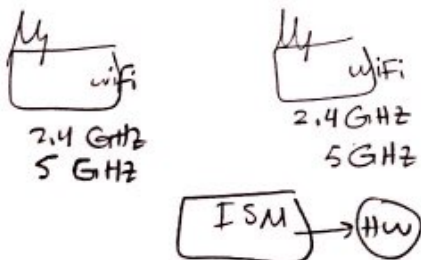
very effective but very expensive we use it in limited situations (ex) Satellite

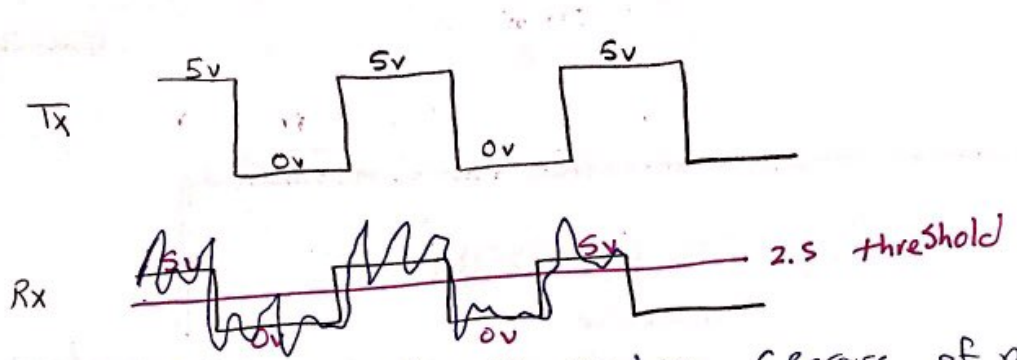
* what is the first stage you should use in your system?!

A Filter effective and cheap

If you put these 2 wifi's nearby each other there will be interference (they will create electro magnetic interference against each other)

Bluetooth 2.4GHz
Microwave oven 2.4GHz





The Blue signal will receive. (Because of noise)
 IS the receiver confused

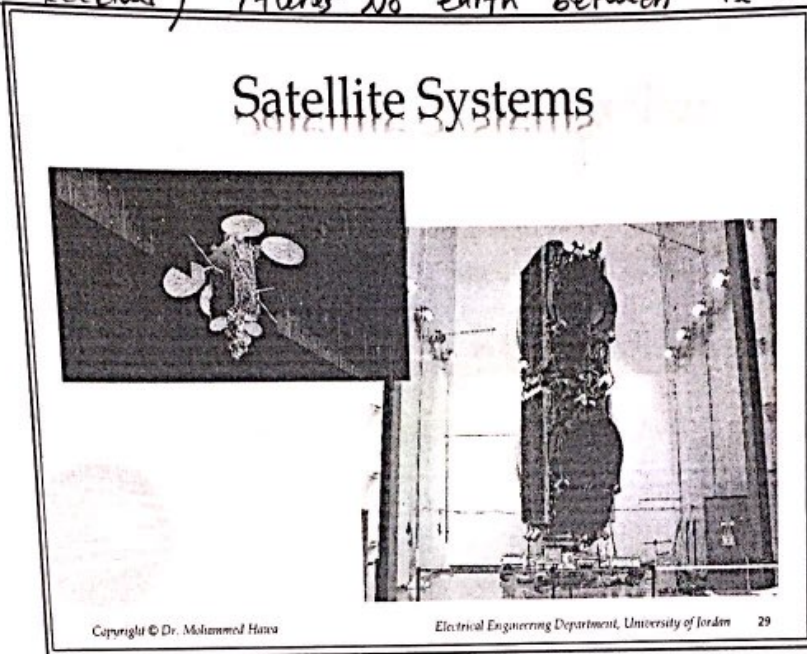
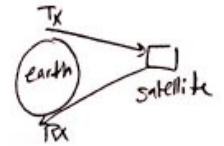
why do we need satellite?!

If you want to send a ^{wireless} signal from point to another ~~then~~ earth it will pass through heavy attenuation

So, we use satellite to act like an amplifier

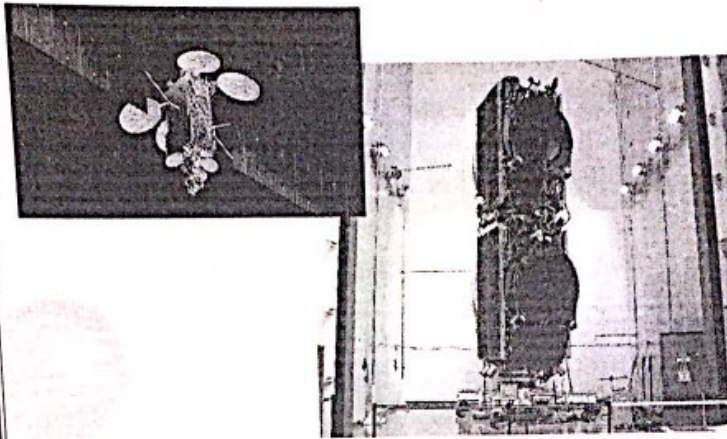
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(we send our signal to the satellite and it sends it back to the ~~transmitter~~ Receiver) there's no earth between Tx and Rx



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Satellite Systems



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LEO : Low earth orbit

~ 1000 km above surface of earth
less attenuation and less noise

MEO : Medium earth orbit

~ 10,000 km need 5-6 satellite

GEO

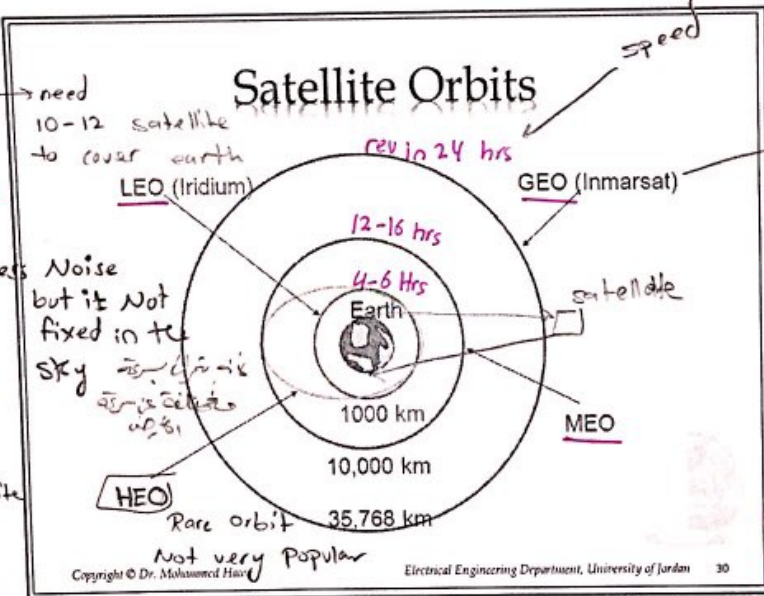
① geosynchronous or geostationary earth orbit

~ 36,000 km

② fixed in sky → it rotates at the same speed of earth

③ need 3 satellite minimum to cover surface of earth

④ wider footprint



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The difference between these 3 orbits:-
* Rotation speed.

(How fast the satellite rotate in its orbit)

Disadvantage for GEO :-
more attenuation and more noise ^{because of the distance}

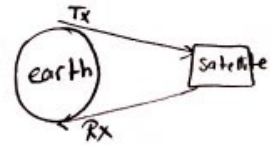


why do we need satellite ?!


If you want to send a wireless signal from point to another on earth, it will pass through heavy attenuation.

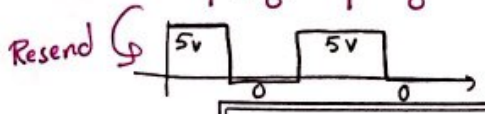
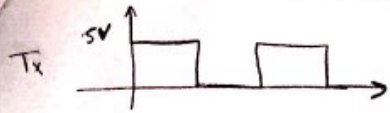
So, we use satellite to act like an amplifier (we send out signal to the satellite and it sends it back to the Receiver)

There's No earth between Tx and Rx



* Satellite orbits :-

	LEO Low earth orbit	MEO Medium earth orbit	GEO geosynchronous or geostationary earth orbit
	~ 1000 Km above surface of earth	~ 10,000 Km	~ 36,000 Km
	needs 10-12 satellite to cover earth	5-6 satellite (Between LEO and GEO)	needs 3 satellites minimum to cover surface of earth 
	Not fixed in the sky if it is in the sky it is not fixed	Not fixed in the sky	Fixed in sky (it rotates at the same speed of earth)
	less attenuation and less Noise	between LEO and GEO	more attenuation and more noise (because of the distance) (disadvantage)
<u>speed</u>	4-6 hrs	12-16 hrs	Rev in 24 hrs



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Impairments ALL Together

Attenuation + Noise:
Come from noise

$m(t) \rightarrow 0.1 m(t) + n(t) \rightarrow m(t) + 10 n(t)$

\downarrow I loose 0.9 $m(t)$ because of attenuation \rightarrow Gain = 10 $\rightarrow m(t) * \text{gain} =$

We need new solutions: **Regenerators** (Digital Transmission)

$m(t) \rightarrow 0.1 m(t) + n(t) \rightarrow R \rightarrow m(t) \rightarrow R$

$R = RX + TX$

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Nowadays, Satellites are Regenerator Not Amplifiers

Transponder in Satellite is Regenerator.

- * much more difficult to build than amplifier
- ① more expensive
- ② error propagating

Other Channel Impairments

Not exist in all channels (just in specific ones)

5. **Fading:** Variable attenuation with time of day and receiver location (wireless systems).
6. **Doppler Shift:** Shift in the frequency of the transmitted signal. Shows up when we have a wireless channel and fast moving objects.
7. **Frequency-reuse interference:** Shows up in wireless systems when we re-use the same frequencies at multiple nearby locations to increase system capacity.
8. **Chromatic Dispersion:** Specific to optical fiber channels.

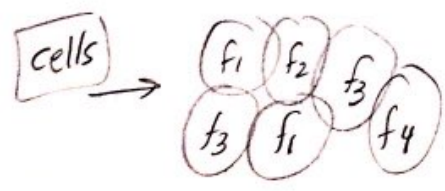
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- examples**
- ① cellular
 - ② WiFi
 - ③ Wimax
 - ④ Satellite
- any wireless thing problems in cellular*

- examples**
- ① cellular
 - ② satellite
 - ③ airplane comm
- wireless and moving*

Frequency-reuse-interference

cellular $f_1 f_2 f_3 f_4$



* what is the effect of channel impairments?!

they are working against sending information.

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Shannon's Limit

$$C = B_{ch} \times \log_2(1 + \frac{SNR}{})$$

↳ lecture 8

- **C**: Capacity of the channel in bits/second (bps)
- B_{ch} : Channel bandwidth (units of Hz)
- SNR: Signal-to-Noise Ratio (unitless)(not dB)
 - = $\frac{\text{signal power (watt)}}{\text{noise power (watt)}}$

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Bandwidth of the channel limits the capacity of the channel

noise ↑ SNR ↓ C ↓
 signal power ↓ ↓ ↓

* Be careful to substitute signal power and noise power unitless

Not in dB

ex → 1000 unitless ≡ 30 dB

⊛ \log_2 Not \log_{10} *

$$30 \text{ dB} = 10 \log_{10}(1000)$$

How to use \log_2

$$\log_2(x) = \log_2(10) \log_{10}(x)$$

بفضل آلة الحاسبة

calculator بالإنجليزية

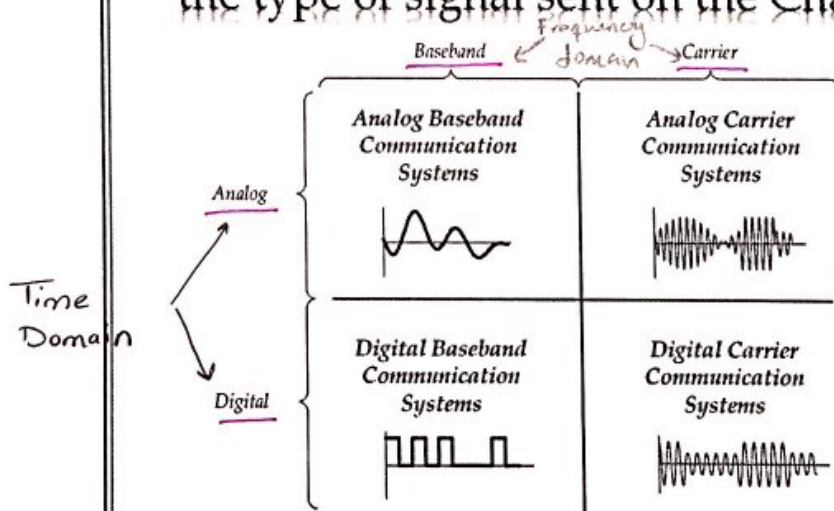
$$\approx 3.322 \log_{10}(x)$$

Lecture 2: Classification of Communication Systems

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EE421: Communications I

Comm Systems are classified based on the type of signal sent on the Channel



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Each system has its advantages!

Analog Baseband

- Simplest system to build
- Inexpensive

Analog Carrier

- Allows use of Antennas
- Allows Multiplexing (FDM)
- Allows exchanging SNR for Bandwidth

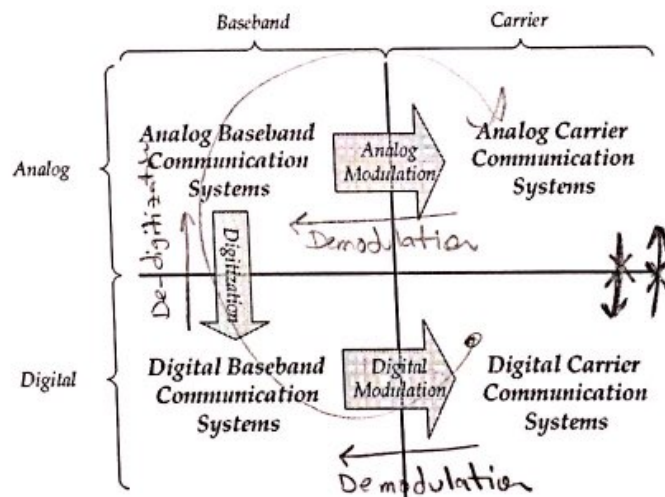
Digital Baseband

- Immunity to Noise
- Allows Multiplexing at baseband level (TDM)
- More bandwidth efficient
- Allows exchanging SNR for Bandwidth
- For more, see Handout

Digital Carrier

- Allows use of Antennas
- Allows Multiplexing (FDM)
- Allows exchanging SNR for Bandwidth
- Also the advantages of digital baseband

Modulation and Digitization



$m(t) \rightarrow t\text{-domain} \rightarrow \text{analog vs Digital}$

$\mathcal{F}\{m(t)\} = M(\omega) \rightarrow f\text{-domain} \rightarrow \text{Baseband vs carrier}$

$t\text{-domain} \rightarrow \text{periodic vs aperiodic}$
or
 $f\text{-domain}$

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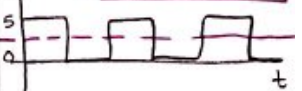
Analog Baseband Systems

- **Analog:** $m(t)$ can assume any value in a continuous range of values at any point in time t .
- **Digital:** $m(t)$ can assume only finite voltages or shapes and uses threshold detection.
- **Baseband:** $m(t)$ has a frequency-domain spectrum clustered around zero frequency (the base).

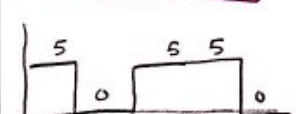
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It doesn't come from nature, you create it

ex $m(t) = \text{digital and periodic}$



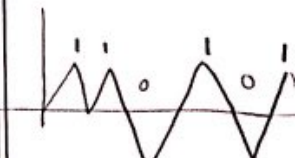
ex $m(t) = \text{digital and aperiodic}$



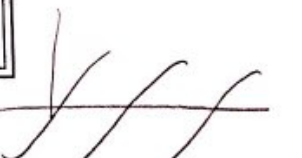
$m(t) = \text{Analog and periodic}$



$m(t) = \text{Digital and aperiodic}$



$m(t) = \text{analog and periodic}$



Examples: Audio

→ **Baseband.** Its very close to 0 Hz (voice come from nature, things come from nature called baseband)

→ **Analog**

→ **Aperiodic**

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$|M(\omega)|$



Carrier \rightarrow Far away from zero

$|M(\omega)|$

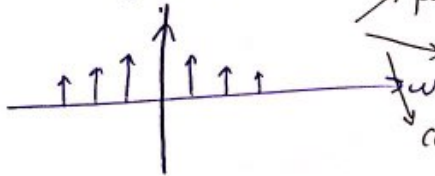


Baseband

\rightarrow Find Fourier Inverse $\mathcal{F}^{-1}\{M(\omega)\} = m(t)$ to decide if it's analog or digital

\rightarrow aperiodic (smooth curve but not sum of cosines)

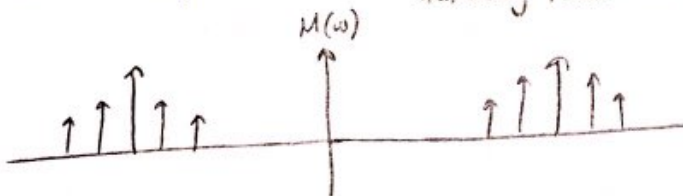
$|M(\omega)|$



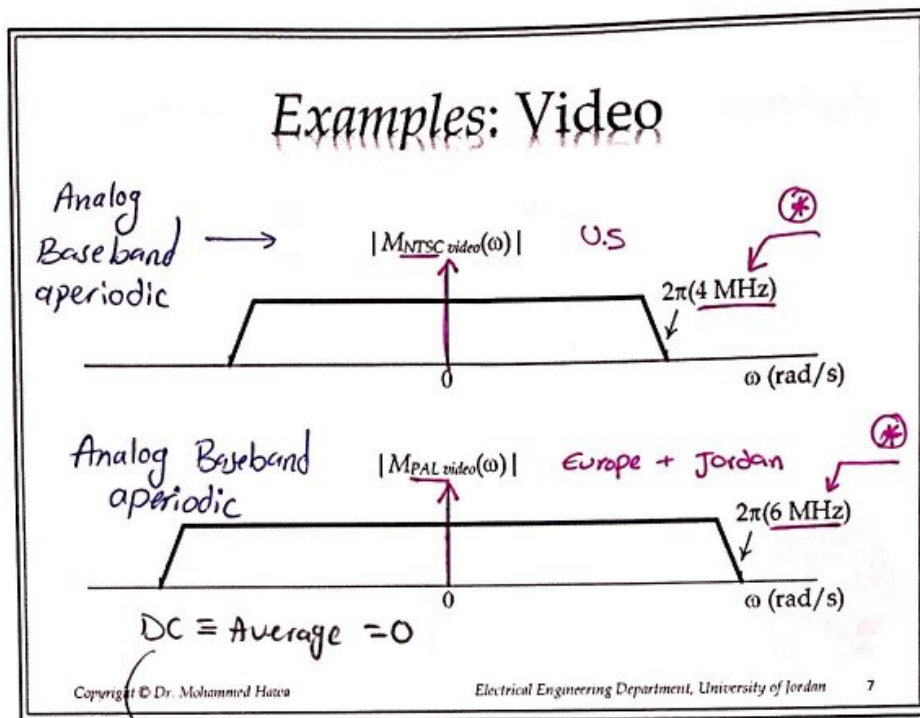
\rightarrow periodic (sum of cosines)
 \rightarrow Baseband (around zero)

cannot decide if it's analog or digital only if we find $\mathcal{F}^{-1}\{M(\omega)\}$

* Show an example of carrier and periodic signal & -
 Far away from zero \rightarrow impulses Not smooth curves



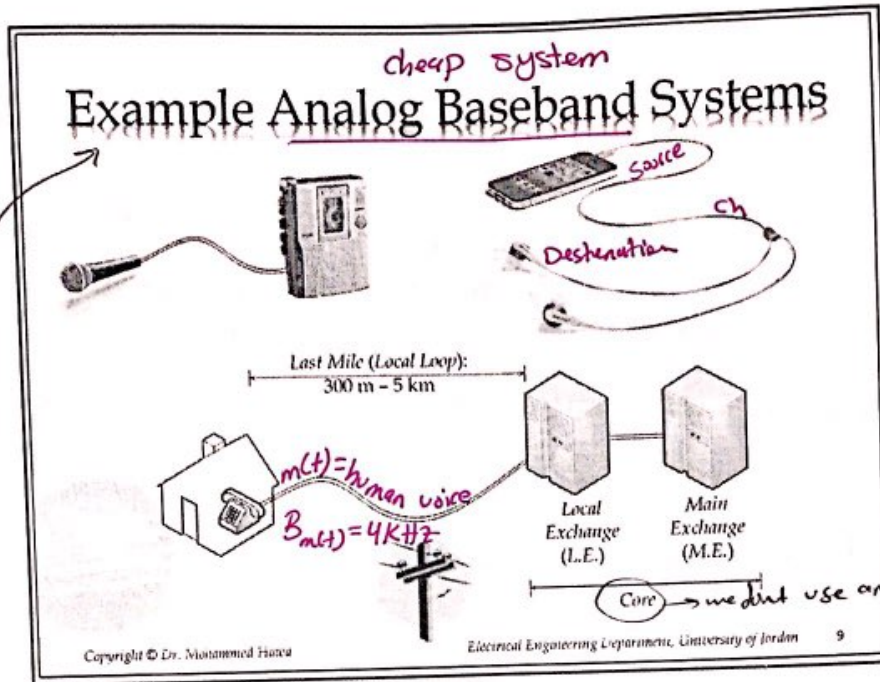
$$\begin{aligned} x(t) &= \sum \text{cosines} \\ \mathcal{F}\{x(t)\} &= \mathcal{F}\{\sum \text{cosines}\} \\ &= \sum \mathcal{F}\{\text{cosine}\} \\ &= \text{impulses} \end{aligned}$$



The impulse at 0 \rightarrow and there is no impulse, so DC = 0

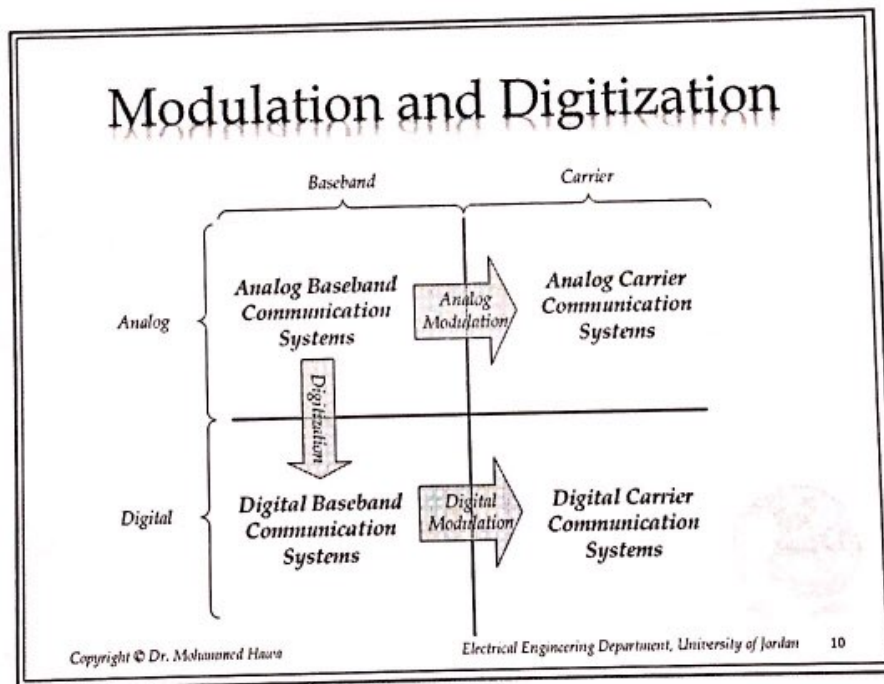
Analog Baseband Systems

- An analog baseband system sends the analog baseband signal $m(t)$ as is (without any modifications).
- Advantages:
 - Simplest possible system.
 - Inexpensive to build.
- Usually used for short-distance communications.
- Examples of such systems in the next slide.



PSTN
POTS

we don't use analog baseband in the core
(because it's a long distance)
(a lot of noise, a lot of attenuation)





1/28/2018

Modulation

- In modulation, the signal $m(t)$ is combined with a high-frequency signal called the carrier.
- Hence, frequencies are shifted.

$m(t)$: Baseband

$F\{m(t)\} = M(\omega)$

carrier

$c(t) = \cos(\omega_c t)$

Baseband aperiodic

carrier aperiodic

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- FDM**: frequency division multiplexing
- TDM**: Time division multiplexing
- CDMA**: code division multiple access
- OFDMA**: orthogonal frequency

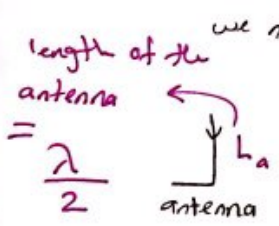
Analog and Digital Carrier Systems

- Modulation (i.e., analog and digital carrier systems) advantages:
 - Allows the use of reasonable antenna lengths.
 - Allows Multiplexing (FDM). As well as CDMA and OFDMA in digital systems.
 - Allows exchanging SNR for Bandwidth.

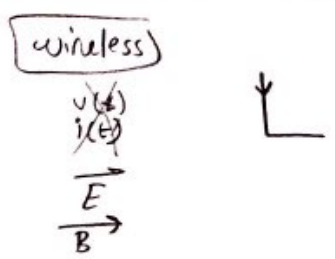
ability to send multiple signals simultaneously in the same channel.

FDM

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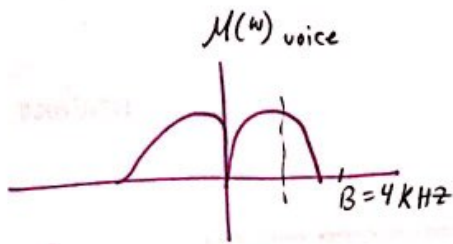


we need to convert voltage and current to \vec{E} and \vec{B}



$L_a = \frac{\lambda}{2}$ → wavelength of signal

$\lambda = \frac{c}{f} = \frac{\text{speed of light}}{\text{freq. of signal}} = \frac{3 \times 10^8 \text{ m/s}}{f \text{ Hz}}$



$$L_a = \frac{\lambda}{2}$$

$$\lambda_{\text{voice}} = \frac{c}{f} = \frac{3 \times 10^8}{3 \times 10^3}$$

$$= 1 \times 10^5 = 100 \text{ km}$$

$$L_a = \frac{100 \text{ km}}{2} = 50 \text{ km} \rightarrow \text{this is Not Practical .}$$

Because of that we cannot send baseband by wireless.

$$\text{wifi} \rightarrow f = 2.4 \text{ GHz} \approx 3 \text{ GHz}$$

$$\lambda_{\text{wifi}} = \frac{c}{f} = \frac{3 \times 10^8}{3 \times 10^9} = 1 \times 10^{-1} = 10 \text{ cm}$$

$$L_a = \frac{\lambda}{2} = 5 \text{ cm} \quad \checkmark \quad \text{Practical}$$

Practical system uses modulation \rightarrow wireless
 wifi
 Radio
 Multiplexing

Example Carrier Systems

Amplitude modulator ←

↑ Frequency modulation

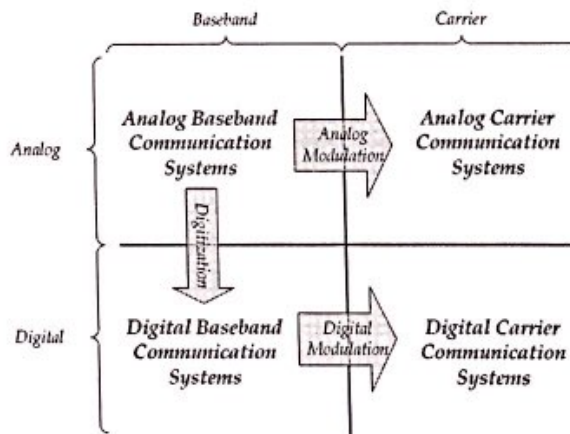
- Examples of analog carrier systems:
 - AM and FM radio broadcasting. *US Europe*
 - Analog TV broadcasting (NTSC and PAL).
- Examples of digital carrier systems:
 - Digital radio broadcasting (DAB). *Digital Audio Broadcasting*
 - Digital TV broadcasting (DVB-S, DVB-T, ATSC). *Handover K (Appreciation)*
 - WiMAX metropolitan area network. *Digital video Broadcasting*
 - Wi-Fi wireless local area network.
 - Cellular Telephony (2nd, 3rd and 4th generations).
 - Bluetooth, Zigbee and NFC
 - Old dial-up modems.
 - ADSL modems.

Why we need modulation while its not wireless?

← copper wires

→ multiplexing
(we need it to use the internet)
also to make a phone call

Modulation and Digitization



Digitization

- To convert the analog baseband signal into a digital baseband signal :

- ◀ Sampling.
- ◀ Quantization.
- ◀ Mapping.
- ◀ Encoding (coding).
- ◀ Pulse Shaping.

- Digital baseband Advantages:

- Immunity to Noise. (threshold detection, regenerators, FEC ---)
- Allows Multiplexing at baseband level (TDM).

- Immunity to Attenuation

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- Allows Multiplexing at carrier level (CDMA and OFDMA)

Example Digital Baseband Systems

- Digital baseband Advantages (Continue):
 - More bandwidth efficient (compression and line coding).
 - Allows exchanging SNR for Bandwidth at the baseband level.
 - For more, see Handout.

- Examples of digital baseband systems:

- Serial (RS-232) and USB port connections.

- Ethernet (a popular local area network).

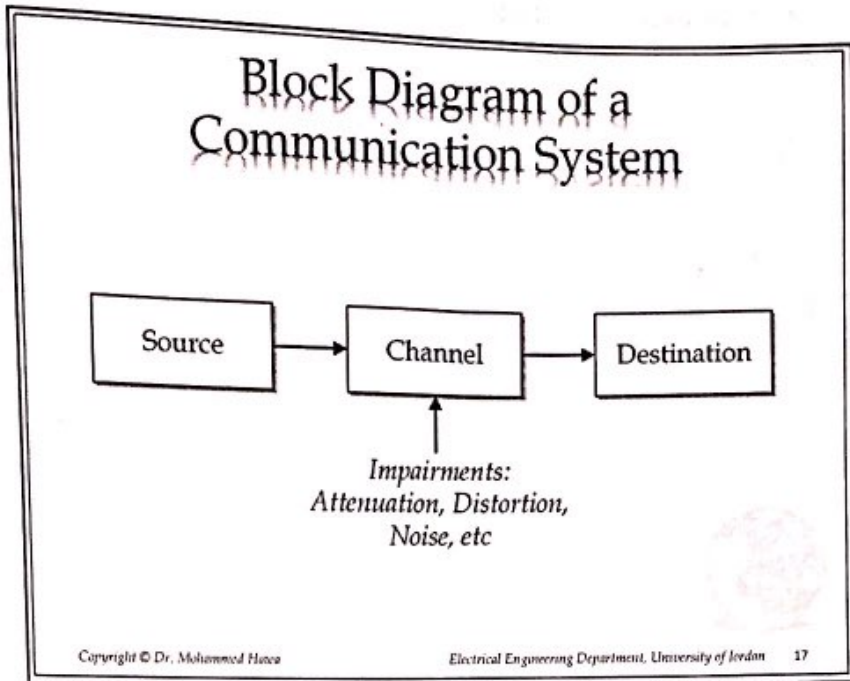
to connect computers to each others
 - Telephony (between local exchanges), such as the T-1, T-2, ..., E1, E2, ... etc PDH carriers.

→ Universal Serial Bus

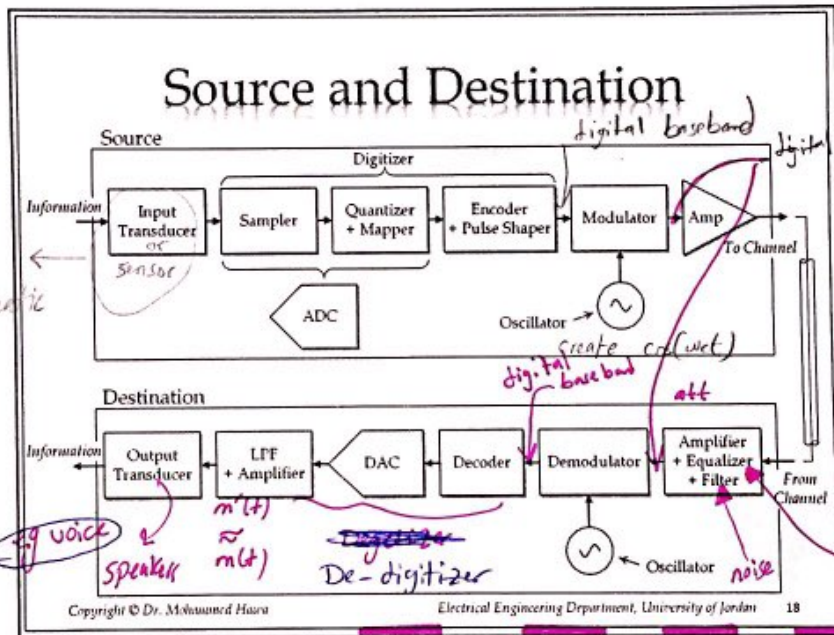
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ex
Microphone
convert voice
into electromagnetic
system



digital
baseband
block
diagram

analog
Baseband
- cheap
- simple to build

distortion
(linear and non-linear)

Lecture 3: Review of Signal Analysis Basics

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EE427: Communications I

Exponential/Trigonometric/Compact

$$x(t) = \sum_{n=-\infty}^{\infty} \alpha_n \cdot e^{jn\omega_0 t}, \quad \omega_0 = \frac{2\pi}{T}$$

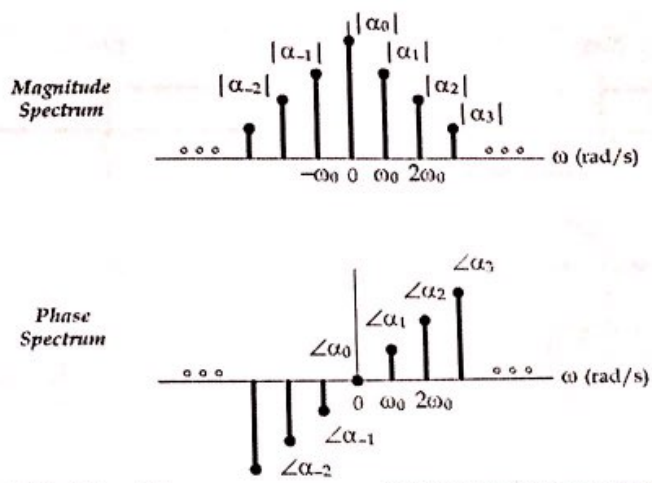
$$x(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} (a_n \cos(n\omega_0 t) + b_n \sin(n\omega_0 t)), \quad \omega_0 = \frac{2\pi}{T}$$

$$x(t) = \frac{c_0}{2} + \sum_{n=1}^{\infty} c_n \cos(n\omega_0 t - \theta_n), \quad \omega_0 = \frac{2\pi}{T}$$

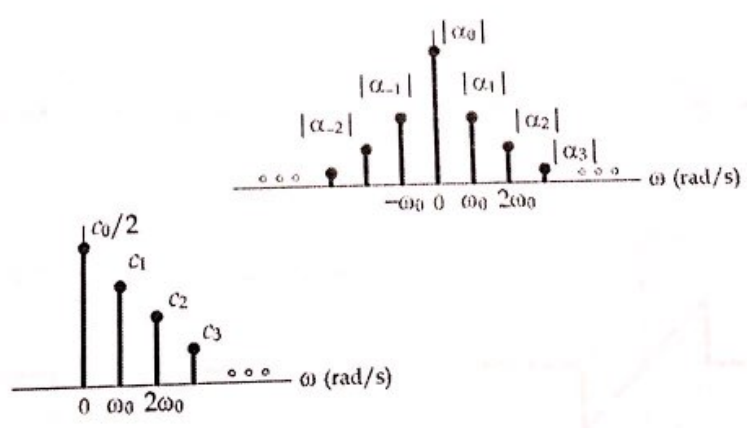
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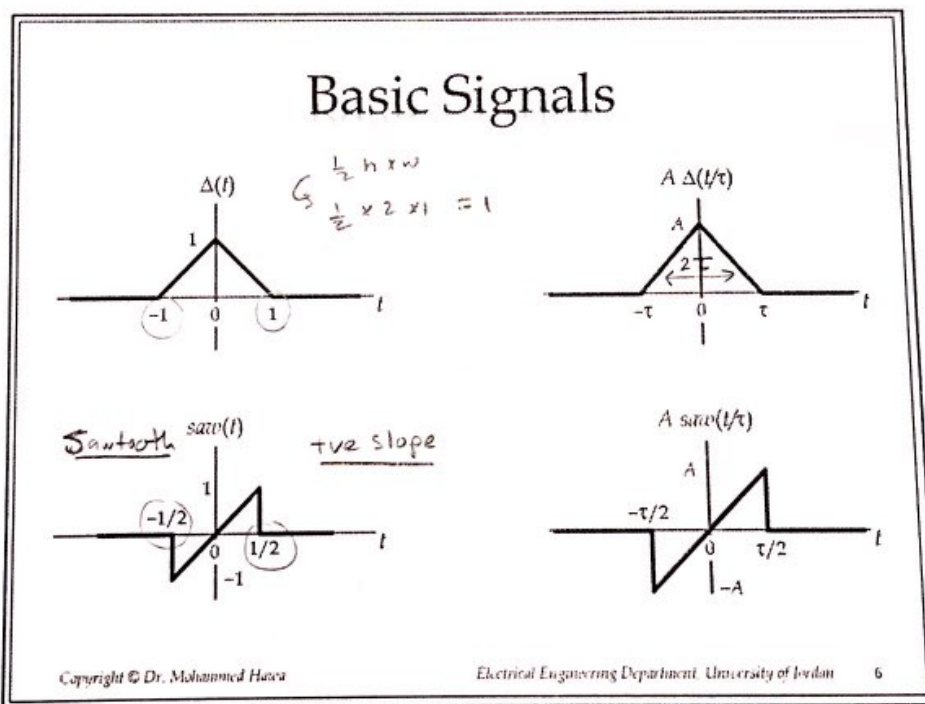
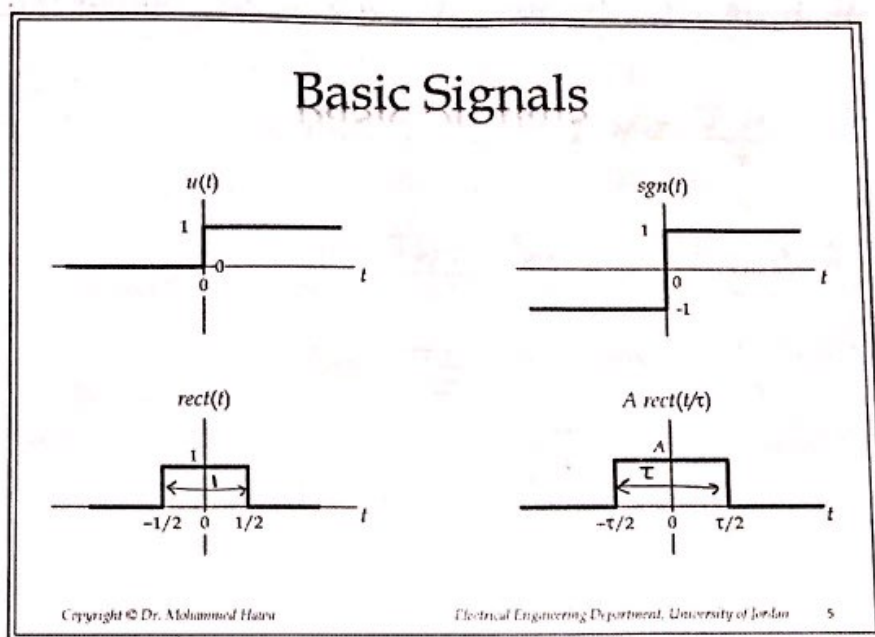
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Exponential Fourier Series

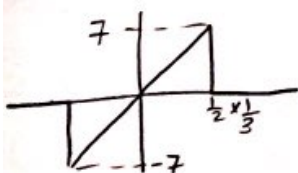


Single-Sided vs. Double-Sided





7 saw (3t)

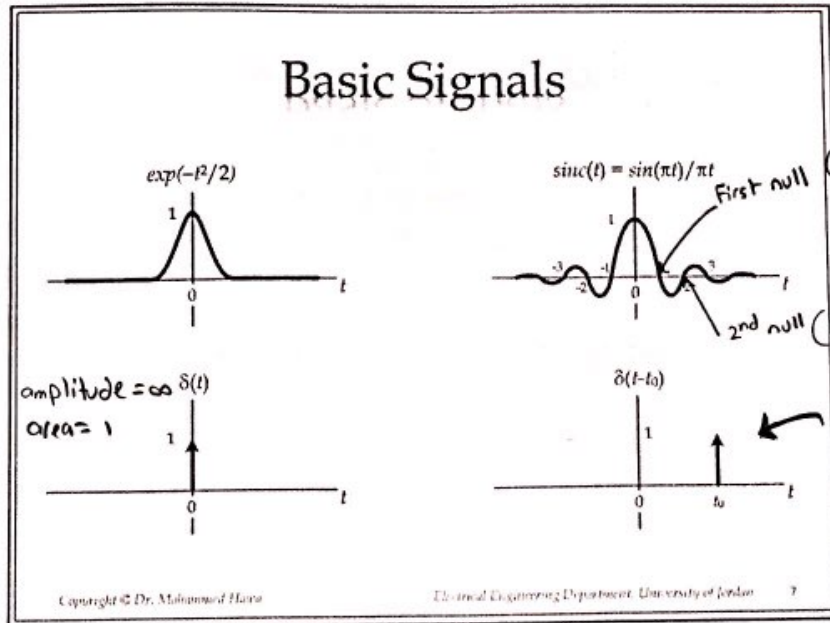


$$\text{sinc}(T) = \frac{\sin \pi T}{\pi T}$$

$$\text{sinc}(t) = \frac{\sin t}{t}$$

$$8 \delta(t)$$

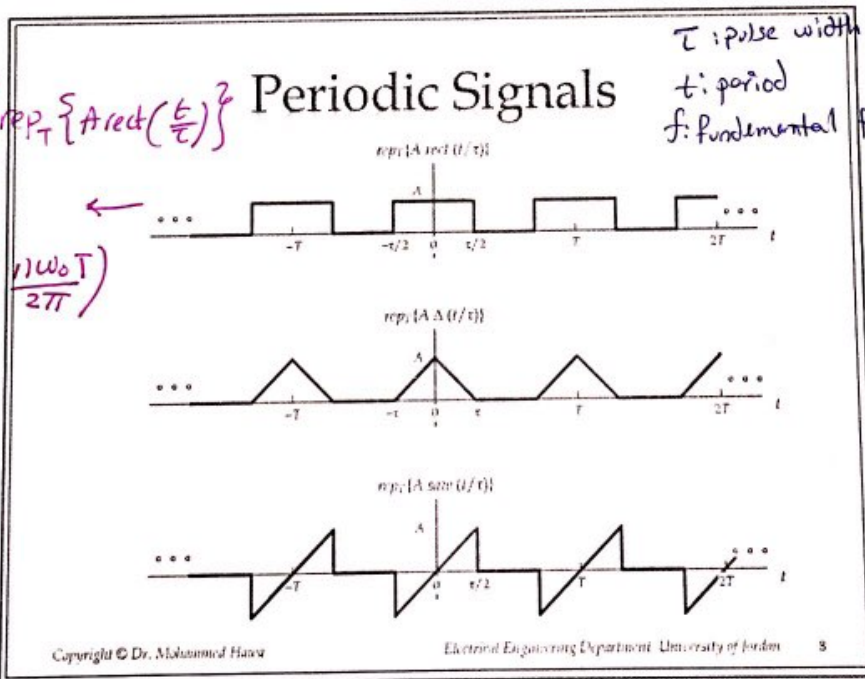
↑
8



$$F_{\text{series}} \{x(t)\} = F_{\text{series}} \left\{ A \text{rect}\left(\frac{t}{\tau}\right) \right\}$$

↓

$$a_n = \frac{A\tau}{T} \text{sinc}\left(\frac{n\omega_0 T}{2\pi}\right)$$



ex) Find the bandwidth of $x(t) = \text{rept}_T \{A \text{rect}(\frac{t}{T})\}$

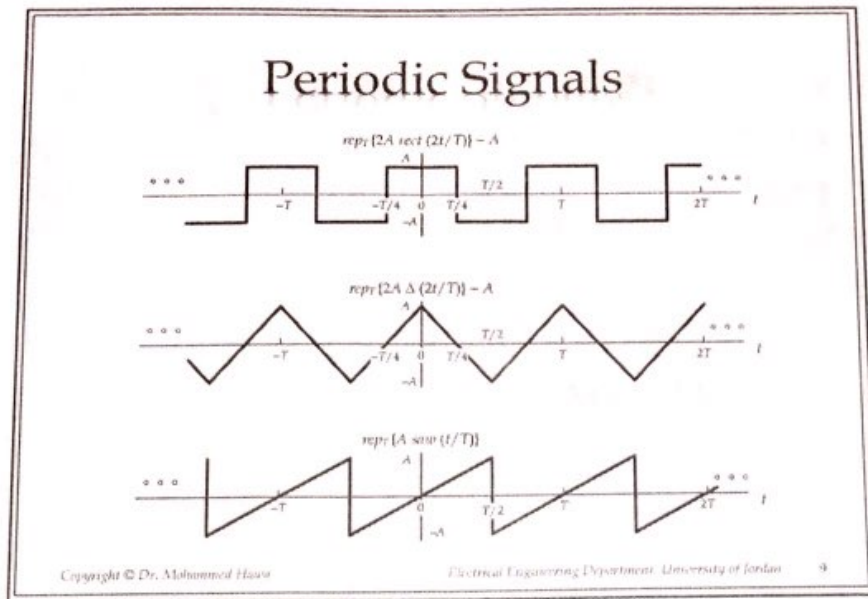
$$\alpha_n = \frac{A T}{T} \text{sinc}\left(\frac{n \omega_0 T}{2\pi}\right) = 1$$

to get first null, you need $\frac{n \omega_0 T}{2\pi} = 1$

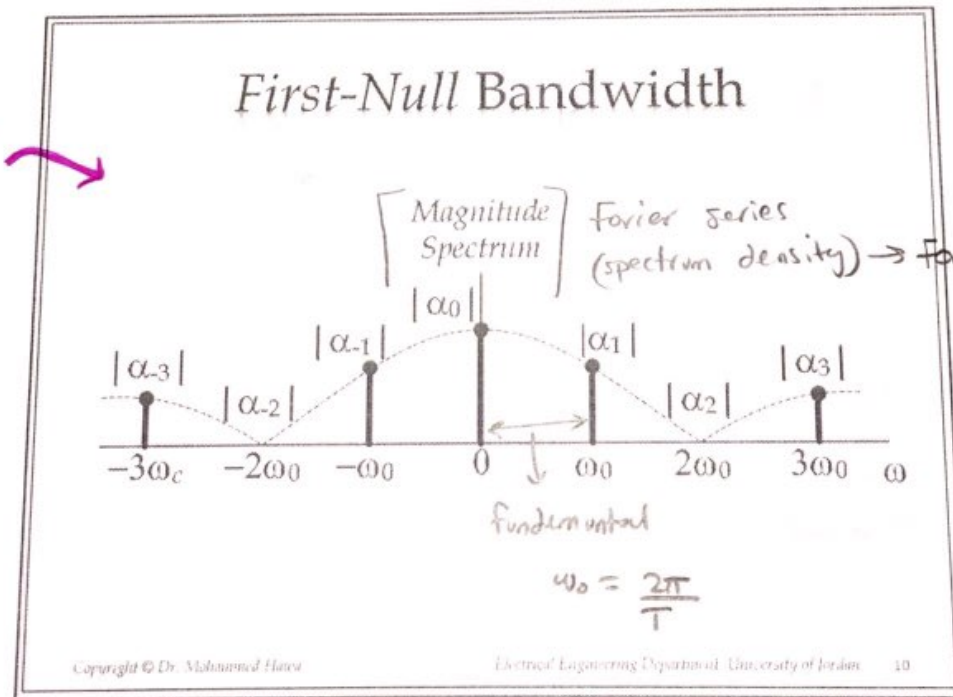
So, the frequency = $n \omega_0 = \frac{2\pi}{T} \frac{\text{rad}}{\text{s}}$

$$\text{or } B = \frac{1}{T} \text{ Hz}$$

$$n f_0 = \frac{1}{T}$$



In this example bandwidth is $2\omega_0$



* IF Fourier series / transform has $\text{sinc}(\cdot)$ or $\text{sinc}^2(\cdot)$ or $\text{sinc}^3(\cdot)$ or $\text{sinc}^n(\cdot)$, then bandwidth of signal is 1st null frequency.

- ① $F\{\cos(\omega_0 t)\} = \pi \delta(\omega - \omega_0) + \pi \delta(\omega + \omega_0)$
- ② $F\{\sin(\omega_0 t)\} = -j\pi \delta(\omega - \omega_0) + j\pi \delta(\omega + \omega_0)$
- ③ $F\{\delta(t)\} = 1$
- ④ $F\{\text{rect}(t)\} = \text{sinc}\left(\frac{\omega}{2\pi}\right)$
- ⑤ $F\{\Delta(t)\} = \text{sinc}^2\left(\frac{\omega}{2\pi}\right)$

works for both
 - periodic (and looks like fourier series)
 - Aperiodic

Fourier Transform

$$X(\omega) = \mathcal{F}\{x(t)\} = \int_{-\infty}^{\infty} x(t)e^{-j\omega t} dt$$

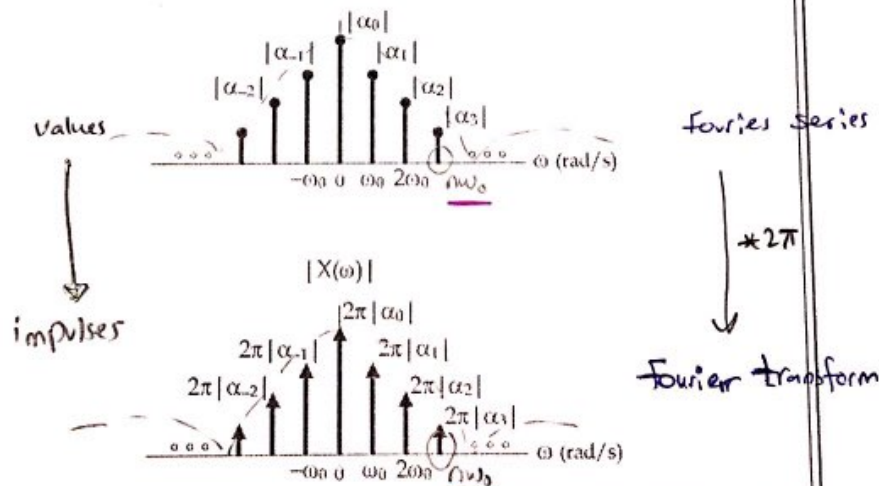
$$x(t) = \mathcal{F}^{-1}\{X(\omega)\} = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega)e^{j\omega t} d\omega$$

* $F\{A \text{ rect}\left(\frac{t}{T}\right)\} = A|T| \text{sinc}\left(\frac{\omega T}{2\pi}\right)$

* $F\{A \text{ rect}(t)\} = A \text{sinc}\left(\frac{\omega}{2\pi}\right)$

* $F\{x(t) + y(t)\} = X(\omega) + Y(\omega)$
 superposition

Fourier Series vs. Transform

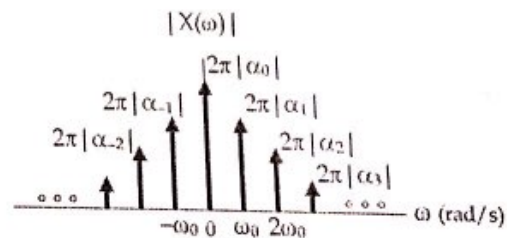
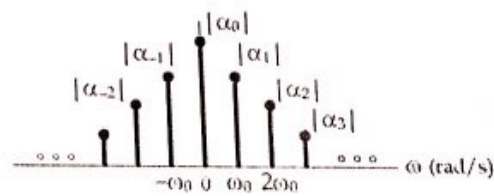


Fourier Transform

$$X(\omega) = \mathcal{F}\{x(t)\} = \int_{-\infty}^{\infty} x(t)e^{-j\omega t} dt$$

$$x(t) = \mathcal{F}^{-1}\{X(\omega)\} = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega)e^{j\omega t} d\omega$$

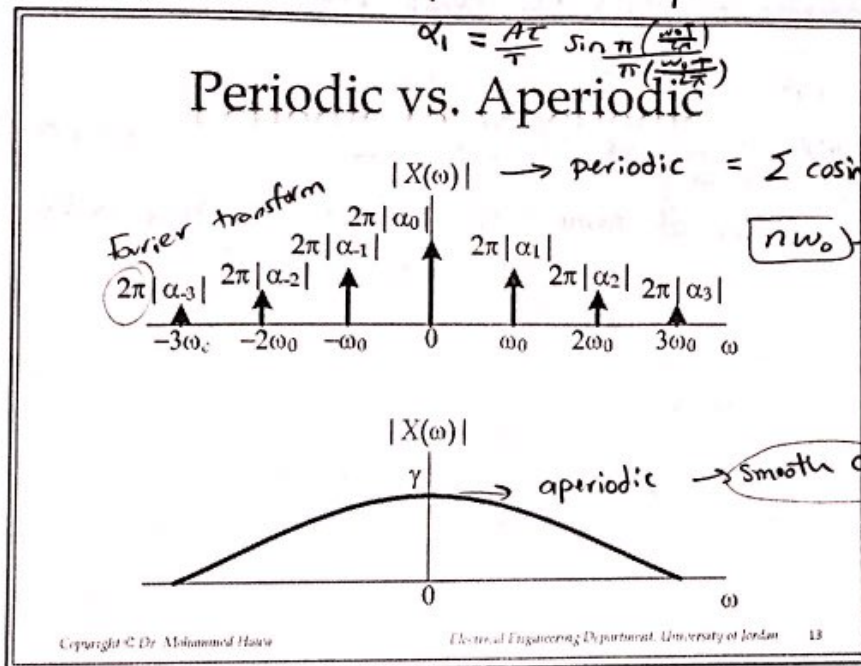
Fourier Series vs. Transform



Fourier series $\{x(t)\} = \{rep_T \{A \text{ rect}(\frac{t}{T})\}$

9/8/2018

$$\rightarrow \alpha_n = \frac{AT}{T} \text{sinc}\left(\frac{n\omega_0 T}{2\pi}\right) \rightarrow \alpha_0 = \frac{AT}{T} \text{sinc}\left(\frac{0 \times \omega_0 T}{2\pi}\right) = \frac{AT}{T}$$



DC vs. Average Power

The DC value or average value of the signal $x(t)$ is:

$$DC = \overline{x(t)} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} x(t) dt \rightarrow \text{Average of the signal}$$

$$DC = \overline{x(t)} = \alpha_0$$

The average power in the signal $x(t)$ is:

$$P_x = \overline{x^2(t)} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} |x(t)|^2 dt \rightarrow \text{average of the } (\text{signal})^2 \text{ power}$$

$$P_x = \overline{x^2(t)} = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_x(\omega) d\omega \text{ power spectral density.}$$

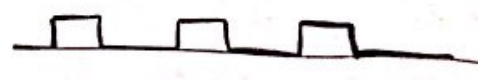
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* For power consider both negative and positive freq.

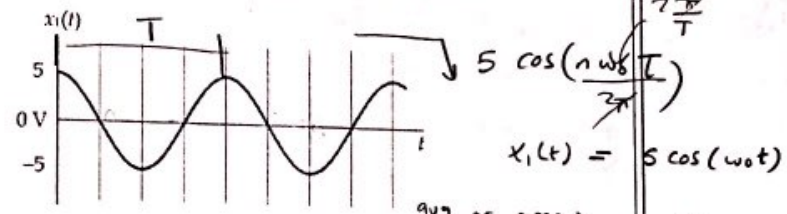
Ex: $x(t) = \text{rep}_T \left\{ A \text{ rect} \left(\frac{t}{T} \right) \right\}$

Area $\rightarrow \overline{x(t)} = \frac{AT}{T}$
 $\overline{x^2(t)} = \frac{A^2 T}{T}$



9/8/2018

DC vs. Average Power



$x_1(t) = 5 \cos(\omega_0 t)$
 avg or mean:
 $x_1(t) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} x(t) dt = 0$

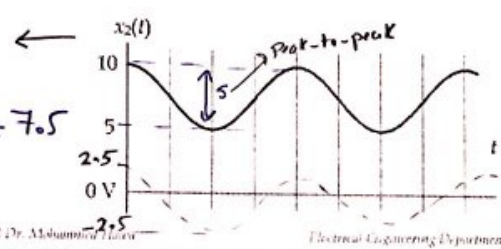
avg power for $x_2(t)$:-
 $= \frac{S^2}{2}$

$x_2(t) = 2.5 \cos(\omega_0 t) + 7.5$

$\overline{x_2(t)} = 0 + 7.5 = 7.5$

they are orthogonal

$\overline{x_2^2(t)} = \frac{(2.5)^2}{2} + 7.5^2$

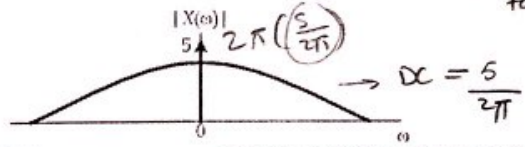
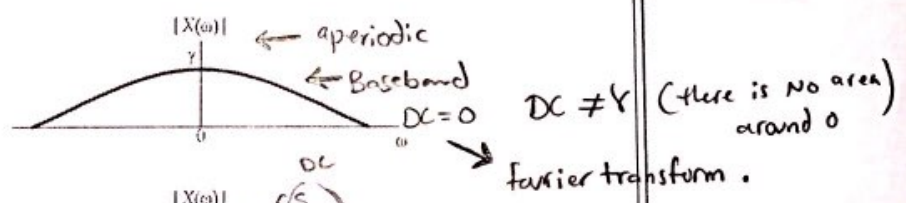
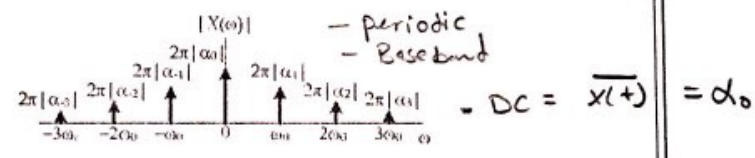


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Ex: ~~$x(t) = \text{rep}_T \left\{ A \text{ rect} \left(\frac{t}{T} \right) \right\}$~~

\rightarrow we **cannot** use superposition for power **except** if the signals are orthogonal.

DC from Frequency Domain



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* Examples of orthogonal signals :-

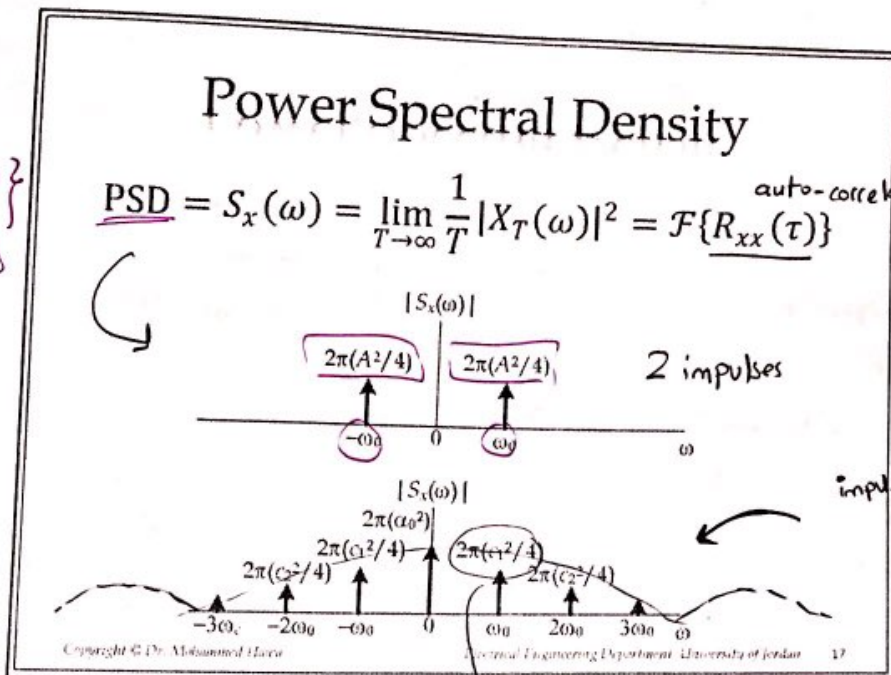
① DC + AC ex: $7.5 + 5\sin(\omega t)$

② multiple cosines (or sines) of different freq. $\rightarrow \cos(50t) + \cos(70t)$

③ cos and sin at same frequency but 90° phase shift
 $\cos(600t) + \sin(600t)$

$x(t) \rightarrow$ voltage
 $x^2(t) \rightarrow$ power

$F\{A \cos(\omega_0 t)\}$



Quick Review of Filters Devices Not signals

- There are four main filter types that you studied in signal analysis:
 - ① LPF: Low-Pass Filter
 - ② BPF: Band-Pass Filter
 - ③ HPF: High-Pass Filter
 - ④ Band-Stop Filter / Notch Filter.
- } very effective and cheap solutions for Noise

Find $R_{xx}(\tau)$ and then $S_x(\omega)$, then $P_{av} = \overline{x^2(t)}$ for:

① $x(t) = A \cos(\omega_0 t)$

② $x(t) = \text{rep}_T \left\{ A \text{rect}\left(\frac{t}{T}\right) \right\} \rightarrow \text{any periodic } x(t)$

↓ $P_{av} = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_x(\omega) d\omega$

$= \frac{1}{2\pi} \left(\cancel{2\pi \frac{A^2}{4}} + \cancel{2\pi \frac{A^2}{4}} \right) = \boxed{\frac{A^2}{2}}$

$\sum \cosines(n\omega_0 t)$

↪ orthogonal

$\overline{x^2(t)} = P_{av} = \frac{A^2 T}{T}$

Low-Pass Filter (LPF)

- Symbol:

high frequencies are rejected
(low freq. are passed)

frequency response function

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Frequency-response function \equiv Frequency Transfer function.

$$H(\omega) = \frac{V_o(\omega)}{V_i(\omega)}$$

$$V_o(\omega) = H(\omega) V_i(\omega)$$

$|H(\omega)|$

1 (or k)

- ω_1 0 ω_1 ω

$|V_o(\omega)| = |H(\omega)| \times |V_i(\omega)|$

$|V_i(\omega)|$

periodic signal (impulses)

Baseband

ω (rad/s)

0 $2\pi B$

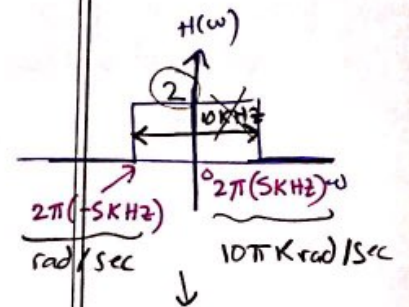
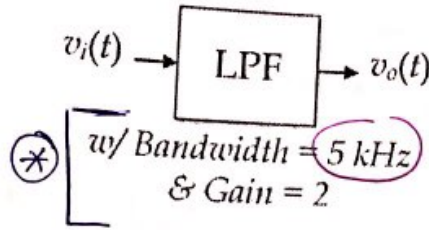
$2\pi B_{LPF}$

Bandwidth of the LPF

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Characteristics/Specifications

- Always centered at 0 rad/s.
- Bandwidth = Cut-off frequency = ω_1 rad/s
 - Gain = k.



The Bandwidth = 5kHz
Not 10kHz

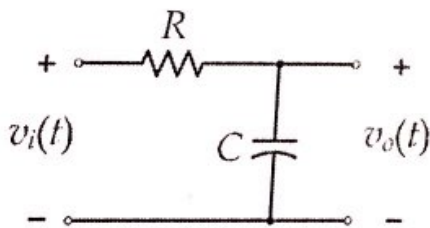
For Bandwidth calculations consider only positive freq.

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Example Circuit

* first order low pass filter *



low freq → C → open circuit
high freq → C → short C

$$B_{LPF} = \frac{1}{2\pi RC} \text{ Hz}$$

$$\text{Gain} = 1$$

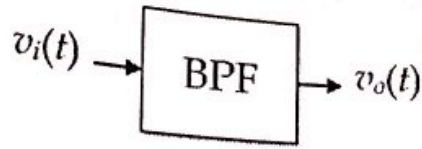
$$\frac{1}{RC} \rightarrow \text{Rad/s}$$

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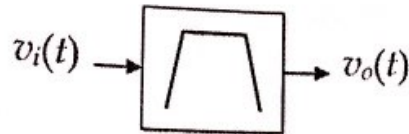
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Band-Pass Filter (BPF)

- Symbol:



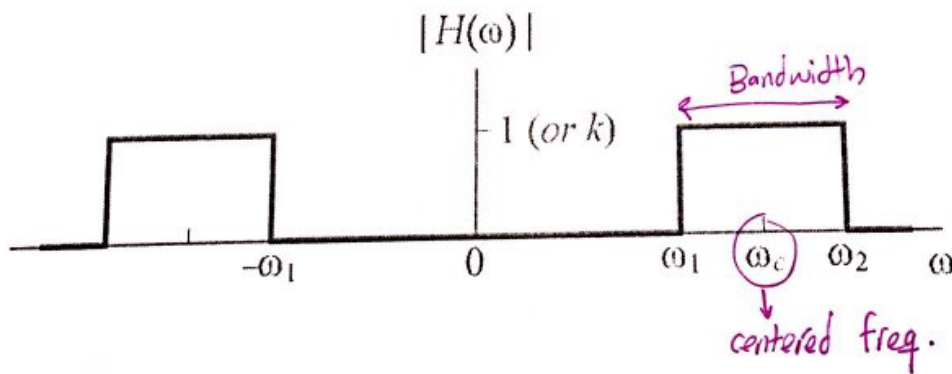
high and low freq. are rejected



Frequency-response function

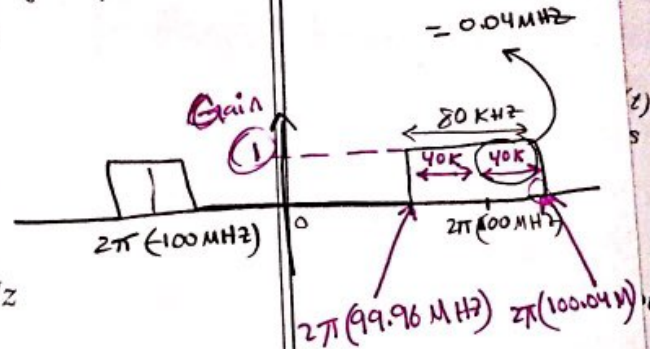
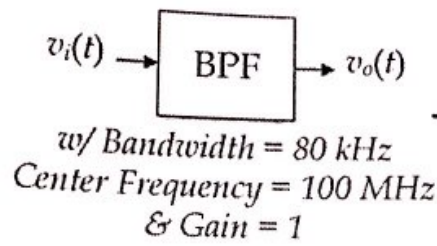
***Ideal BPF**

$$H(\omega) = \frac{V_o(\omega)}{V_i(\omega)}$$

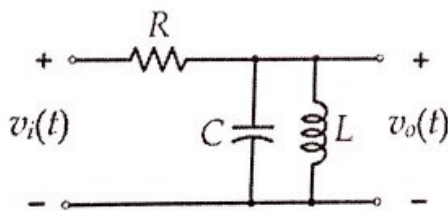


Characteristics/Specifications

- Centered around center frequency ω_c rad/s.
- Bandwidth of Filter = $\omega_2 - \omega_1$ rad/s
- Gain = k.



Example Circuit



centered freq. $f_c = f_{\text{resonant}} = \frac{1}{2\pi\sqrt{LC}} \text{ Hz}$
 $B_{\text{BPF}} = \Delta f = \frac{R}{2\pi L} \text{ Hz}$

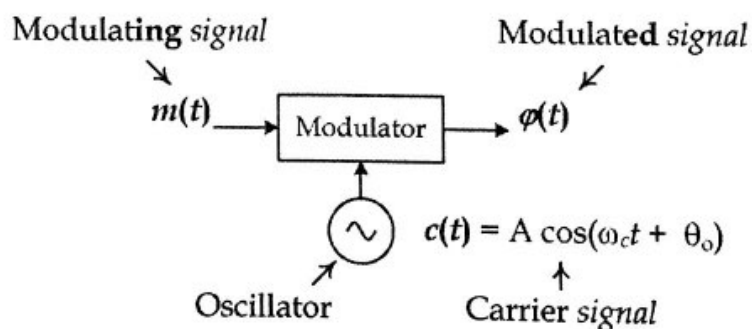
Gain = 1

Lecture 4: Amplitude Modulation (Double Sideband *Suppressed* Carrier, DSB-SC)

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EE-421 Communications I

Notation



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Three Modulation Types

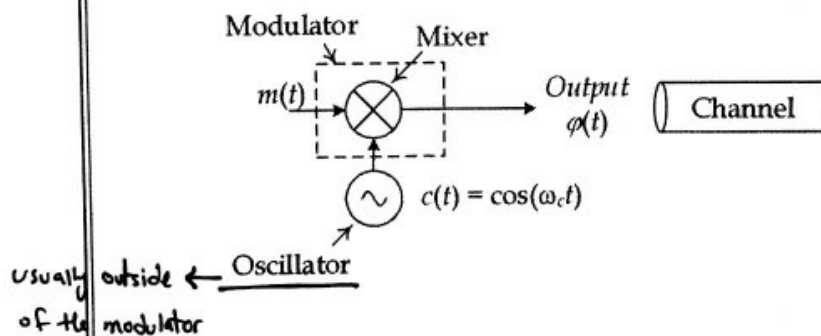
- $A \propto m(t)$; $\omega_c = \text{constant}$; $\theta_o = \text{constant}$
 - Amplitude Modulation (AM)
 - Amplitude Shift Keying (ASK)
- $A = \text{constant}$; $\omega_c \propto m(t)$; $\theta_o = \text{constant}$
 - Frequency Modulation (FM)
 - Frequency Shift Keying (FSK)
- $A = \text{constant}$; $\omega_c = \text{constant}$; $\theta_o \propto m(t)$
 - Phase Modulation (PM)
 - Phase Shift Keying (PSK)

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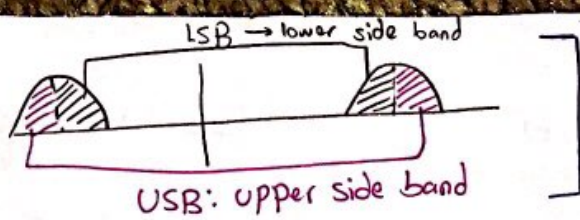
DSB-SC Modulator: Mixer

$$\phi_{\text{DSB-SC}}(t) = m(t) \cdot \cos(\omega_c t)$$



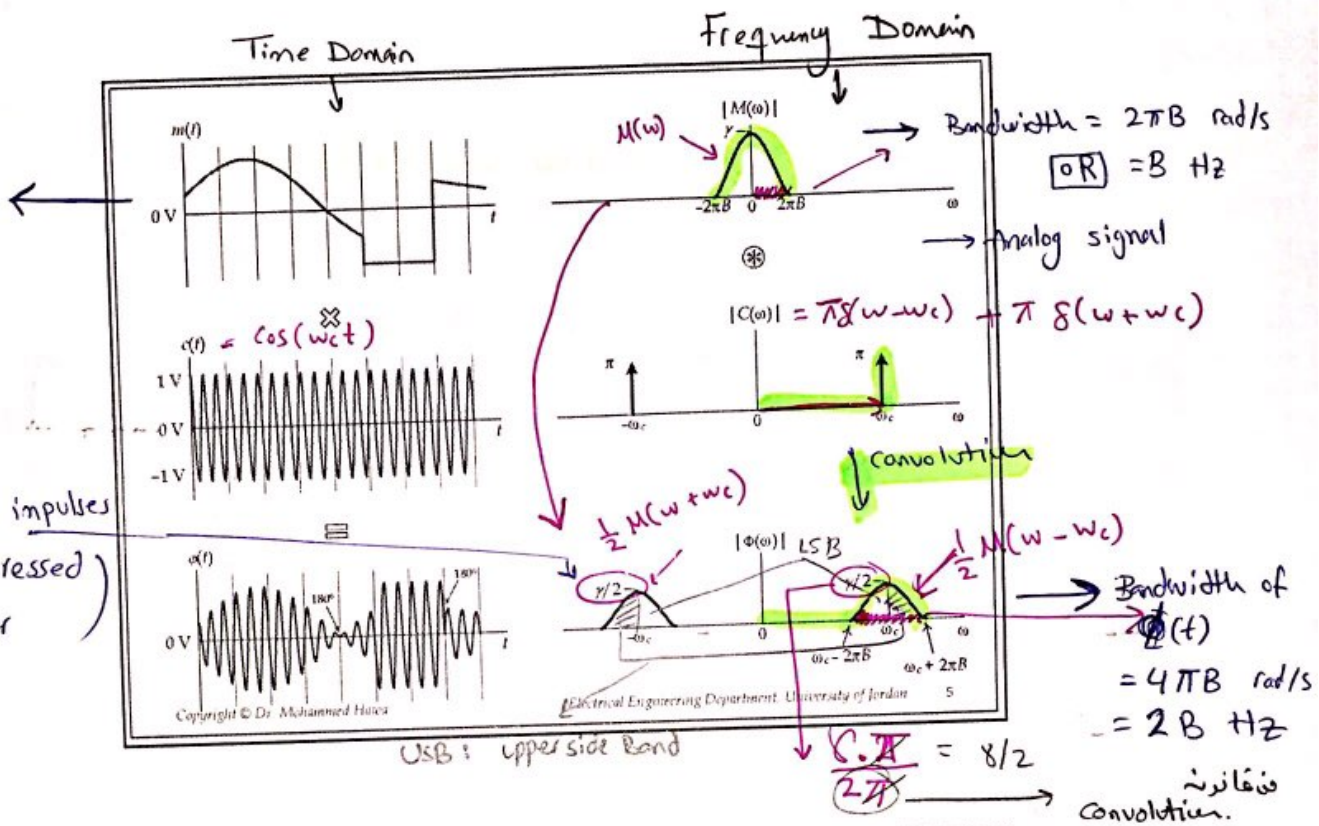
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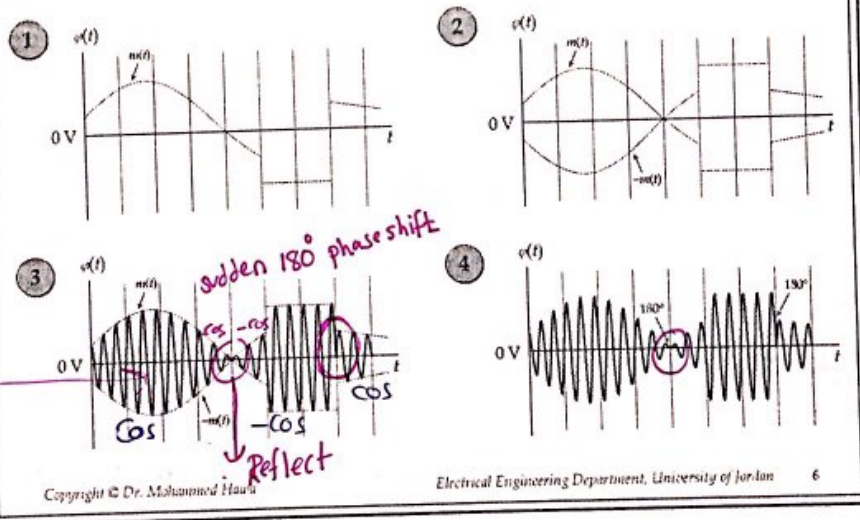


DSB : double side Band

9/8/2018



Drawing a DSB-SC modulated signal



\boxed{HW} rep { saw }

* In modulation, we require $\omega_c \gg 2\pi B$

slide 5

* For the first signal :-

Q1:- Find $\Phi(\omega)$
DSB-SC

Sol 1: math.

$$\Phi(\omega) = F \{ \phi(\omega) \}_{\text{DSB-SC}} = F \{ m(t) \cdot \cos(\omega_c t) \}$$

$$= F \left\{ m(t) \frac{e^{j\omega_c t} + e^{-j\omega_c t}}{2} \right\}$$

$$= F \left\{ \frac{1}{2} m(t) e^{j\omega_c t} + \frac{1}{2} m(t) e^{-j\omega_c t} \right\}$$

$$= F \left\{ \frac{1}{2} m(t) e^{j\omega_c t} \right\} + F \left\{ \frac{1}{2} m(t) e^{-j\omega_c t} \right\}$$

shift
↓

* There is shift in frequency domain

$$\Phi_{\text{DSB-SC}}(\omega) = \frac{1}{2} M(\omega - \omega_c) + \frac{1}{2} M(\omega + \omega_c)$$

Sol 2: Graphical sol

$$\Phi(\omega) = F \{ \phi(t) \} = F \{ m(t) \cdot c(t) \}$$

$$= \frac{1}{2\pi} M(\omega) * C(\omega) \quad (\text{convolution})$$

→ Conv(signal, δ) = same signal shifted by shift of impulse.
and scaled by area of impulse

Ex: * when multiplying by $c(t) = \cos(\omega_c t)$:-

① shift right by ω_c

② shift left by ω_c

③ multiply by $\frac{1}{2\pi} = \frac{1}{2}$

④ Bandwidth of $m(t)$ multiplied by 2 ($\times 2$) bandwidth of $\phi(t)$

⑤ Power of $m(t)$ ($\times \frac{1}{2}$) avg power in $\phi(t)$

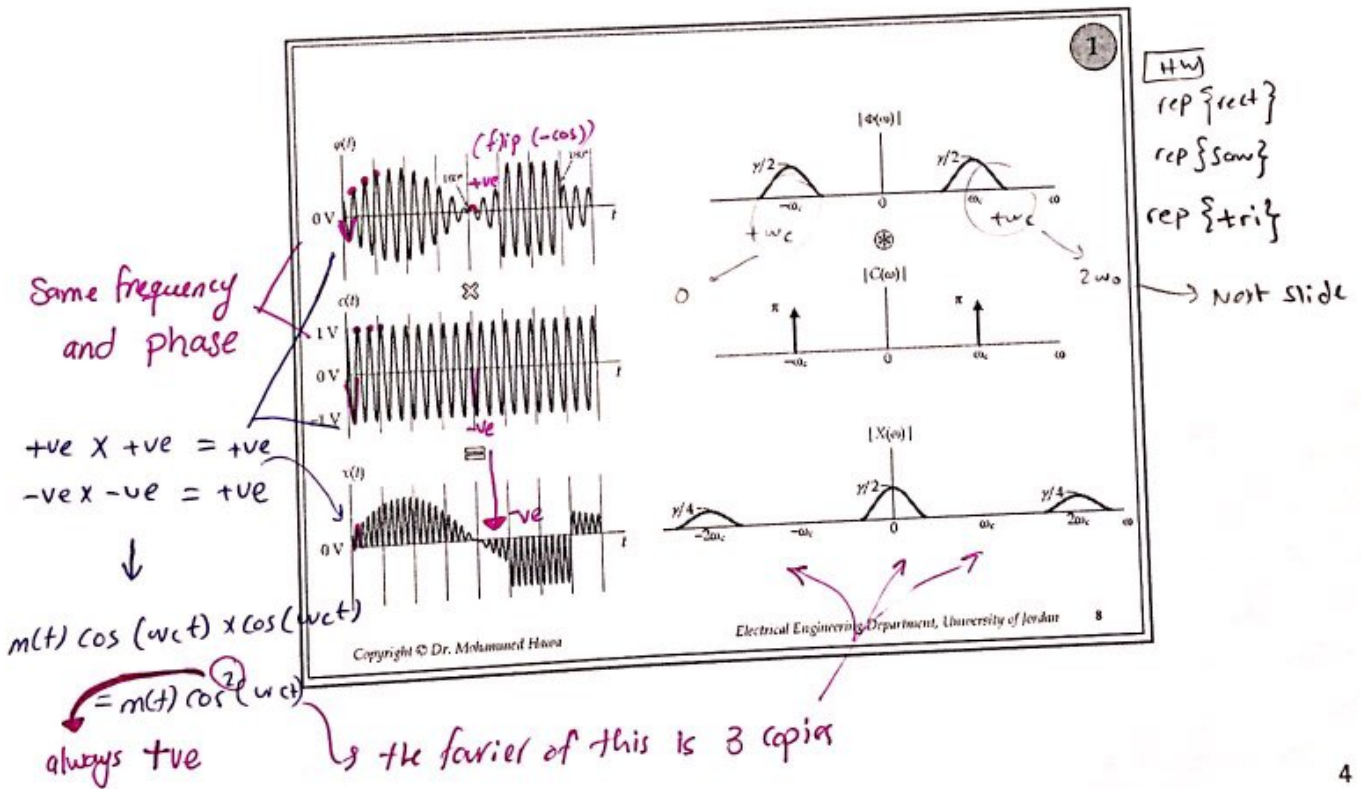
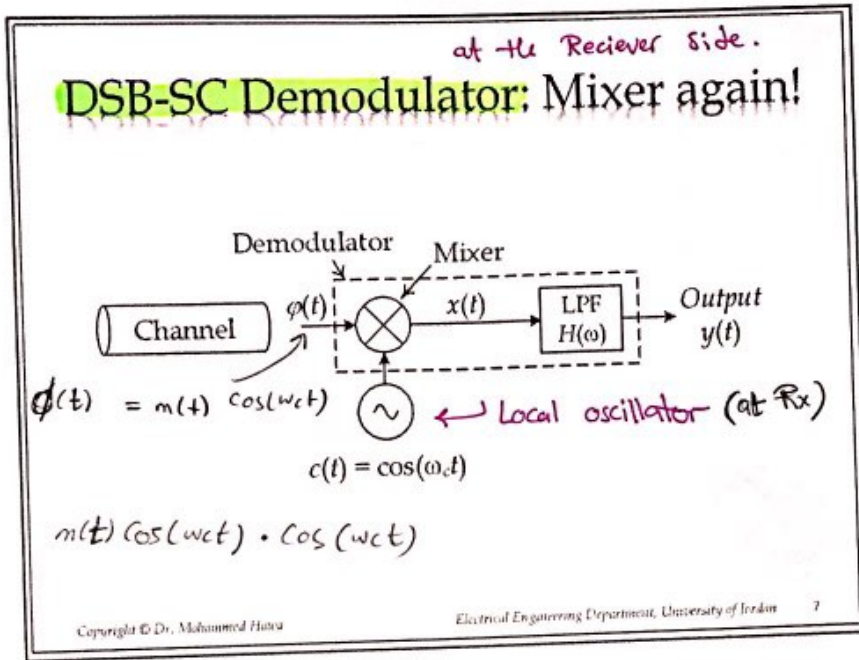
→ $\boxed{+w}$ Find P_{avg} in $m(t) = 2\cos(10t)$ → $P = \frac{(2)^2}{2} = 2$
 $\phi(t) = \frac{\cos(10t)}{m(t)} \cdot \frac{\cos(2000t)}{c(t)} \rightarrow \frac{1}{\sqrt{2}}$

$$\text{sol } ① \quad F\{x(t)\} = F\{\phi(t) \cdot c(t)\}$$

$$= \frac{1}{2\pi} \Phi(\omega) \otimes C(\omega) = X(\omega)$$

9/8/2018

← sol ②



slide 5

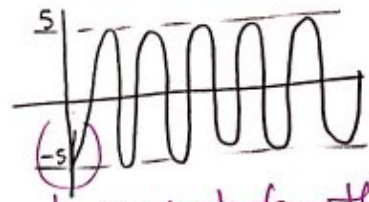
Q2: Sketch $\phi(t) = m(t) \cdot \cos(\omega_c t)$
DSB-SC

→ sketch $5 \cos(\omega t)$



↳ Remember to erase the guide lines.

$(-5 \cos(\omega t))$

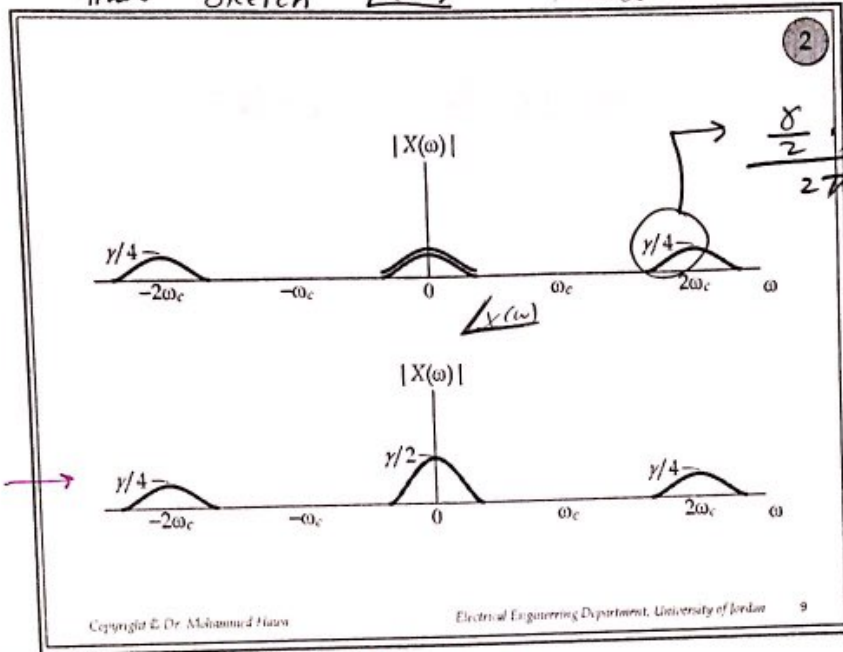


↳ It starts from the -ve

Sol ② :-

$$\begin{aligned} & F \{ \phi(t) \cdot c(t) \} \\ &= F \{ m(t) \cos(\omega_c t) \cos(\omega_c t) \} \\ &= F \{ m(t) \cos^2(\omega_c t) \} \\ &= F \left\{ m(t) \left\{ \frac{1}{2} + \frac{1}{2} \cos(2\omega_c t) \right\} \right\} \\ &= F \left\{ \frac{1}{2} m(t) \right\} + \frac{1}{2} F \left\{ m(t) \cos(2\omega_c t) \right\} + \frac{1}{2} F \left\{ m(t) \frac{e^{j2\omega_c t} + e^{-j2\omega_c t}}{2} \right\} \\ &= \frac{1}{2} F \{ m(t) \} + \frac{1}{4} F \left\{ m(t) e^{j2\omega_c t} \right\} + \frac{1}{4} F \left\{ m(t) e^{-j2\omega_c t} \right\} \\ &= \frac{1}{2} M(\omega) + \frac{1}{4} M(\omega - 2\omega_c) + \frac{1}{4} M(\omega + 2\omega_c) \end{aligned}$$

#(ω) - sketch $|X(ω)|$ f_w



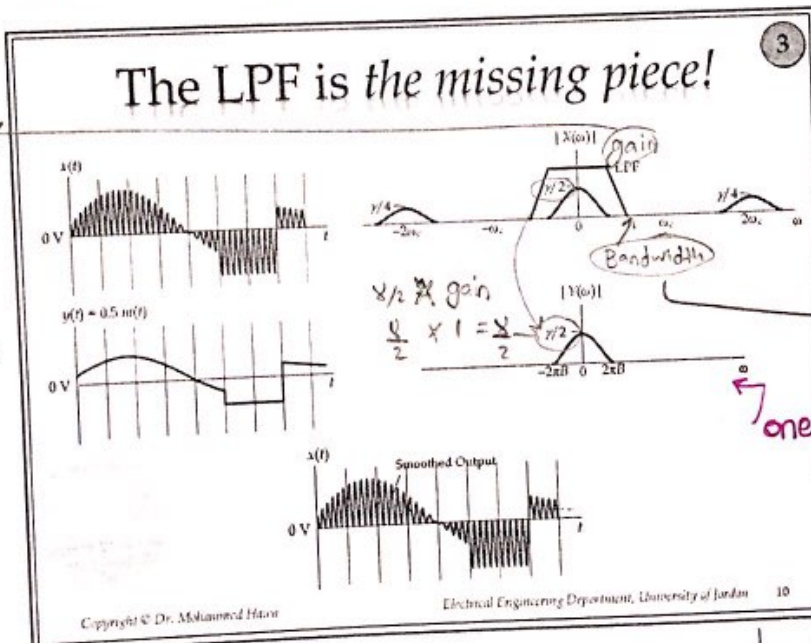
$$\frac{\frac{\gamma}{2}}{2} = \frac{\gamma}{4}$$

$$\frac{5/180}{5/30} = \frac{5/0}{5/30}$$

$$|X(\omega)| = \frac{1}{2}M(\omega) + \frac{1}{4}M(\omega - 2\omega_c) + \frac{1}{4}M(\omega + 2\omega_c)$$

The LPF is the missing piece!

we use gain = 1
the gain must be corresponded to the specifications

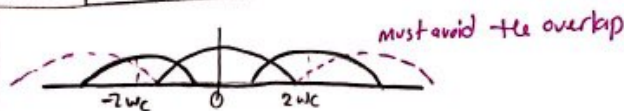
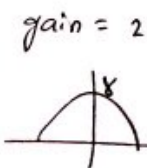
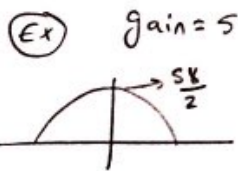


It's not easy to work with filters in the time domain (Do Fourier)

one copy Bandwidth of the LPF must = B_{signal}

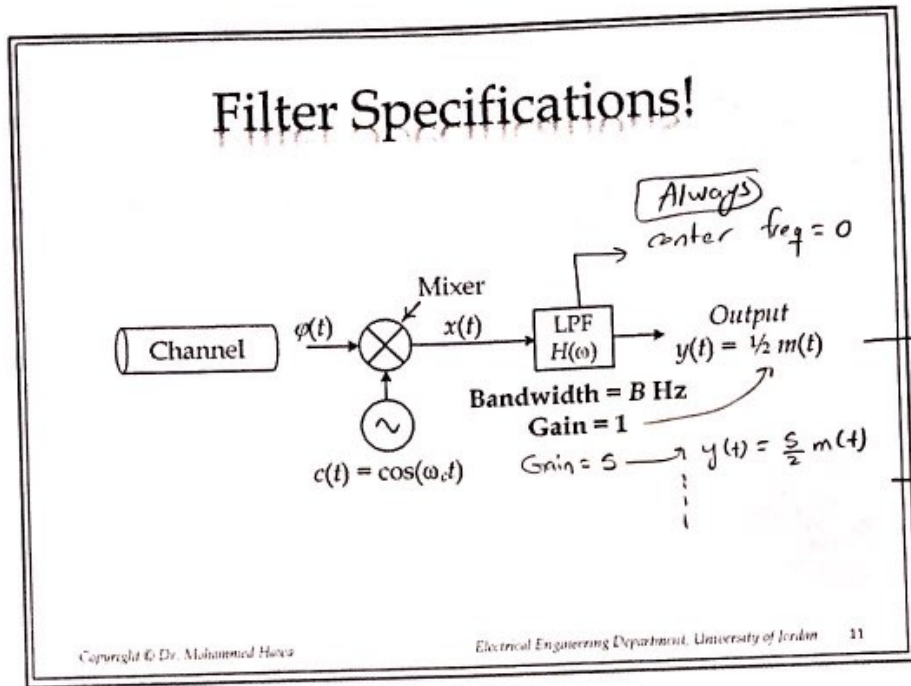
Because

If it was smaller some of the signal will be distorted and if it was bigger more noise will happen



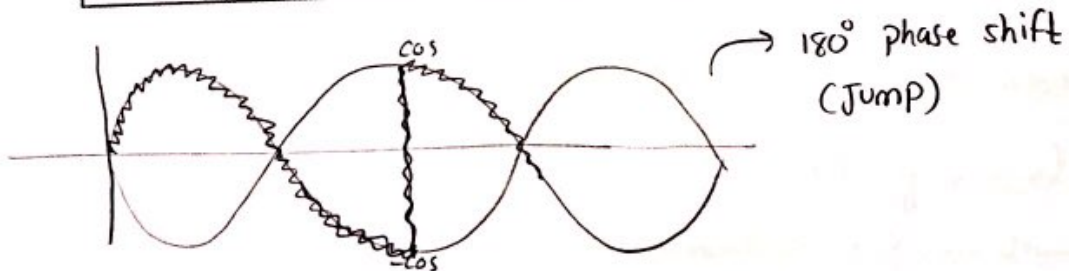
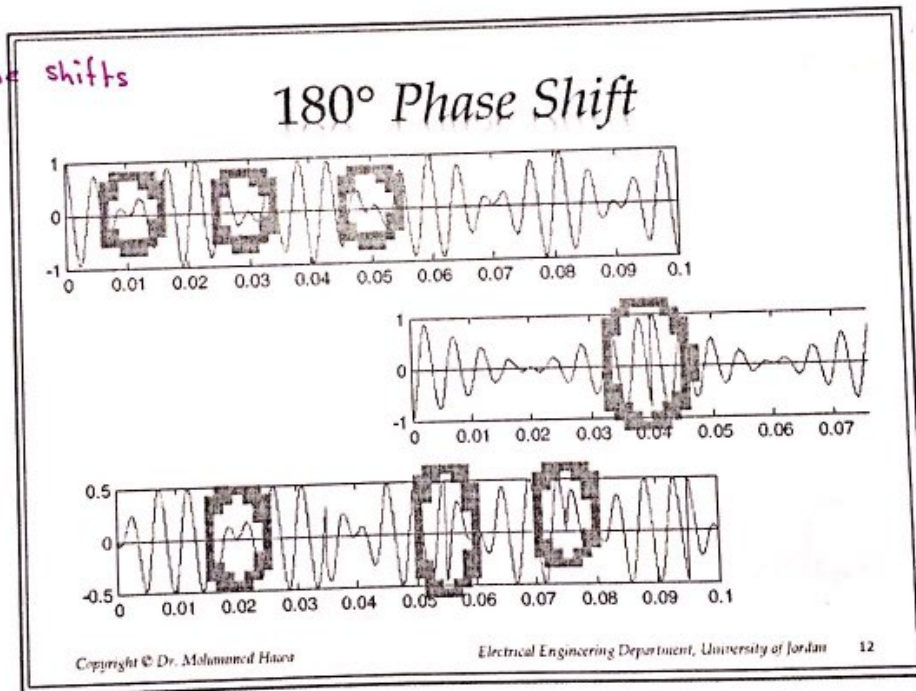
$$2\omega_c \geq 2\pi B + 2\pi B$$

$$\omega_c \geq 2\pi B$$



Be careful!!

$\phi(t)$ has ^{sudden} 180° phase shifts
 DSG-SC
 when
 $m(t) +ve \rightarrow -ve$
 or
 $m(t) -ve \rightarrow +ve$
 (disadvantage)



Example

- Assume we perform DSB-SC modulation for the baseband signal $m(t) = \alpha \cos(\omega_m t)$ [the case of tone modulation], where $\omega_c \gg \omega_m$:
 - Sketch the **time-domain** modulated signal $\phi(t)$.
 - Sketch the **Fourier transform** of the modulated signal $\Phi(\omega)$ [frequency domain].
 - Find the **bandwidth** of $m(t)$ and $\phi(t)$.
 - Find the **average power** in both $m(t)$ and $\phi(t)$.
 - Show the demodulator hardware.
 - Sketch $x(t)$ and $y(t)$ in the demodulator.

tone modulation means
 $m(t) = \alpha \cos(\omega_m t)$
 small freq
 the carrier and the signal are both (cos)

From the freq domain

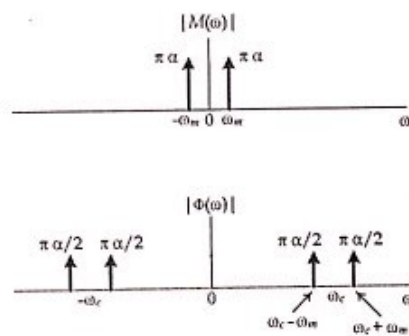
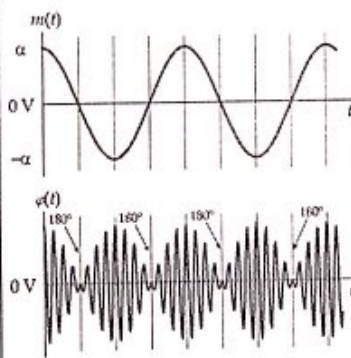
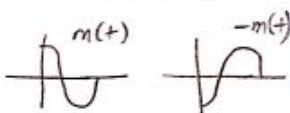
$$\overline{\phi^2(t)} = \overline{\frac{1}{2} m^2(t)}$$

$$= \frac{1}{2} \frac{\alpha^2}{2}$$

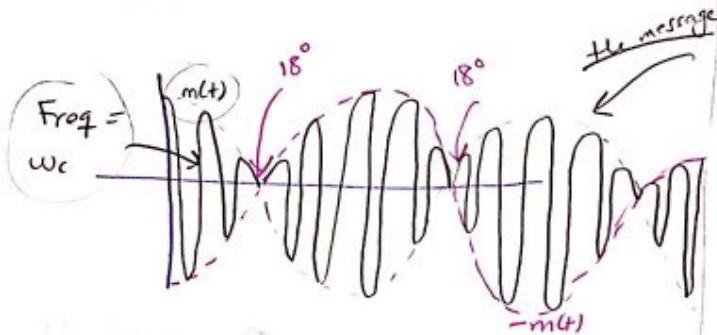
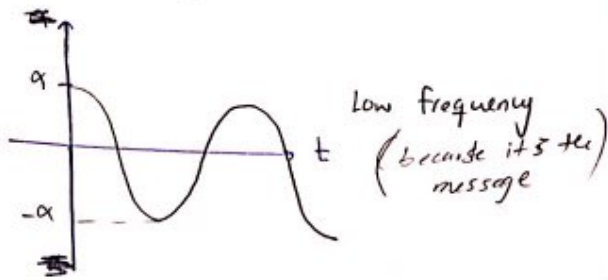
$$= \frac{\alpha^2}{4}$$

Solution

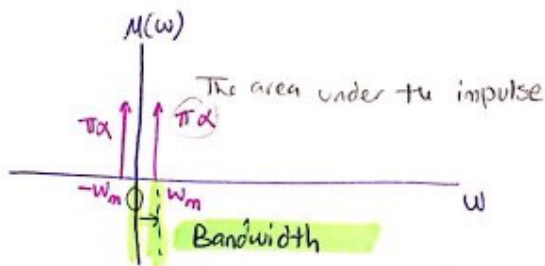
لازم ننبه اذا كانت
 $m(t)$ او $-m(t)$
 فنلبرسه



Q) $\phi(t)$ vs t



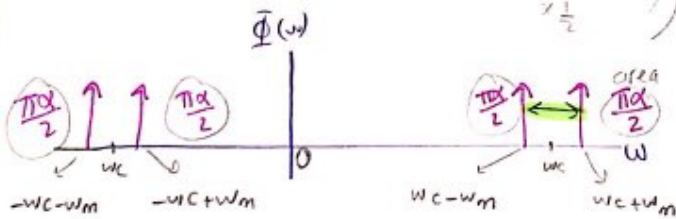
$\Phi(\omega)$ → mathematical (HW)
 ↓
 Graphical ✓



$$M(\omega) = \mathcal{F}\{m(t)\} = \mathcal{F}\{\alpha \cos(\omega_m t)\}$$

$$= \pi\alpha \delta(\omega - \omega_m) + \pi\alpha \delta(\omega + \omega_m)$$

convolution with another cosine
 (shift right, shift left) $\times \frac{1}{2}$



* Bandwidth of $m(t) = \omega_m$ rad/s

$= f_m = \frac{\omega_m}{2\pi}$ Hz

* Band width of $\phi(t) = 2\omega_m$ rad/s

$= 2f_m$ Hz

Homework

- For the following signals $m(t)$, sketch:
 - The modulated signal $\varphi(t)$ at the modulator
 - The Fourier transform $\Phi(\omega)$
 - The signals $x(t)$ and $y(t)$ at the demodulator
 - The Fourier transform $X(\omega)$ and $Y(\omega)$
- Find the average power and bandwidth for the signals $\varphi(t)$ and $y(t)$.
- Are there any phase shifts in $\varphi(t)$? If so, where?
- Determine the DC value in $m(t)$, $\varphi(t)$ and $y(t)$.

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Homework

The figure shows three plots of $m(t)$ versus t (seconds):

- Top plot:** A pulse train with pulses of height 1 and width 0.25, starting at $t = 0.25$. Handwritten notes: "Time shifted by 0.125", "(same power as rect)", "It won't be affected", "* phase shift also won't be affected".
- Middle plot:** A square wave with amplitude 2 and period 1, centered at $t = 0$. Handwritten notes: "DC shift", "here is no sudden phase shift (just a shift)", "Sw, amplitude is".
- Bottom plot:** A triangular wave with peak amplitude 2 and period 2, centered at $t = 1$. Handwritten notes: "CH4", "1", "2".

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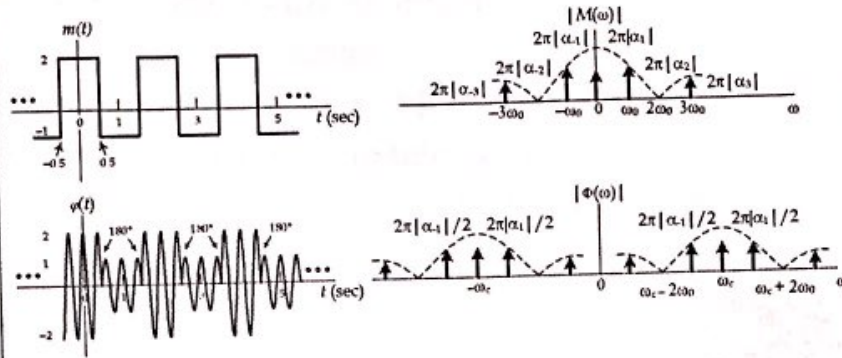
$F\{x(t)\} = X(\omega)$
 $F\{x(t-t_0)\} = X(\omega)e^{-j\omega t_0}$ (phase shift)
 will be affected (avg 100 DC values)

Bandwidth = $\frac{1}{T}$
 $T = 1$
 $B = 1 \text{ Hz}$
 $= 2\pi \text{ rad/s}$

← Be careful!

Time shifted by 0.125
 (same power as rect)
 It won't be affected
 * phase shift also won't be affected
 here is no sudden phase shift (just a shift)
 Sw, amplitude is

Solution: Part(b)



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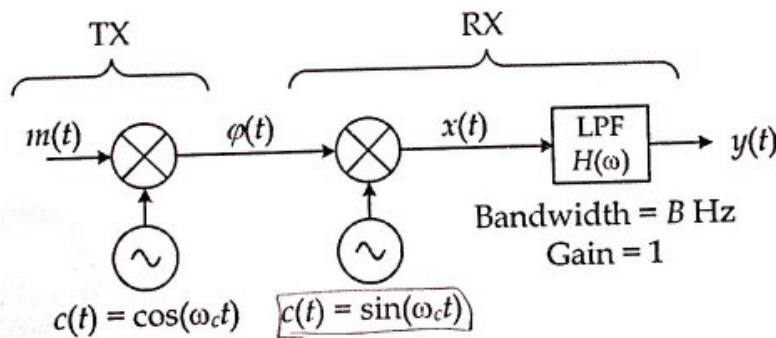
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Exam problem

Homework

DSB-SC

- For the following circuit, sketch $x(t)$ and $y(t)$, along with the Fourier transform $X(\omega)$ and $Y(\omega)$.



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$= \cos(\omega_c t - 90^\circ) \rightarrow$ It affects the phase spectrum density.